

PAW3504 PURE USB OPTICAL MOUSE SINGLE CHIP

General Description

The PAW3504 is a CMOS process optical mouse sensor single chip with USB interface that serves as a nonmechanical motion estimation engine for implementing a computer mouse.

Feat	ures	Key Specification	
	USB interface	Dawan Gummler	Wide operating supply range
	Single power supply	Power Supply	4.25V ~ 5.5V
	Optical motion estimation technology	Interface	USB
	Complete 2-D motion sensor		
	Accurate motion estimation over a wide range of	Optical Lens	
	surfaces	System Clock	24.000 MHz
	High speed motion detection up to 28 inches/sec		
	Power saving mode during times of no	Speed	28 inches/sec
	movement	Acceleration	20g
	Supports three buttons (R, M, L) and three axes		\leq
	(X, Y, Z) output	Resolution	800 CPI
	Z-axis support mechanical input (Z/2)	Frame Rate	3000 frames/sec
	Reduce jiggle happen		10mA @Mouse moving (Normal)
ום	USB spec.	Operating Current	5mA @Mouse not moving (Sleep)
۶	Complete Universal Serial Bus specs V1.1		480uA @USB suspend (Suspend)
	compatibility	Package	Shrunk DIP14
	Complete USB HID specs V1.11 compatibility		

> Integrated USB transceiver and 1.5Mbps USB serial interface engine

Ordering Information

Part Number		CPI
PAW3504DLY	4	800

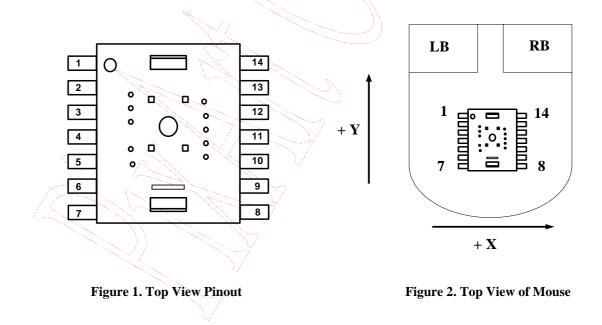
Pure USB Optical Mouse Sensor Single Chip

1. Pin Configuration

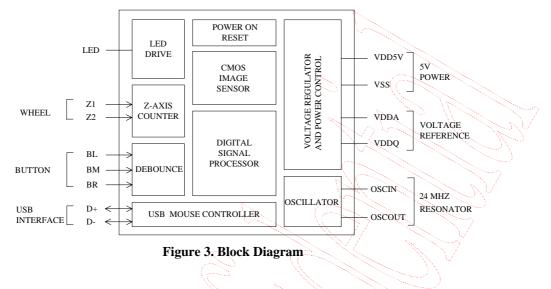
1.1 Pin Description

Pin #	Name	Type	Definition
ГШ#	Ivallie	Туре	Deminition
1	OSCIN	IN	Oscillator input, connected to resonator or resistor
2	BL	IN	Button left key input, normal pull-high (50k), press connect to low
3	LED	OUT	LED control
4	VDDQ	BYPASS	I/O voltage reference
5	VSS	GND	Chip ground
6	VDD5V	PWR	Chip power VDD, 5.0V
7	VDDA	BYPASS	Analog voltage reference
8	D+	I/O	USB D+
9	D-	I/O	USB D-
10	BR	IN	Button right key input, normal pull-high (50k), press connect to low
11	ВМ	IN	Button middle key input, normal pull-high (50k), press connect to low
12	Z2	IN	Z axis, support mechanical scroller input
13	Z1	IN	Z axis, support mechanical scroller input
14	OSCOUT	OUT	Oscillator output, connected to resonator

1.2 Pin Assignment



2. Block Diagram and Operation



The PAW3504 supports X, Y, Z three axes, and L, R, M three buttons under USB mode. It is a CMOS process optical mouse sensor single chip with USB interface that serves as a non-mechanical motion estimation engine for implementing a computer mouse.

The PAW3504 is in a 14-pin optical package and comes with the resolution of 800 counts per inch (CPI) and the rate of motion up to 28 inches per second. It includes USB interface so that no mouse controller is needed to interface through USB. The PAW3504 can receive command and echo status or data format, both complete Universal Serial Bus[®] spec V1.1 and USB HID spec V1.11 compatibility. It is also a cost effective solution to support USB Mouse.

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3. Specifications

3.1 Absolute Maximum Ratings

Exposure to absolute maximum rating may affect device reliability.

Symbol	Parameter	Min.	Max.	Unit	Notes
T _{STG}	Storage Temperature	-40	85	°C	
ТА	Operating Temperature	-15	55	°C	Sell Sell
	Lead Solder Temp		260	°C	For 10 seconds, 1.6 mm below seating plane.
ESD			2	kV	All pins, human body model MIL 883 Method 3015
V _{DC}	DC Supply Voltage	-0.5	5.5	V	
V	DC Input Voltage	-0.5	5.5	V	Z1, Z2
V_{IN}	DC input voltage	-0.5	4.0	V	BL, BR, BM

3.2 Recommend Operating Condition

Symbol	Parameter	Min.	Тур.	Max.	Unit	Notes
T _A	Operating Temperature	0	L.	40	°C	$\sum_{i=1}^{N}$
V _{DD}	Power Supply Voltage	4.25	5.0	5.5	V	
V _N	Supply Noise			100	mV	Peak to peak within 0 - 80 MHz
Z	Distance from Lens Reference Plane to Surface	2.3	2.4	2.5	mm	Refer to Figure 4.
R	Resolution	400	800	<i>V</i>	CPI	
А	Acceleration	$\overline{\gamma}$		20) g	
F _{CLK}	Clock Frequency		24	and the second	MHz	
FR	Frame Rate		3000	5	frames/sec	
S	Speed	0	20	28	inches/sec	28 inches/sec @400CPI 20 inches/sec @800CPI

3.3 AC Electrical Characteristics

Electrical characteristics over recommended operating conditions. Typical values at 25 °C, $V_{DD} = 5.0 \text{ V}$, $F_{CLK} = 24 \text{ MHz}$

Symbol	Parameters	Min.	Тур.	Max.	Unit	Notes
Tb	Mouse Button Debounce Time	-	10.24	-	ms	
Tz	Mouse Z Debounce Time	-	1.024	-	ms	

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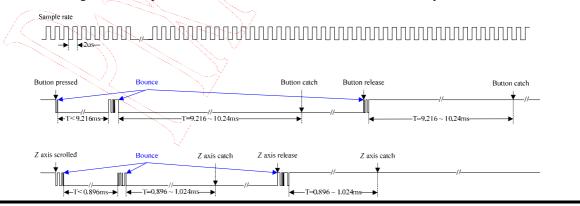
3.4 DC Electrical Characteristics

Electrical characteristics over recommended operating conditions. Typical values at 25 °C, V_{DD} =5.0 V, F_{CLK} =24 MHz.

Symbol	Parameter	Min.	Тур.	Max.	Unit	Notes
Type: U	SB Mouse PWR					
I_{DD}	Supply Current Mouse moving (Normal)	-	10	-	mA	
I_{DD}	Supply Current Mouse not moving (Sleep)	-	5	-	mA	
I_{DD}	Supply Current USB suspend current	-	-	480	uA	
Type: B	L, BM, BR					
$R_{\rm PH}$	Internal Pull Up Resistance	-	50	5	Kohm	
V_{IH}	Input High Voltage	2.0	-	-	V	
V _{IL}	Input Low Voltage	-		0.8	V	
Type: Z	1, Z2		\mathcal{C}	5	~ <i>U</i>	
R _{PD}	Internal Pull Down Resistance	-	50	<u> - </u>	Kohm	
V _{IH}	Input High Voltage	2.0	-	-X	V	\sim
V _{IL}	Input Low Voltage	-	-	0.8	V	
Type: U	SB DP, DN			MC		
$R_{\rm PH}$	Internal Pull Up Resistance (USB Spec 5%)	-20%	1.5	+20%	Kohm	
Type: O	SCIN					
V_{IH}	Input High Voltage	2.1	-		V	When driving from an external source
V _{IL}	Input Low Voltage	-	-	0.5	V	When driving from an external source
Type: V	TDDQ				T.	
VDDQ	I/O Voltage Reference	-	3.3	-	V	
	· · · · · · · · · · · · · · · · · · ·	/		and the second sec)	

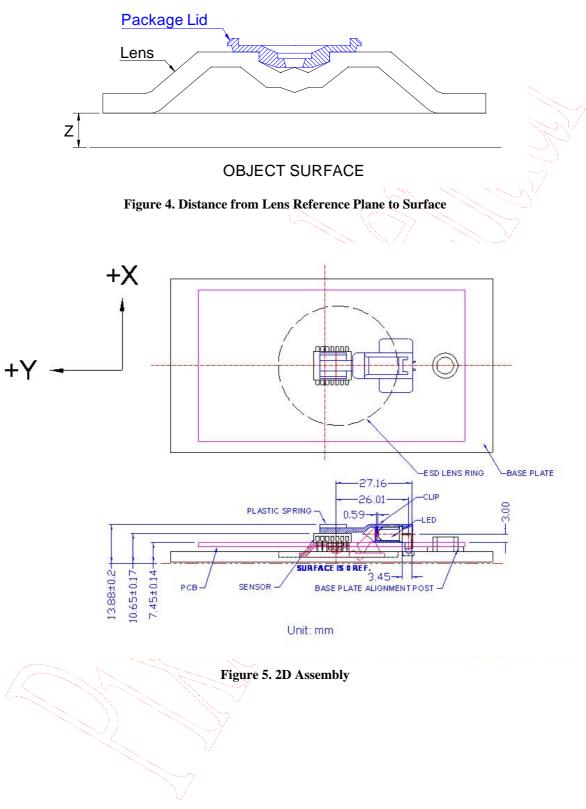
3.5 Button and Z-Wheel Debounce Timing

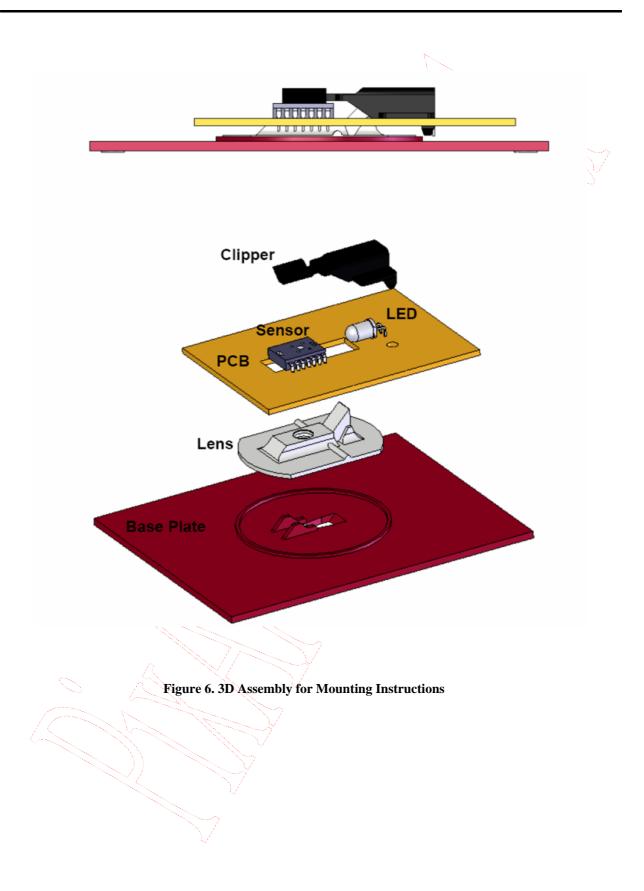
Buttons and Z wheel of PAW3504DLY include detect and debounce function which are hardware implement. When press button input signals need keeping low level up to 9.216ms. Button function just can catch data otherwise debounce function will judge it is bounce issue. When scroll Z wheel input signals need keeping turning level up to 0.896ms. Z wheel function just can catch data otherwise debounce function will judge it is bounce issue. And the hardware sample rate is 2us so if bounce time is less than 2us the debounce function will ignore it. Following the below specifications Buttons and Z wheel will work normally.



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4. Z and 2D/3D Assembly





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5. USB Interface

5.1 USB Command Set Description (USB Descriptor)

The USB HOST detects USB mouse device plug-in and assigns a new unique address to the USB mouse device, then asking USB mouse device for information about the device description, configuration description, and assigning a configuration value for USB mouse device during enumeration period. After enumeration, the USB mouse device is able to transfer motion and button value to the USB host.

Degeninten Trune	D-to	D-rto	Derto	D-rto	Detto	Data	Date	
Descriptor Type	Byte	Byte	Byte	Byte	Byte	Byte	Byte	Byte
	12	01	10	01	00	. 00	00	-08
Device Descriptor (18 bytes)	3A	09	10	25	00	01	01	02
	00	01		C				\sim
Carfirmentian Descripton (0 hotes)	09	02	22	00	01	01	04	A0
Configuration Descriptor (9 bytes)	32			L.	11/1		2VV	-
Interface Descriptor (0 bytes)	09	04	00	00	01	03	01	02
Interface Descriptor (9 bytes)	00			<u> </u>	77		$\overline{\mathbf{N}}$	
Human Interface Device Descriptor	09	21	10	01	/ 00	01	22	3E
(9 bytes)	00	\sim				\mathcal{M}	1	
Endpoint Descriptor (7 bytes)	07	-05	81	03	04	-00	0A	
	05	01	09	02	A1	01	05	09
	19	01	//29	03	15	00	25	01
	95	03 2	75	01	81	02	95	01
Human Interface Device Report	75	05	81	03	05	01	09	01
Descriptor (62 bytes, 3D3B)	A1	00	- 09	- 30	09	31	15	81
	25	7F	75	08	95	02	81	06
	C0	- 09	38	15	81	25	7F	75
	08	95	01	81	/06	C0		
Language String Descriptor (4 bytes)	04	03	09	04	\sim			
Manufacture String Descriptor	PIXART	[$\ll \nabla$	/			
Product String Descriptor	USB OF	TICAL N	MOUSE	\mathcal{N}				
Configuration String Descriptor	HID-cor	npliant N	10USE					
× .	11		11					

5.2 USB Data Report Format

The USB report has two data formats, depending on boot or report protocol is selected. One kind of data format is the boot protocol used in legacy environment as 5.2.1. The other kind of data format is USB report protocol format which includes Z-wheel movement data in the fourth byte as 5.2.2. The Z-wheel is moved forward the fourth byte data is 01H, the Z-wheel is moved backward the fourth byte data is FFH, and the Z-wheel is idle the fourth byte data is 00H.

5.2.1 USB Boot Protocol for Legacy Operation

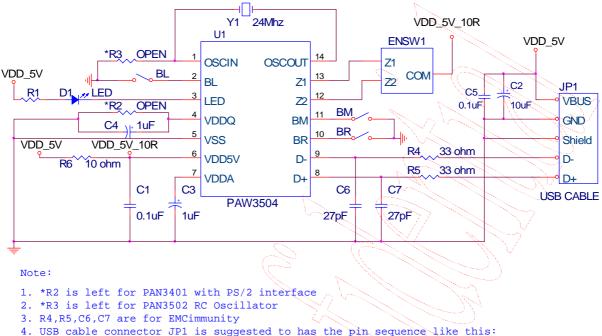
Byte	Bit	Symbol	Description
	0	BL	1 = Left button pressed
1	1	BR	1 = Right button pressed
1	2	BM	1 = Middle button pressed
	3 ~ 7	NC	Reserved
2	0 - 7	X0 ~ X7	X data (D0 - D7). A positive value indicates motion to the right; a negative value
Z	0-7	$X0 \sim X/$	indicates motion to the left. Bit $0 = LSB$.
3	0 - 7	- 7 Y0 ~ Y7	Y data (D0 - D7). A positive value indicates device motion upward; a negative
2	0-7		value indicates motion downward. Bit $0 = LSB$.

5.2.2 USB Report Protocol

Byte	Bit	Symbol	Description
	0	BL	1 = Left button pressed
	1	BR	1 = Right button pressed
1	2	BM	1 = Middle button pressed
1	3	B4	Reserved
	4	B5	Reserved
	5~7	NC	Reserved
2	0 - 7 X0 ~ X		X data (D0 - D7). A positive value indicates motion to the right; a negative value
2	0-7	$\Lambda 0 \sim \Lambda /$	indicates motion to the left. Bit $0 = LSB$.
3	0 - 7	Y0 ~ Y7	Y data (D0 - D7). A positive value indicates device motion upward; a negative
5		10~17	value indicates motion downward. Bit 0 = LSB.
			Z-wheel motion data (D0 - D7). A positive value indicates device motion
4	0 - 7	Z0 ~ Z7	downward; a negative value indicates motion upward. The Z0 - Z7 limit value is
			\pm 7. Bit 0 = LSB.

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6. Referencing Application Circuit



VBUS, GND, Shield, D-, D+

Figure 7. Application Circuit for PAW3504

6.2 PCB Layout Guideline

The following guidelines apply to component placement and routing on the PCB. That will get an optimum EMC solution and tracking performance.

6.2.1 Key Components Placement Rules

- 1. Place resonator (Y1) near SENSOR pin1 and pin 14.
- 2. Place bulk capacitor (C2) and bypass (C5) near the USB CABLE.
- 3. Place C1 and C3 near SENSOR pin 6 and pin 7.
- 4. The C6/C7 and R4/R5 should be placed as close to the USB CABLE.

6.2.2 Routing Rules

- 1. Caps for pins 4, 6, 7 trace length must be less than 5 mm.
- 2. The trace length of OSCOUT, OSCIN must be less than 10 mm.
- 3. Other general rules refer file"PAW3504DLY PCB Layout Guide"

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6.3 Recommended Value for R1

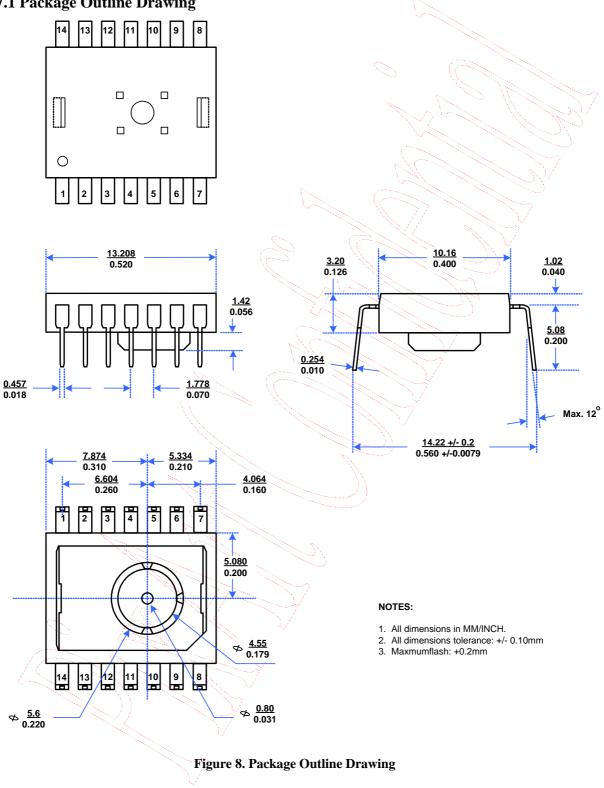
Radiometric intensity of LED Bin limits (mW/Sr at 20mA)

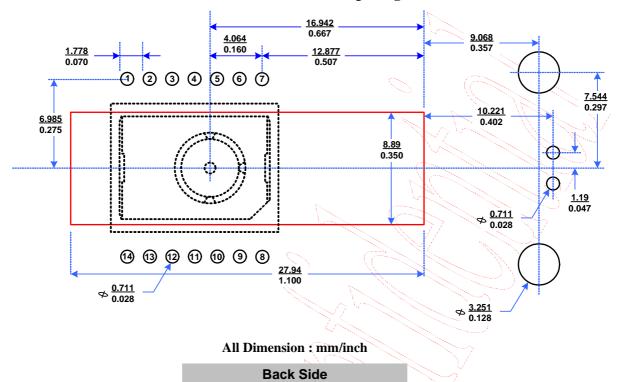
LED Bin Grade	Min	Тур	Max	Unit 🔿	
N	14.7	-	17.7	mW/Sr	
Р	17.7	-	21.2	mW/Sr	
Q	21.2	-	25.4	mW/Sr	

Note: Tolerance for each bin will be $\pm 15\%$

R1 value (ohm), V _{DD}				
LED Bin Grade	Min	Тур	Max	Unit
N	56.2	100	2	ohm
Р	56.2	100	6	ohm
Q	56.2	100	-	ohm

- 7. Package Information
- 7.1 Package Outline Drawing





7.2 Recommended PCB Mechanical Cutouts and Spacing

Figure 9. Recommended PCB Mechanical Cutouts and Spacing

8. Update History

Update	Date
Creation, Preliminary 1 st version	06/09/2008
	Creation, Preliminary 1 st version

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