

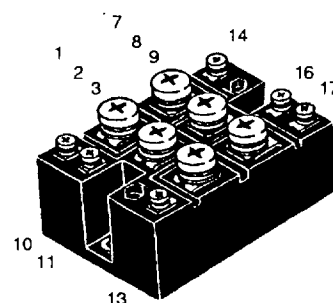
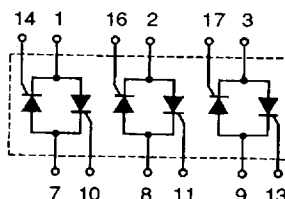
Three Phase AC Controller Modules

VWO95

$I_{RMS} = 95 \text{ A}$
 $V_{RRM} = 800 - 1600 \text{ V}$

Preliminary data

V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V	Type
800	800	VWO 95-08io7
1200	1200	VWO 95-12io7
1400	1400	VWO 95-14io7
1600	1600	VWO 95-16io7



Symbol	Test Conditions	Maximum Ratings
I_{RMS}	$T_C = 85^\circ\text{C}$, 50 - 400 Hz (per phase)	96 A
I_{TRMS}	$T_{VJ} = T_{VJM}$	69 A
I_{TAVM}	$T_C = 85^\circ\text{C}$; (180° sine)	44 A
I_{TSM}	$T_{VJ} = 45^\circ\text{C}$; $V_R = 0$	$t = 10 \text{ ms}$ (50 Hz), sine 1150 A $t = 8.3 \text{ ms}$ (60 Hz), sine 1230 A
	$T_{VJ} = T_{VJM}$; $V_R = 0$	$t = 10 \text{ ms}$ (50 Hz), sine 1000 A $t = 8.3 \text{ ms}$ (60 Hz), sine 1100 A
$\int i^2 dt$	$T_{VJ} = 45^\circ\text{C}$; $V_R = 0$	$t = 10 \text{ ms}$ (50 Hz), sine 6600 A ² s $t = 8.3 \text{ ms}$ (60 Hz), sine 6280 A ² s
	$T_{VJ} = T_{VJM}$; $V_R = 0$	$t = 10 \text{ ms}$ (50 Hz), sine 5000 A ² s $t = 8.3 \text{ ms}$ (60 Hz), sine 5080 A ² s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$; $f = 50 \text{ Hz}$, $t_p = 200 \mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.3 \text{ A}$ $di_G/dt = 0.3 \text{ A}/\mu\text{s}$	repetitive, $I_T = 150 \text{ A}$ 100 A/ μs non repetitive, $I_T = I_{TAVM}$ 500 A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$; $R_{GK} = \infty$; method 1 (linear voltage rise)	$V_{DR} = 2/3 V_{DRM}$ 1000 V/ μs
P_{GM}	$T_{VJ} = T_{VJM}$; $I_T = I_{TAVM}$	$t_p = 30 \mu\text{s}$ 10 W $t_p = 300 \mu\text{s}$ 5 W
P_{GAVM}		0.5 W
V_{RGM}		10 V
T_{VJ}		-40...+125 °C
T_{VJM}		125 °C
T_{sg}		-40...+125 °C
V_{ISOL}	50/60 Hz, RMS; $I_{ISOL} \leq 1 \text{ mA}$	$t = 1 \text{ min}$ 2500 V~ $t = 1 \text{ s}$ 3000 V~
M_d	Mounting torque (M5) Terminal connection torque (M3; M5)	5/44±15 % Nm/lb.in. 1.5/13±15 % Nm/lb.in.
Weight	typ.	180 g

Features

- Thyristor controller for AC (circuit W3C acc. to IEC) for mains frequency
- Package with metal base plate
- Isolation voltage 3000 V~
- Planar passivated chips
- UL applied

Applications

- Switching and control of three phase AC circuits
- Softstart AC motor controller
- Solid state switches
- Light and temperature control

Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling
- High power density

Data according to DIN/IEC 747 and to a single thyristor unless otherwise stated.

Symbol	Test Conditions	Characteristic Values	
I_D, I_R	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	$\leq$	5 mA
V_T	$I_T = 150 \text{ A}; T_{VJ} = 25^\circ\text{C}$	$\leq$	1.57 V
V_{T0}	For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$)	0.85	V
r_T		4.8	m Ω
V_{GT}	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	$\leq$	1.0 V
	$T_{VJ} = -40^\circ\text{C}$	$\leq$	1.6 V
I_{GT}	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	$\leq$	100 mA
	$T_{VJ} = -40^\circ\text{C}$	$\leq$	150 mA
V_{GD}	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	$\leq$	0.2 V
I_{GD}		$\leq$	5 mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 10 \mu\text{s}$ $I_G = 0.3 \text{ A}; di_G/dt = 0.3 \text{ A}/\mu\text{s}$	$\leq$	200 mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$	$\leq$	150 mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.3 \text{ A}; di_G/dt = 0.3 \text{ A}/\mu\text{s}$	$\leq$	2 μs
t_q	$T_{VJ} = T_{VJM}; I_T = 20 \text{ A}; t_p = 200 \mu\text{s}; di/dt = -10 \text{ A}/\mu\text{s}$ typ. $V_R = 100 \text{ V}; dv/dt = 15 \text{ V}/\mu\text{s}; V_D = 2/3 V_{DRM}$	150	μs
R_{thJC}	per thyristor; sine 180°el	0.66	K/W
	per module	0.11	K/W
R_{thJK}	per thyristor; sine 180°el	0.93	K/W
	per module	0.155	K/W
d_s	Creeping distance on surface	8.0	mm
d_A	Creepage distance in air	4.5	mm
a	Max. allowable acceleration	50	m/s ²

Dimensions in mm (1 mm = 0.0394")

