Document Title

512Kx36 & 1Mx18 Synchronous Pipelined SRAM

Revision History

Rev. No.	<u>History</u>	Draft Date	<u>Remark</u>
Rev. 0.0	- Initial Document	Dec. 2001	Advance
Rev. 0.1	- Absolute maximum ratings are changed VDD : 2.815 -> 3.13 VDDQ : 2.815 -> 2.4 VTERM: 2.815 -> VDDQ+0.5 (2.4V MAX) - Recommended DC operating conditions are changed VREF / VCM-CLK : 0.68 -> 0.6, 0.95 -> 0.9 - DC characteristics is changed ISBZZ : 150 -> 128 - AC Characteristics are changed TAVKH / TDVKH / TWVKH / TSVKH : 0.4 / 0.5 / 0.5 -> 0.3 / 0.3 / 0.3	Oct. 2002	Advance
	TKHAX/TKHDX/TKHWX/TKHSX: 0.5/0.5/0.5 -> 0.5/0.6/0.6		
Rev. 0.2	- Recommended DC operating condition is changed Max VDIF-CLK: VDDQ+0.3 -> VDDQ+0.6	Jan. 2003	Advance
Rev. 0.3	- Correct typo VDD -> VDDQ: in MODE CONTROL at page4	Sep. 2003	Final

The attached data sheets are prepared and approved by SAMSUNG Electronics. SAMSUNG Electronics CO., LTD. reserve the right to change the specifications. SAMSUNG Electronics will evaluate and reply to your requests and questions on the parameters of this device. If you have any questions, please contact the SAMSUNG branch office near your office, call or cortact Headquarters.



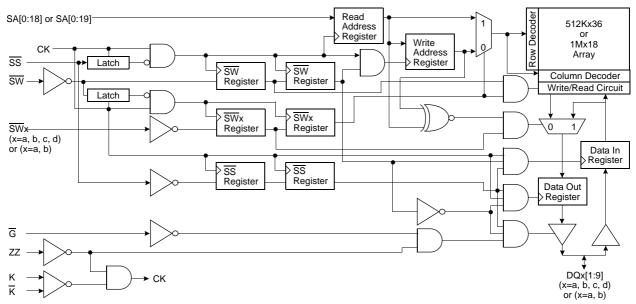
512Kx36 & 1Mx18 Synchronous Pipelined SRAM

FEATURES

- 512Kx36 or 1Mx18 Organizations.
- 2.5V Core/1.5V Output Power Supply (1.9V max VDDQ).
- HSTL Input and Output Levels.
- Differential, HSTL Clock Inputs K, $\overline{\mathsf{K}}$.
- Synchronous Read and Write Operation
- Registered Input and Registered Output
- Internal Pipeline Latches to Support Late Write.
- Byte Write Capability(four byte write selects, one for each 9bits)
- Synchronous or Asynchronous Output Enable.
- Power Down Mode via ZZ Signal.
- Programmable Impedance Output Drivers.
- JTAG 1149.1 Compatible Test Access port.
- 119(7x17)Pin Ball Grid Array Package(14mmx22mm).

Organization	Part Number	Maximum Frequency	Access Time
512Kx36	K7P163666A-HC33	333MHz	1.5
	K7P163666A-HC30	300MHz	1.6
	K7P163666A-HC25	250MHz	2.0
	K7P161866A-HC33	333MHz	1.5
1Mx18	K7P161866A-HC30	300MHz	1.6
	K7P161866A-HC25	250MHz	2.0

FUNCTIONAL BLOCK DIAGRAM



PIN DESCRIPTION

Pin Name	Pin Description	Pin Name	Pin Description
K, K	Differential Clocks	VREF	HSTL Input Reference Voltage
SAn	Synchronous Address Input	M1, M2	Read Protocol Mode Pins (M1=Vss, M2=VDDQ)
DQn	Bi-directional Data Bus	G	Asynchronous Output Enable
SW	Synchronous Global Write Enable	SS	Synchronous Select
SWa	Synchronous Byte a Write Enable	TCK	JTAG Test Clock
SWb	Synchronous Byte b Write Enable	TMS	JTAG Test Mode Select
SWc	Synchronous Byte c Write Enable	TDI	JTAG Test Data Input
SWd	Synchronous Byte d Write Enable	TDO	JTAG Test Data Output
ZZ	Asynchronous Power Down	ZQ	Output Driver Impedance Control
VDD	Core Power Supply	Vss	GND
VDDQ	Output Power Supply	NC	No Connection



PACKAGE PIN CONFIGURATIONS(TOP VIEW)

K7P163666A(512Kx36)

	1	2	3	4	5	6	7
Α	VDDQ	SA13	SA ₁₀	NC	SA ₇	SA4	VDDQ
В	NC	SA ₁₈	SA9 NC		SA8	SA ₁₇	NC
С	NC	SA ₁₂	SA ₁₁	VDD	SA ₆	SA ₅	NC
D	DQc8	DQc9	Vss	ZQ	Vss	DQb9	DQb8
E	DQc6	DQc7	Vss	SS	Vss	DQb7	DQb6
F	VDDQ	DQc5	Vss	G	Vss	DQb5	VDDQ
G	DQc3	DQc4	SWc	NC	SWb	DQb4	DQb3
н	DQc1	DQc2	Vss	NC	Vss	DQb2	DQb1
J	VDDQ	Vdd	VREF	VDD	VREF	VDD	VDDQ
K	DQd1	DQd2	Vss	К	Vss	DQa ₂	DQa ₁
L	DQd3	DQd4	SWd	ĸ	SWa	DQa4	DQa3
М	VDDQ	DQd5	Vss	SW	Vss	DQa ₅	VDDQ
N	DQd6	DQd7	Vss	SA ₀	Vss	DQa7	DQa6
Р	DQd8	DQd9	Vss	SA ₁	Vss	DQa9	DQa8
R	NC	SA ₁₅	M1	VDD	M2	SA ₂	NC
Т	NC	NC	SA ₁₄	SA ₁₆	SA ₃	NC	ZZ
U	VDDQ	TMS	TDI	TCK	TDO	NC	VDDQ

K7P161866A(1Mx18)

	1	2	3	4	5	6	7
Α	VDDQ	SA13	SA ₁₀	NC	SA ₇	SA4	Vddq
В	NC	SA ₁₉	SA ₉	NC	SA ₈	SA17	NC
С	NC	SA ₁₂	SA ₁₁	Vdd	SA ₆	SA ₅	NC
D	DQb1	NC	Vss	ZQ	Vss	DQa ₉	NC
E	NC	DQb2	Vss	SS	Vss	NC	DQa8
F	VDDQ	NC	Vss	G	Vss	DQa7	Vddq
G	NC	DQb3	SWb	NC	NC	NC	DQa ₆
Н	DQb4	NC	Vss	NC	Vss	DQa ₅	NC
J	VDDQ	Vdd	VREF	Vdd	VREF	Vdd	VDDQ
K	NC	DQb5	Vss	K	Vss	NC	DQa4
L	DQb6	NC	NC	K	SWa	DQa ₃	NC
М	VDDQ	DQb7	Vss	SW	Vss	NC	VDDQ
N	DQb8	NC	Vss	SA ₀	Vss	DQa ₂	NC
Р	NC	DQb9	Vss	SA ₁	Vss	NC	DQa ₁
R	NC	SA ₁₅	M 1	Vdd	M ₂	SA ₂	NC
Т	NC	SA18	SA ₁₄	NC	SA ₃	SA ₁₆	ZZ
U	VDDQ	TMS	TDI	TCK	TDO	NC	VDDQ

FUNCTION DESCRIPTION

The K7P163666A and K7P161866A are 18,874,368 bit Synchronous Pipeline Mode SRAM. It is organized as 524,288 words of 36 bits(or 1,048,576 words of 18 bits)and is implemented in SAMSUNGs advanced CMOS technology.

Single differential HSTL level K clocks are used to initiate the read/write operation and all internal operations are self-timed. At the updated from output registers edge of the next rising edge of the K clock. An internal write data buffer allows write data to follow one cycle after addresses and controls. The package is 119(7x17) Ball Grid Array with balls on a 1.27mm pitch.

Read Operation

During reads, the address is registered during the frist clock edge, the internal array is read between this first edge and the second edge, and data is captured in the output register and driven to the CPU during the second clock edge. SS is driven low during this cycle, signaling that the SRAM should drive out the data.

During consecutive read cycles where the address is the same, the data output must be held constant without any glitches. This characteristic is because the SRAM will be read by devices that will operate slower than the SRAM frequency and will require multiple SRAM cycles to perform a single read operation.

Write (Stire) Operation

All addresses and SW are sampled on the clock rising edge. $\overline{\text{SW}}$ is low on the rising clock. Write data is sampled on the rising clock, one cycle after write address and $\overline{\text{SW}}$ have been sampled by the SRAM. $\overline{\text{SS}}$ will be driven low during the same cycle that the Address, $\overline{\text{SW}}$ and $\overline{\text{SW}}$ [a:d] are valid to signal that a valid operation is on the Address and Control Input.

Pipelined write are supported. This is done by using write data buffers on the SRAM that capture the write addresses on one write cycle, and write the array on the next write cycle. The "next write cycle" can actually be many cycles away, broken by a series of read cycles. Byte writes are supported. The byte write signals \overline{SW} [a:d] signal which 9-bit bytes will be writen. Timing of \overline{SW} [a:d] is the same as the \overline{SW} signal.

Bypass Read Operation

Since write data is not fully written into the array on first write cycle, there is a need to sense the address in case a future read is to be done from the location that has not been written yet. For this case, the address comparator check to see if the new read address is the same as the contents of the stored write address Latch. If the contents match, the read data must be supplied from the stored write data latch with standard read timing. If there is no match, the read data comes from the SRAM array. The bypassing of the SRAM array occurs on a byte by byte basis. If one byte is written and the other bytes are not, read data from the last written will have new byte data from the write data buffer and the other bytes from the SRAM array.

Programmable Impedance Output Buffer Operation

This HSTL Late Write SRAM has been designed with programmable impedance output buffers. The SRAMs output buffer impedance can be adjusted to match the system data bus impedance, by connecting a external resistor (RQ) between the ZQ pin of the SRAM and Vss. The value of RQ must be five times the value of the intended line impedance driven by the SRAM. For example, a 250Ω resistor will give an output buffer impedance of 50Ω . The allowable range of RQ is from 175Ω to 350Ω . Internal circuits evaluate and periodically adjust the output buffer impedance, as the impedance is affected by drifts in supply voltage and temperature. One evaluation occurs every 32 clock cycles, with each evaluation moving the output buffer impedance level only one step at a time toward the optimum level. Impedance updates occur when the SRAM is in High-Z state, and thus are triggered by write and deselect operations. Updates will also be triggered with G HIGH initiated High-Z state, providing the specified G setup and hold times are met. Impedance match is not instantaneous upon power-up. In order to guarantee optimum output driver impedance, the SRAM requires a minimum number of non-read cycles (1,024) after power-up. The output buffers can also be programmed in a minimum impedance configuration by connecting ZQ to Vss or Vpd.

Mode Control

There are two mode control select pins (M₁ and M₂) used to set the proper read protocol. This SRAM supports single clock pipelined operating mode. For proper specified device operation, M₁ must be connected to Vss and M₂ must be connected to VDDQ. These mode pins must be set at power-up and must not change during device operation.

Power-Up/Power-Down Supply Voltage Sequencing

The following power-up supply voltage application is recommended: Vss, Vdd, Vdd, VREF, then Vin. Vdd and Vddq can be applied simultaneously, as long as Vddq does not exceed Vdd by more than 0.5V during power-up. The following power-down supply voltage removal sequence is recommended: Vin, VREF, Vddq, Vdd, Vss. Vdd and Vddq can be removed simultaneously, as long as Vddq does not exceed Vdd by more than 0.5V during power-down.

Sleep Mode

Sleep mode is a low power mode initiated by bringing the asynchronous ZZ pin high. During sleep mode, all other inputs are ignored and outputs are brought to a High-Impedance state. Sleep mode current and output High-Z are guaranteed after the specified sleep mode enable time. During sleep mode the memory array data content is preserved. Sleep mode must not be initiated until after all pending operations have completed, as any pending operation is not guaranteed to properly complete after sleep mode is initiated. Normal operations can be resumed by bringing the ZZ pin low, but only after the specified sleep mode recovery time.



FUNCTION DESCRIPTION

The K7P163666A and K7P161866A are 18,874,368 bit Dual Mode (supports both Register Register and Late Select Mode) SRAM devices. They are organized as 524,288 words by 36 bits for K7P163666A and 1,048,576 words by 18 bits for K7P161866A, fabricated using Samsung's advanced CMOS technology. Late Write/Pipelined Read(RR) for x36/x18 organizations and Late Write/Late Select Read(LS) for x36 organization are supported.

The chip is operated with a single +2.5V power supply and is compatible with HSTL input and output. The package is 119(7x17) Plastic Ball Grid Array with balls on a 1.27mm pitch.

Read Operation for Register Register Mode(x36 and x18)

During read operations, addresses and controls are registered during the first rising edge of K clock and then the internal array is read between first and second edges of K clock. Data outputs are updated from output registers off the second rising edge of K clock.

Read Operation for Late Select Mode(x36)

During read operations, addresses(SA) and controls except the Way Select Address(SAS) are registered during the first rising edge of K clock. The internal array(x72 bit data) is read between the first edge and the second edge, and as the Way Select Address(SAS) is registered at the second clock edge, x36 bit data is mux selected before the output register.

Write Operation(Late Write)

During write operations, addresses including the Way Select Address(SAS) and controls are registered at the first rising edge of K clock and data inputs are registered at the following rising edge of K clock. Write addresses and data inputs are stored in the data in registers until the next write operation, and only at the <u>next</u> write operation are data inputs fully written into SRAM array. Byte write operation is supported using \overline{SW} [a:d] and the timing of \overline{SW} [a:d] is the same as the \overline{SW} signal.

Bypass Read Operation

Since write data is not fully written into the array on first write cycle, there is a need to sense the address in case a future read is to be done from the location that has not been written yet. For this case, the address comparator check to see if the new read address is the same as the contents of the stored write address Latch. If the contents match, the read data must be supplied from the stored write data latch with standard read timing. If there is no match, the read data comes from the SRAM array. The bypassing of the SRAM array occurs on a byte by byte basis. If one byte is written and the other bytes are not, read data from the last written will have new byte data from the write data buffer and the other bytes from the SRAM array.

Programmable Impedance Output Buffer Operation

This HSTL Late Write SRAM has been designed with programmable impedance output buffers. The SRAMs output buffer impedance can be adjusted to match the system data bus impedance, by connecting a external resistor (RQ) between the ZQ pin of the SRAM and Vss. The value of RQ must be five times the value of the intended line impedance driven by the SRAM. For example, a 250Ω resistor will give an output buffer impedance of 50Ω . The allowable range of RQ is from 175Ω to 350Ω . Internal circuits evaluate and periodically adjust the output buffer impedance, as the impedance is affected by drifts in supply voltage and temperature. One evaluation occurs every 32 clock cycles, with each evaluation moving the output buffer impedance level only one step at a time toward the optimum level. Impedance updates occur when the SRAM is in High-Z state, and thus are triggered by write and deselect operations. Updates will also be triggered with G HIGH initiated High-Z state, providing the specified G setup and hold times are met. Impedance match is not instantaneous upon power-up. In order to guarantee optimum output driver impedance, the SRAM requires a minimum number of non-read cycles (1,024) after power-up. The output buffers can also be programmed in a minimum impedance configuration by connecting ZQ to Vss or Vpd.

Mode Control

There are two mode control select pins (M₁ and M₂) used to set the proper read protocol. This SRAM supports single clock pipelined operating mode. For proper specified device operation, M₁ must be connected to Vss and M₂ must be connected to VDD. These mode pins must be set at power-up and must not change during device operation.

Power-Up/Power-Down Supply Voltage Sequencing

The following power-up supply voltage application is recommended: Vss, Vdd, VddQ, VREF, then VIN. Vdd and VddQ can be applied simultaneously, as long as VddQ does not exceed Vdd by more than 0.5V during power-up. The following power-down supply voltage removal sequence is recommended: VIN, VREF, VddQ, Vdd, Vss. Vdd and VddQ can be removed simultaneously, as long as VddQ does not exceed Vdd by more than 0.5V during power-down.

Sleep Mode

Sleep mode is a low power mode initiated by bringing the asynchronous ZZ pin high. During sleep mode, all other inputs are ignored and outputs are brought to a High-Impedance state. Sleep mode current and output High-Z are guaranteed after the specified sleep mode enable time. During sleep mode the memory array data content is preserved. Sleep mode must not be initiated until after all pending operations have completed, as any pending operation is not guaranteed to properly complete after sleep mode is initiated. Normal operations can be resumed by bringing the ZZ pin low, but only after the specified sleep mode recovery time.



TRUTH TABLE

K	ZZ	G	SS	SW	SWa	SWb	SWc	SWd	DQa	DQb	DQc	DQd	Operation
Х	Н	Х	Х	Х	Х	Х	Х	Х	Hi-Z	Hi-Z	Hi-Z	Hi-Z	Power Down Mode. No Operation
Х	L	Η	Х	Х	Х	Х	Х	Х	Hi-Z	Hi-Z	Hi-Z	Hi-Z	Output Disabled.
↑	L	┙	Ι	X	X	Х	Х	Х	Hi-Z	Hi-Z	Hi-Z	Hi-Z	Output Disabled. No Operation
\uparrow	L	L	L	Η	Х	Х	Х	Х	Dout	D оит	D оит	D оит	Read Cycle
\uparrow	L	Х	L	L	Η	Н	Н	Н	Hi-Z	Hi-Z	Hi-Z	Hi-Z	No Bytes Written
\uparrow	L	Х	L	L	L	Н	Н	Н	DIN	Hi-Z	Hi-Z	Hi-Z	Write first byte
\uparrow	L	Х	L	L	Η	L	Н	Н	Hi-Z	DIN	Hi-Z	Hi-Z	Write second byte
\uparrow	L	Х	L	L	Η	Н	L	Н	Hi-Z	Hi-Z	DIN	Hi-Z	Write third byte
\uparrow	L	Х	L	L	Η	Н	Н	L	Hi-Z	Hi-Z	Hi-Z	DIN	Write fourth byte
↑	L	Х	L	L	L	L	L	L	DIN	DIN	DIN	DIN	Write all bytes

NOTE : K & K are complementary

ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Value	Unit
Core Supply Voltage Relative to Vss	VDD	-0.5 to 3.13	V
Output Supply Voltage Relative to Vss	VDDQ	-0.5 to 2.4	V
Voltage on any I/O pin Relative to Vss	VTERM	-0.5 to VDDQ+0.5 (2.4V MAX)	V
Output Short-Circuit Current	Іоит	25	mA
Operating Temperature	Topr	0 to 70	°C
Storage Temperature	Тѕтс	-55 to 125	°C

Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operating sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

RECOMMENDED DC OPERATING CONDITIONS

Parameter	Symbol	Min	Тур	Max	Unit	Note
Core Power Supply Voltage	VDD	2.37	2.5	2.63	V	
Output Power Supply Voltage	Vddq	1.4	1.5	1.9	V	
Input High Level	ViH	VREF+0.1	-	VDDQ+0.3	V	
Input Low Level	VIL	-0.3	-	VREF-0.1	V	
Input Reference Voltage	VREF	0.6	0.75	0.9	V	
Clock Input Signal Voltage	VIN-CLK	-0.3	-	VDDQ+0.3	V	
Clock Input Differential Voltage	VDIF-CLK	0.1	-	VDDQ+0.6	V	
Clock Input Common Mode Voltage	Vcm-CLK	0.6	0.75	0.9	V	

PIN CAPACITANCE

Parameter	Symbol	Test Condition	Min	Max	Unit
Input Capacitance	CIN	VIN=0V	-	4	pF
Data Output Capacitance	Соит	Vout=0V	-	5	pF

NOTE: Periodically sampled and not 100% tested.(TA=25°C, f=1MHz)

DC CHARACTERISTICS

Parameter	Symbol	Min	Max	Unit	Note
Average Power Supply Operating Current-x36 (VIN=VIH or VIL, ZZ & SS=VIL)	IDD33 IDD30 IDD25	-	700 620 550	mA	1, 2
Average Power Supply Operating Current-x18 (VIN=VIH or VIL, ZZ & SS=VIL)	IDD33 IDD30 IDD25	-	650 570 500	mA	1, 2
Power Supply Standby Current (VIN=VIH or VIL, ZZ=VIH)	Isbzz	-	128	mA	1
Active Standby Power Supply Current (VIN=VIH or VIL, \$\overline{SS}=VIH, ZZ=VIL)	Isbss	-	200	mA	1
Input Leakage Current (VIN=Vss or VDDQ)	lu	-1	1	μА	
Output Leakage Current (Vout=Vss or VDDQ, DQ in High-Z)	llo	-1	1	μА	
Output High Voltage(Programmable Impedance Mode)	Voн1	VDDQ/2	VDDQ	V	3,5
Output Low Voltage(Programmable Impedance Mode)	Vol1	Vss	VDDQ/2	V	4,5
Output High Voltage(Iон=-0.1mA)	VOH2	VDDQ-0.2	VDDQ	V	6
Output Low Voltage(IoL=0.1mA)	VOL2	Vss	0.2	V	6
Output High Voltage(IoH=-6mA)	Vонз	VDDQ-0.4	VDDQ	V	6
Output Low Voltage(IoL=6mA)	VOL3	Vss	0.4	V	6

NOTE: 1. Minimum cycle. Iout=0mA.

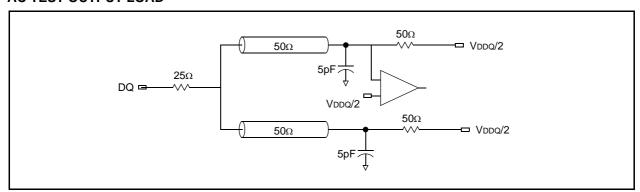
- 2. 50% read cycles. 3. |IoH|=(VDDQ/2)/(RQ/5)±15% @VoH=VDDQ/2 for 175 Ω ≤ RQ ≤ 350 Ω .
- 4. $|IoL|=(VDDQ/2)/(RQ/5)\pm15\%$ @Vol=VDDQ/2 for $175\Omega \le RQ \le 350\Omega$.
- 5. Programmable Impedance Output Buffer Mode. The ZQ pin is connected to Vss through RQ. 6. Minimum Impedance Output Buffer Mode. The ZQ pin is connected to Vss or Vpd.

AC TEST CONDITIONS (TA=0 to 70°C, VDD=2.37 -2.63V, VDDQ=1.5V)

Parameter	Symbol	Value	Unit
Core Power Supply Voltage	VDD	2.37~2.63	V
Output Power Supply Voltage	VDDQ	1.5	V
Input High/Low Level	VIH/VIL	1.25/0.25	٧
Input Reference Level	VREF	0.75	V
Input Rise/Fall Time	Tr/Tr	0.5/0.5	ns
Input and Out Timing Reference Level		0.75	V
Clock Input Timing Reference Level		Cross Point	V

NOTE : Parameters are tested with RQ=250 Ω and VDDQ=1.5V.

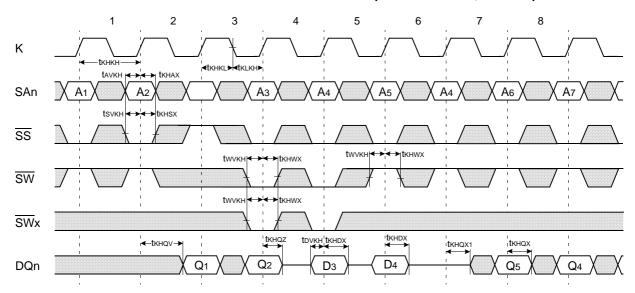
AC TEST OUTPUT LOAD



AC CHARACTERISTICS

Parameter	Symbol	-:	33	-30		-25		Unit	Note
Farameter	Symbol	Min	Max	Min	Max	Min	Max	Oiiii I	Note
Clock Cycle Time	tkhkh	3.0	-	3.3	-	4.0	-	ns	
Clock High Pulse Width	tkhkl	1.2	-	1.3	-	1.6	-	ns	
Clock Low Pulse Width	tklkh	1.2	-	1.3	-	1.6	-	ns	
Clock High to Output Valid	tkhqv	-	1.5	-	1.6	-	2.0	ns	
Clock High to Output Hold	tkhqx	0.5	-	0.5	-	0.5	-	ns	
Address Setup Time	tavkh	0.3	-	0.3	-	0.3	-	ns	
Address Hold Time	tkhax	0.5	-	0.6	-	0.6	-	ns	
Write Data Setup Time	tdvkh	0.3	-	0.3	-	0.3	-	ns	
Write Data Hold Time	tkhdx	0.5	-	0.6	-	0.6	-	ns	
SW, SW[a:d] Setup Time	twvkh	0.3	-	0.3	-	0.3	-	ns	
SW, SW[a:d] Hold Time	tkhwx	0.5	-	0.6	-	0.6	-	ns	
SS Setup Time	tsvkh	0.3	-	0.3	-	0.3	-	ns	
SS Hold Time	tĸĸsx	0.5	-	0.6	-	0.6	-	ns	
Clock High to Output Hi-Z	tkhqz	-	1.5	-	1.6	-	2.0	ns	
Clock High to Output Low-Z	tKHQX1	0.5	-	0.5	-	0.5	-	ns	
G High to Output High-Z	tghqz	-	1.5	-	1.6	-	2.0	ns	
G Low to Output Low-Z	tGLQX	0.5	-	0.5	-	0.5	-	ns	
G Low to Output Valid	tGLQV	-	1.5	-	1.6	-	2.0	ns	
ZZ High to Power Down(Sleep Time)	tzze	-	15	-	15	-	15	ns	
ZZ Low to Recovery(Wake-up Time)	tzzr	-	20	-	20	-	20	ns	

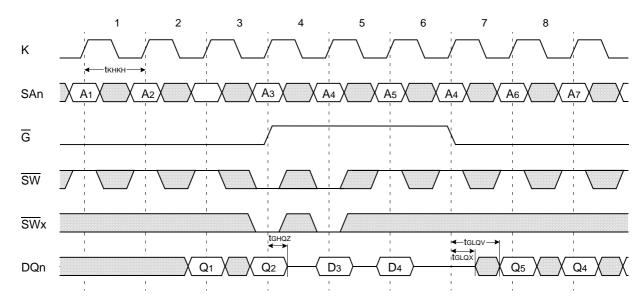
TIMING WAVEFORMS OF NORMAL ACTIVE CYCLES (SS Controlled, G=Low)



NOTE

- 1. D₃ is the input data written in memory location A₃.
- 2. Q4 is the output data read from the write data buffer(not from the cell array), as a result of address A4 being a match from the last write cycle address.

TIMING WAVEFORMS OF NORMAL ACTIVE CYCLES (G Controlled, SS=Low)

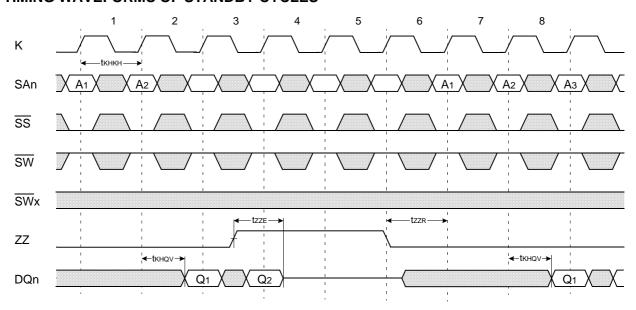


NOTE

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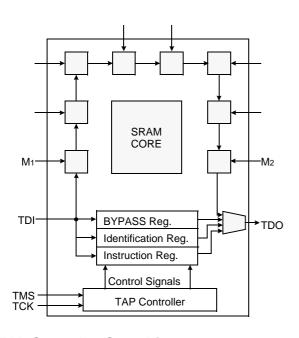
TIMING WAVEFORMS OF STANDBY CYCLES



IEEE 1149.1 TEST ACCESS PORT AND BOUNDARY SCAN-JTAG

The SRAM provides a limited set of IEEE standard 1149.1 JTAG functions. This is to test the connectivity during manufacturing between SRAM, printed circuit board and other components. Internal data is not driven out of SRAM under JTAG control. In conformance with IEEE 1149.1, the SRAM contains a TAP controller, Instruction Register, Bypass Register and ID register. The TAP controller has a standard 16-state machine that resets internally upon power-up, therefore, TRST signal is not required. It is possible to use this device without utilizing the TAP. To disable the TAP controller without interfacing with normal operation of the SRAM, TCK must be tied to Vss to preclude mid level input. TMS and TDI are designed so an undriven input will produce a response identical to the application of a logic 1, and therefore can be left unconnected. But they may also be tied to Vpp through a resistor. TDO should be left unconnected.

JTAG Block Diagram



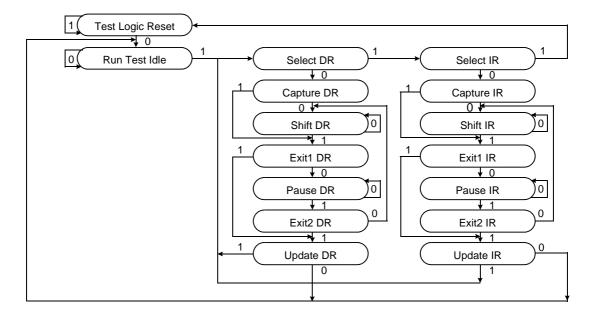
JTAG Instruction Coding

IR2	IR1	IR0	Instruction	ction TDO Output	
0	0	0	SAMPLE-Z	Boundary Scan Register	1
0	0	1	IDCODE	Identification Register	2
0	1	0	SAMPLE-Z	Boundary Scan Register	1
0	1	1	BYPASS	Bypass Register	3
1	0	0	SAMPLE	Boundary Scan Register	4
1	0	1	BYPASS	Bypass Register	3
1	1	0	BYPASS	Bypass Register	3
1	1	1	BYPASS	Bypass Register	3

NOTE

- Places DQs in Hi-Z in order to sample all input data regardless of other SRAM inputs.
- TDI is sampled as an input to the first ID register to allow for the serial shift of the external TDI data.
- Bypass register is initiated to Vss when BYPASS instruction is invoked. The Bypass Register also holds serially loaded TDI when exiting the Shift DR states.
- 4. SAMPLE instruction does not places DQs in Hi-Z.

TAP Controller State Diagram



SCAN REGISTER DEFINITION

Part	Instruction Register	Bypass Register	ID Register	Boundary Scan
512Kx36	3 bits	1 bits	32 bits	70 bits
1Mx18	3 bits	1 bits	32 bits	51 bits

ID REGISTER DEFINITION

Part	Revision Number (31:28)	Part Configuration (27:18)	Vendor Definition (17:12)	Samsung JEDEC Code (11: 1)	Start Bit(0)
512Kx36	0000	00111 00100	XXXXXX	00001001110	1
1Mx18	0000	01000 00011	XXXXXX	00001001110	1

BOUN	DARY	SCAN	EXIT	ORDE	R(x36))
36	3B	SA ₉		SA ₈	5B	35
37	2B	SA ₁₈		SA ₁₇	6B	34
38	3A	SA ₁₀		SA ₇	5A	33
39	3C	SA ₁₁		SA ₆	5C	32
40	2C	SA ₁₂		SA ₅	6C	31
41	2A	SA13		SA ₄	6A	30
42	2D	DQc9		DQb9	6D	29
43	1D	DQc8		DQb8	7D	28
44	2E	DQc7		DQb7	6E	27
45	1E	DQc6		DQb6	7E	26
46	2F	DQc5		DQb5	6F	25
47	2G	DQc4		DQb4	6G	24
48	1G	DQc3		DQb3	7G	23
49	2H	DQc2		DQb2	6H	22
50	1H	DQc1		DQb1	7H	21
51	3G	SWc		SWb	5G	20
52	4D	ZQ		G	4F	19
53	4E	SS		K	4K	18
54	4G	NC*		K	4L	17
55	4H	NC* ¹		SWa	5L	16
56	4M	SW		DQa ₁	7K	15
57	3L	SWd		DQa ₂	6K	14
58	1K	DQd1		DQa ₃	7L	13
59	2K	DQd2		DQa4	6L	12
60	1L	DQd3		DQa ₅	6M	11
61	2L	DQd4		DQa ₆	7N	10
62	2M	DQd5		DQa7	6N	9
63	1N	DQd6		DQa8	7P	8
64	2N	DQd7		DQa ₉	6P	7
65	1P	DQd8		ZZ	7T	6
66	2P	DQd9		SA ₃	5T	5
67	3T	SA ₁₄		SA ₂	6R	4
68	2R	SA ₁₅		SA ₁₆	4T	3
69	4N	SA ₀		SA ₁	4P	2
70	3R	M1		M ₂	5R	1

BOUNDARY SCAN EXIT ORDER(x18)

		+			
26	3B	SA ₉	SA ₈	5B	25
27	2B	SA19	SA ₁₇	6B	24
28	3A	SA ₁₀	SA ₇	5A	23
29	3C	SA ₁₁	SA ₆	5C	22
30	2C	SA ₁₂	SA ₅	6C	21
31	2A	SA ₁₃	SA ₄	6A	20
			DQa ₉	6D	19
32	1D	DQb1			
33	2E	DQb2			
			DQa8	7E	18
			DQa7	6F	17
34	2G	DQb3			
			DQa ₆	7G	16
			DQa ₅	6H	15
35	1H	DQb4			
36	3G	SWb			
37	4D	ZQ	G	4F	14
38	4E	SS	K	4K	13
39	4G	NC	K	4L	12
40	4H	NC	SWa	5L	11
41	4M	SW	DQa4	7K	10
42	2K	DQb5	DQa ₃	6L	9
43	1L	DQb6			
44	2M	DQb7	DQa2	6N	8
45	1N	DQb8	DQa ₁	7P	7
			ZZ	7T	6
46	2P	DQb9	SA ₃	5T	5
47	3T	SA ₁₄	SA ₂	6R	4
48	2R	SA ₁₅			
49	4N	SA ₀	SA ₁	4P	3
50	2T	SA ₁₈	SA ₁₆	6T	2
51	3R	M1	M2	5R	1

NOTE :1. Pins 4G and 4H are no connection pin to internal chip. The scanned data are fixed to "0" and "1" respectively.

JTAG DC OPERATING CONDITIONS

Parameter	Symbol	Min	Тур	Max	Unit	Note
Power Supply Voltage	VDD	2.37	2.5	2.63	V	
Input High Level	VIH	1.7	-	VDD+0.3	V	
Input Low Level	VIL	-0.3	-	0.8	V	
Output High Voltage(IoH=-2mA)	Voн	2.1	-	VDD	V	
Output Low Voltage(IoL=2mA)	Vol	Vss	-	0.2	V	

NOTE: 1. The input level of SRAM pin is to follow the SRAM DC specification.

JTAG AC TEST CONDITIONS

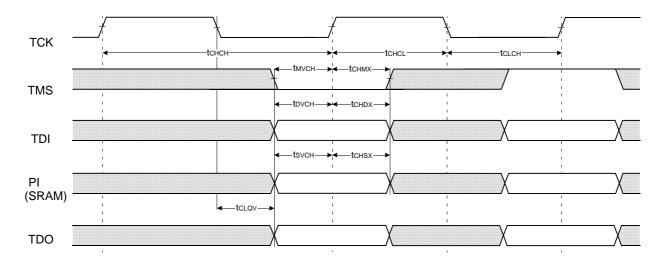
Parameter	Symbol	Min	Unit	Note
Input High/Low Level	VIH/VIL	2.5/0.0	V	
Input Rise/Fall Time	TR/TF	1.0/1.0	ns	
Input and Output Timing Reference Level		1.25	V	1

NOTE: 1. See SRAM AC test output load on page 7.

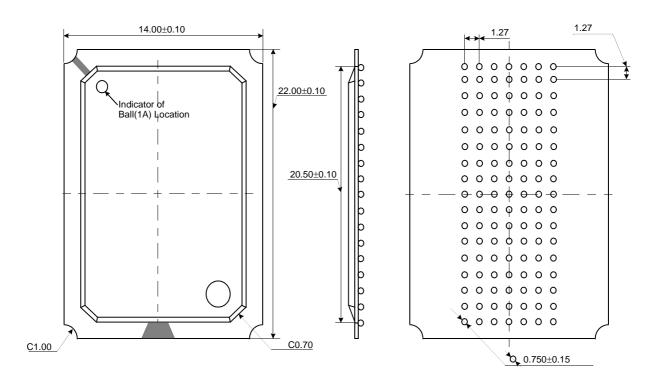
JTAG AC Characteristics

Parameter	Symbol	Min	Max	Unit	Note
TCK Cycle Time	tснсн	50	-	ns	
TCK High Pulse Width	tchcl	20	-	ns	
TCK Low Pulse Width	tclch	20	-	ns	
TMS Input Setup Time	tmvch	5	-	ns	
TMS Input Hold Time	tchmx	5	-	ns	
TDI Input Setup Time	tdvch	5	-	ns	
TDI Input Hold Time	tCHDX	5	-	ns	
SRAM Input Setup Time	tsvch	5	-	ns	
SRAM Input Hold Time	tchsx	5	-	ns	
Clock Low to Output Valid	tclqv	0	10	ns	

JTAG TIMING DIAGRAM



119 BGA PACKAGE DIMENSIONS





NOTE:

All Dimensions are in Millimeters.
 Solder Ball to PCB Offset: 0.10 MAX.
 PCB to Cavity Offset: 0.10 MAX.

119 BGA PACKAGE THERMAL CHARACTERISTICS

Parameter	Symbol	Thermal Resistance	Unit	Note
Junction to Ambient(at still air)	Theta_JA	TBD	°C/W	1W Heating
Junction to Case	Theta_JC	TBD	°C/W	
Junction to Board	Theta_JB	TBD	°C/W	2W Heating

NOTE : 1. Junction temperature can be calculated by : $T_J = T_A + P_D x Theta_JA$.