

# SONY

# CXA1445M

## HDD Equalizer (Pulse Slimming) IC

### Description

The CXA1445M is an IC for HDD read data equalizers (cosine equalization).

The delay circuit realized through the adoption of an active filter circuit dispenses from the expensive delay line so far in use. Delay time may be changed at will by altering the resistance value.

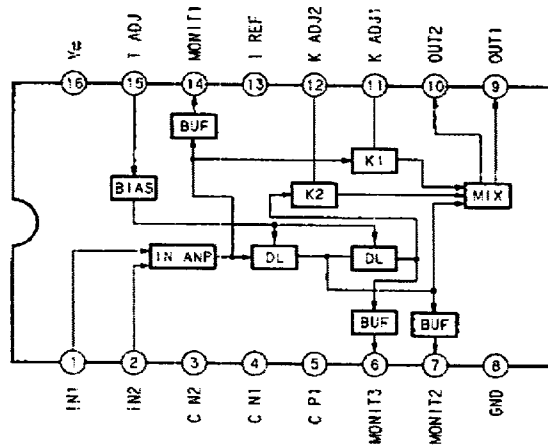
### Features

- The delay circuit obtained through an active filter circuit dispenses from external delay lines. Delay time adjustment is possible by changing the external resistance value.
- Mix ratio adjustment of K1 and K2 is possible by changing the external resistance value.
- 5V single power supply

16pin SOP (Plastic)



### Block Diagram and Pin Configuration



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**Absolute Maximum Ratings (Ta=25°C)**

- Supply voltage  $V_{CC}$  7 V
- Storage temperature  $T_{stg}$  -55 to +150 °C

**Operating Conditions**

- Supply voltage  $V_{CC}$  4.5 to 5.5 V
- Operating temperature  $T_{opr}$  -20 to +75 °C

**Pin Description**

| No. | Symbol | Voltage | Equivalent circuit | Description  |
|-----|--------|---------|--------------------|--|
| 1   | IN1    | 2.0V    |                    | Inputs data signals from read amplifier as differential signals through a capacitor. Internal impedance is approx. 16kΩ. |
| 2   | IN2    |         |                    |  |
| 3   | CN2    | 1.7V    |                    | Connects capacitor (0.01μF) between this pin and GND to control noise in the circuit.                                    |
| 4   | CN1    |         |                    |  |
| 5   | CP1    | 3.5V    |                    | Connects capacitor (0.01μF) between this pin and V <sub>CC</sub> to control noise in the circuit.                        |
| 6   | MONIT3 | 2.4V    |                    | Monitor pin output through buffer after input signal passing two delay lines.  |
| 7   | MONIT2 | 2.4V    |                    | Monitor pin output through buffer after input signal passing the first delay line.                                       |

| No. | Symbol          | Voltage | Equivalent circuit | Description  |
|-----|-----------------|---------|--------------------|--|
| 8   | GND             | 0V      |                    | GND pin for all circuits   |
| 9   | OUT1            | 3.8V    |                    | Signal output pin. Equalized signal is output to pulse detector.   |
| 10  | OUT2            |         |                    |  |
| 11  | K ADJ1          | 1.2V    |                    | A resistor is connected to set $K_1$ . $K_1$ = approx. 0.25 at 12k $\Omega$ (Typ.) Varying the resistance value from $\infty$ to 4k $\Omega$ varies $K_1$ from 0 to 0.3. |
| 12  | K ADJ2          | 1.2V    |                    | A resistor is connected to set $K_2$ . $K_2$ = approx. 0.25 at 12k $\Omega$ (Typ.) Varying the resistance value from $\infty$ to 4k $\Omega$ varies $K_2$ from 0 to 0.3. |
| 13  | I REF           | 1.2V    |                    | 12k $\Omega$ resistor is connected to obtain internal reference current  |
| 14  | MONIT1          | 2.4V    |                    | Output monitor pin of IN AMP   |
| 15  | T ADJ           | 4.0     |                    | A resistor is connected to set delay time. Set to 58ns at 10k $\Omega$ (Typ.). Varying from 5 to 25k $\Omega$ produces a change from 40 to 150ns.                        |
| 16  | V <sub>CC</sub> | 5V      |                    | Connects 5V power supply.  |

**Electrical Characteristics**

S3 and S4 taken as "a" side unless specified especially.

(Ta=25°C, Vcc=5V)

| Item                        | Symbol             | Conditions  | Test point | Min. | Typ. | Max. | Unit              |
|-----------------------------|--------------------|---|------------|------|------|------|-------------------|
| Current consumption         | I <sub>CC</sub>    | S1=ON, S2=ON  | 1M1        | 8    | 11   | 14   | mA                |
| Mix ratio accuracy *        | K <sub>1</sub>     | f=200kHz V <sub>IN</sub> =100mVp-p<br>S1=ON, S2=OFF | VM1        | -10  | 0    | +10  | %                 |
|                             | K <sub>2</sub>     | f=200kHz V <sub>IN</sub> =100mVp-p<br>S1=OFF, S2=ON | VM1        | -10  | 0    | +10  | %                 |
| Delay time accuracy *       | T <sub>L</sub>     | f=6MHz V <sub>IN</sub> =100mVp-p                    | VM1        | -13  | 0    | +13  | %                 |
|                             | T <sub>H</sub>     | f=10MHz V <sub>IN</sub> =100mVp-p                   | VM1        | -22  | 0    | +22  | %                 |
| Frequency characteristics   | FC                 | -3dB V <sub>IN</sub> =25mVp-p<br>S1=OFF, S2=OFF     | VM1        | 15   |      |      | MHz               |
| Gain                        | GAIN               | f=200kHz<br>S1=OFF, S2=OFF                          | VM1        | 7.5  | 9    | 10.5 | dB                |
| Maximum input voltage range | V <sub>INMAX</sub> | f=3MHz THD≤5%<br>S1=OFF, S2=OFF                     | VM1        | 300  |      |      | mVp-p             |
| Output noise voltage        | V <sub>NOISE</sub> | S1=OFF, S2=OFF<br>S3=b, S4=b                        | VM2        |      |      | 630  | μV <sub>rms</sub> |

\* With the center value of mix ratio and delay time taken as K<sub>1,2</sub>=0.255 and T=58ns.

The testing methods of mix ratio and delay time can be defined as follows: Equalizer frequency characteristics taken as H (W). To find K<sub>1</sub>, suppose K<sub>2</sub>=0 (S2=OFF), then,

$$|H(W)|^2 = 1 + K_1^2 - 2K_1 \cos \omega \tau$$

Here K<sub>1</sub>=0 (S1=OFF), 200kHz gain is taken as G<sub>0</sub> (dB). When a certain K<sub>1</sub> is set, 200kHz gain is taken as G<sub>1</sub> (dB). K<sub>1</sub> is calculated through the following formula:

$$K_1 = 1 - 10^{\frac{G_1 - G_0}{20}}$$

K<sub>2</sub> is solved in a similar way by supposing K<sub>1</sub>=0 (S1=OFF)

Delay time T<sub>L</sub> is calculated through the following formula:

S1 and S2 are OFF (where K<sub>1</sub> and K<sub>2</sub> are set to 0), 200kHz and 6MHz gain are taken as G<sub>0</sub>, G<sub>2</sub> (dB). When a certain K<sub>1</sub> and K<sub>2</sub> (S1 and S2=ON, K<sub>1</sub>=K<sub>2</sub>) are set, 200kHz and 6MHz gain are taken as G<sub>1</sub>', G<sub>3</sub>' (dB). T<sub>L</sub> is calculated through the following formula:

$$T_L = \frac{1}{\omega} \cos^{-1} \left( \frac{1 - 10^{\frac{G_1' - G_0}{20}}}{2K} \right)$$

K is calculated through the following formula:

$$K = \frac{1 - 10^{\frac{G_1' - G_0}{20}}}{2}$$

As the equalizer frequency characteristics have exceeded the gain peak at  $f=10\text{MHz}$ , delay time  $T_H$  when 10MHz gain are taken as  $G_3$ ,  $G_2$  (dB) is expressed by the following formula :

$$T_H = \frac{1}{\omega} \left\{ 2\pi - \cos^{-1} \left[ \frac{1 - 10^{\frac{G_3 - G_2}{20}}}{2K} \right] \right\}$$

The calculating method for this delay time is applied when it is set around 60ns. For setting to any other delay time, the frequency used to test the gain should be changed.

#### Calculation of delay time

T ADJ1 pin current is taken as I, while delay time is obtained approximately through the following formula :

$$\Delta t = \frac{5.4 \times 10^{-12}}{I}$$

As T ADJ pin voltage is 4.0V, the resistance to be connected to T ADJ pin is taken as R. We have

$$I = \frac{1.0}{R}$$

T ADJ pin voltage changes slightly according to the connected resistance value. However, ignoring this fluctuation, the relation between the delay time and R is given through the following formula:

$$\begin{aligned} \Delta t &= \frac{5.4 \times 10^{-12}}{1.0} \times R \\ &= 5.4 \times 10^{-12} \times R \end{aligned}$$

When  $R=10\text{k}\Omega$ , we have

$$\Delta t = 5.4 \times 10^{-12} \times 10 \times 10^3 = 54\text{ns}$$

Calculation of mix ratio  $K_1$ ,  $K_2$

Mix ratio calculation  $K_1$  generally follows the following formula :

$$2K_1 = \frac{I_1}{I_1 + I_2} \quad \begin{array}{l} I_1: 11 \text{ pin (K ADJ1) current} \\ I_2: 13 \text{ pin (I REF) current} \end{array}$$

K ADJ1 pin, I REF pin voltage is approx. 1.2V As a  $12\text{k}\Omega$  is connected to I REF pin.  $I_2=100\mu\text{A}$ . K ADJ1 pin voltage changes slightly according to the connected resistance value. However, ignoring this fluctuation, the relation between the mix ratio and R is given through the following formula :

$$I_1 = \frac{1.2}{R}$$

Therefore, the relation between  $K_1$  and R is as follows :

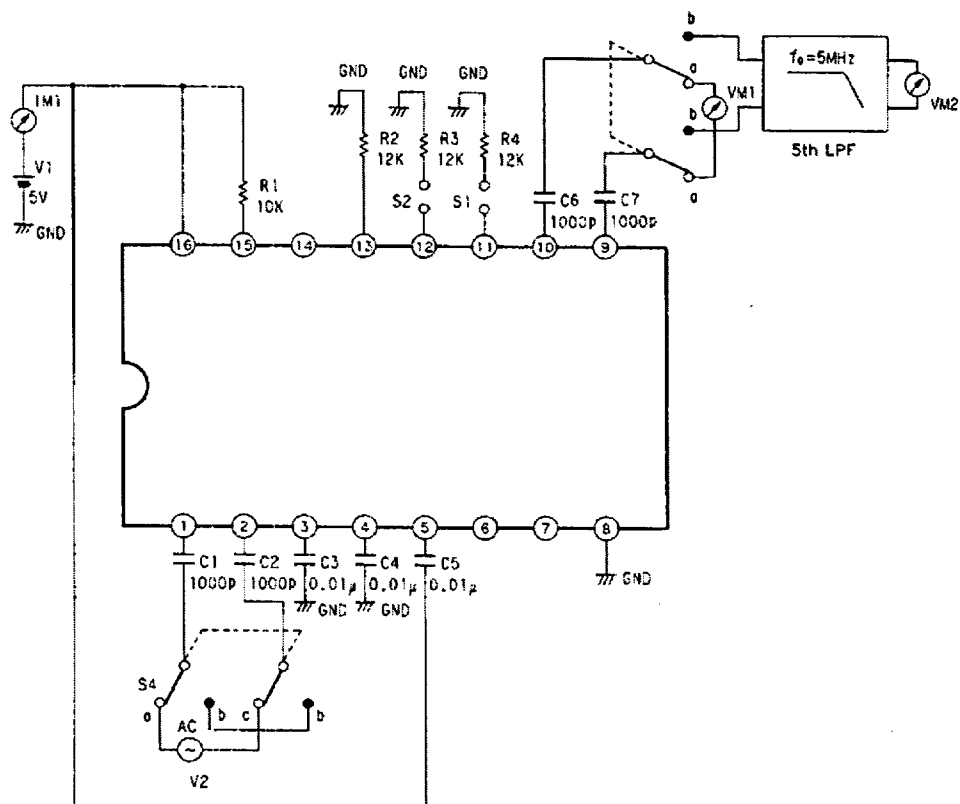
$$K_1 = \frac{0.6}{1.2 + 100 \times 10^{-6} \times R}$$

For example, when  $R=12\text{k}\Omega$ , we have

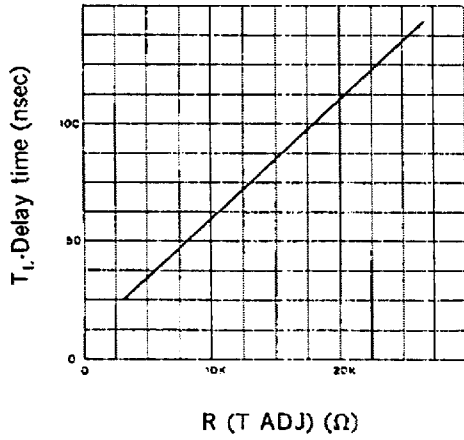
$$K_1 = \frac{0.6}{1.2 + 100 \times 10^{-6} \times 12 \times 10^3} = 0.25$$

$K_2$  is solved in a similar way as being 12 pin K ADJ2 current.

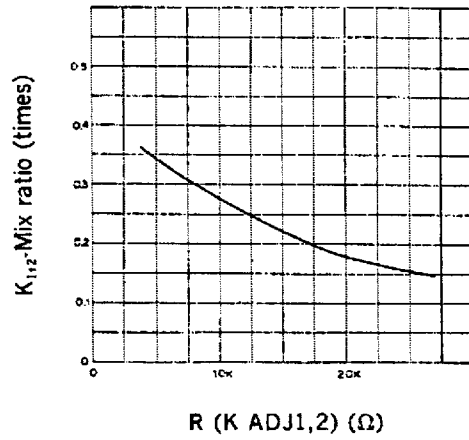
Electrical Characteristics Test Circuit



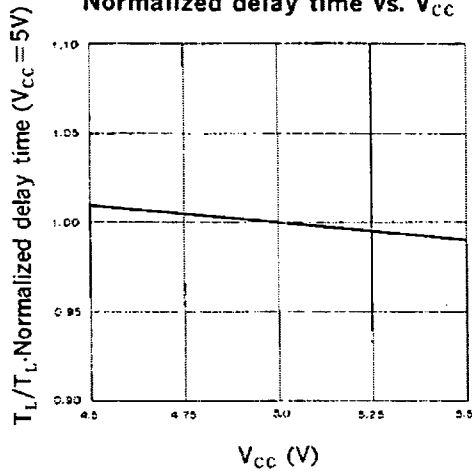
Delay time vs. Setting resistance



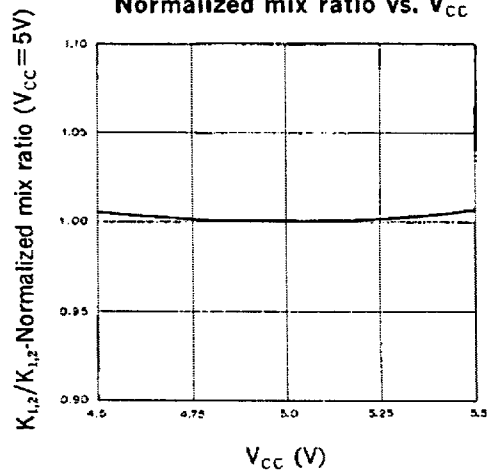
Mix ratio vs. Setting resistance



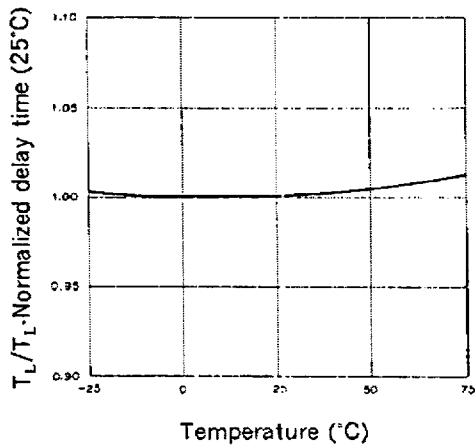
Normalized delay time vs. V<sub>CC</sub>



Normalized mix ratio vs. V<sub>CC</sub>



Normalized delay time vs. Temperature



Normalized mix ratio vs. Temperature

