

PAW3504 PURE USB OPTICAL MOUSE SINGLE CHIP

General Description

The PAW3504 is a CMOS process optical mouse sensor single chip with USB interface that serves as a nonmechanical motion estimation engine for implementing a computer mouse.

| Feat | ures | Key Specification | |
|------|---|--------------------------|-------------------------------|
| | USB interface | Dawan Gummler | Wide operating supply range |
| | Single power supply | Power Supply | 4.25V ~ 5.5V |
| | Optical motion estimation technology | Interface | USB |
| | Complete 2-D motion sensor | | |
| | Accurate motion estimation over a wide range of | Optical Lens | |
| | surfaces | System Clock | 24.000 MHz |
| | High speed motion detection up to 28 inches/sec | | |
| | Power saving mode during times of no | Speed | 28 inches/sec |
| | movement | Acceleration | 20g |
| | Supports three buttons (R, M, L) and three axes | | \leq |
| | (X, Y, Z) output | Resolution | 800 CPI |
| | Z-axis support mechanical input (Z/2) | Frame Rate | 3000 frames/sec |
| | Reduce jiggle happen | | 10mA @Mouse moving (Normal) |
| ום | USB spec. | Operating Current | 5mA @Mouse not moving (Sleep) |
| ۶ | Complete Universal Serial Bus specs V1.1 | | 480uA @USB suspend (Suspend) |
| | compatibility | Package | Shrunk DIP14 |
| | Complete USB HID specs V1.11 compatibility | | |

> Integrated USB transceiver and 1.5Mbps USB serial interface engine

Ordering Information

| Part Number | | CPI |
|-------------|---|-----|
| PAW3504DLY | 4 | 800 |

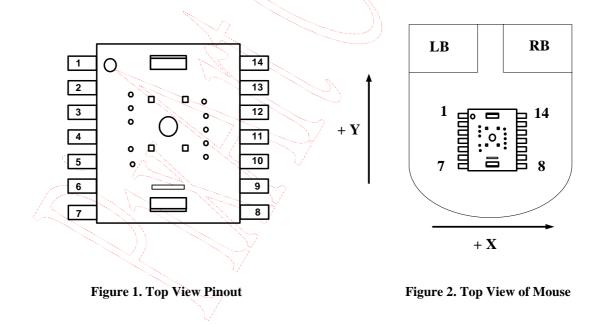
Pure USB Optical Mouse Sensor Single Chip

1. Pin Configuration

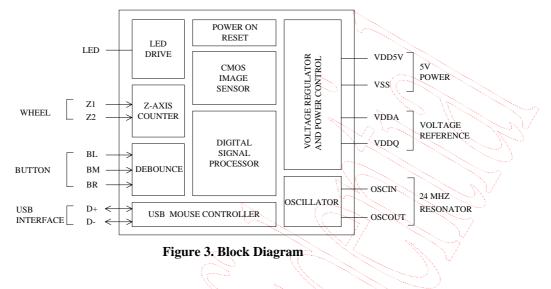
1.1 Pin Description

| Pin # | Name | Type | Definition |
|-------|---------|--------|---|
| ГШ# | Ivallie | Туре | Deminition |
| 1 | OSCIN | IN | Oscillator input, connected to resonator or resistor |
| 2 | BL | IN | Button left key input, normal pull-high (50k), press connect to low |
| 3 | LED | OUT | LED control |
| 4 | VDDQ | BYPASS | I/O voltage reference |
| 5 | VSS | GND | Chip ground |
| 6 | VDD5V | PWR | Chip power VDD, 5.0V |
| 7 | VDDA | BYPASS | Analog voltage reference |
| 8 | D+ | I/O | USB D+ |
| 9 | D- | I/O | USB D- |
| 10 | BR | IN | Button right key input, normal pull-high (50k), press connect to low |
| 11 | ВМ | IN | Button middle key input, normal pull-high (50k), press connect to low |
| 12 | Z2 | IN | Z axis, support mechanical scroller input |
| 13 | Z1 | IN | Z axis, support mechanical scroller input |
| 14 | OSCOUT | OUT | Oscillator output, connected to resonator |

1.2 Pin Assignment



2. Block Diagram and Operation



The PAW3504 supports X, Y, Z three axes, and L, R, M three buttons under USB mode. It is a CMOS process optical mouse sensor single chip with USB interface that serves as a non-mechanical motion estimation engine for implementing a computer mouse.

The PAW3504 is in a 14-pin optical package and comes with the resolution of 800 counts per inch (CPI) and the rate of motion up to 28 inches per second. It includes USB interface so that no mouse controller is needed to interface through USB. The PAW3504 can receive command and echo status or data format, both complete Universal Serial Bus[®] spec V1.1 and USB HID spec V1.11 compatibility. It is also a cost effective solution to support USB Mouse.

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3. Specifications

3.1 Absolute Maximum Ratings

Exposure to absolute maximum rating may affect device reliability.

| Symbol | Parameter | Min. | Max. | Unit | Notes |
|------------------|-----------------------|------|------|------|--|
| T _{STG} | Storage Temperature | -40 | 85 | °C | |
| ТА | Operating Temperature | -15 | 55 | °C | Sell Sell |
| | Lead Solder Temp | | 260 | °C | For 10 seconds, 1.6 mm below seating plane. |
| ESD | | | 2 | kV | All pins, human body model MIL 883 Method 3015 |
| V _{DC} | DC Supply Voltage | -0.5 | 5.5 | V | |
| V | DC Input Voltage | -0.5 | 5.5 | V | Z1, Z2 |
| V_{IN} | DC input voltage | -0.5 | 4.0 | V | BL, BR, BM |

3.2 Recommend Operating Condition

| Symbol | Parameter | Min. | Тур. | Max. | Unit | Notes |
|------------------|--|---------------------|------|--|------------|--|
| T _A | Operating Temperature | 0 | L. | 40 | °C | $\sum_{i=1}^{N}$ |
| V _{DD} | Power Supply Voltage | 4.25 | 5.0 | 5.5 | V | |
| V _N | Supply Noise | | | 100 | mV | Peak to peak within 0 - 80 MHz |
| Z | Distance from Lens Reference Plane to Surface | 2.3 | 2.4 | 2.5 | mm | Refer to Figure 4. |
| R | Resolution | 400 | 800 | <i>V</i> | CPI | |
| А | Acceleration | $\overline{\gamma}$ | | 20 |) g | |
| F _{CLK} | Clock Frequency | | 24 | and the second | MHz | |
| FR | Frame Rate | | 3000 | 5 | frames/sec | |
| S | Speed | 0 | 20 | 28 | inches/sec | 28 inches/sec @400CPI 20 inches/sec @800CPI |

3.3 AC Electrical Characteristics

Electrical characteristics over recommended operating conditions. Typical values at 25 °C, $V_{DD} = 5.0 \text{ V}$, $F_{CLK} = 24 \text{ MHz}$

| Symbol | Parameters | Min. | Тур. | Max. | Unit | Notes |
|--------|----------------------------|------|-------|------|------|-------|
| Tb | Mouse Button Debounce Time | - | 10.24 | - | ms | |
| Tz | Mouse Z Debounce Time | - | 1.024 | - | ms | |

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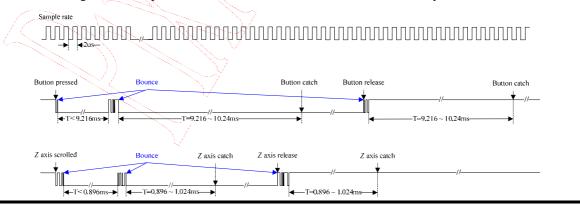
3.4 DC Electrical Characteristics

Electrical characteristics over recommended operating conditions. Typical values at 25 °C, V_{DD} =5.0 V, F_{CLK} =24 MHz.

| Symbol | Parameter | Min. | Тур. | Max. | Unit | Notes |
|-------------------|--|------|---------------|--|------------|--------------------------------------|
| Type: U | SB Mouse PWR | | | | | |
| I_{DD} | Supply Current Mouse moving (Normal) | - | 10 | - | mA | |
| I_{DD} | Supply Current Mouse not moving (Sleep) | - | 5 | - | mA | |
| I_{DD} | Supply Current USB suspend current | - | - | 480 | uA | |
| Type: B | L, BM, BR | | | | | |
| $R_{\rm PH}$ | Internal Pull Up Resistance | - | 50 | 5 | Kohm | |
| V_{IH} | Input High Voltage | 2.0 | - | - | V | |
| V _{IL} | Input Low Voltage | - | | 0.8 | V | |
| Type: Z | 1, Z2 | | \mathcal{C} | 5 | ~ <i>U</i> | |
| R _{PD} | Internal Pull Down Resistance | - | 50 | <u> - </u> | Kohm | |
| V _{IH} | Input High Voltage | 2.0 | - | -X | V | \sim |
| V _{IL} | Input Low Voltage | - | - | 0.8 | V | |
| Type: U | SB DP, DN | | | MC | | |
| $R_{\rm PH}$ | Internal Pull Up Resistance (USB Spec 5%) | -20% | 1.5 | +20% | Kohm | |
| Type: O | SCIN | | | | | |
| V_{IH} | Input High Voltage | 2.1 | - | | V | When driving from an external source |
| V _{IL} | Input Low Voltage | - | - | 0.5 | V | When driving from an external source |
| Type: V | TDDQ | | | | T. | |
| VDDQ | I/O Voltage Reference | - | 3.3 | - | V | |
| | · · · · · · · · · · · · · · · · · · · | / | | and the second sec |) | |

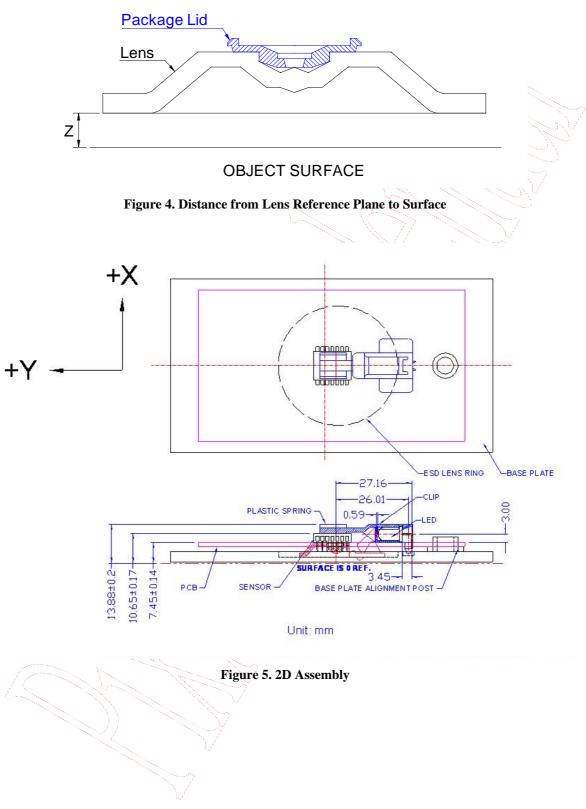
3.5 Button and Z-Wheel Debounce Timing

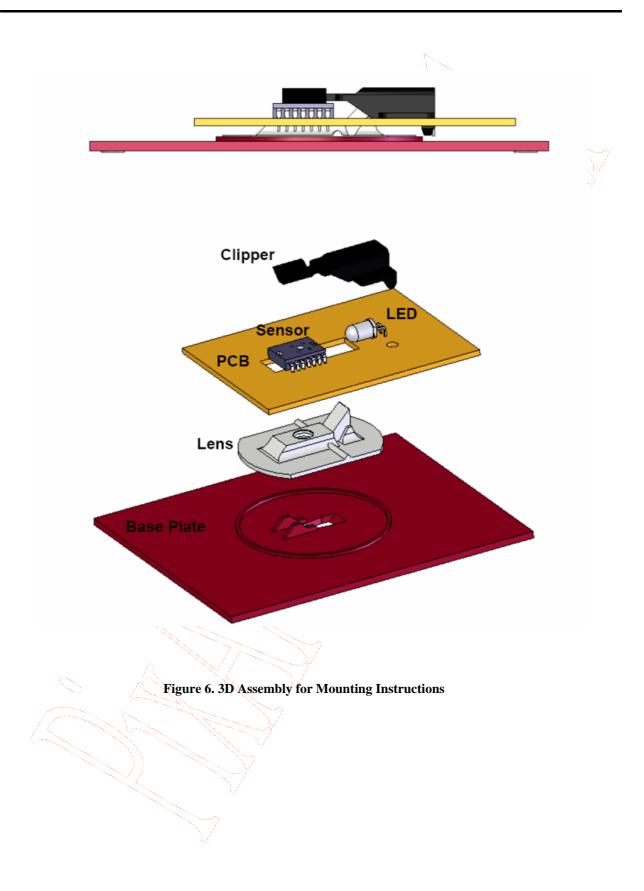
Buttons and Z wheel of PAW3504DLY include detect and debounce function which are hardware implement. When press button input signals need keeping low level up to 9.216ms. Button function just can catch data otherwise debounce function will judge it is bounce issue. When scroll Z wheel input signals need keeping turning level up to 0.896ms. Z wheel function just can catch data otherwise debounce function will judge it is bounce issue. And the hardware sample rate is 2us so if bounce time is less than 2us the debounce function will ignore it. Following the below specifications Buttons and Z wheel will work normally.



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4. Z and 2D/3D Assembly





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5. USB Interface

5.1 USB Command Set Description (USB Descriptor)

The USB HOST detects USB mouse device plug-in and assigns a new unique address to the USB mouse device, then asking USB mouse device for information about the device description, configuration description, and assigning a configuration value for USB mouse device during enumeration period. After enumeration, the USB mouse device is able to transfer motion and button value to the USB host.

| Degeninten Trune | D-to | D-rto | Derto | D-rto | Detto | Data | Date | |
|--------------------------------------|---------|-----------|--------------|---------------|--------|---------------|-------------------------|--------|
| Descriptor Type | Byte | Byte | Byte | Byte | Byte | Byte | Byte | Byte |
| | 12 | 01 | 10 | 01 | 00 | . 00 | 00 | -08 |
| Device Descriptor (18 bytes) | 3A | 09 | 10 | 25 | 00 | 01 | 01 | 02 |
| | 00 | 01 | | C | | | | \sim |
| Carfirmentian Descripton (0 hotes) | 09 | 02 | 22 | 00 | 01 | 01 | 04 | A0 |
| Configuration Descriptor (9 bytes) | 32 | | | L. | 11/1 | | 2VV | - |
| Interface Descriptor (0 bytes) | 09 | 04 | 00 | 00 | 01 | 03 | 01 | 02 |
| Interface Descriptor (9 bytes) | 00 | | | <u> </u> | 77 | | $\overline{\mathbf{N}}$ | |
| Human Interface Device Descriptor | 09 | 21 | 10 | 01 | / 00 | 01 | 22 | 3E |
| (9 bytes) | 00 | \sim | | | | \mathcal{M} | 1 | |
| Endpoint Descriptor (7 bytes) | 07 | -05 | 81 | 03 | 04 | -00 | 0A | |
| | 05 | 01 | 09 | 02 | A1 | 01 | 05 | 09 |
| | 19 | 01 | //29 | 03 | 15 | 00 | 25 | 01 |
| | 95 | 03 2 | 75 | 01 | 81 | 02 | 95 | 01 |
| Human Interface Device Report | 75 | 05 | 81 | 03 | 05 | 01 | 09 | 01 |
| Descriptor (62 bytes, 3D3B) | A1 | 00 | - 09 | - 30 | 09 | 31 | 15 | 81 |
| | 25 | 7F | 75 | 08 | 95 | 02 | 81 | 06 |
| | C0 | - 09 | 38 | 15 | 81 | 25 | 7F | 75 |
| | 08 | 95 | 01 | 81 | /06 | C0 | | |
| Language String Descriptor (4 bytes) | 04 | 03 | 09 | 04 | \sim | | | |
| Manufacture String Descriptor | PIXART | [| | $\ll \nabla$ | / | | | |
| Product String Descriptor | USB OF | TICAL N | MOUSE | \mathcal{N} | | | | |
| Configuration String Descriptor | HID-cor | npliant N | 10USE | | | | | |
| × . | 11 | | 11 | | | | | |

5.2 USB Data Report Format

The USB report has two data formats, depending on boot or report protocol is selected. One kind of data format is the boot protocol used in legacy environment as 5.2.1. The other kind of data format is USB report protocol format which includes Z-wheel movement data in the fourth byte as 5.2.2. The Z-wheel is moved forward the fourth byte data is 01H, the Z-wheel is moved backward the fourth byte data is FFH, and the Z-wheel is idle the fourth byte data is 00H.

5.2.1 USB Boot Protocol for Legacy Operation

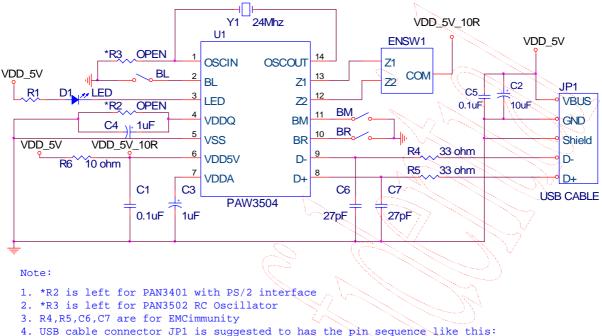
| Byte | Bit | Symbol | Description |
|------|-------|--------------|--|
| | 0 | BL | 1 = Left button pressed |
| 1 | 1 | BR | 1 = Right button pressed |
| 1 | 2 | BM | 1 = Middle button pressed |
| | 3 ~ 7 | NC | Reserved |
| 2 | 0 - 7 | X0 ~ X7 | X data (D0 - D7). A positive value indicates motion to the right; a negative value |
| Z | 0-7 | $X0 \sim X/$ | indicates motion to the left. Bit $0 = LSB$. |
| 3 | 0 - 7 | - 7 Y0 ~ Y7 | Y data (D0 - D7). A positive value indicates device motion upward; a negative |
| 2 | 0-7 | | value indicates motion downward. Bit $0 = LSB$. |

5.2.2 USB Report Protocol

| Byte | Bit | Symbol | Description |
|------|--------------|----------------------------|--|
| | 0 | BL | 1 = Left button pressed |
| | 1 | BR | 1 = Right button pressed |
| 1 | 2 | BM | 1 = Middle button pressed |
| 1 | 3 | B4 | Reserved |
| | 4 | B5 | Reserved |
| | 5~7 | NC | Reserved |
| 2 | 0 - 7 X0 ~ X | | X data (D0 - D7). A positive value indicates motion to the right; a negative value |
| 2 | 0-7 | $\Lambda 0 \sim \Lambda /$ | indicates motion to the left. Bit $0 = LSB$. |
| 3 | 0 - 7 | Y0 ~ Y7 | Y data (D0 - D7). A positive value indicates device motion upward; a negative |
| 5 | | 10~17 | value indicates motion downward. Bit 0 = LSB. |
| | | | Z-wheel motion data (D0 - D7). A positive value indicates device motion |
| 4 | 0 - 7 | Z0 ~ Z7 | downward; a negative value indicates motion upward. The Z0 - Z7 limit value is |
| | | | \pm 7. Bit 0 = LSB. |

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6. Referencing Application Circuit



VBUS, GND, Shield, D-, D+

Figure 7. Application Circuit for PAW3504

6.2 PCB Layout Guideline

The following guidelines apply to component placement and routing on the PCB. That will get an optimum EMC solution and tracking performance.

6.2.1 Key Components Placement Rules

- 1. Place resonator (Y1) near SENSOR pin1 and pin 14.
- 2. Place bulk capacitor (C2) and bypass (C5) near the USB CABLE.
- 3. Place C1 and C3 near SENSOR pin 6 and pin 7.
- 4. The C6/C7 and R4/R5 should be placed as close to the USB CABLE.

6.2.2 Routing Rules

- 1. Caps for pins 4, 6, 7 trace length must be less than 5 mm.
- 2. The trace length of OSCOUT, OSCIN must be less than 10 mm.
- 3. Other general rules refer file"PAW3504DLY PCB Layout Guide"

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6.3 Recommended Value for R1

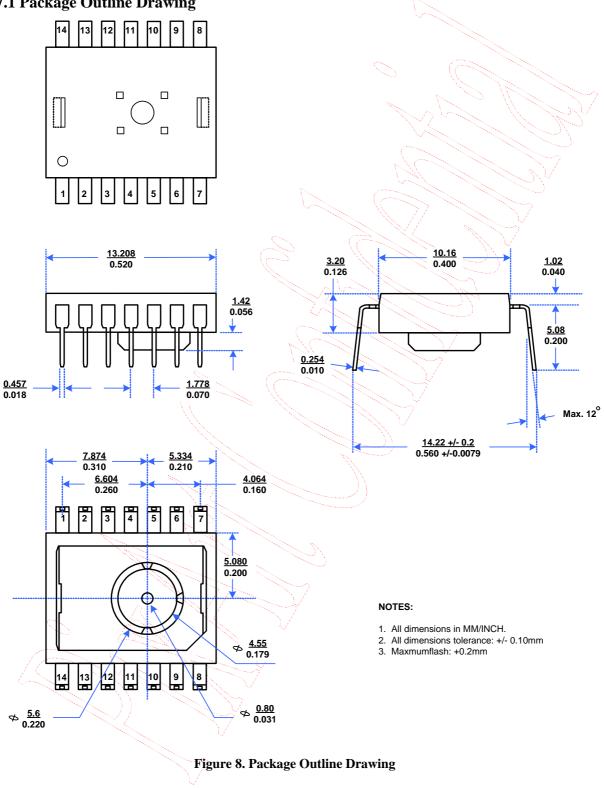
Radiometric intensity of LED Bin limits (mW/Sr at 20mA)

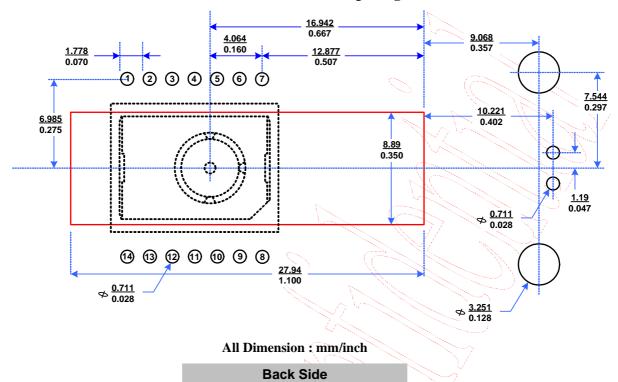
| LED Bin Grade | Min | Тур | Max | Unit 🔿 | |
|---------------|------|-----|------|--------|--|
| N | 14.7 | - | 17.7 | mW/Sr | |
| Р | 17.7 | - | 21.2 | mW/Sr | |
| Q | 21.2 | - | 25.4 | mW/Sr | |

Note: Tolerance for each bin will be $\pm 15\%$

| R1 value (ohm), V _{DD} | | | | |
|---------------------------------|------|-----|-----|------|
| LED Bin Grade | Min | Тур | Max | Unit |
| N | 56.2 | 100 | 2 | ohm |
| Р | 56.2 | 100 | 6 | ohm |
| Q | 56.2 | 100 | - | ohm |

- 7. Package Information
- 7.1 Package Outline Drawing





7.2 Recommended PCB Mechanical Cutouts and Spacing

Figure 9. Recommended PCB Mechanical Cutouts and Spacing

8. Update History

| Update | Date |
|---|---|
| Creation, Preliminary 1 st version | 06/09/2008 |
| | |
| | |
| | |
| | Creation, Preliminary 1 st version |

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