# SONY

# **ICX418ALB**

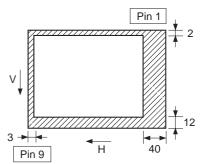
# Diagonal 8mm (Type 1/2) CCD Image Sensor for EIA B/W Video Cameras

# Description

The ICX418ALB is an interline CCD solid-state image sensor suitable for EIA B/W video cameras with a diagonal 8mm (Type 1/2) system. Compared with the current product ICX038DLB, basic characteristics such as sensitivity, smear, dynamic range and S/N are improved drastically.

This chip features a field period readout system and an electronic shutter with variable charge-storage time. Also, this outline is miniaturized by using original package. This chip is compatible with the pins of the ICX038DLB and has the same drive conditions.

# 16 pin DIP (Ceramic)



Optical black position (Top View)

### **Features**

- High sensitivity (+5.0dB compared with the ICX038DLB)
- Low smear (-5.0dB compared with the ICX038DLB
- High D range (+2.0dB compared with the ICX038DLB)
- High S/N
- · High resolution and low dark current
- Excellent antiblooming characteristics
- Continuous variable-speed shutter

Substrate bias: Adjustment free (external adjustment also possible with 6 to 14V)

• Reset gate pulse: 5Vp-p adjustment free (drive also possible with 0 to 9V)

Horizontal register: 5V drive
Maximum package dimensions: \$\phi13.2mm

# **Device Structure**

• Interline CCD image sensor

• Optical size: Diagonal 8mm (Type 1/2)

• Number of effective pixels: 768 (H)  $\times$  494 (V) approx. 380K pixels • Total number of pixels: 811 (H)  $\times$  508 (V) approx. 410K pixels

 $\begin{array}{ll} \bullet \; \text{Chip size:} & 7.40\text{mm (H)} \times 5.95\text{mm (V)} \\ \bullet \; \text{Unit cell size:} & 8.4\mu\text{m (H)} \times 9.8\mu\text{m (V)} \\ \end{array}$ 

• Optical black: Horizontal (H) direction: Front 3 pixels, rear 40 pixels

Vertical (V) direction: Front 12 pixels, rear 2 pixels

Number of dummy bits: Horizontal 22

Vertical 1 (even fields only)

• Substrate material: Silicon

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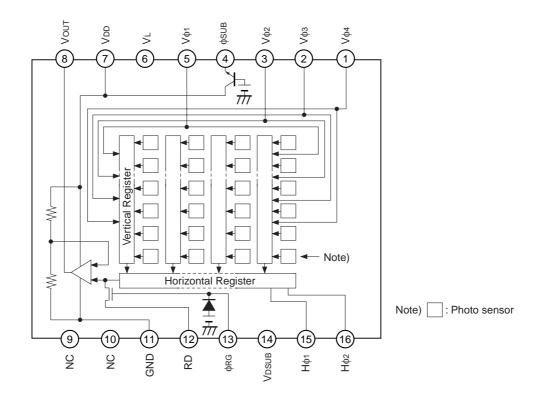
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# **Block Diagram and Pin Configuration**

(Top View)



# **Pin Description**

Pin No.	Symbol	Description	Pin No.	Symbol	Description
1	Vф4	Vertical register transfer clock	9	NC	
2	Vф3	Vertical register transfer clock	10	NC	
3	Vф2	Vertical register transfer clock	11	GND	GND
4	фѕив	Substrate clock	12	RD	Reset drain bias
5	Vф1	Vertical register transfer clock	13	фRG	Reset gate clock
6	VL	Protective transistor bias	14	VDSUB	Substrate bias circuit supply voltage
7	VDD	Output circuit supply voltage	15	Нф1	Horizontal register transfer clock
8	Vouт	Signal output	16	Нф2	Horizontal register transfer clock

# **Absolute Maximum Ratings**

	Item	Ratings	Unit	Remarks
Substrate clock \$\psi\$su	в – GND	-0.3 to +50	V	
Cupply voltage	Vdd, Vrd, Vdsub, Vout – GND	-0.3 to +18	V	
Supply voltage	Vdd, Vrd, Vdsub, Vout — фsub	-55 to +10	V	
Clock input valtage	Vφ1, Vφ2, Vφ3, Vφ4 – GND	-15 to +20	V	
Clock input voltage	Vφ1, Vφ2, Vφ3, Vφ4 – φsuв	to +10	V	
Voltage difference b	etween vertical clock input pins	to +15	V	*1
Voltage difference b	etween horizontal clock input pins	to +17	V	
Hφ1, Hφ2 – Vφ4		-17 to +17	V	
φRG – GND		-10 to +15	V	
φRG — φSUB		-55 to +10	V	
VL - \$SUB		-65 to +0.3	V	
Pins other than GN	D and фsuв – VL	-0.3 to +30	V	
Storage temperature	е	-30 to +80	°C	
Operating temperate	ure	-10 to +60	°C	

 $<sup>^{*1}\,</sup>$  +27V (Max.) when clock width < 10µs, clock duty factor < 0.1%.

# Bias Conditions 1 [when used in substrate bias internal generation mode]

Item	Symbol	Min.	Тур.	Max.	Unit	Remarks
Output circuit supply voltage	VDD	14.55	15.0	15.45	V	
Reset drain voltage	VRD	14.55	15.0	15.45	V	VRD = VDD
Protective transistor bias	VL		*1			
Substrate bias circuit supply voltage	VDSUB	14.55	15.0	15.45	V	
Substrate clock	фѕив		*2			

<sup>\*1</sup> VL setting is the VvL voltage of the vertical transfer clock waveform, or the same supply voltage as the VL power supply for the V driver should be used. (When CXD1267AN is used.)

# Bias Conditions 2 [when used in substrate bias external adjustment mode]

Item	Symbol	Min.	Тур.	Max.	Unit	Remarks
Output circuit supply voltage	VDD	14.55	15.0	15.45	V	
Reset drain voltage	VRD	14.55	15.0	15.45	V	VRD = VDD
Protective transistor bias	VL		*3			
Substrate bias circuit supply voltage	VDSUB		*4			
Substrate voltage adjustment range	VsuB	6.0		14.0	V	*5
Substrate voltage adjustment precision	ΔVsub	-3		+3	%	*5

<sup>\*3</sup> VL setting is the V<sub>VL</sub> voltage of the vertical transfer clock waveform, or the same supply voltage as the V<sub>L</sub> power supply for the V driver should be used. (When CXD1267AN is used.)

Vsub code — one character indication

Code and optimal setting correspond to each other as follows.

VsuB code	Е	f	G	h	J	K	L	m	N	Р	Q	R	S	Т	U	V	W
Optimal setting	6.0	6.5	7.0	7.5	8.0	8.5	9.0	9.5	10.0	10.5	11.0	11.5	12.0	12.5	13.0	13.5	14.0

<Example> "L"  $\rightarrow$  Vsub = 9.0V

### **DC Characteristics**

Item	Symbol	Min.	Тур.	Max.	Unit	Remarks
Output circuit supply current	IDD		5.0	10.0	mA	

<sup>\*2</sup> Do not apply a DC bias to the substrate clock pin, because a DC bias is generated within the CCD.

<sup>\*4</sup> Connect to GND or leave open.

<sup>\*5</sup> The setting value of the substrate voltage (Vsub) is indicated on the back of the image sensor by a special code. When adjusting the substrate voltage externally, adjust the substrate voltage to the indicated voltage. The adjustment precision is ±3%. However, this setting value has not significance when used in substrate bias internal generation mode.

# **Clock Voltage Conditions**

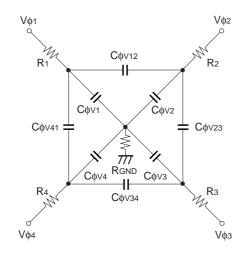
Item	Symbol	Min.	Тур.	Max.	Unit	Waveform diagram	Remarks
Readout clock voltage	Vvт	14.55	15.0	15.45	V	1	
	VvH1, VvH2	-0.05	0	0.05	V	2	$V_{VH} = (V_{VH1} + V_{VH2})/2$
	VvH3, VvH4	-0.2	0	0.05	V	2	
	VVL1, VVL2, VVL3, VVL4	-9.6	-9.0	-8.5	V	2	VVL = (VVL3 + VVL4)/2
	Vφv	8.3	9.0	9.65	Vp-p	2	$V\phi V = VVHN - VVLN (n = 1 to 4)$
Vertical transfer clock	Vvh1 — Vvh2			0.1	V	2	
voltage	VvH3 – VvH	-0.25		0.1	V	2	
	Vvh4 – Vvh	-0.25		0.1	V	2	
	Vvнн			0.5	V	2	High-level coupling
	Vvhl			0.5	V	2	High-level coupling
	VVLH			0.5	V	2	Low-level coupling
	Vvll			0.5	V	2	Low-level coupling
Horizontal transfer	Vфн	4.75	5.0	5.25	Vp-p	3	
clock voltage	VHL	-0.05	0	0.05	V	3	
	VRGL		*1		V	4	
Reset gate clock voltage*1	Vþrg	4.5	5.0	5.5	Vp-p	4	
1 5.1.5.90	Vrglh – Vrgll			0.8	V	4	Low-level coupling
Substrate clock voltage	Vфѕив	23.0	24.0	25.0	Vp-p	5	

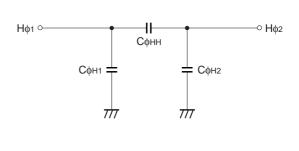
<sup>\*1</sup> Input the reset gate clock without applying a DC bias. In addition, the reset gate clock can also be driven with the following specifications.

Item	Symbol	Min.	Тур.	Max.	Unit	Waveform diagram	Remarks
Reset gate clock	VRGL	-0.2	0	0.2	V	4	
voltage	Vþrg	8.5	9.0	9.5	Vp-p	4	

# **Clock Equivalent Circuit Constant**

Item	Symbol	Min.	Тур.	Max.	Unit	Remarks
Capacitance between vertical transfer clock	Сф∨1, Сф∨3		2700		pF	
and GND	Сф∨2, Сф∨4		2700		pF	
Capacitance between vertical transfer clocks	СфV12, СфV34		820		pF	
Capacitance between vertical transier clocks	Сф∨23, Сф∨41		330		pF	
Capacitance between horizontal transfer clock	Сфн1		100		pF	
and GND	Сфн2		91		pF	
Capacitance between horizontal transfer clocks	Сфнн		47		pF	
Capacitance between reset gate clock and GND	СфRG		11		pF	
Capacitance between substrate clock and GND	Сфѕив		680		pF	
Vertical transfer clock series resistor	R1, R3		91		Ω	
vertical transfer clock series resistor	R2, R4		100		Ω	
Vertical transfer clock ground resistor	RGND		68		Ω	



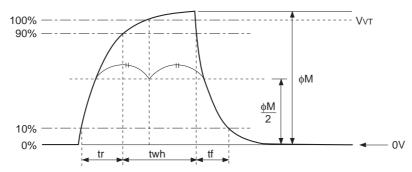


Vertical transfer clock equivalent circuit

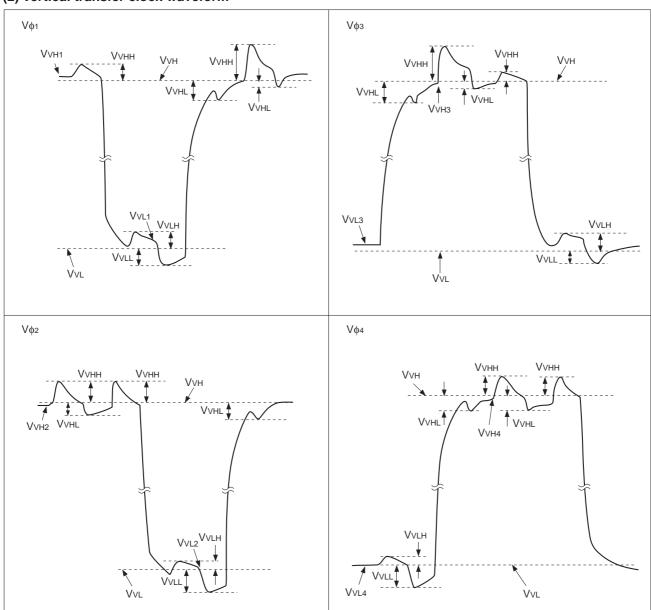
Horizontal transfer clock equivalent circuit

# **Drive Clock Waveform Conditions**

# (1) Readout clock waveform



# (2) Vertical transfer clock waveform

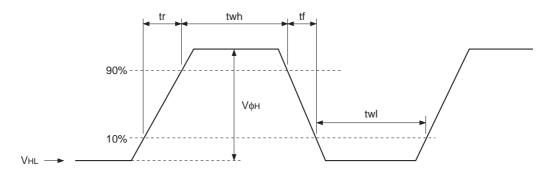


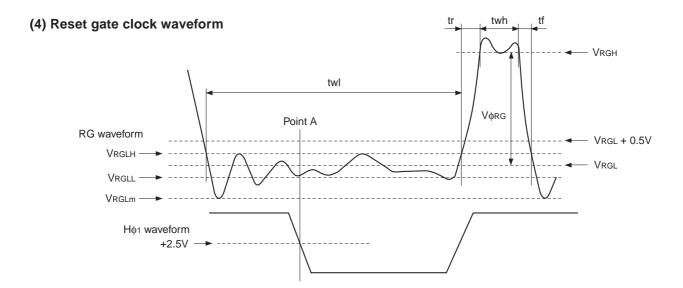
VvH = (VvH1 + VvH2)/2

 $V_{VL} = (V_{VL3} + V_{VL4})/2$ 

 $V\phi v = Vvhn - Vvhn (n = 1 to 4)$ 

# (3) Horizontal transfer clock waveform





VRGLH is the maximum value and VRGLL is the minimum value of the coupling waveform during the period from Point A in the above diagram until the rising edge of RG. In addition, VRGL is the average value of VRGLH and VRGLL.

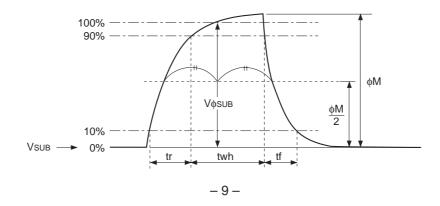
$$V_{RGL} = (V_{RGLH} + V_{RGLL})/2$$

Assuming VRGH is the minimum value during the period twh, then:

$$V\phi RG = VRGH - VRGL$$

Negative overshoot level during the falling edge of RG is VRGLm.

# (5) Substrate clock waveform



# **Clock Switching Characteristics**

	ltom	Symbol		twh			twl			tr			tf		Lloit	Remarks	
	Item	Symbol	Min.	Тур.	Мах.	Min.	Тур.	Max.	Min.	Тур.	Мах.	Min.	Тур.	Мах.	Unit	Remarks	
Rea	adout clock	VT	2.3	2.5					0.5			0.5			μs	During readout	
Ver	tical transfer ck	Vφ1, Vφ2, Vφ3, Vφ4										15		250	ns	*1	
Horizontal transfer clock	During imaging	Нф		20			20			15	19		15	19	ns	*2	
rizon	During	Нф1		5.38						0.01			0.01				
Ho	parallel-serial conversion	Нф2					5.38			0.01			0.01		μs		
Res	set gate clock	φRG	11	13			51			3			3		ns		
Sub	strate clock	φSUB	1.5	1.8							0.5			0.5	μs	When draining charge	

<sup>\*1</sup> When vertical transfer clock driver CXD1267AN is used.

<sup>\*2</sup>  $tf \ge tr - 2ns$ .

Itom	Symbol		two		Lloit	Domorko
Item	Symbol	Min.	Тур.	Max.	Uniii	Remarks
Horizontal transfer clock	Нф1, Нф2	16	20		ns	*3

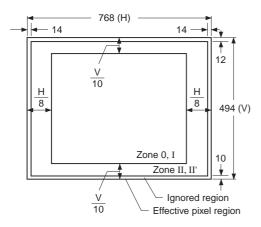
<sup>\*3</sup> The overlap period for twh and twl of horizontal transfer clocks  $H\phi_1$  and  $H\phi_2$  is two.

# **Image Sensor Characteristics**

(Ta = 25°C)

Item	Symbol	Min.	Тур.	Max.	Unit	Measurement method	Remarks
Sensitivity	S	880	1100		mV	1	
Saturation signal	Ysat	1000			mV	2	Ta = 60°C
Smear	Sm		-115	-105	dB	3	
Video signal shading	SH			20	%	4	Zone 0 and I
Video signal shading	ЗП			25	%	4	Zone 0 to II'
Dark signal	Vdt			2	mV	5	Ta = 60°C
Dark signal shading	ΔVdt			1	mV	6	Ta = 60°C
Flicker	F			2	%	7	
Lag	Lag			0.5	%	8	

# Zone Definition of Video Signal Shading



# **Image Sensor Characteristics Measurement Method**

### Measurement conditions

 In the following measurements, the device drive conditions are at the typical values of the bias and clock voltage conditions. (when used with substrate bias external adjustment, set the substrate voltage to the value indicated on the device.)

2) In the following measurements, spot blemishes are excluded and, unless otherwise specified, the optical black level (OB) is used as the reference for the signal output, which is taken as the value of Y signal output or chroma signal output of the measurement system.

# Definition of standard imaging conditions

## 1) Standard imaging condition I:

Use a pattern box (luminance 706cd/m², color temperature of 3200K halogen source) as a subject. (Pattern for evaluation is not applicable.) Use a testing standard lens with CM500S (t = 1.0mm) as an IR cut filter and image at F8. The luminous intensity to the sensor receiving surface at this point is defined as the standard sensitivity testing luminous intensity.

# 2) Standard imaging condition II:

Image a light source (color temperature of 3200K) with a uniformity of brightness within 2% at all angles. Use a testing standard lens with CM500S (t = 1.0mm) as an IR cut filter. The luminous intensity is adjusted to the value indicated in each testing item by the lens diaphragm.

# 1. Sensitivity

Set to standard imaging condition I. After selecting the electronic shutter mode with a shutter speed of 1/250s, measure the signal output (Vs) at the center of the screen and substitute the value into the following formula.

$$S = Vs \times \frac{250}{60} [mV]$$

### 2. Saturation signal

Set to standard imaging condition II. After adjusting the luminous intensity to 10 times the intensity with average value of the signal output, 200mV, measure the minimum value of the signal output.

# 3. Smear

Set to standard imaging condition II. With the lens diaphragm at F5.6 to F8, adjust the luminous intensity to 500 times the intensity with average value of the signal output, 200mV. When the readout clock is stopped and the charge drain is executed by the electronic shutter at the respective H blankings, measure the maximum value VSm [mV] of the signal output and substitute the value into the following formula.

Sm = 
$$20 \times log \left( \frac{VSm}{200} \times \frac{1}{500} \times \frac{1}{10} \right)$$
 [dB] (1/10V method conversion value)

### 4. Video signal shading

Set to standard imaging condition II. With the lens diaphragm at F5.6 to F8, adjust the luminous intensity so that the average value of the signal output is 200mV. Then measure the maximum (Vmax [mV]) and minimum (Vmin [mV]) values of the signal output and substitute the values into the following formula.

$$SH = (Vmax - Vmin)/200 \times 100 [\%]$$

# 5. Dark signal

Measure the average value of the signal output (Vdt [mV]) with the device ambient temperature 60°C and the device in the light-obstructed state, using the horizontal idle transfer level as a reference.

### 6. Dark signal shading

After measuring 5, measure the maximum (Vdmax [mV]) and minimum (Vdmin [mV]) values of the dark signal output and substitute the values into the following formula.

$$\Delta Vdt = Vdmax - Vdmin [mV]$$

# 7. Flicker

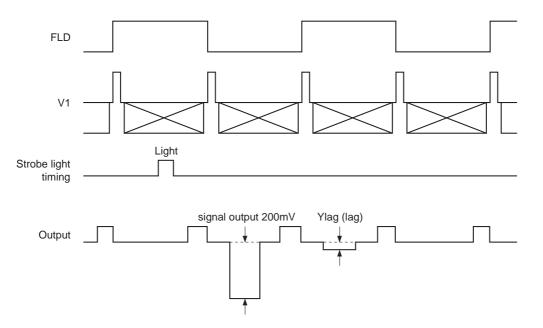
Set to standard imaging condition II. Adjust the luminous intensity so that the average value of the signal output is 200mV, and then measure the difference in the signal level between fields ( $\Delta$ Vf [mV]). Then substitute the value into the following formula.

$$Fy = (\Delta Vf/200) \times 100 [\%]$$

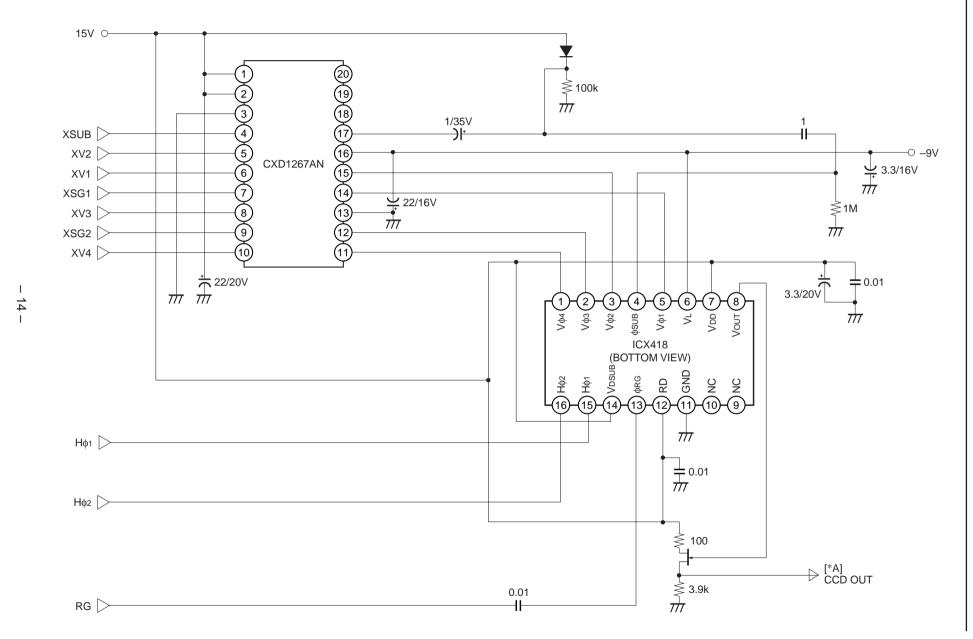
# 10. Lag

Adjust the signal output value generated by strobe light to 200mV. After setting the strobe light so that it strobes with the following timing, measure the residual signal (Vlag). Substitute the value into the following formula.

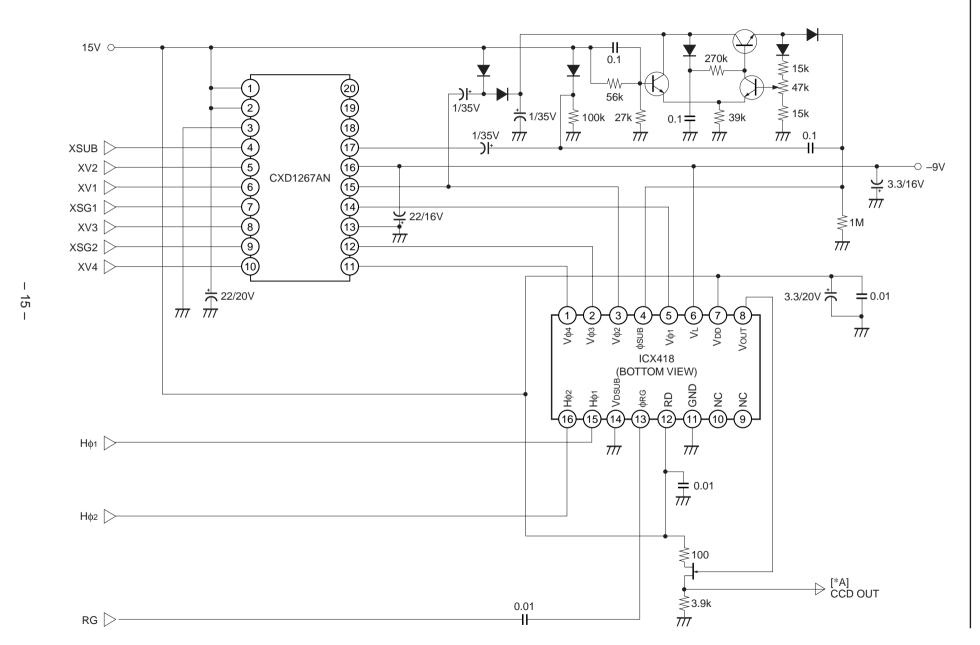
$$Lag = (Vlag/200) \times 100 [\%]$$



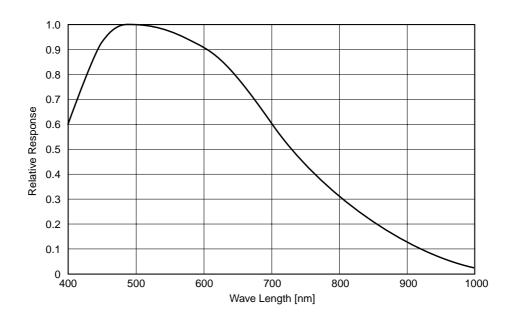
# **Drive Circuit 1 (substrate bias internal generation mode)**



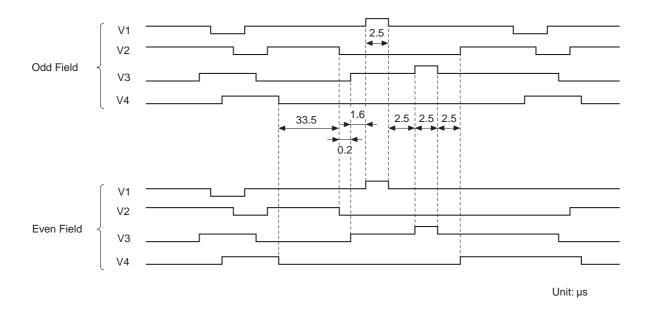
# **Drive Circuit 2 (substrate bias external adjustment mode)**

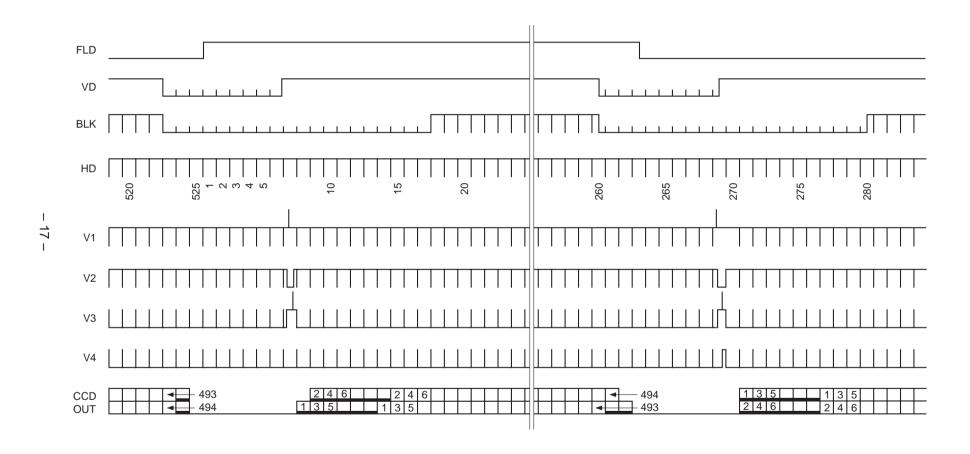


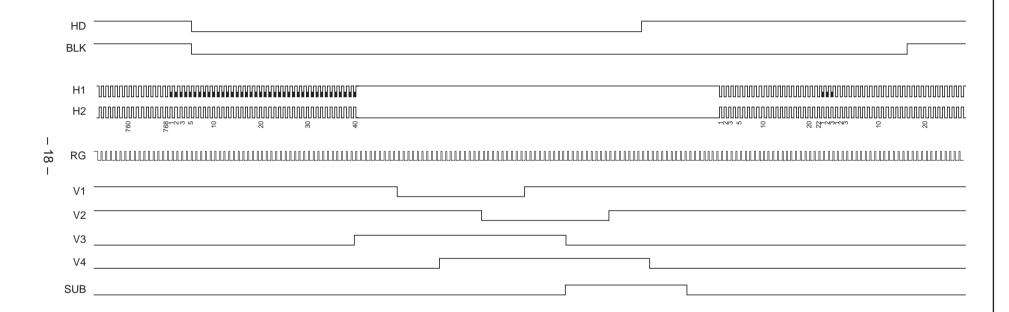
Spectral Sensitivity Characteristics (Excludes lens characteristics and light source characteristics)



# **Sensor Readout Clock Timing Chart**







# **Notes on Handling**

### 1) Static charge prevention

CCD image sensors are easily damaged by static discharge. Before handling be sure to take the following protective measures.

- a) Either handle bare handed or use non-chargeable gloves, clothes or material.
   Also use conductive shoes.
- b) When handling directly use an earth band.
- c) Install a conductive mat on the floor or working table to prevent the generation of static electricity.
- d) Ionized air is recommended for discharge when handling CCD image sensor.
- e) For the shipment of mounted substrates, use boxes treated for the prevention of static charges.

## 2) Soldering

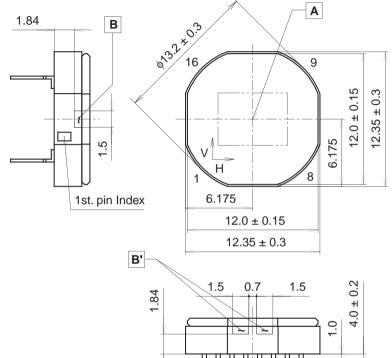
- a) Make sure the package temperature does not exceed 80°C.
- b) Solder dipping in a mounting furnace causes damage to the glass and other defects. Use a ground 30W soldering iron and solder each pin in less than 2 seconds. For repairs and remount, cool sufficiently.
- c) To dismount an image sensor, do not use a solder suction equipment. When using an electric desoldering tool, use a thermal controller of the zero cross On/Off type and connect it to ground.

# 3) Dust and dirt protection

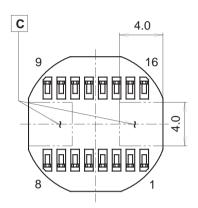
Image sensors are packed and delivered by taking care of protecting its glass plates from harmful dust and dirt. Clean glass plates with the following operations as required, and use them.

- a) Perform all assembly operations in a clean room (class 1000 or less).
- b) Do not either touch glass plates by hand or have any object come in contact with glass surfaces. Should dirt stick to a glass surface, blow it off with an air blower. (For dirt stuck through static electricity ionized air is recommended.)
- c) Clean with a cotton bud and ethyl alcohol if grease stained. Be careful not to scratch the glass.
- d) Keep in a case to protect from dust and dirt. To prevent dew condensation, preheat or precool when moving to a room with great temperature differences.
- e) When a protective tape is applied before shipping, just before use remove the tape applied for electrostatic protection. Do not reuse the tape.
- 4) Do not expose to strong light (sun rays) for long periods. For continuous using under cruel condition exceeding the normal using condition, consult our company.
- 5) Exposure to high temperature or humidity will affect the characteristics. Accordingly avoid storage or usage in such conditions.
- 6) CCD image sensors are precise optical equipment that should not be subject to too much mechanical shocks.

# 16 pin DIP (300mil)



3.29 ± 0.3 2.54 270



- 1. "A" is the center of the effective image area.
- 2. The point "B" of the package is the horizontal reference. The point "B" of the package is the vertical reference.
- 3. The bottom "C" of the package is the height reference.
- 4. The center of the effective image area relative to the center of the package (\*) is  $(H, V) = (0, 0) \pm 0.15$ mm.
- 5. The rotation angle of the effective image area relative to H and V is  $\pm$  1 $^{\circ}$ .
- 6. The height from the bottom "C" to the effective image area is  $1.41 \pm 0.15$ mm.
- 7. The tilt of the effective image area relative to the bottom "C" is less than 60µm.
- 8. The thickness of the cover glass is 0.75mm, and the refractive index is 1.5.
- \* Center of the package : The center is halfway between two pairs of opposite sides, as measured from "B", "B".

# PACKAGE STRUCTURE

PACKAGE MATERIAL	Ceramic
LEAD TREATMENT	GOLD PLATING
LEAD MATERIAL	42 ALLOY
PACKAGE MASS	0.90g
DRAWING NUMBER	AS-B4-01(E)

0.6

1.27

0.3

0.3 M