Features

- High-performance, Low-power AVR® 8-bit Microcontroller
  - 130 Powerful Instructions – Most Single Clock Cycle Execution
  - 32 x 8 General Purpose Working Registers
  - Fully Static Operation
  - Up to 8 MIPS Throughput at 8 MHz
  - On-chip 2-cycle Multiplier
- Nonvolatile Program and Data Memories
- Self-programming In-System Programmable Flash Memory
  - 16K Bytes with Optional Boot Block (256 - 2K Bytes)
    Endurance: 1,000 Write/Erase Cycles
  - Boot Section Allows Reprogramming of Program Code without External Programmer
  - Optional Boot Code Section with Independent Lock Bits
  - 512 Bytes EEPROM
    Endurance: 100,000 Write/Erase Cycles
  - 1024 Bytes Internal SRAM
  - Programming Lock for Software Security
- Peripheral Features
  - Two 8-bit Timer/Counters with Separate Prescaler and Compare Mode
  - One 16-bit Timer/Counter with Separate Prescaler, Compare Mode, and Capture Mode
  - Real Time Clock with Separate Oscillator and Counter Mode
  - Three PWM Channels
  - 8-channel, 10-bit ADC
  - Byte-oriented Two-wire Serial Interface
  - Programmable Serial UART
  - Master/Slave SPI Serial Interface
  - Programmable Watchdog Timer with Separate On-chip Oscillator
  - Analog Comparator
- Special Microcontroller Features
  - Power-on Reset and Programmable Brown-out Detection
  - Internal Calibrated RC Oscillator
  - External and Internal Interrupt Sources
  - Four Sleep Modes: Idle, ADC Noise Reduction, Power-save, and Power-down
- Power Consumption at 4 MHz, 3.0V, 25°C
  - Active 5.0 mA
  - Idle Mode 1.9 mA
  - Power-down Mode < 1 µA
- I/O and Packages
  - 32 Programmable I/O Lines
  - 40-pin PDIP and 44-pin TQFP
- Operating Voltages
  - 2.7 - 5.5V for ATmega163L
  - 4.0 - 5.5V for ATmega163
- Speed Grades
  - 0 - 4 MHz for ATmega163L
  - 0 - 8 MHz for ATmega163

8-bit AVR® Microcontroller with 16K Bytes In-System Programmable Flash

ATmega163
ATmega163L

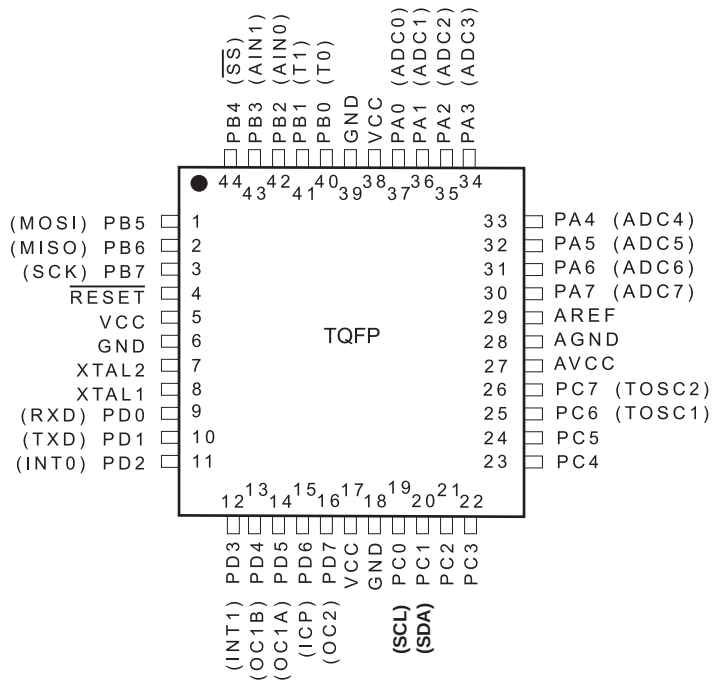
Summary

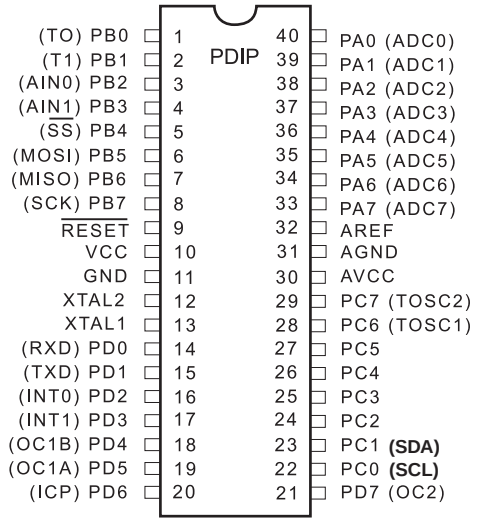
Not Recommend for New Designs. Use ATmega16.

Rev.1142ES–AVR–02/03

Note: This is a summary document. A complete document is available on our web site at *www.atmel.com*.

Pin Configurations



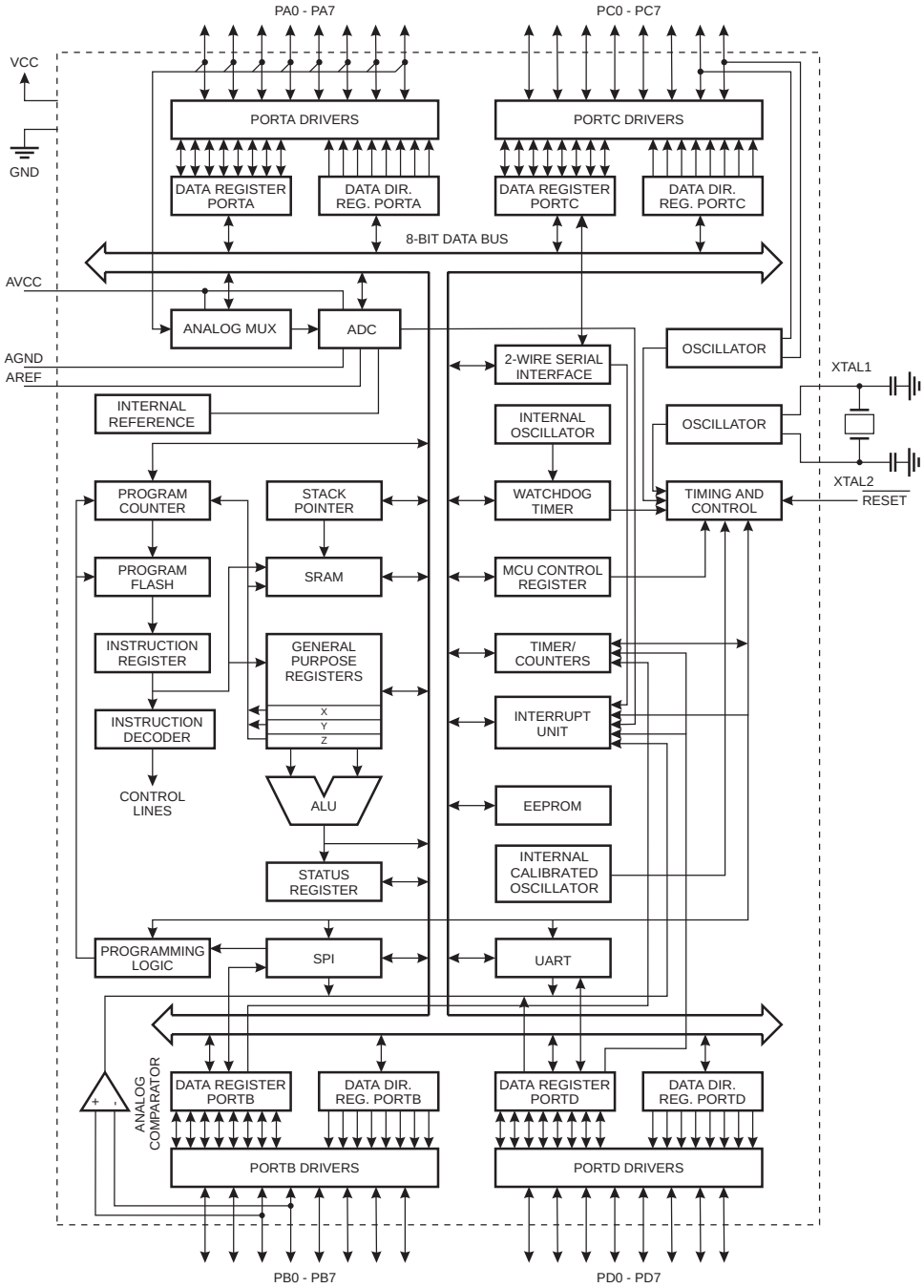


Description

The ATmega163 is a low-power CMOS 8-bit microcontroller based on the AVR architecture. By executing powerful instructions in a single clock cycle, the ATmega163 achieves throughputs approaching 1 MIPS per MHz allowing the system designer to optimize power consumption versus processing speed.

Block Diagram

Figure 1. Block Diagram



The AVR core combines a rich instruction set with 32 general purpose working registers. All the 32 registers are directly connected to the Arithmetic Logic Unit (ALU), allowing two independent registers to be accessed in one single instruction executed in one clock

cycle. The resulting architecture is more code efficient while achieving throughputs up to ten times faster than conventional CISC microcontrollers.

The ATmega163 provides the following features: 16K bytes of In-System Self-Programmable Flash, 512 bytes EEPROM, 1024 bytes SRAM, 32 general purpose I/O lines, 32 general purpose working registers, three flexible Timer/Counters with compare modes, internal and external interrupts, a byte oriented Two-wire Serial Interface, an 8-channel, 10-bit ADC, a programmable Watchdog Timer with internal Oscillator, a programmable serial UART, an SPI serial port, and four software selectable power saving modes. The Idle mode stops the CPU while allowing the SRAM, Timer/Counters, SPI port, and interrupt system to continue functioning. The Power-down mode saves the register contents but freezes the Oscillator, disabling all other chip functions until the next interrupt or Hardware Reset. In Power-save mode, the asynchronous Timer Oscillator continues to run, allowing the user to maintain a timer base while the rest of the device is sleeping. The ADC Noise Reduction mode stops the CPU and all I/O modules except asynchronous timer and ADC, to minimize switching noise during ADC conversions.

The On-chip ISP Flash can be programmed through an SPI serial interface or a conventional programmer. By installing a Self-Programming Boot Loader, the microcontroller can be updated within the application without any external components. The Boot Program can use any interface to download the application program in the Application Flash memory. By combining an 8-bit CPU with In-System Self-Programmable Flash on a monolithic chip, the Atmel ATmega163 is a powerful microcontroller that provides a highly flexible and cost effective solution to many embedded control applications.

The ATmega163 AVR is supported with a full suite of program and system development tools including: C compilers, macro assemblers, program debugger/simulators, In-Circuit Emulators, and evaluation kits.

Pin Descriptions

VCC Digital supply voltage.

GND Digital ground.

Port A (PA7..PA0) Port A serves as the analog inputs to the A/D Converter.

Port A also serves as an 8-bit bi-directional I/O port, if the A/D Converter is not used. Port pins can provide internal pull-up resistors (selected for each bit). The Port A output buffers can sink 20mA and can drive LED displays directly. When pins PA0 to PA7 are used as inputs and are externally pulled low, they will source current if the internal pull-up resistors are activated. The Port A pins are tristated when a reset condition becomes active, even if the clock is not running.

Port B (PB7..PB0) Port B is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port B output buffers can sink 20 mA. As inputs, Port B pins that are externally pulled low will source current if the pull-up resistors are activated. Port B also serves the functions of various special features of the ATmega83/163 as listed on page 117. The Port B pins are tristated when a reset condition becomes active, even if the clock is not running.

Port C (PC7..PC0) Port C is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port C output buffers can sink 20 mA. As inputs, Port C pins that are externally pulled low will source current if the pull-up resistors are activated. The Port C pins are tristated when a reset condition becomes active, even if the clock is not running.

Port C also serves the functions of various special features of the ATmega163 as listed on page 124.

Port D (PD7..PD0) Port D is an 8-bit bidirectional I/O port with internal pull-up resistors (selected for each bit). The Port D output buffers can sink 20 mA. As inputs, Port D pins that are externally pulled low will source current if the pull-up resistors are activated. Port D also serves the functions of various special features of the ATmega163 as listed on page 128. The Port D pins are tristated when a reset condition becomes active, even if the clock is not running.

$\overline{\text{RESET}}$ Reset input. A low level on this pin for more than 500 ns will generate a Reset, even if the clock is not running. Shorter pulses are not guaranteed to generate a Reset.

XTAL1 Input to the inverting Oscillator amplifier and input to the internal clock operating circuit.

XTAL2 Output from the inverting Oscillator amplifier.

AVCC This is the supply voltage pin for Port A and the A/D Converter. It should be externally connected to V_{CC}, even if the ADC is not used. If the ADC is used, it should be connected to V_{CC} through a low-pass filter. See page 105 for details on operation of the ADC.

AREF AREF is the analog reference input pin for the A/D Converter. For ADC operations, a voltage in the range 2.5V to AVCC can be applied to this pin.

AGND Analog ground. If the board has a separate analog ground plane, this pin should be connected to this ground plane. Otherwise, connect to GND.

Register Summary

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
$3F ($5F)	SREG	I	T	H	S	V	N	Z	C	20
$3E ($5E)	SPH	–	–	–	–	–	SP10	SP9	SP8	21
$3D ($5D)	SPL	SP7	SP6	SP5	SP4	SP3	SP2	SP1	SP0	21
$3C ($5C)	Reserved									
$3B ($5B)	GIMSK	INT1	INT0	–	–	–	–	–	–	30
$3A ($5A)	GIFR	INTF1	INTF0	–	–	–	–	–	–	31
$39 ($59)	TIMSK	OCIE2	TOIE2	TICIE1	OCIE1A	OCIE1B	TOIE1	–	TOIE0	32
$38 ($58)	TIFR	OCF2	TOV2	ICF1	OCF1A	OCF1B	TOV1	–	TOV0	32
$37 ($57)	SPMCR	–	ASB	–	ASRE	BLBSET	PGWRT	PGERS	SPMEN	140
$36 ($56)	TWCR	TWINT	TWEA	TWSTA	TWSTO	TWWC	TWEN	–	TWIE	82
$35 ($55)	MCUCR	–	SE	SM1	SM0	ISC11	ISC10	ISC01	ISC00	34
$34 ($54)	MCUSR	–	–	–	–	WDRF	BORF	EXTRF	PORF	28
$33 ($53)	TCCR0	–	–	–	–	–	CS02	CS01	CS00	41
$32 ($52)	TCNT0	Timer/Counter0 (8 Bits)								42
$31 ($51)	OSCCAL	Oscillator Calibration Register								37
$30 ($50)	SFIOR	–	–	–	–	ACME	PUD	PSR2	PSR10	40
$2F ($4F)	TCCR1A	COM1A1	COM1A0	COM1B1	COM1B0	FOC1A	FOC1B	PWM11	PWM10	44
$2E ($4E)	TCCR1B	ICNC1	ICES1	–	–	CTC1	CS12	CS11	CS10	45
$2D ($4D)	TCNT1H	Timer/Counter1 – Counter Register High Byte								46
$2C ($4C)	TCNT1L	Timer/Counter1 – Counter Register Low Byte								46
$2B ($4B)	OCR1AH	Timer/Counter1 – Output Compare Register A High Byte								47
$2A ($4A)	OCR1AL	Timer/Counter1 – Output Compare Register A Low Byte								47
$29 ($49)	OCR1BH	Timer/Counter1 – Output Compare Register B High Byte								47
$28 ($48)	OCR1BL	Timer/Counter1 – Output Compare Register B Low Byte								47
$27 ($47)	ICR1H	Timer/Counter1 – Input Capture Register High Byte								48
$26 ($46)	ICR1L	Timer/Counter1 – Input Capture Register Low Byte								48
$25 ($45)	TCCR2	FOC2	PWM2	COM21	COM20	CTC2	CS22	CS21	CS20	52
$24 ($44)	TCNT2	Timer/Counter2 (8 Bits)								53
$23 ($43)	OCR2	Timer/Counter2 Output Compare Register								54
$22 ($42)	ASSR	–	–	–	–	AS2	TCN2UB	OCR2UB	TCR2UB	57
$21 ($41)	WDTCR	–	–	–	WDTOE	WDE	WDP2	WDP1	WDP0	60
$20 ($40)	UBRRHI	–	–	–	–	UBRR[11:8]				78
$1F ($3F)	EEARH	–	–	–	–	–	–	–	EEAR8	62
$1E ($3E)	EEARL	EEAR7	EEAR6	EEAR5	EEAR4	EEAR3	EEAR2	EEAR1	EEAR0	62
$1D ($3D)	EEDR	EEPROM Data Register								62
$1C ($3C)	EECR	–	–	–	–	EERIE	EEMWE	EEWE	EERE	63
$1B ($3B)	PORTA	PORTA7	PORTA6	PORTA5	PORTA4	PORTA3	PORTA2	PORTA1	PORTA0	115
$1A ($3A)	DDRA	DDA7	DDA6	DDA5	DDA4	DDA3	DDA2	DDA1	DDA0	115
$19 ($39)	PINA	PINA7	PINA6	PINA5	PINA4	PINA3	PINA2	PINA1	PINA0	115
$18 ($38)	PORTB	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	117
$17 ($37)	DDRB	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	117
$16 ($36)	PINB	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	117
$15 ($35)	PORTC	PORTC7	PORTC6	PORTC5	PORTC4	PORTC3	PORTC2	PORTC1	PORTC0	123
$14 ($34)	DDRC	DDC7	DDC6	DDC5	DDC4	DDC3	DDC2	DDC1	DDC0	123
$13 ($33)	PINC	PINC7	PINC6	PINC5	PINC4	PINC3	PINC2	PINC1	PINC0	123
$12 ($32)	PORTD	PORTD7	PORTD6	PORTD5	PORTD4	PORTD3	PORTD2	PORTD1	PORTD0	128
$11 ($31)	DDRD	DDD7	DDD6	DDD5	DDD4	DDD3	DDD2	DDD1	DDD0	128
$10 ($30)	PIND	PIND7	PIND6	PIND5	PIND4	PIND3	PIND2	PIND1	PIND0	128
$0F ($2F)	SPDR	SPI Data Register								69
$0E ($2E)	SPSR	SPIF	WCOL	–	–	–	–	–	SPI2X	68
$0D ($2D)	SPCR	SPIE	SPE	DORD	MSTR	CPOL	CPHA	SPR1	SPR0	67
$0C ($2C)	UDR	UART I/O Data Register								74
$0B ($2B)	UCSRA	RXC	TXC	UDRE	FE	OR	–	U2X	MPCM	74
$0A ($2A)	UCSRB	RXCIE	TXCIE	UDRIE	RXEN	TXEN	CHR9	RXB8	TXB8	76
$09 ($29)	UBRR	UART Baud Rate Register								78
$08 ($28)	ACSR	ACD	ACBG	ACO	ACI	ACIE	ACIC	ACIS1	ACIS0	102
$07 ($27)	ADMUX	REFS1	REFS0	ADLAR	MUX4	MUX3	MUX2	MUX1	MUX0	110
$06 ($26)	ADCSR	ADEN	ADSC	ADFR	ADIF	ADIE	ADPS2	ADPS1	ADPS0	111
$05 ($25)	ADCH	ADC Data Register High Byte								112
$04 ($24)	ADCL	ADC Data Register Low Byte								112
$03 ($23)	TWDR	Two-wire Serial Interface Data Register								84
$02 ($22)	TWAR	TWA6	TWA5	TWA4	TWA3	TWA2	TWA1	TWA0	TWGCE	85
$01 ($21)	TWSR	TWS7	TWS6	TWS5	TWS4	TWS3	–	–	–	84

Register Summary (Continued)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
$00 ($20)	TWBR	Two-wire Serial Interface Bit Rate Register								82

Note: 1. For compatibility with future devices, reserved bits should be written to zero if accessed. Reserved I/O memory addresses should never be written.

2. Some of the Status Flags are cleared by writing a logical one to them. Note that the CBI and SBI instructions will operate on all bits in the I/O Register, writing a one back into any flag read as set, thus clearing the flag. The CBI and SBI instructions work with registers $00 to $1F only.

Instruction Set Summary

Mnemonics	Operands	Description	Operation	Flags	#Clocks
ARITHMETIC AND LOGIC INSTRUCTIONS					
ADD	Rd, Rr	Add two Registers	Rd ← Rd + Rr	Z,C,N,V,H	1
ADC	Rd, Rr	Add with Carry two Registers	Rd ← Rd + Rr + C	Z,C,N,V,H	1
ADIW	Rdl,K	Add Immediate to Word	Rdh:Rdl ← Rdh:Rdl + K	Z,C,N,V,S	2
SUB	Rd, Rr	Subtract two Registers	Rd ← Rd - Rr	Z,C,N,V,H	1
SUBI	Rd, K	Subtract Constant from Register	Rd ← Rd - K	Z,C,N,V,H	1
SBC	Rd, Rr	Subtract with Carry two Registers	Rd ← Rd - Rr - C	Z,C,N,V,H	1
SBCI	Rd, K	Subtract with Carry Constant from Reg.	Rd ← Rd - K - C	Z,C,N,V,H	1
SBIW	Rdl,K	Subtract Immediate from Word	Rdh:Rdl ← Rdh:Rdl - K	Z,C,N,V,S	2
AND	Rd, Rr	Logical AND Registers	Rd ← Rd • Rr	Z,N,V	1
ANDI	Rd, K	Logical AND Register and Constant	Rd ← Rd • K	Z,N,V	1
OR	Rd, Rr	Logical OR Registers	Rd ← Rd v Rr	Z,N,V	1
ORI	Rd, K	Logical OR Register and Constant	Rd ← Rd v K	Z,N,V	1
EOR	Rd, Rr	Exclusive OR Registers	Rd ← Rd ⊕ Rr	Z,N,V	1
COM	Rd	One's Complement	Rd ← $FF – Rd	Z,C,N,V	1
NEG	Rd	Two's Complement	Rd ← $00 – Rd	Z,C,N,V,H	1
SBR	Rd,K	Set Bit(s) in Register	Rd ← Rd v K	Z,N,V	1
CBR	Rd,K	Clear Bit(s) in Register	Rd ← Rd • ($FF - K)	Z,N,V	1
INC	Rd	Increment	Rd ← Rd + 1	Z,N,V	1
DEC	Rd	Decrement	Rd ← Rd – 1	Z,N,V	1
TST	Rd	Test for Zero or Minus	Rd ← Rd • Rd	Z,N,V	1
CLR	Rd	Clear Register	Rd ← Rd ⊕ Rd	Z,N,V	1
SER	Rd	Set Register	Rd ← $FF	None	1
MUL	Rd, Rr	Multiply Unsigned	R1:R0 ← Rd x Rr	Z,C	2
MULS	Rd, Rr	Multiply Signed	R1:R0 ← Rd x Rr	Z,C	2
MULSU	Rd, Rr	Multiply Signed with Unsigned	R1:R0 ← Rd x Rr	Z,C	2
FMUL	Rd, Rr	Fractional Multiply Unsigned	R1:R0 ← (Rd x Rr) << 1	Z,C	2
FMULS	Rd, Rr	Fractional Multiply Signed	R1:R0 ← (Rd x Rr) << 1	Z,C	2
FMULSU	Rd, Rr	Fractional Multiply Signed with Unsigned	R1:R0 ← (Rd x Rr) << 1	Z,C	2
BRANCH INSTRUCTIONS					
RJMP	k	Relative Jump	PC ← PC + k + 1	None	2
IJMP		Indirect Jump to (Z)	PC ← Z	None	2
JMP	k	Direct Jump	PC ← k	None	3
RCALL	k	Relative Subroutine Call	PC ← PC + k + 1	None	3
ICALL		Indirect Call to (Z)	PC ← Z	None	3
CALL	k	Direct Subroutine Call	PC ← k	None	4
RET		Subroutine Return	PC ← STACK	None	4
RETI		Interrupt Return	PC ← STACK	I	4
CPSE	Rd,Rr	Compare, Skip if Equal	if (Rd = Rr) PC ← PC + 2 or 3	None	1 / 2 / 3
CP	Rd,Rr	Compare	Rd – Rr	Z, N,V,C,H	1
CPC	Rd,Rr	Compare with Carry	Rd – Rr – C	Z, N,V,C,H	1
CPI	Rd,K	Compare Register with Immediate	Rd – K	Z, N,V,C,H	1
SBRC	Rr, b	Skip if Bit in Register Cleared	if (Rr(b)=0) PC ← PC + 2 or 3	None	1 / 2 / 3
SBRS	Rr, b	Skip if Bit in Register is Set	if (Rr(b)=1) PC ← PC + 2 or 3	None	1 / 2 / 3
SBIC	P, b	Skip if Bit in I/O Register Cleared	if (P(b)=0) PC ← PC + 2 or 3	None	1 / 2 / 3
SBIS	P, b	Skip if Bit in I/O Register is Set	if (P(b)=1) PC ← PC + 2 or 3	None	1 / 2 / 3
BRBS	s, k	Branch if Status Flag Set	if (SREG(s) = 1) then PC←PC+k + 1	None	1 / 2
BRBC	s, k	Branch if Status Flag Cleared	if (SREG(s) = 0) then PC←PC+k + 1	None	1 / 2
BREQ	k	Branch if Equal	if (Z = 1) then PC ← PC + k + 1	None	1 / 2
BRNE	k	Branch if Not Equal	if (Z = 0) then PC ← PC + k + 1	None	1 / 2
BRCS	k	Branch if Carry Set	if (C = 1) then PC ← PC + k + 1	None	1 / 2
BRCC	k	Branch if Carry Cleared	if (C = 0) then PC ← PC + k + 1	None	1 / 2
BRSH	k	Branch if Same or Higher	if (C = 0) then PC ← PC + k + 1	None	1 / 2
BRLO	k	Branch if Lower	if (C = 1) then PC ← PC + k + 1	None	1 / 2
BRMI	k	Branch if Minus	if (N = 1) then PC ← PC + k + 1	None	1 / 2
BRPL	k	Branch if Plus	if (N = 0) then PC ← PC + k + 1	None	1 / 2
BRGE	k	Branch if Greater or Equal, Signed	if (N ⊕ V= 0) then PC ← PC + k + 1	None	1 / 2
BRLT	k	Branch if Less Than Zero, Signed	if (N ⊕ V= 1) then PC ← PC + k + 1	None	1 / 2
BRHS	k	Branch if Half Carry Flag Set	if (H = 1) then PC ← PC + k + 1	None	1 / 2
BRHC	k	Branch if Half Carry Flag Cleared	if (H = 0) then PC ← PC + k + 1	None	1 / 2
BRTS	k	Branch if T Flag Set	if (T = 1) then PC ← PC + k + 1	None	1 / 2
BRTC	k	Branch if T Flag Cleared	if (T = 0) then PC ← PC + k + 1	None	1 / 2
BRVS	k	Branch if Overflow Flag is Set	if (V = 1) then PC ← PC + k + 1	None	1 / 2
BRVC	k	Branch if Overflow Flag is Cleared	if (V = 0) then PC ← PC + k + 1	None	1 / 2

Instruction Set Summary (Continued)

BRIE	k	Branch if Interrupt Enabled	if (I = 1) then PC ← PC + k + 1	None	1 / 2
BRID	k	Branch if Interrupt Disabled	if (I = 0) then PC ← PC + k + 1	None	1 / 2
DATA TRANSFER INSTRUCTIONS					
MOV	Rd, Rr	Move Between Registers	Rd ← Rr	None	1
MOVW	Rd, Rr	Copy Register Word	Rd+1:Rd ← Rr+1:Rr	None	1
LDI	Rd, K	Load Immediate	Rd ← K	None	1
LD	Rd, X	Load Indirect	Rd ← (X)	None	2
LD	Rd, X+	Load Indirect and Post-Inc.	Rd ← (X), X ← X + 1	None	2
LD	Rd, - X	Load Indirect and Pre-Dec.	X ← X - 1, Rd ← (X)	None	2
LD	Rd, Y	Load Indirect	Rd ← (Y)	None	2
LD	Rd, Y+	Load Indirect and Post-Inc.	Rd ← (Y), Y ← Y + 1	None	2
LD	Rd, - Y	Load Indirect and Pre-Dec.	Y ← Y - 1, Rd ← (Y)	None	2
LDD	Rd,Y+q	Load Indirect with Displacement	Rd ← (Y + q)	None	2
LD	Rd, Z	Load Indirect	Rd ← (Z)	None	2
LD	Rd, Z+	Load Indirect and Post-Inc.	Rd ← (Z), Z ← Z+1	None	2
LD	Rd, -Z	Load Indirect and Pre-Dec.	Z ← Z - 1, Rd ← (Z)	None	2
LDD	Rd, Z+q	Load Indirect with Displacement	Rd ← (Z + q)	None	2
LDS	Rd, k	Load Direct from SRAM	Rd ← (k)	None	2
ST	X, Rr	Store Indirect	(X) ← Rr	None	2
ST	X+, Rr	Store Indirect and Post-Inc.	(X) ← Rr, X ← X + 1	None	2
ST	- X, Rr	Store Indirect and Pre-Dec.	X ← X - 1, (X) ← Rr	None	2
ST	Y, Rr	Store Indirect	(Y) ← Rr	None	2
ST	Y+, Rr	Store Indirect and Post-Inc.	(Y) ← Rr, Y ← Y + 1	None	2
ST	- Y, Rr	Store Indirect and Pre-Dec.	Y ← Y - 1, (Y) ← Rr	None	2
STD	Y+q,Rr	Store Indirect with Displacement	(Y + q) ← Rr	None	2
ST	Z, Rr	Store Indirect	(Z) ← Rr	None	2
ST	Z+, Rr	Store Indirect and Post-Inc.	(Z) ← Rr, Z ← Z + 1	None	2
ST	-Z, Rr	Store Indirect and Pre-Dec.	Z ← Z - 1, (Z) ← Rr	None	2
STD	Z+q,Rr	Store Indirect with Displacement	(Z + q) ← Rr	None	2
STS	k, Rr	Store Direct to SRAM	(k) ← Rr	None	2
LPM		Load Program Memory	R0 ← (Z)	None	3
LPM	Rd, Z	Load Program Memory	Rd ← (Z)	None	3
LPM	Rd, Z+	Load Program Memory and Post-Inc	Rd ← (Z), Z ← Z+1	None	3
SPM		Store Program Memory	(Z) ← R1:R0	None	-
IN	Rd, P	In Port	Rd ← P	None	1
OUT	P, Rr	Out Port	P ← Rr	None	1
PUSH	Rr	Push Register on Stack	STACK ← Rr	None	2
POP	Rd	Pop Register from Stack	Rd ← STACK	None	2
BIT AND BIT-TEST INSTRUCTIONS					
SBI	P,b	Set Bit in I/O Register	I/O(P,b) ← 1	None	2
CBI	P,b	Clear Bit in I/O Register	I/O(P,b) ← 0	None	2
LSL	Rd	Logical Shift Left	Rd(n+1) ← Rd(n), Rd(0) ← 0	Z,C,N,V	1
LSR	Rd	Logical Shift Right	Rd(n) ← Rd(n+1), Rd(7) ← 0	Z,C,N,V	1
ROL	Rd	Rotate Left Through Carry	Rd(0)←C,Rd(n+1)← Rd(n),C←Rd(7)	Z,C,N,V	1
ROR	Rd	Rotate Right Through Carry	Rd(7)←C,Rd(n)← Rd(n+1),C←Rd(0)	Z,C,N,V	1
ASR	Rd	Arithmetic Shift Right	Rd(n) ← Rd(n+1), n=0..6	Z,C,N,V	1
SWAP	Rd	Swap Nibbles	Rd(3..0)←Rd(7..4),Rd(7..4)←Rd(3..0)	None	1
BSET	s	Flag Set	SREG(s) ← 1	SREG(s)	1
BCLR	s	Flag Clear	SREG(s) ← 0	SREG(s)	1
BST	Rr, b	Bit Store from Register to T	T ← Rr(b)	T	1
BLD	Rd, b	Bit load from T to Register	Rd(b) ← T	None	1
SEC		Set Carry	C ← 1	C	1
CLC		Clear Carry	C ← 0	C	1
SEN		Set Negative Flag	N ← 1	N	1
CLN		Clear Negative Flag	N ← 0	N	1
SEZ		Set Zero Flag	Z ← 1	Z	1
CLZ		Clear Zero Flag	Z ← 0	Z	1
SEI		Global Interrupt Enable	I ← 1	I	1
CLI		Global Interrupt Disable	I ← 0	I	1
SES		Set Signed Test Flag	S ← 1	S	1
CLS		Clear Signed Test Flag	S ← 0	S	1
SEV		Set Twos Complement Overflow.	V ← 1	V	1
CLV		Clear Twos Complement Overflow	V ← 0	V	1
SET		Set T in SREG	T ← 1	T	1
CLT		Clear T in SREG	T ← 0	T	1
SEH		Set Half Carry Flag in SREG	H ← 1	H	1

Instruction Set Summary (Continued)

CLH		Clear Half Carry Flag in SREG	H ← 0	H	1
NOP		No Operation		None	1
SLEEP		Sleep	(see specific descr. for Sleep function)	None	1
WDR		Watchdog Reset	(see specific descr. for WDR/timer)	None	1

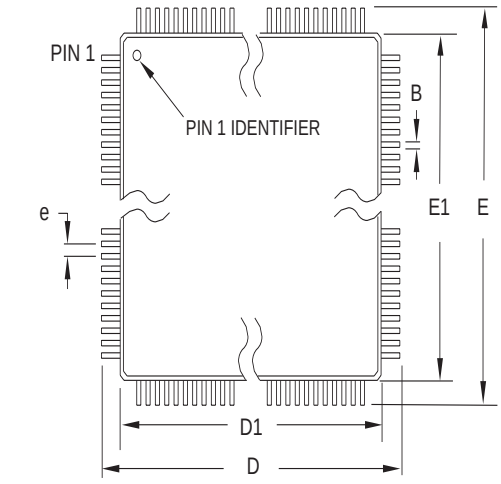
Ordering Information

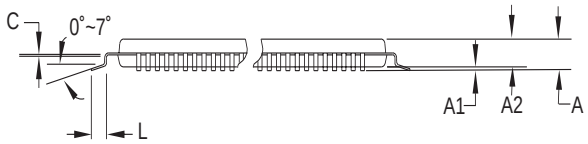
Speed (MHz)	Power Supply	Ordering Code	Package	Operation Range
4	2.7 - 5.5V	ATmega163L-4AC ATmega163L-4PC	44A 40P6	Commercial (0°C to 70°C)
		ATmega163L-4AI ATmega163L-4PI	44A 40P6	Industrial (-40°C to 85°C)
8	4.0 - 5.5V	ATmega163-8AC ATmega163-8PC	44A 40P6	Commercial (0°C to 70°C)
		ATmega163-8AI ATmega163-8PI	44A 40P6	Industrial (-40°C to 85°C)

Package Type	
44A	44-lead, Thin (1.0 mm) Plastic Gull Wing Quad Flat Package (TQFP)
40P6	40-lead, 0.600" Wide, Plastic Dual Inline Package (PDIP)

Packaging Information

44A





COMMON DIMENSIONS
(Unit of Measure = mm)

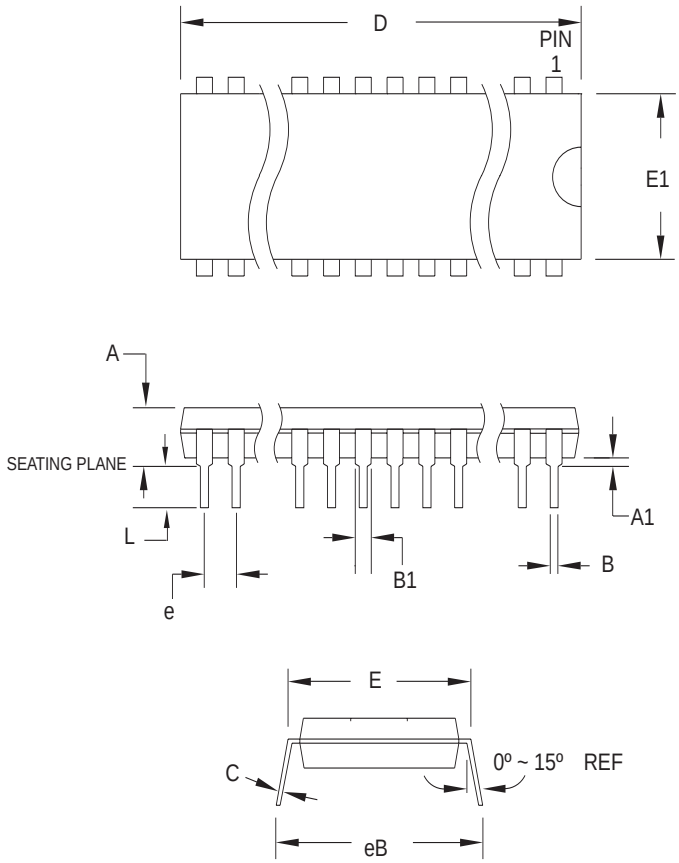
SYMBOL	MIN	NOM	MAX	NOTE
A	–	–	1.20	
A1	0.05	–	0.15	
A2	0.95	1.00	1.05	
D	11.75	12.00	12.25	
D1	9.90	10.00	10.10	Note 2
E	11.75	12.00	12.25	
E1	9.90	10.00	10.10	Note 2
B	0.30	–	0.45	
C	0.09	–	0.20	
L	0.45	–	0.75	
e	0.80 TYP			

Notes:
1. This package conforms to JEDEC reference MS-026, Variation ACB.
2. Dimensions D1 and E1 do not include mold protrusion. Allowable protrusion is 0.25 mm per side. Dimensions D1 and E1 are maximum plastic body size dimensions including mold mismatch.
3. Lead coplanarity is 0.10 mm maximum.

10/5/2001

	TITLE	DRAWING NO.	REV.
2325 Orchard Parkway San Jose, CA 95131	**44A,** 44-lead, 10 x 10 mm Body Size, 1.0 mm Body Thickness, 0.8 mm Lead Pitch, Thin Profile Plastic Quad Flat Package (TQFP)	44A	B

40P6



COMMON DIMENSIONS
(Unit of Measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE
A	–	–	4.826	
A1	0.381	–	–	
D	52.070	–	52.578	Note 2
E	15.240	–	15.875	
E1	13.462	–	13.970	Note 2
B	0.356	–	0.559	
B1	1.041	–	1.651	
L	3.048	–	3.556	
C	0.203	–	0.381	
eB	15.494	–	17.526	
e	2.540 TYP			

Notes: 1. This package conforms to JEDEC reference MS-011, Variation AC.
2. Dimensions D and E1 do not include mold Flash or Protrusion. Mold Flash or Protrusion shall not exceed 0.25 mm (0.010").

09/28/01

	TITLE	DRAWING NO.	REV.
2325 Orchard Parkway San Jose, CA 95131	**40P6**, 40-lead (0.600"/15.24 mm Wide) Plastic Dual Inline Package (PDIP)	40P6	B

Erratas

ATmega163(L) Errata Rev. F

- **Increased Interrupt Latency**
- **Interrupts Abort TWI Power-down**
- **TWI Master Does not Accept Spikes on Bus Lines**
- **TWCR Write Operations Ignored**
- **PWM not Phase Correct**
- **TWI is Speed Limited in Slave Mode**

6. Increased Interrupt Latency

In this device, some instructions are not interruptable, and will cause the interrupt latency to increase. The only practical problem concerns a loop followed by a two-word instruction while waiting for an interrupt. The loop may consist of a branch instruction or an absolute or relative jump back to itself like this:

```
loop: rjmp loop
<Two-word instruction>
```

In this case, a dead-lock situation arises.

Problem Fix/Workaround

In assembly, insert a nop instruction immediately after a loop to itself. The problem will normally be detected during development. In C, the only construct that will give this problem is an empty “for” loop; “for(;;)”. Use “while(1)” or “do{} while (1)” to avoid the problem.

5. Interrupts Abort TWI Power-down

TWI Power-down operation may be aborted by other interrupts. If an interrupt (e.g., INT0) occurs during TWI Power-down address watch and wakes the CPU up, the TWI aborts operation and returns to its idle state.

Problem Fix/Workaround

Ensure that the TWI Address Match is the only enabled interrupt when entering Power-down.

4. TWI Master Does not Accept Spikes on Bus Lines

When the part operates as Master, and the bus is idle (SDA = 1; SCL = 1), generating a short spike on SDA (SDA = 0 for a short interval), no interrupt is generated, and the status code is still $F8 (idle). But when the software initiates a new start condition and clears TWINT, nothing happens on SDA or SCL, and TWINT is never set again.

Problem Fix/Workaround

Either of the following:

1. Ensure that no spikes occur on SDA or SCL lines.
2. Receiving a valid START condition followed by a STOP condition provokes a bus error reported as a TWI interrupt with status code $00.
3. In a Single Master systems, the user should write the TWSTO bit immediately before writing the TWSTA bit.

3. TWCR Write Operation Ignored

Repeated write to TWCR must be delayed. If a write operation to TWCR is immediately followed by another write operation to TWCR, the first write operation may be ignored.

Problem Fix/Workaround

Ensure at least one instruction (e.g., nop) is executed between two writes to TWCR.

2. PWM not Phase Correct

In Phase-correct PWM mode, a change from OCRx = TOP to anything less than TOP does not change the OCx output. This gives a phase error in the following period.

Problem Fix/Workaround

Make sure this issue is not harmful to the application.

1. TWI is Speed Limited in Slave Mode

When the two-wire Serial Interface operates in Slave mode, frames may be undetected if the CPU frequency is less than 64 times the bus frequency.

Problem Fix/Workaround

Ensure that the CPU frequency is at least 64 times the TWI bus frequency.

Change Log

This section containes a log on the changes made to the data sheet for ATmega163. All refereces to pages in Change Log, are referred to this document.

Changes from Rev. 1142C-09/01 to Rev. 1142D-09/02

1. **Added “Not Recommend for New Designs. Use ATmega16.”.**

Changes from Rev. 1142D-09/09 to Rev. 1142E-02/03

1. **Updated Table 52, “Boot Reset Fuse,” on page 136.**
2. **Corrected pin numbers in Figure 62 on page 113.**
3. **Corrected a constant in the Boot Loader code example on page 141.**
4. **Changed max bit rate for the TWI from 400 kHz to 217 kHz.**
5. **Removed redundant and harmful loop in a code example for Slave Receiver mode for the TWI on page 96.**
6. **Added AGND and AVCC in Figure 81 on page 145 and Figure 86 on page 154.**
7. **Updated the “Packaging Information” on page 12.**
8. **Added “Erratas” on page 14.**

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