# M5222L/P/FP

# **DUAL VCA FOR LOW VOLTAGE ELECTRONIC VOLUME CONTROL**

#### **DESCRIPTION**

The M5222 is a dual VCA designed as an electronic volume control capable of operating in a wide supply voltage range between 1.8V to 20V.

The IC is an optimum device for electronic equipment requiring low voltage operation, such as video movie systems.

#### **FEATURES**

- Capable of operating at low voltage ····· Vcc = 1.8 to 20V
- ■Two built-in channels

......Simultaneous control of both channels is possible with Vc(control) at pin (§)

- Logarithmic response VCA
  - ..... Logarithmic response equivalent to A-curve volume
- High maximum input voltage
  - .....Vi = 1.0Vrms(typ)(@Vcc = 3V)
- Low distortion ratio ......THD = 0.05 %
- Similar characteristics between 2 channels

# HIH

## Outline 8P5(L)

2.54mm pitch 340mil SIP (2.8mm × 19.0mm × 6.4mm)



Outline 8P4(P)

2.54mm pitch 300mil DIP (6.3mm × 8.9mm × 3.3mm)



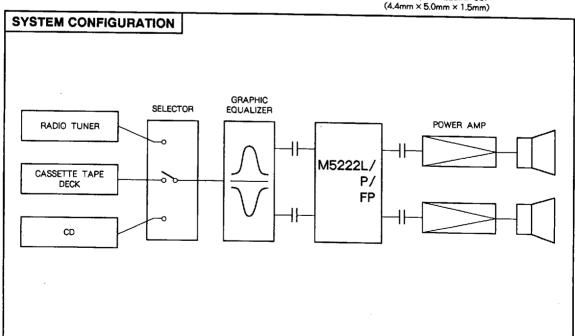
Outline 8P2S-A(FP)

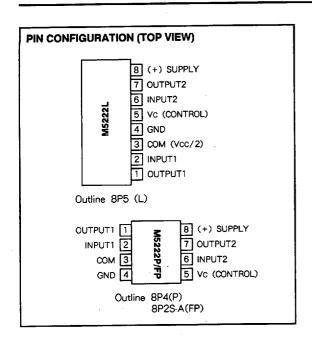
1.27mm pitch 225mil SOP (4.4mm × 5.0mm × 1.5mm)

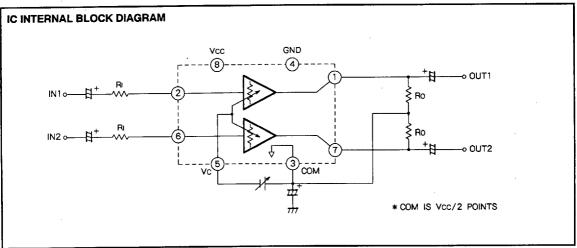
# **RECOMMENDED OPERATING CONDITIONS**

Supply voltage range Vcc = 1.8 to 20V

Rated dissipation voltage 800(L), 625(P), 440(FP)mW







Note 1. Rt is used to convert input voltage to current.

- 2. Ro is an output resistor used to convert the currentoutput signal to voltage. Connect this output with COM pin 3 to fix the DC output potential.
- 3. The COM pin is used for making a 1/2pint supply voltage within the IC. It is used in connecting Ro and in Vc control.

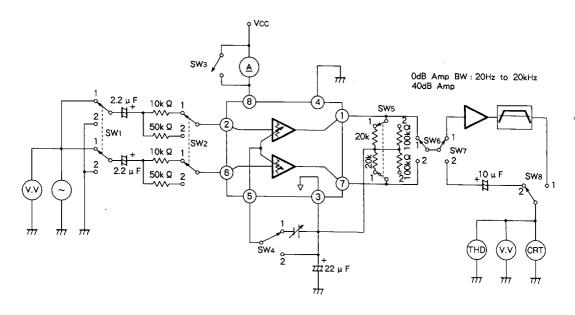
## ABSOLUTE MAXIMUM RATINGS (Ta = 25 ℃, unless otherwise noted)

Symbol	Parameter	Ratings	Unit	
Vcc	Supply voltage	20	V	
Pa	Power dissipation	800 (SIP) /625 (DIP) /440 (FP)	mW	
Kθ	Thermal derating (Ta ≥ 25 °C)	8(SIP)/6.25(DIP)/4.4(FP)	mW/℃	
Topr	Operating temperature	- 20 to + 75	°C	
T <sub>stg</sub>	Storage temperature	- 55 to + 125	°	

## ELECTRICAL CHARACTERISTICS (Ta = 25 °C, unless otherwise noted)

Symbol	Parameter	Test cond	Test conditions			Limits			
		Test conditions		Vcc	Min	Тур	Max	Unit	
lcc	Circuit current	$V_i = 0$ , $V_C = 0$	$V_i = 0, \ V_C = 0$			3.6	5.5	mA	
ViM1	Maximum input voltage	f = 1kHz Vc = 0	R <sub>I</sub> = 10k Ω R <sub>O</sub> = 20k Ω	3٧	0.7	1.0	_	Vrms	
ViM2	Maximum input voltage	THD = 1 %	$R_i = 50k \Omega$ $R_0 = 100k \Omega$	9V	2.3	3.4	-	Vrms	
АТТм	Maximum attenuation	$R_i = 10k \Omega, R_0 = 20$ $V_0 = -270 \text{mV}$	$R_i = 10k \Omega$ , $R_0 = 20k \Omega$ $V_0 = -270mV$			90	-	dB	
ATT <sub>01</sub>	Attenuation error	f = 1kHz Vc = 0	Ri = $10k \Omega$ Ro = $20k \Omega$	3V	- 4.4	- 1.4	+ 1.6	dB	
ATT <sub>02</sub>	Attenuation error	V <sub>i</sub> = 0dBm	R <sub>I</sub> = 50k Ω R <sub>O</sub> = 100k Ω	9V	- 5.0	- 2.0	+ 1.0	dB	
ΔATT	Attenuation deviation between channels		$f = 1 \text{kHz}, V_C = 0, V_i = 0 \text{dBm}$ $R_i = 10 \text{k } \Omega, R_0 = 20 \text{k } \Omega$			0.1	3.0	dB	
V <sub>NO1</sub>	Noise output voltage	$V_C = 0$ , $R_I = 10k \Omega$ $R_0 = 20k \Omega$ , $BW = 2$	$V_C = 0$ , $R_I = 10k \Omega$ $R_0 = 20k \Omega$ , $BW = 20Hz$ to $20kHz$			30	60	μ Vrms	
V <sub>NO2</sub>	Noise output voltage		ATT = $-40dB$ , R <sub>i</sub> = $10k \Omega$ Ro = $20k \Omega$ , BW = $20Hz$ to $20kHz$			5	-	μ Vrms	

### **TEST CIRCUIT**



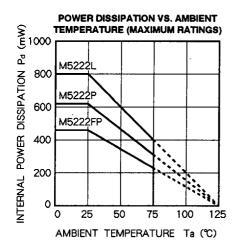
#### **SWITCH MATRIX**

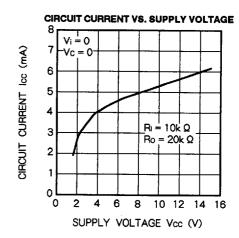
Parameter		SW <sub>1</sub>	SW <sub>2</sub>	SW₃	SW <sub>4</sub>	SW <sub>5</sub>	SW <sub>6</sub>	SW <sub>7</sub>	SW <sub>8</sub>
lcc		2	1	OFF	2	1	1/2	2	2
Vim	1	1	1	ON	2	1	1/2	1	1
	2	1	2	ON	2	2	1/2	1	1
ATTM		1	1	ON	• 1	1	1/2	2	2
ATT	01	1	1	ON	2	1	1/2	2	2
	02	1	2	ON	2	2	1/2	2	2
Vno	1	2	1	ON	2	1	1/2	1	1
	2	2	1	ON	1	1	1/2	1	1

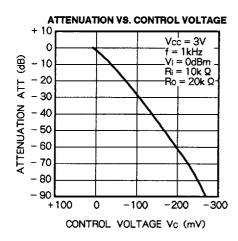
Note 1. Use 0dB amplification when measuring VIM

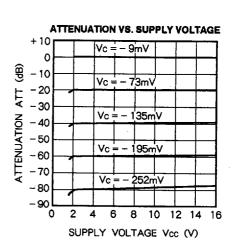
- 2. Use 40dB amplification when measuring VNO
- 3. VNo = measurement value/100 (40dB) [µ Vrms]

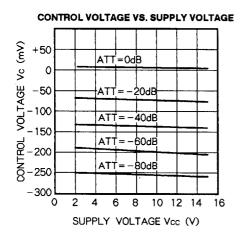
#### **TYPICAL CHARACTERISTICS**

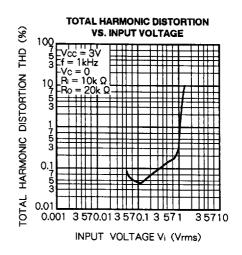


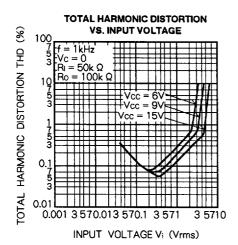


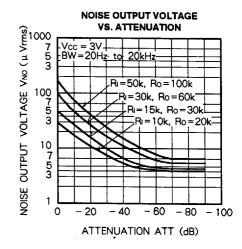


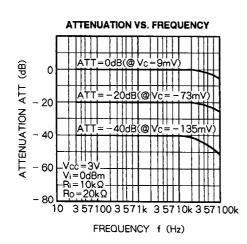


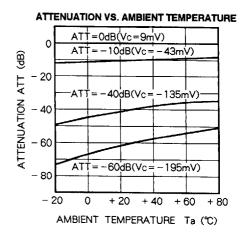














#### **BASIC PRINCIPLE OF OPERATION**

The M5222 is a current input, current output type of VCA IC. This amplifier uses the principle by which changing the balance of the differential circuit with external control voltage

Vc will change gm. The circuit is also called a variable transconductance (variable gm) OP amp. The basic principle of operation will be simply explained below.

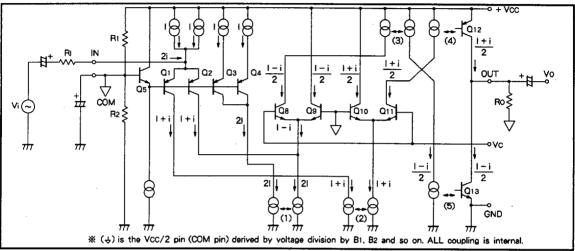


Fig. 1 M5222 Equivalent circuit

# Basic voltage-current conversion mechanism for input and output

Applying the input signal Vi which flows through external input resistor Ri results in a change to a current signal at input terminal IN. The VBE level shift of Ri, R2, Q5, Q1, and Q2 will cause input pin IN to become ground level by means of Vcc/2 in terms of direct current and to become ground level by means of the externally-connected capacitor in terms of alternating current. The signal input in this way will be sent to the output pin as a current signal by the current mirror and differential circuit. By taking this current signal through the externally-connected output resistor (load resistor), the signal can go through a current-to-voltage conversion and be obtained as output signal Vo.

The output transistors combine the currents by means of the joined PNP and NPN collector circuits. Basically, the DC potential floats and is not determined in this joining of currents. This is why one end of externally-connected resistor Ro is connected to the Vcc/2 pin and the DC level (Vcc/2) at the time of no signal is set.

#### Basic mechanism of attenuation

The output is controlled by means of changing the control voltage applied to the Vc pin with respect to the COM pin (Vcc/2 pin). By applying voltage from the COM pin to the base of one side of a differential circuit and applying voltage from the Vc pin to the other base, the current distribution of the differential circuit is changed and the gain of this circuit is changed.

Let us first consider when Vc equals zero (Vc - COM is shorted). Input signal Vi is converted to current by input

resistor R<sub>I</sub> and the i currents  $(2_i = V_i/R_i)$  flow through the collectors of  $Q_1$  and  $Q_2$ . When the current flowing in  $Q_1$  becomes i+i, the overall emitter current of the differential circuit consisting of  $Q_{10}$  and  $Q_{11}$  will also be determined as I+i by means of current mirror (2). Since the base potential of  $Q_{10}$  and  $Q_{11}$  is the same, the current will be divided equally and current (I+i)/2 will flow in each of  $Q_{10}$  and  $Q_{11}$ . The current of current mirror (4) will also be determined as (I+i)/2 because of this.

Since the current of current mirror (1) is determined as 2l by the current flowing in Q3 and Q4, the total of the current flowing in Q2 and the current flowing in differential circuit Q8, Q8 will also be 2l. The current from Q2 which will become l+i flows here and as a result, the overall emitter current of the differential circuit will be 2l-(l+i)=l-i. This current is devided the same way as in the differential circuit consisting of Q10 and Q11 with current (l-i)/2 flowing in each of Q8 and Q9. From this, the current of current mirror (3) is determined as (l-i)/2 and the current of current mirror (5) becomes (l+i)/2.

Now, current (I-i)/2 from current mirror (4) flows in transistor  $Q_{12}$  of the output stage. Since the current flowing in transistor  $Q_{13}$  from current mirror (5) is held at (I-i)/2, connecting output resistor Ro between the output pin and the COM pin will result in current i flowing through Ro and providing a voltage signal  $Vo = i \cdot Ro$ .

Here, by selecting Ro = 2Ri,  $Vo = i \cdot Ro = 2i \cdot Ri = V_i$  and the amplifier will have a gain of 1.

Next, we will consider case of when control voltage Vc is applied with regard to the selection of this resistance.



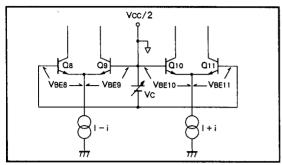


Fig. 2 Differential circuit

The values of  $V_{BE}$  of the differential stage will be as follows:

$$V_{BE8} = \frac{kT}{q} \ln \left( \frac{lc_8}{ls} \right)$$

$$V_{BE9} = \frac{kT}{q} \ln \left( \frac{lc_9}{ls} \right)$$

$$V_{BE10} = \frac{kT}{q} \ln \left( \frac{lc_{10}}{ls} \right)$$

$$V_{BE11} = \frac{kT}{q} \ln \left( \frac{lc_{11}}{ls} \right)$$

where.

Is: the saturation current
k: the Boltzmann constant
q: the amount of electric charge on the electrons

From this,

$$\begin{split} &-\text{VC} = \text{VBE8} - \text{VBE9} = \frac{kT}{q} \ln \frac{\text{IC8}}{\text{Ic9}} \\ &-\text{VC} = \text{VBE11} - \text{VBE10} = \frac{kT}{q} \ln \frac{\text{Ic11}}{\text{Ic10}} \end{split}$$

Here

$$\begin{aligned} &\text{Ic10} + \text{Ic11} &= \text{I} + \text{i} \\ &- \text{Vc} = \frac{kT}{q} \ln \frac{\text{Ic8}}{\text{I} - \text{i} - \text{Ic8}} \\ &- \text{Vc} = \frac{kT}{q} \ln \frac{\text{Ic11}}{\text{I} + \text{i} - \text{Ic11}} \end{aligned}$$

lca + lca ≒ I - i

The current flowing through Qs and Q11 will be

$$l_{C8} = \frac{(l-i)exp(-\frac{q}{kT}Vc)}{1 + exp(-\frac{q}{kT}Vc)} = \frac{l-i}{1 + exp(\frac{q}{kT}Vc)}$$

$$I_{C11} = \frac{(I+i)\exp(-\frac{Q}{kT} V_C)}{1 + \exp(-\frac{Q}{kT} V_C)} = \frac{I-i}{1 + \exp(\frac{Q}{kT} V_C)}$$

Current lc11 is the current of current mirror (4), and lca will be the same as the current of current mirror (5).

At this time, the current that will flow through the output pin will be the same as that in the explanation when Vc was equal to zero, and is expressed as

$$io = \frac{2i}{1 + \exp(\frac{\mathbf{q}}{\mathbf{k}T} \cdot \mathbf{V_C})}$$

The gain will be

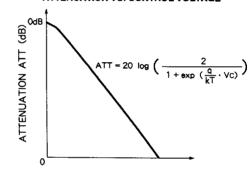
$$\frac{V_0}{V_i} = \frac{i_0 \cdot R_0}{2_i \cdot R_i} = \frac{2}{1 + \exp(\frac{Q}{L^T} \cdot V_C)}$$

and when calculated in dB,

ATT = 20 log 
$$\left(\frac{2}{1 + \exp\left(\frac{\mathbf{q}}{\mathbf{L} \cdot \mathbf{V} \cdot \mathbf{C}}\right)}\right)$$

As in the graph below, the attenuation will change logarithmically with respect to the change of Vc.

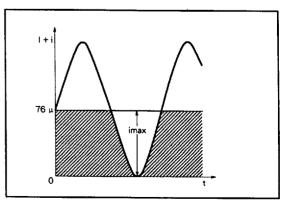
#### ATTENUATION VS. CONTROL VOLTAGE



CONTROL VOLTAGE VC (V)

#### Setting and connection of input/output resistance

As explained above, the input signal is converted to current, but since the transistor of the input stage is biased at a fixed current of  $I = 76 \,\mu$  A, the maximum value of the input current is determined at the least upper bound of I (Fig.3). Accordingly, when a large signal is input it is necessary to select a large input/output resistance and decrease the input current. Note that increasing the resistance will also increase the noise distortion factor, so the value of the setting should be made to suit the particular application.



Flg. 3 Maximum current signal

The M5222 has a floating-type output stage with the collectors of Q<sub>12</sub> and Q<sub>13</sub> joined as shown in FIG. 4. Here, the difference of the combined currents will become the output current that will flow through the load. Note that it is necessary to set the DC potential of this output pin by externally-connected resistor Ro and that it is generally DC-connected to the Vcc/2 pin (or to pin (3)).

In terms of AC, it is necessary to set the output pin to ground level so that capacitor C is required. Since the voltage gain (amount of attenuation) is determined by Ro, the value of the input impedance connected to the next stage is sometimes affected. (Placing Zi in parallel with Ro will lower the impedance.) Generally, a buffer amplifier composed of a transistor or OP amp connected.

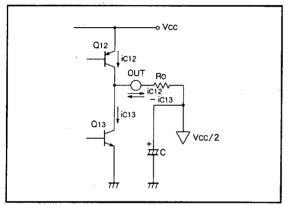


Fig. 4 Equivalent circuit of output stage

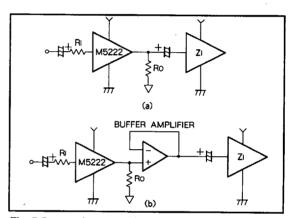
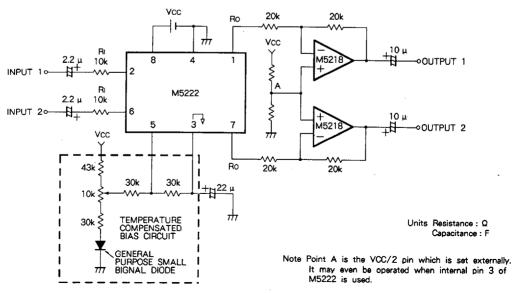


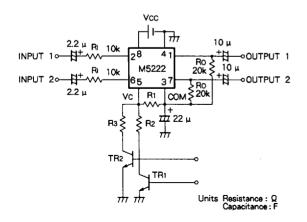
Fig. 5 Connection example

#### APPLICATION EXAMPLES

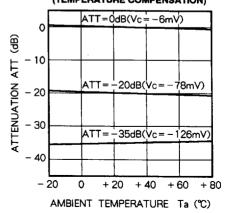
#### (1) TEMPERATURE COMPENSATED BIAS AND OUTPUT BUFFER CIRCUITS



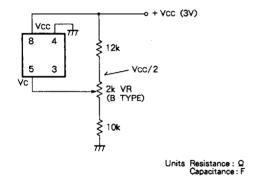
#### (2) PROGRAMMABLE ATTENUATION CIRCUIT



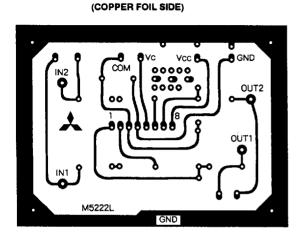
# ATTENUATION VS. AMBIENT TEMPERATURE (TEMPERATURE COMPENSATION)



# (3) CONTROL APPLICATION WITH EXISTING VOLTAGE CONTROL



# PRINTED CIRCUIT BOARD FOR CIRCUIT TESTING PRINTED CIRCUIT BOARD WIRING DIAGRAM



#### (PARTS SIDE)

