

flowPIM 0

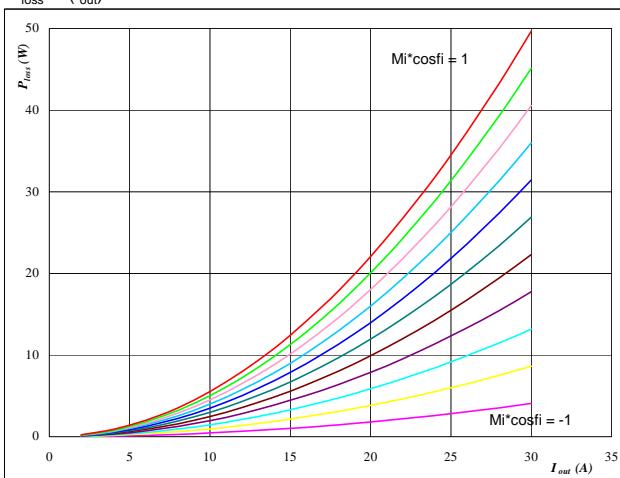
Output Inverter Application

600V/15A
General conditions
3phase SPWM

V_{GEon}	=	15 V
V_{GEOFf}	=	0 V
R_{gon}	=	16 Ω
R_{goff}	=	8 Ω

Figure 1
IGBT
Typical average static loss as a function of output current

$$P_{loss} = f(I_{out})$$

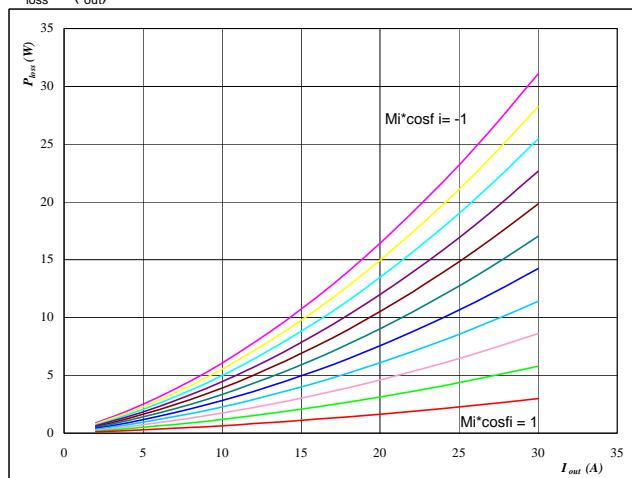

At

$$T_j = 125 \quad ^\circ C$$

 $Mi \cdot \cos \phi$ from -1 to 1 in steps of 0,2

Figure 2
FWD
Typical average static loss as a function of output current

$$P_{loss} = f(I_{out})$$

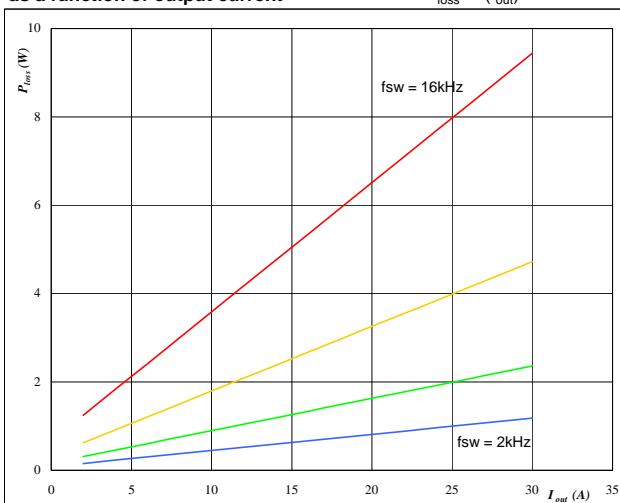

At

$$T_j = 125 \quad ^\circ C$$

 $Mi \cdot \cos \phi$ from -1 to 1 in steps of 0,2

Figure 3
IGBT
Typical average switching loss as a function of output current

$$P_{loss} = f(I_{out})$$


At

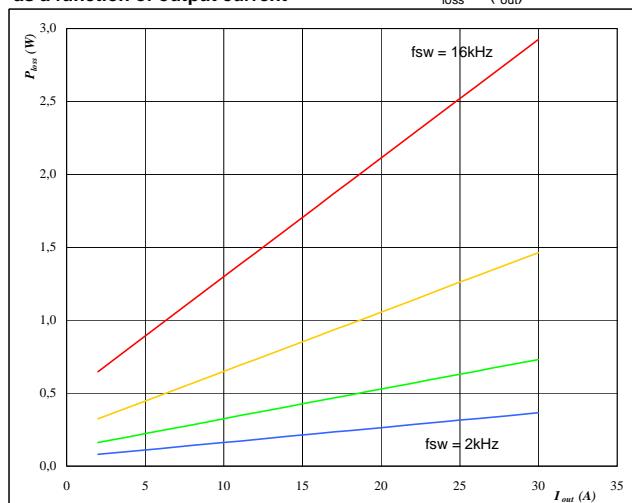
$$T_j = 125 \quad ^\circ C$$

$$DC \text{ link} = 320 \quad V$$

 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 4
FWD
Typical average switching loss as a function of output current

$$P_{loss} = f(I_{out})$$


At

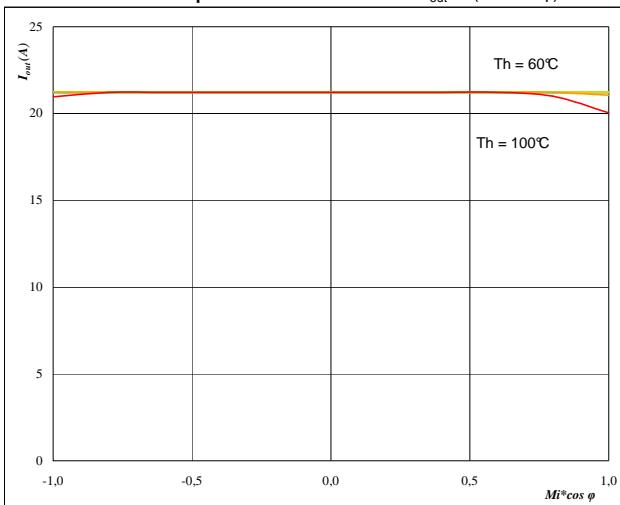
$$T_j = 125 \quad ^\circ C$$

$$DC \text{ link} = 320 \quad V$$

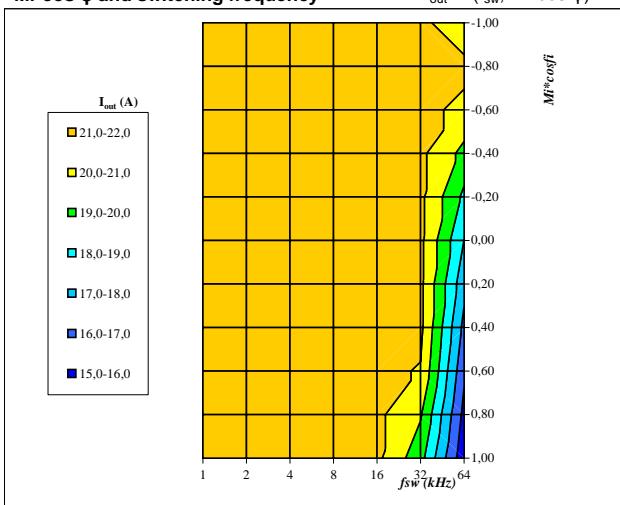
 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

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Figure 5
**Typical available 50Hz output current
as a function $M_i \cos \varphi$**

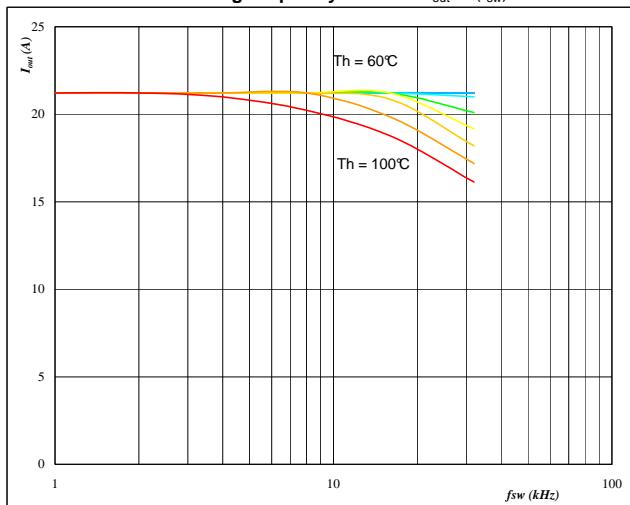
$$I_{out} = f(M_i \cos \varphi)$$


At
 $T_j = 125 \text{ } ^\circ\text{C}$
 $\text{DC link} = 320 \text{ } \text{V}$
 $f_{sw} = 4 \text{ } \text{kHz}$
 $T_h \text{ from } 60 \text{ } ^\circ\text{C to } 100 \text{ } ^\circ\text{C in steps of } 5 \text{ } ^\circ\text{C}$
Figure 7
**Typical available 50Hz output current as a function of
 $M_i \cos \varphi$ and switching frequency**

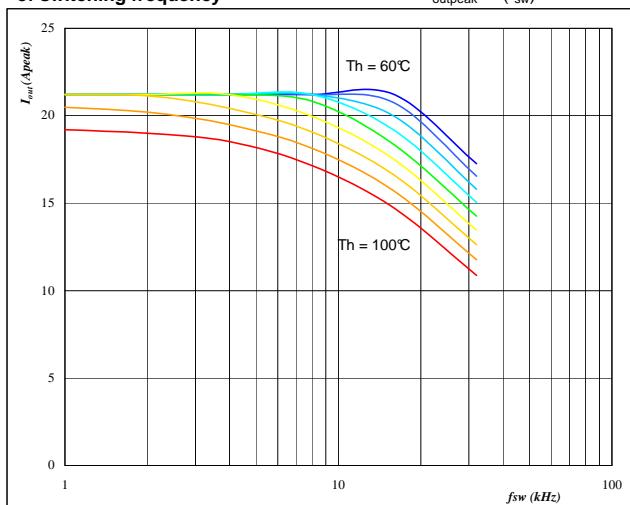
$$I_{out} = f(f_{sw}, M_i \cos \varphi)$$


At
 $T_j = 125 \text{ } ^\circ\text{C}$
 $\text{DC link} = 320 \text{ } \text{V}$
 $T_h = 80 \text{ } ^\circ\text{C}$
Figure 6
**Typical available 50Hz output current
as a function of switching frequency**

$$I_{out} = f(f_{sw})$$


At
 $T_j = 125 \text{ } ^\circ\text{C}$
 $\text{DC link} = 320 \text{ } \text{V}$
 $M_i \cos \varphi = 0,8$
 $T_h \text{ from } 60 \text{ } ^\circ\text{C to } 100 \text{ } ^\circ\text{C in steps of } 5 \text{ } ^\circ\text{C}$
Figure 8
**Typical available 0Hz output current as a function
of switching frequency**

$$I_{outpeak} = f(f_{sw})$$

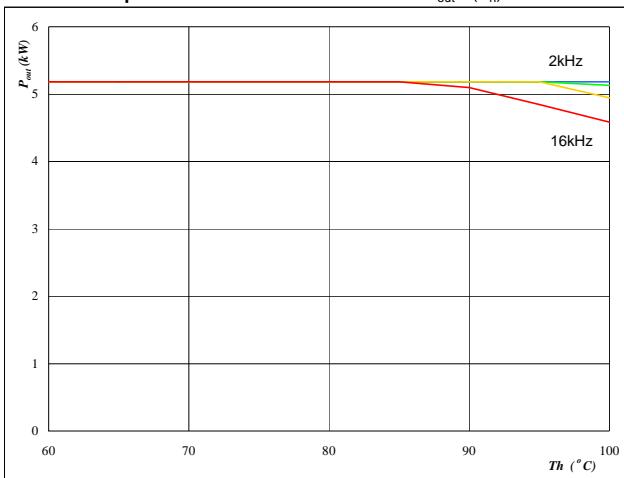

At
 $T_j = 125 \text{ } ^\circ\text{C}$
 $\text{DC link} = 320 \text{ } \text{V}$
 $T_h \text{ from } 60 \text{ } ^\circ\text{C to } 100 \text{ } ^\circ\text{C in steps of } 5 \text{ } ^\circ\text{C}$
 $M_i = 0$

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Figure 9

Typical available peak output power as a function of heatsink temperature
 $P_{out}=f(T_h)$


At

T_j = 125 °C

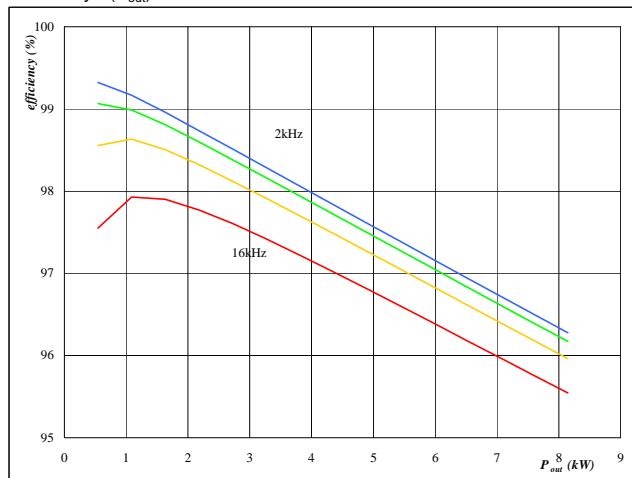
DC link = 320 V

Mi = 1

cos φ = 0,80

f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 10

Typical efficiency as a function of output power
efficiency=f(P_{out})


At

T_j = 125 °C

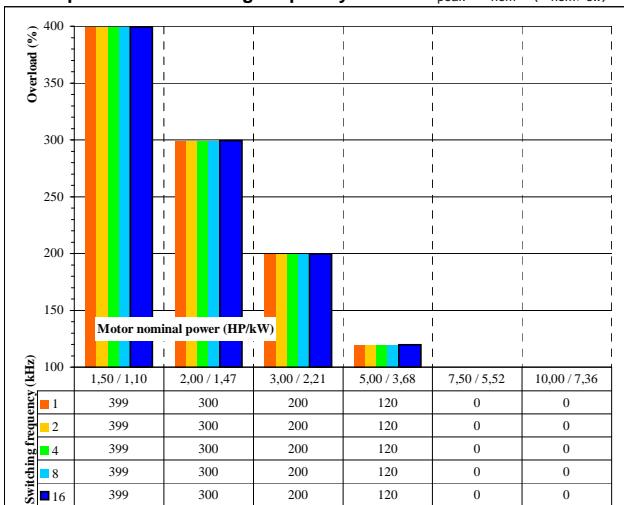
DC link = 320 V

Mi = 1

cos φ = 0,80

f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 11

Typical available overload factor as a function of motor power and switching frequency
 $P_{peak} / P_{nom}=f(P_{nom}, f_{sw})$


At

T_j = 125 °C

DC link = 320 V

Mi = 1

cos φ = 0,8

f_{sw} from 1 kHz to 16 kHz in steps of factor 2

T_h = 80 °C

Motor eff = 0,85