

2M x 8 (16-MBIT) DYNAMIC RAM WITH EDO PAGE MODE

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APRIL 2005

FEATURES

- Extended Data-Out (EDO) Page Mode access cycle
- · TTL compatible inputs and outputs
- · Refresh Interval:
 - -- 2,048 cycles/32 ms
- Refresh Mode: RAS-Only,
 - CAS-before-RAS (CBR), and Hidden
- Single power supply: 3.3V ± 10%
- Byte Write and Byte Read operation via two CAS
- Lead-free available

PRODUCT SERIES OVERVIEW

Part No.	Refresh	Voltage		
IS41LV8200A	2K	3.3V ± 10%		

DESCRIPTION

The *ISSI* IS41LV8200A is 2,097,152 x 8-bit high-performance CMOS Dynamic Random Access Memory. These devices offer an accelerated cycle access called EDO Page Mode. EDO Page Mode allows 2,048 random accesses within a single row with access cycle time as short as 20 ns per 4-bit word.

These features make the IS41LV8200A ideally suited for high-bandwidth graphics, digital signal processing, high-performance computing systems, and peripheral applications.

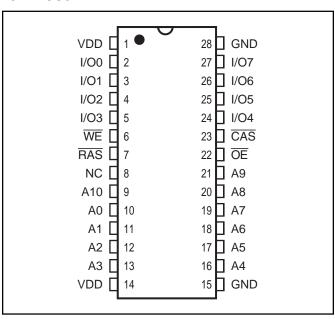
The IS41LV8200A is packaged in 28-pin 300-mil SOJ with JEDEC standard pinouts.

KEY TIMING PARAMETERS

Parameter	-50	-60	Unit
RAS Access Time (trac)	50	60	ns
CAS Access Time (tcac)	14	15	ns
Column Address Access Time (taa)	25	30	ns
EDO Page Mode Cycle Time (tpc)	20	25	ns
Read/Write Cycle Time (tRC)	85	104	ns

PIN CONFIGURATION

28 Pin SOJ



PIN DESCRIPTIONS

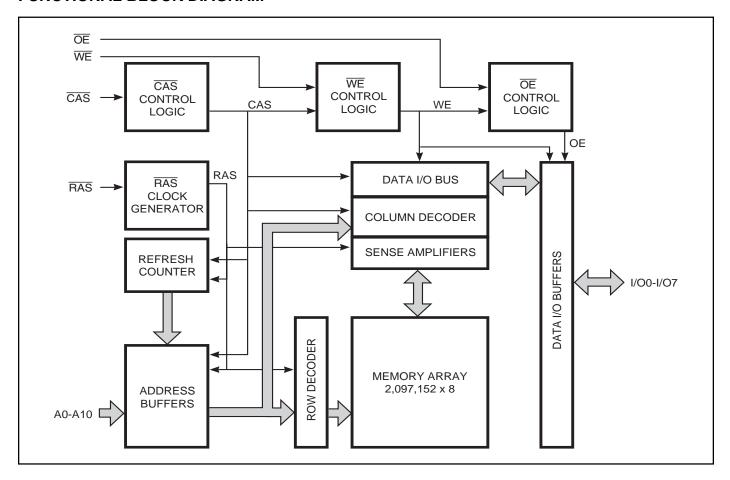
A0-A10	Address Inputs
I/O0-7	Data Inputs/Outputs
WE	Write Enable
ŌĒ	Output Enable
RAS	Row Address Strobe
CAS	Column Address Strobe
VDD	Power
GND	Ground
NC	No Connection

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ISSI®

FUNCTIONAL BLOCK DIAGRAM

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TRUTH TABLE

Function		RAS	CAS	WE	ŌĒ	Address tr/tc	I/O
Standby		Н	Н	Χ	Х	Χ	High-Z
Read		L	L	Н	L	ROW/COL	D оит
Write: Word (Early Write	e)	L	L	L	Х	ROW/COL	DIN
Read-Write		L	L	H→L	L→H	ROW/COL	Dout, Din
EDO Page-Mode Read	1st Cycle:	L	H→L	Н	L	ROW/COL	D оит
	2nd Cycle:	L	$H{ ightarrow} L$	Н	L	NA/COL	D оит
EDO Page-Mode Write	1st Cycle:	L	$H{ ightarrow} L$	L	Χ	ROW/COL	DIN
	2nd Cycle:	L	$H{ ightarrow} L$	L	Χ	NA/COL	DIN
EDO Page-Mode	1st Cycle:	L	$H{ ightarrow} L$	$H{ ightarrow} L$	$L{ ightarrow}H$	ROW/COL	Dout, DIN
Read-Write	2nd Cycle:	L	$H{ ightarrow} L$	$H{ ightarrow} L$	$L{ ightarrow}H$	NA/COL	Dout, DIN
Hidden Refresh	Read	$L{\rightarrow}H{\rightarrow}L$	L	Н	L	ROW/COL	D оит
	Write ⁽¹⁾	$L{\rightarrow}H{\rightarrow}L$	L	L	Χ	ROW/COL	D оит
RAS-Only Refresh		L	Н	Χ	Χ	ROW/NA	High-Z
CBR Refresh		H→L	L	Х	Х	X	High-Z

Note:

1. EARLY WRITE only.



Functional Description

The IS41LV8200A is CMOS DRAMs optimized for high-speed bandwidth, low power applications. During READ or WRITE cycles, each bit is uniquely addressed through the 11 address bits. These are entered 11 bits (A0-A10) at a time. The row address is latched by the Row Address Strobe (RAS). The column address is latched by the Column Address Strobe (CAS). RAS is used to latch the first nine bits and CAS is used the latter ten bits.

Memory Cycle

A memory cycle is initiated by bring RAS LOW and it is terminated by returning both RAS and CAS HIGH. To ensures proper device operation and data integrity any memory cycle, once initiated, must not be ended or aborted before the minimum tras time has expired. A new cycle must not be initiated until the minimum precharge time trp, tcp has elapsed.

Read Cycle

A read cycle is initiated by the falling edge of \overline{CAS} or \overline{OE} , whichever occurs last, while holding \overline{WE} HIGH. The column address must be held for a minimum time specified by tar. Data Out becomes valid only when trac, tar, tar, tar and toer are all satisfied. As a result, the access time is dependent on the timing relationships between these parameters.

Write Cycle

A write cycle is initiated by the falling edge of $\overline{\text{CAS}}$ and $\overline{\text{WE}}$, whichever occurs last. The input data must be valid at or before the falling edge of $\overline{\text{CAS}}$ or $\overline{\text{WE}}$, whichever occurs last.

Auto Refresh Cycle

To retain data, 2,048 refresh cycles are required in each 32 ms period. There are two ways to refresh the memory:

- By clocking each of the 2,048 row addresses (A0 through A10) with RAS at least once every 32 ms. Any read, write, read-modify-write or RAS-only cycle refreshes the addressed row.
- Using a CAS-before-RAS refresh cycle. CAS-before-RAS refresh is activated by the falling edge of RAS, while holding CAS LOW. In CAS-before-RAS refresh cycle, an internal 9-bit counter provides the row addresses and the external address inputs are ignored.

CAS-before-RAS is a refresh-only mode and no data access or device selection is allowed. Thus, the output remains in the High-Z state during the cycle.

Power-On

After application of the V_{DD} supply, an initial pause of 200 μ s is required followed by a minimum of eight initialization cycles (any combination of cycles containing a \overline{RAS} signal).

During power-on, it is recommended that **RAS** track with VDD or be held at a valid VIH to avoid current surges.



ABSOLUTE MAXIMUM RATINGS(1)

Symbol	Parameters		Rating	Unit
VT	Voltage on Any Pin Relative to GND	3.3V	-0.5 to +4.6	V
Vdd	Supply Voltage	3.3V	-0.5 to +4.6	V
Іоит	Output Current		50	mA
PD	Power Dissipation		1	W
Тѕтс	Storage Temperature		-55 to +125	°C

Note:

RECOMMENDED OPERATING CONDITIONS (Voltages are referenced to GND.)

Symbol	Parameter		Min.	Тур.	Max.	Unit
VDD	Supply Voltage	3.3V	3.0	3.3	3.6	V
VIH	Input High Voltage	3.3V	2.0	_	VDD + 0.3	V
VIL	Input Low Voltage	3.3V	-0.3	_	0.8	V

CAPACITANCE(1,2)

Symbol	Parameter	Max.	Unit
CIN1	Input Capacitance: A0-A10(A11)	5	pF
CIN2	Input Capacitance: RAS, CAS, WE, OE	7	pF
Сю	Data Input/Output Capacitance: I/O0-I/O3	7	pF

Notes:

- 1. Tested initially and after any design or process changes that may affect these parameters.
- 2. Test conditions: TA = 25°C, f = 1 MHz.

Stress greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device.
This is a stress rating only and functional operation of the device at these or any other conditions above those indicated
in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended
periods may affect reliability.



ELECTRICAL CHARACTERISTICS(1)

(Recommended Operating Conditions unless otherwise noted.)

Symbol	Parameter	Test Condition	\mathbf{V}_{DD}	Speed	Min.	Max.	Unit
lıL	Input Leakage Current	Any input $0V \le V_{IN} \le V_{DD}$ Other inputs not under test = $0V$			- 5	5	μA
lio	Output Leakage Current	Output is disabled (Hi-Z) 0V ≤ Vouт ≤ Vpp			– 5	5	μA
Vон	Output High Voltage Level	IOH = -5.0 mA, VDD = 5V IOH = -2.0 mA, VDD = 3.3V			2.4	_	V
Vol	Output Low Voltage Level	IOL = 4.2 mA, VDD = 5V IOL = 2 mA, VDD = 3.3V			_	0.4	V
lcc1	Standby Current: TTL	$\overline{\text{RAS}}, \overline{\text{CAS}} \ge VIH$	3.3V		_	1	mA
lcc2	Standby Current: CMOS	$\overline{\text{RAS}}, \overline{\text{CAS}} \ge V_{DD} - 0.2V$	3.3V		_	1	mΑ
Icc3	Operating Current: Random Read/Write ^(2,3,4) Average Power Supply Current	RAS, CAS, Address Cycling, trc = trc (min.)		-50 -60	_	150 140	mA
Icc4	Operating Current: EDO Page Mode ^(2,3,4) Average Power Supply Current	RAS= VIL, CAS ≥ VIH trc = trc (min.)		-50 -60	_	150 140	mA
Icc5	Refresh Current: RAS-Only ^(2,3) Average Power Supply Current	RAS Cycling, CAS ≥ VIH trc = trc (min.)		-50 -60	_	150 140	mA
Icc6	Refresh Current: CBR ^(2,3,5) Average Power Supply Current	RAS, CAS Cycling trc = trc (min.)		-50 -60	_	150 140	mA

Notes:

^{1.} An initial pause of 200 μ s is required after power-up followed by eight $\overline{\textbf{RAS}}$ refresh cycles ($\overline{\textbf{RAS}}$ -Only or CBR) before proper device operation is assured. The eight FAS cycles wake-up should be repeated any time the tREF refresh requirement is exceeded.

^{2.} Dependent on cycle rates.

^{3.} Specified values are obtained with minimum cycle time and the output open.

^{4.} Column-address is changed once each EDO Page cycle.

^{5.} Enables on-chip refresh and address counters.



AC CHARACTERISTICS(1,2,3,4,5,6)

 $(Recommended\,Operating\,Conditions\,unless\,otherwise\,noted.)$

			-50		60	
Symbol	Parameter	Min.	Max.	Min.	Max.	Units
trc	Random READ or WRITE Cycle Time	85	_	104	_	ns
t RAC	Access Time from RAS (6, 7)	_	50	_	60	ns
tcac	Access Time from CAS(6, 8, 15)	_	14	_	15	ns
t AA	Access Time from Column-Address ⁽⁶⁾	_	25	_	30	ns
tras	RAS Pulse Width	50	10K	60	10K	ns
t RP	RAS Precharge Time	30	_	40	_	ns
tcas	CAS Pulse Width(23)	8	10K	10	10K	ns
t CP	CAS Precharge Time ⁽⁹⁾	8	_	15	_	ns
tcsh	CAS Hold Time (21)	45	_	45	_	ns
t RCD	RAS to CAS Delay Time(10, 20)	19	37	18	45	ns
tasr	Row-Address Setup Time	0	_	0	_	ns
t RAH	Row-Address Hold Time	9	_	10	_	ns
tasc	Column-Address Setup Time(20)	0	_	0	_	ns
t CAH	Column-Address Hold Time(20)	7	_	10	_	ns
t ar	Column-Address Hold Time (referenced to RAS)	44	_	55	_	ns
t RAD	RAS to Column-Address Delay Time(11)	14	25	13	30	ns
tral	Column-Address to RAS Lead Time	25	_	30	_	ns
t RPC	RAS to CAS Precharge Time	5	_	5	_	ns
trsh	RAS Hold Time	14	_	13	_	ns
t RHCP	RAS Hold Time from CAS Precharge	30	_	35	_	ns
tclz	CAS to Output in Low-Z(15, 24)	0	_	0	_	ns
tcrp	CAS to RAS Precharge Time(21)	5	_	5	_	ns
top	Output Disable Time(19,24)	5	15	5	15	ns
toe	Output Enable Time(15, 16)	_	12	_	15	ns
toed	Output Enable Data Delay (Write)	8	_	13	_	ns
toehc	OE HIGH Hold Time from CAS HIGH	7	_	7	_	ns
toep	OE HIGH Pulse Width	8	_	8	_	ns
toes	OE LOW to CAS HIGH Setup Time	5	_	5	_	ns
trcs	Read Command Setup Time(17,20)	0	_	0	_	ns
t RRH	Read Command Hold Time (referenced to RAS) ⁽¹²⁾	0	_	0	_	ns
t RCH	Read Command Hold Time (referenced to CAS)(12, 17, 21)	0	_	0	_	ns
twch	Write Command Hold Time(17)	8	_	10	_	ns
twcr	Write Command Hold Time (referenced to RAS)(17)	40	_	50	_	ns
twp	Write Command Pulse Width(17)	8	_	10	_	ns
twpz	WE Pulse Widths to Disable Outputs	7	_	7	_	ns



AC CHARACTERISTICS (Continued)(1,2,3,4,5,6)

(Recommended Operating Conditions unless otherwise noted.)

		-5	50	-	-60		
Symbol	Parameter	Min.	Max.	Min.	Max.	Units	
trwL	Write Command to RAS Lead Time(17)	13	_	15	_	ns	
tcwL	Write Command to CAS Lead Time(17, 21)	8	_	10	_	ns	
twcs	Write Command Setup Time(14, 17, 20)	0	_	0	_	ns	
t DHR	Data-in Hold Time (referenced to RAS)	46	_	55	_	ns	
tach	Column-Address Setup Time to CAS Precharge during WRITE Cycle	15	_	15	_	ns	
t OEH	OE Hold Time from WE during READ-MODIFY-WRITE cycle(18)	8	_	10	_	ns	
tos	Data-In Setup Time(15, 22)	0	_	0	_	ns	
t DH	Data-In Hold Time(15,22)	8	_	10	_	ns	
t RWC	READ-MODIFY-WRITE Cycle Time	108	_	133	_	ns	
trwd	RAS to WE Delay Time during READ-MODIFY-WRITE Cycle ⁽¹⁴⁾	64	_	79	_	ns	
tcwd	CAS to WE Delay Time(14, 20)	25	_	32	_	ns	
t awd	Column-Address to WE Delay Time(14)	37	_	47	_	ns	
tpc	EDO Page Mode READ or WRITE Cycle Time	20	_	25	_	ns	
trasp	RAS Pulse Width in EDO Page Mode	50	100K	60	100K	ns	
t CPA	Access Time from CAS Precharge(15)	_	30	_	32	ns	
t PRWC	READ-WRITE Cycle Time(24)	59	_	63	_	ns	
tсон	Data Output Hold after CAS LOW	5	_	5	_	ns	
toff	Output Buffer Turn-Off Delay from CAS or RAS(13,15,19,24)	0	12	0	15	ns	
twnz	Output Disable Delay from WE	3	10	3	10	ns	
tcsr	CAS Setup Time (CBR REFRESH)(20, 25)	10	_	10	_	ns	
tchr	CAS Hold Time (CBR REFRESH)(21,25)	10	_	10	_	ns	
tord	OE Setup Time prior to RAS during HIDDEN REFRESH Cycle	0	_	0	_	ns	
tref	Auto Refresh Period 2,048 Cycles	_	32	_	32	ms	
tτ	Transition Time (Rise or Fall)(2,3)	2	50	2	50	ns	

AC TEST CONDITIONS

Output load: One TTL Load and 50 pF ($VDD = 3.3V \pm 10\%$)

Input timing reference levels: VIH = 2.0V, VIL = 0.8V ($VDD = 3.3V \pm 10\%$)

Output timing reference levels: VOH = 2.0V, VOL = 0.8V ($VDD = 3.3V \pm 10\%$)

Notes:

- 1. An initial pause of 200 µs is required after power-up followed by eight **RAS** refresh cycle (**RAS**-Only or CBR) before proper device operation is assured. The eight **RAS** cycles wake-up should be repeated any time the tree refresh requirement is exceeded.
- 2. Viн (MIN) and Vi∟ (MAX) are reference levels for measuring timing of input signals. Transition times, are measured between Viн and Vi⊢ (or between Vi⊢ and Vi⊢) and assume to be 1 ns for all inputs.
- 3. In addition to meeting the transition rate specification, all input signals must transit between V_{IH} and V_{IL} (or between V_{IL} and V_{IH}) in a monotonic manner.
- 4. If \overline{CAS} and $\overline{RAS} = V_{IH}$, data output is High-Z.
- 5. If **CAS** = VIL, data output may contain data from the last valid READ cycle.
- 6. Measured with a load equivalent to one TTL gate and 50 pF.
- 7. Assumes that tRCD ≤ tRCD (MAX). If tRCD is greater than the maximum recommended value shown in this table, tRAC will increase by the amount that tRCD exceeds the value shown.
- 8. Assumes that $trcd \ge trcd$ (MAX).
- 9. If CAS is LOW at the falling edge of RAS, data out will be maintained from the previous cycle. To initiate a new cycle and clear the data output buffer, CAS and RAS must be pulsed for tcp.
- 10. Operation with the tRCD (MAX) limit ensures that tRAC (MAX) can be met. tRCD (MAX) is specified as a reference point only; if tRCD is greater than the specified tRCD (MAX) limit, access time is controlled exclusively by tCAC.
- 11. Operation within the trad (MAX) limit ensures that trcd (MAX) can be met. trad (MAX) is specified as a reference point only; if trad is greater than the specified trad (MAX) limit, access time is controlled exclusively by trad.
- 12. Either trich or trich must be satisfied for a READ cycle.
- 13. toff (MAX) defines the time at which the output achieves the open circuit condition; it is not a reference to Voh or Vol.
- 14. twcs, trwb, tawb and tcwb are restrictive operating parameters in LATE WRITE and READ-MODIFY-WRITE cycle only. If twcs ≥ twcs (MIN), the cycle is an EARLY WRITE cycle and the data output will remain open circuit throughout the entire cycle. If trwb ≥ trwb (MIN), tawb ≥ tawb (MIN) and tcwb ≥ tcwb (MIN), the cycle is a READ-WRITE cycle and the data output will contain data read from the selected cell. If neither of the above conditions is met, the state of I/O (at access time and until CAS and RAS or OE go back to Vih) is indeterminate. OE held HIGH and WE taken LOW after CAS goes LOW result in a LATE WRITE (OE-controlled) cycle.
- 15. Output parameter (I/O) is referenced to corresponding **CAS** input.
- 16. During a READ cycle, if **OE** is LOW then taken HIGH before **CAS** goes HIGH, I/O goes open. If **OE** is tied permanently LOW, a LATE WRITE or READ-MODIFY-WRITE is not possible.
- 17. Write command is defined as WE going low.
- 18. LATE WRITE and READ-MODIFY-WRITE cycles must have both top and toeh met (OE HIGH during WRITE cycle) in order to ensure that the output buffers will be open during the WRITE cycle. The I/Os will provide the previously written data if CAS remains LOW and OE is taken back to LOW after toeh is met.
- 19. The I/Os are in open during READ cycles once top or toff occur.
- 20. Determined by falling edge of CAS.
- 21. Determined by rising edge of CAS.
- 22. These parameters are referenced to $\overline{\text{CAS}}$ leading edge in EARLY WRITE cycles and $\overline{\text{WE}}$ leading edge in LATE WRITE or READ-MODIFY-WRITE cycles.
- 23. **CAS** must meet minimum pulse width.
- 24. The 3 ns minimum is a parameter guaranteed by design.
- 25. Enables on-chip refresh and address counters.



◆ trch
◆

Valid Data

toes

- toff(1)

tod

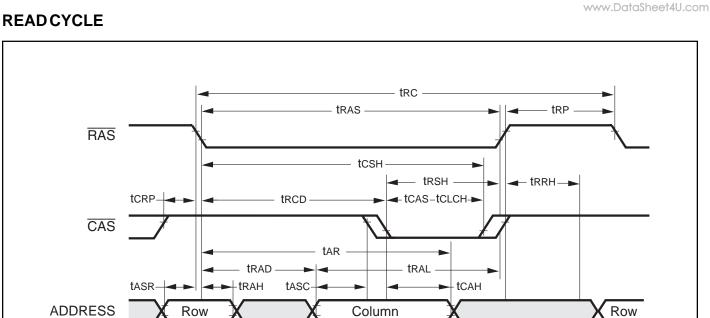
Open -

Don't Care

 $\overline{\mathsf{WE}}$

I/O

ŌĒ



trcs-

tRAC

- taa

tCAC tCLC-

toe

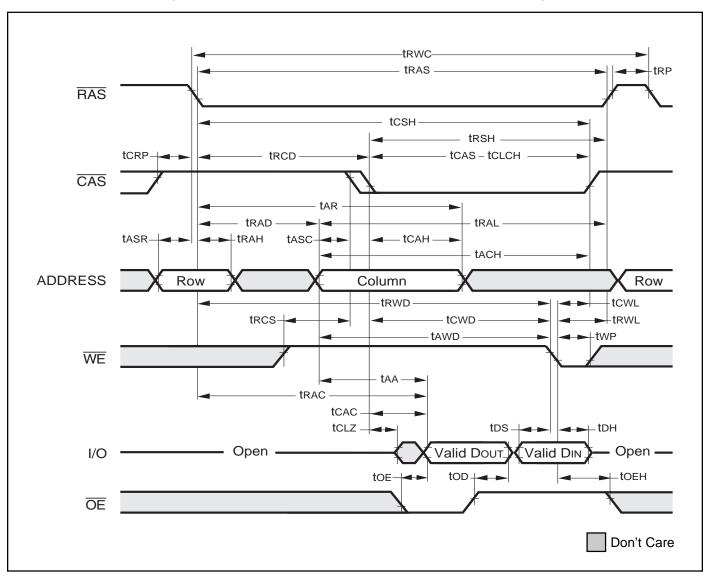
Note:

1. toff is referenced from rising edge of \overline{RAS} or \overline{CAS} , whichever occurs last.

Open -

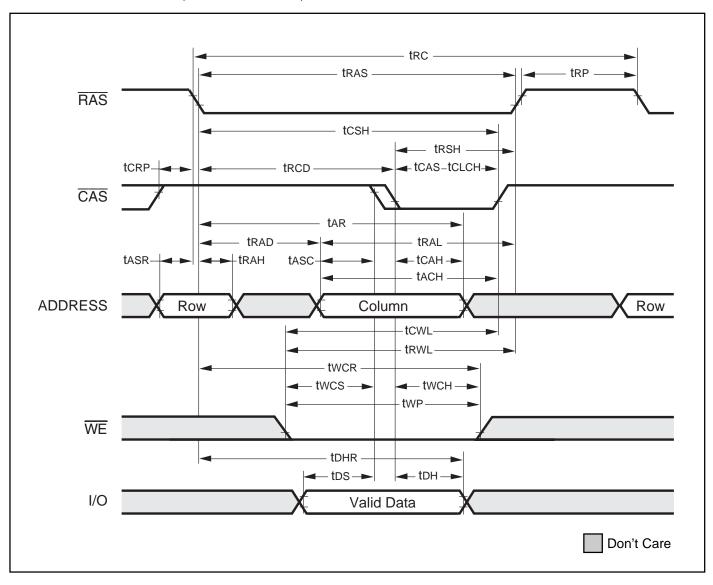


READ WRITE CYCLE (LATE WRITE and READ-MODIFY-WRITE CYCLES)



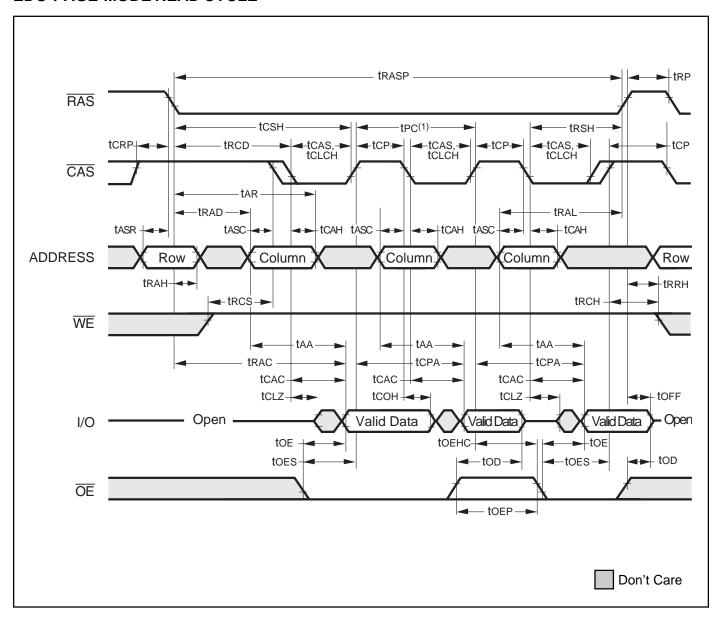


EARLY WRITE CYCLE (OE = DON'T CARE)



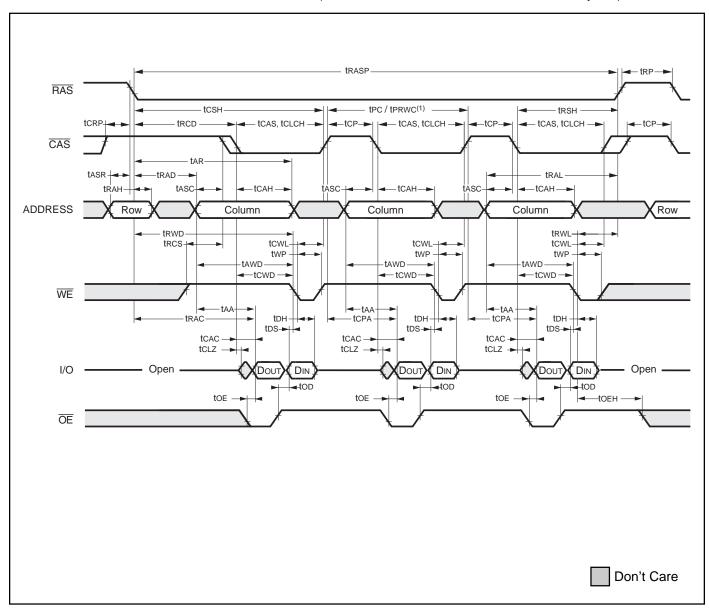


EDO-PAGE-MODE READ CYCLE



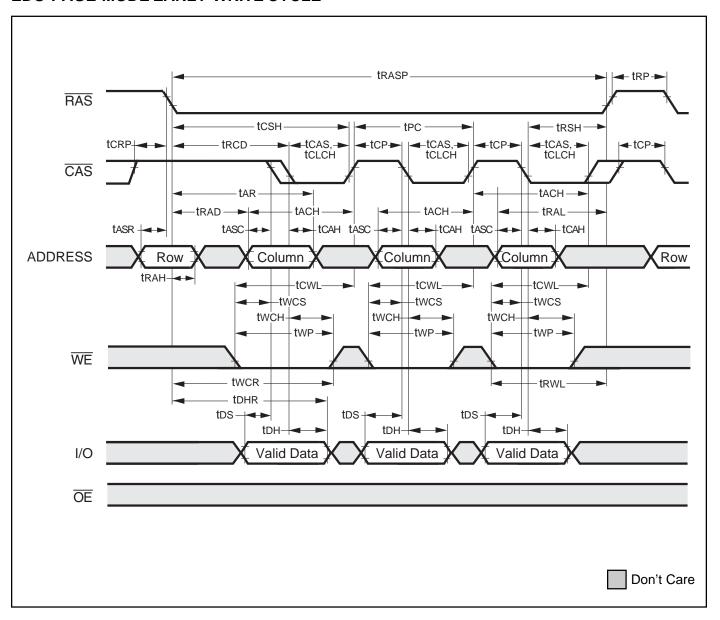


EDO-PAGE-MODE READ-WRITE CYCLE (LATE WRITE and READ-MODIFY-WRITE Cycles)



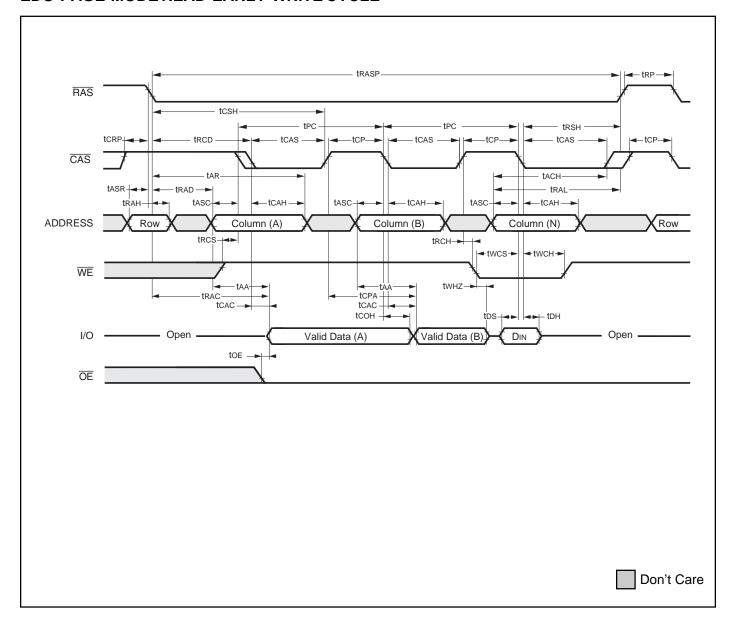


EDO-PAGE-MODE EARLY-WRITE CYCLE





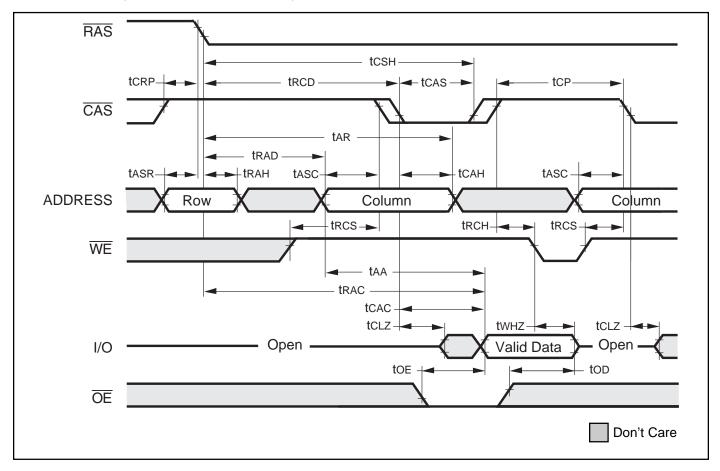
EDO-PAGE-MODE READ-EARLY-WRITE CYCLE



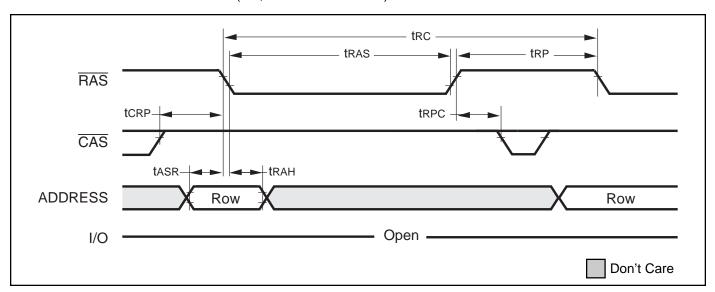


AC WAVEFORMS

$\textbf{READ CYCLE} \ (\textbf{With } \overline{\textbf{WE}}\text{-}\textbf{Controlled Disable})$



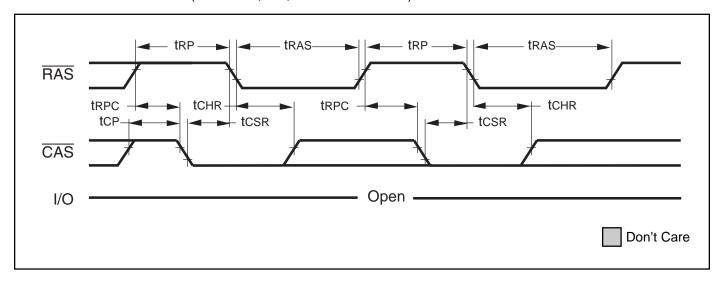
RAS-ONLY REFRESH CYCLE (OE, WE = DON'T CARE)



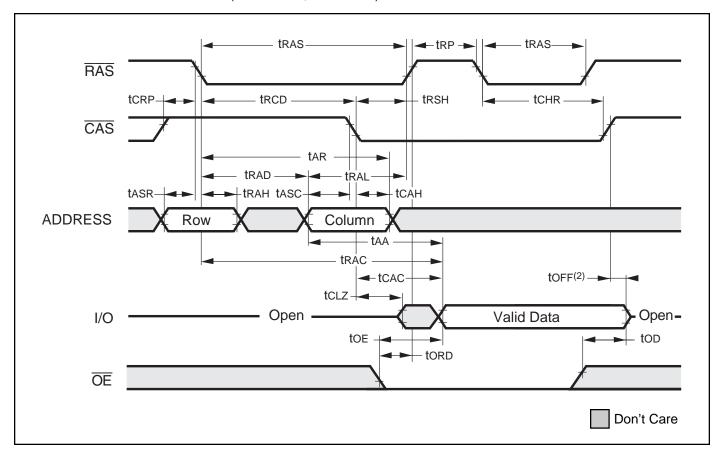


 $\overline{\textbf{CBR}}$ REFRESH CYCLE (Addresses; $\overline{\textbf{WE}}$, $\overline{\textbf{OE}}$ = DON'T CARE)





HIDDEN REFRESH CYCLE⁽¹⁾ (WE = HIGH; OE = LOW)





ORDERING INFORMATION

Voltage: 3.3V

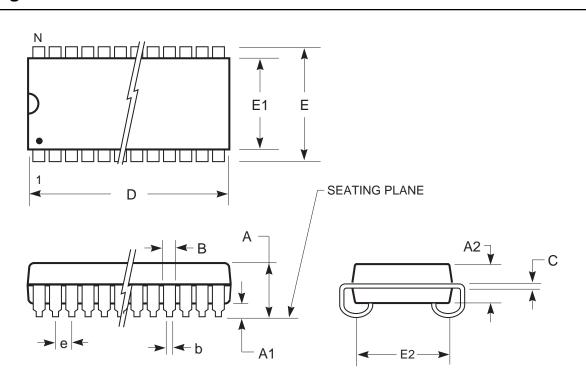
Speed (ns)	Order Part No.	Package
50	IS41LV8200A-50J	300-mil SOJ
50	IS41LV8200A-50JL	300-mil SOJ, Lead-free
60	IS41LV8200A-60J	300-mil SOJ
60	IS41LV8200A-60JL	300-mil SOJ, Lead-free

PACKAGING INFORMATION



300-mil Plastic SOJ Package Code: J

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	MILLIMETERS			IN	INCHES			
Sym.	Min.	Тур.	Max.	Min.	Тур.	Max.		
N0. Leads		24/26						
A	_	_	3.56	_	_	0.140		
A1	0.64	_	_	0.025	_	_		
A2	2.41	_	2.67	0.095	_	0.105		
b	0.41	_	0.51	0.016	_	0.020		
В	0.66	_	0.81	0.026	_	0.032		
С	0.20	_	0.25	0.008	_	0.010		
D	17.02	_	17.27	0.670		0.680		
E	8.26	_	8.76	0.325	_	0.345		
E1	7.49	_	7.75	0.295		0.305		
E2	6.27	_	7.29	0.247	_	0.287		
e	1.27 BSC		С	0.0)50 B	SC		

Notes:

- Controlling dimension: inches, unless otherwise specified.
- 2. BSC = Basic lead spacing between centers.
- Dimensions D and E1 do not include mold flash protrusions and should be measured from the bottom of the package.
- 4. Formed leads shall be planar with respect to one another within 0.004 inches at the seating plane.

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PACKAGING INFORMATION



300-mil Plastic SOJ Package Code: J

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	MILL	IMET	ERS	II	NCHE	S	
Sym.	Min.	Тур.	Max.	Min.	Тур.	Max.	
N0. Leads		28					
Α	_	_	3.56	_	_	0.140	
A1	0.64	_	_	0.025	_	_	
A2	2.41	_	2.67	0.095	_	0.105	
b	0.41	_	0.51	0.016	_	0.020	
В	0.66	_	0.81	0.026	_	0.032	
С	0.20	_	0.25	0.008	_	0.010	
D	18.29	_	18.54	0.720	_	0.730	
E	8.26	_	8.76	0.325	_	0.345	
E1	7.49	_	7.75	0.295	_	0.305	
E2	6.27	_	7.29	0.247	_	0.287	
е	1	.27 BS	С	0.0	050 B	SC	

	MILLIMETERS			INCHES			
Sym.	Min.	Тур.	Max.	Min.	Тур.	Max.	
N0. Leads		32					
A	_	_	3.56	_	_	0.140	
A1	0.64	_	_	0.025	_	_	
A2	2.41	_	2.67	0.095	_	0.105	
b	0.41	_	0.51	0.016	_	0.020	
В	0.66	_	0.81	0.026	_	0.032	
С	0.20	_	0.25	0.008	_	0.010	
D	20.83	_	21.08	0.820	_	0.830	
E	8.26	_	8.76	0.325	_	0.345	
E1	7.49	_	7.75	0.295	_	0.305	
E2	6.27	_	7.29	0.247	_	0.287	
е	1.27 BSC			0.	050 B	SC	