

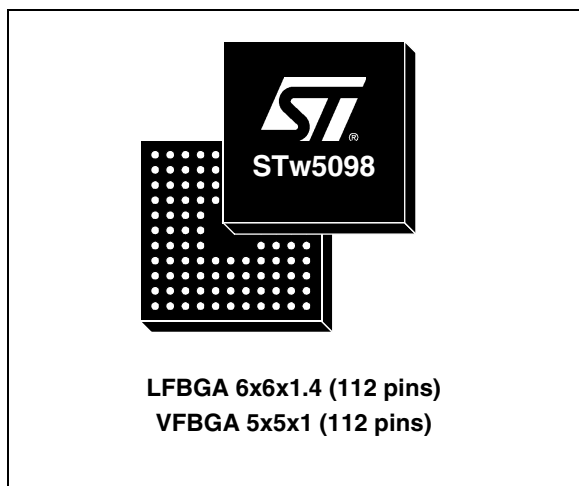
## Dual low power asynchronous stereo audio Codec with integrated power amplifiers

### Features

- Dual 20 bit audio resolution, 8kHz to 96kHz independent rate ADC and DAC
- Dual I<sup>2</sup>S or PCM digital interfaces for dual master
- Sustain complex voice and audio flow with or without mixing
- I<sup>2</sup>C/SPI compatible control I/F
- Asynchronous sampling ADC and DAC: they do not require oversampled clock and information on the audio data sampling frequency (fs). Jitter tolerant fs
- Wide master clock range: from 4MHz to 32MHz
- Stereo headphones drivers, handsfree loudspeaker driver, line out drivers
- Mixable analog line inputs
- Voice filters: 8/16kHz with voice channel filters
- Automatic gain control for microphone and line-in inputs
- Frequency programmable clock outputs
- Multibit  $\Sigma\Delta$  modulators with data weighted averaging ADC and DAC
- DSP functions for bass-treble-volume control, mute, mono/stereo selection, voice channel filters, de-emphasis filter and dynamic compression
- 93 dB dynamic range ADC, 0.001% THD with full scale output @ 2.7V
- 95 dB dynamic range DAC, 0.02% THD performance @ 2.7V over 16 $\Omega$  load

### Applications

- Digital cellular telephones with application processor such as mp3 or gaming and Bluetooth concurrent application



### Description

STw5098 is a dual low power asynchronous stereo audio CODEC device with headphones amplifiers for high quality audio listening and recording.

Two I2S/PCM digital interfaces are available, one per master for example Bluetooth and Application Processor, enabling concurrent audio and voice flow between Network and user.

The STw5098 control registers are accessible through a selectable I<sup>2</sup>C-bus compatible or SPI compatible interface.

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# 1 Overview

- Dual 20 bit audio resolution, 8kHz to 96kHz independent rate ADC and DAC
- Dual I<sup>2</sup>S/PCM digital interfaces for dual master
- Sustain complex voice and audio flow with or without mixing
- Two I<sup>2</sup>C/SPI compatible independent control interfaces
- Asynchronous sampling ADC and DAC that do not require oversampled clock and information on the audio data sampling frequency (fs). Jitter tolerant fs
- Wide master clock range from 4MHz to 32MHz
- Two stereo headphones drivers, hand free loudspeaker driver, line out drivers
- Mixable analog line inputs
- Voice filters: 8/16kHz with voice channel filters
- Automatic gain control for microphone and line-in inputs
- Four programmable master/slave serial audio data interfaces: I<sup>2</sup>S, SPI, PCM compatible and other formats
- Frequency programmable clock outputs
- Multibit  $\Sigma\Delta$  modulators with data weighted averaging ADC and DAC
- Four DSP functions for bass-treble-volume control, mute, mono/stereo selection, voice channel filters, de-emphasis filter and dynamic compression
- 93 dB dynamic range ADC, 0.001% THD with full scale with full scale output @ 2.7V
- 95 dB dynamic range DAC, 0.02% THD performance @ 2.7V over 16 $\Omega$  load

## Analog inputs

- Selectable stereo differential or single-ended microphone amplifier inputs with 51dB range programmable gain
- 2 microphone biasing output
- Microphone plug-in and push-button detection input
- Selectable stereo differential or single-ended line inputs with 38dB range programmable gain

## Analog output drivers

- 2 Stereo headphones outputs. driving capability: 40mW (0.1% THD) over 16 $\Omega$  with 40dB range programmable gain
- Common mode voltage headphones driver (phantom ground)
- 1 Balanced loudspeaker output with driving capability up to 500mW ( $V_{CCLS}>3.5V$ ; 1% THD) over 8 $\Omega$  with 30dB range programmable gain
- 1 Balanced earphone output with driving capability up to 125mW
- Transient suppression filter during power up and power down
- Balanced/unbalanced stereo line outputs with 1 k $\Omega$  driving capability



## 2 Pinout

Figure 1. Pin assignment

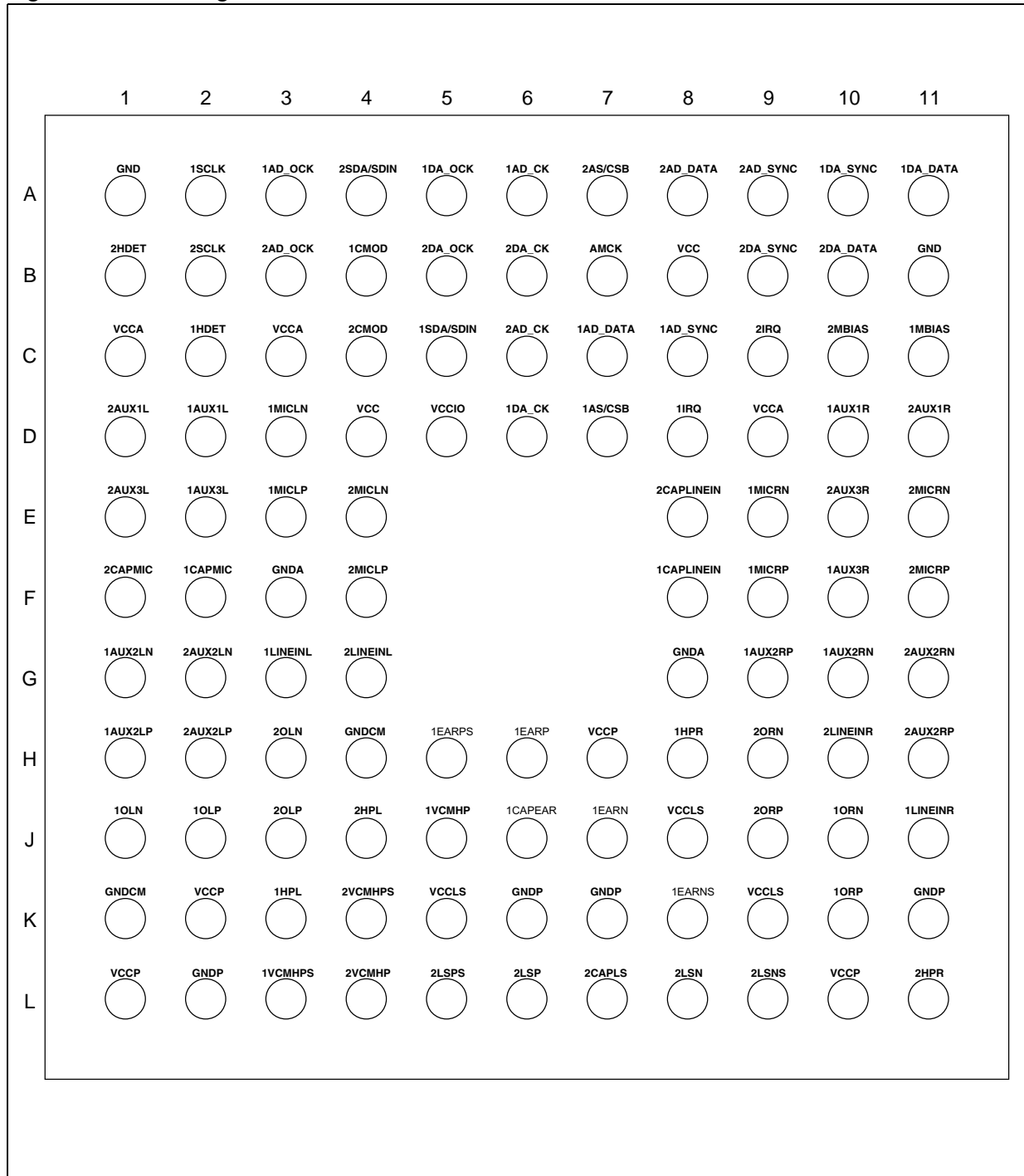


Table 1. STw5098 pin description

Position	Type	Pin name	Description
A1	P	GND	Ground pin for the digital section
A2	DI	1SCLK	Control interface serial clock input
A3	DO	1AD_OCK	Oversampled clock out from AD clock generator
A4	DIOD	2SDA/SDIN	Control interface serial data input-output in I <sup>2</sup> C mode (SDA), control interface serial data input in SPI mode (SDIN).
A5	DO	1DA_OCK	Oversampled clock out from DA clock generator
A6	DIO	1AD_CK	Serial data clock for stereo A/D converter
A7	DI	2AS/CSB	Control interface address select in I <sup>2</sup> C mode (AS). Interface enable signal in SPI mode (CSB).
A8	DO	2AD_DATA	Serial data out for stereo A/D converter
A9	DIO	2AD_SYNC	Frame sync for stereo A/D converter
A10	DIO	1DA_SYNC	Frame sync for stereo D/A converter
A11	DI	1DA_DATA	Serial data In for stereo D/A converter
B1	AI	2HDET	Headset detection input (microphone plug-in and push-button detection)
B2	DI	2SCLK	Control interface serial clock input
B3	DO	2AD_OCK	Oversampled clock out from AD clock generator
B4	DI	1CMOD	Control interface type selector I <sup>2</sup> C-bus mode or SPI mode
B5	DO	2DA_OCK	Oversampled clock out from DA clock generator
B6	DIO	2DA_CK	Serial data clock for stereo D/A converter
B7	DI AI	AMCK	Master clock input. Accepted range 4 MHz to 32 MHz. AMCK is a digital square wave AMCK is an analog sinewave ( <a href="#">Section 10.2 on page 62</a> )
B8	P	VCC	Power supply pin for the digital section. Operating range: from 1.71 V to 2.7 V
B9	DIO	2DA_SYNC	Frame sync for stereo D/A converter
B10	DI	2DA_DATA	Serial data in for stereo D/A converter
B11	P	GND	Ground pin for the digital section
C1	P	VCCA	Power supply pin for the analog section. Standard operating range: from 2.7V to 3.3V Low voltage (LV) range: from 2.4V to 2.7V
C2	AI	1HDET	Headset detection input (microphone plug-in and push-button detection)
C3	P	VCCA	Power supply pin for the analog section. Standard operating range: from 2.7V to 3.3V Low voltage (LV) range: from 2.4V to 2.7V
C4	DI	2CMOD	Control interface type selector I <sup>2</sup> C-bus mode or SPI mode.

Table 1. STw5098 pin description

Position	Type	Pin name	Description
C5	DIOD	1SDA/SDIN	Control interface serial data input-output in I <sup>2</sup> C mode (SDA). Control interface serial data input in SPI mode (SDIN).
C6	DIO	2AD_CK	Serial data clock for stereo A/D converter
C7	DO	1AD_DATA	Serial data out for stereo A/D converter
C8	DIO	1AD_SYNC	Frame sync for stereo A/D converter
C9	DO	2IRQ	Programmable interrupt output. Active low signal.
C10	AO	2MBIAS	Microphone biasing pin. Fixed voltage reference
C11	AO	1MBIAS	Microphone biasing pin. Fixed voltage reference
D1	AI	2AUX1L	Left and right channel single ended pins for microphone or line input
D2	AI	1AUX1L	Left and right channel single ended pins for microphone or line input
D3	AI	1MICLN	Left and right channel differential pins for microphone input
D4	P	VCC	Power supply pin for the digital section. Operating range: from 1.71V to 2.7V
D5	P	VCCIO	Power supply pin for the digital I/O buffers. Operating ranges: from 1.2V to 1.8V and from 1.71V to V <sub>CC</sub>
D6	DIO	1DA_CK	Serial data clock for stereo D/A converter
D7	DI	1AS/CSB	Control interface address select in I <sup>2</sup> C mode (AS) Interface enable signal in SPI mode (CSB)
D8	DO	1IRQ	Programmable interrupt output. Active low signal.
D9	P	VCCA	Power supply pin for the analog section. Standard operating range: from 2.7V to 3.3V Low voltage (LV) range: from 2.4V to 2.7V
D10	AI	1AUX1R	Left and right channel single ended pins for microphone or line input
D11	AI	2AUX1R	Left and right channel single ended pins for microphone or line input
E1	AI	2AUX3L	Left and right channel single ended pins for microphone or line input
E2	AI	1AUX3L	Left and right channel single ended pins for microphone or line input
E3	AI	1MICLP	Left and right channel differential pins for microphone input
E4	AI	2MICLN	Left and right channel differential pins for microphone input
E8	AI	2CAPLINEIN	A capacitor must be connected between CAPLINEIN and ground
E9	AI	1MICRN	Left and right channel differential pins for microphone input
E10	AI	2AUX3R	Left and right channel single ended pins for microphone or line input
E11	AI	2MICRN	Left and right channel differential pins for microphone input
F1	AI	2CAPMIC	A capacitor must be connected between CAPMIC and ground.
F2	AI	1CAPMIC	A capacitor must be connected between CAPMIC and ground
F3	P	GNDA	Ground pin for the analog section
F4	AI	2MICLP	Left and right channel differential pins for microphone input

Table 1. STw5098 pin description

Position	Type	Pin name	Description
F8	AI	1CAPLINEIN	A capacitor must be connected between CAPLINEIN and ground
F9	AI	1MICRP	Left and right channel differential pins for microphone input
F10	AI	1AUX3R	Left and right channel single ended pins for microphone or line input
F11	AI	2MICRP	Left and right channel differential pins for microphone input
G1	AI	1AUX2LN	Left and right channel differential pins for microphone or line input
G2	AI	2AUX2LN	Left and right channel differential pins for microphone or line input
G3	AI	1LINEINL	Left and right channel single ended pins for line input
G4	AI	2LINEINL	Left and right channel single ended pins for line input
G8	P	GNDA	Ground pin for the analog section
G9	AI	1AUX2RP	Left and right channel differential pins for microphone or line input.
G10	AI	1AUX2RN	Left and right channel differential pins for microphone or line input
G11	AI	2AUX2RN	Left and right channel differential pins for microphone or line input
H1	AI	1AUX2LP	Left and right channel differential pins for microphone or line input
H2	AI	2AUX2LP	Left and right channel differential pins for microphone or line input
H3	AO	2OLN	Audio differential line out amplifier for left and right channels. This outputs can drive up to 1k $\Omega$ resistive load. Can be used as single ended output.
H4	P	GNDCM	Ground pin for analog reference. GNDCM can be connected to GNDA
H5	AO	1EARPS	EARPS, EARNs (sense) pins must be connected on the application board to EARP, EARN pins respectively. The connection must be as close as possible to the pins.
H6	AO	1EARP	Analog differential loudspeaker amplifier output for left channel or right channel or the sum of both. This output can drive 50nF (with series resistor) or directly an earpiece transducer from 8 $\Omega$ to 32 $\Omega$ . Can deliver from 500mW to 125mW.
H7	P	VCCP	Power supply pin for the left and right output drivers (headphones and line-out). Operating range: from $V_{CCA}$ to 3.3V
H8	AO	1HPR	Audio single ended headphones amplifier outputs for left and right channels. The outputs can drive 50nF (with series resistor) or directly an earpiece transducer of 16 $\Omega$
H9	AO	2ORN	Audio differential line out amplifier for left and right channels. This outputs can drive up to 1k $\Omega$ resistive load. Can be used as single ended output.
H10	AI	2LINEINR	Left and right channel single ended pins for line input
H11	AI	2AUX2RP	Left and right channel differential pins for microphone or line input
J1	AO	1OLN	Audio differential line out amplifier for left and right channels. This outputs can drive up to 1k $\Omega$ resistive load. Can be used as single ended output.

Table 1. STw5098 pin description

Position	Type	Pin name	Description
J2	AO	1OLP	Audio differential line out amplifier for left and right channels. This outputs can drive up to 1k $\Omega$ resistive load. Can be used as single ended output.
J3	AO	2OLP	Audio differential line out amplifier for left and right channels. This outputs can drive up to 1k $\Omega$ resistive load. Can be used as single ended output.
J4	AO	2HPL	Audio single ended headphones amplifier outputs for left and right channels. The outputs can drive 50nF (with series resistor) or directly an earpiece transducer of 16 $\Omega$
J5	AO	1VCMHP	Common mode voltage headphones output. The negative pins of headphones left and right speakers can be connected to this pin to avoid decoupling capacitors.
J6	AI	1CAPEAR	A capacitor can be connected between this node and ground
J7	AO	1EARN	Analog differential loudspeaker amplifier output for Left channel or Right channel or the sum of both. This output can drive 50nF (with series resistor) or directly an earpiece transducer from 8 $\Omega$ to 32 $\Omega$ ; It can deliver from 500mW to 125mW.
J8	P	VCCLS	Power supply pin for the mono differential output driver. Operating range: from $V_{CCA}$ to 5.5V
J9	AO	2ORP	Audio differential line out amplifier for left and right channels. This outputs can drive up to 1k $\Omega$ resistive load. Can be used as single ended output.
J10	AO	1ORN	Audio differential line out amplifier for left and right channels. This outputs can drive up to 1k $\Omega$ resistive load. Can be used as single ended output.
J11	AI	1LINEINR	Left and right channel single ended pins for line input
K1	P	GNDCM	Ground pin for analog reference. GNDCM can be connected to GNDA
K2	P	VCCP	Power supply pins for the left and right output drivers (headphones and line-out). Operating range: from $V_{CCA}$ to 3.3V
K3	AO	1HPL	Audio single ended headphones amplifier outputs for left and right channels. The outputs can drive 50nF (with series resistor) or directly an earpiece transducer of 16 $\Omega$
K4	AO	2VCMHPS	VCMHPS (sense) pin must be connected on the application board to VCMHP pin. The connection must be as close as possible to the pins.
K5	P	VCCLS	Power supply pin for the mono differential output driver. Operating range: from $V_{CCA}$ to 5.5V
K6	P	GNDP	Ground pin for the left, right and mono-differential output drivers. GNDP and GNDA must be connected together.
K7	P	GNDP	Ground pin for the left, right and mono-differential output drivers. GNDP and GNDA must be connected together.

Table 1. STw5098 pin description

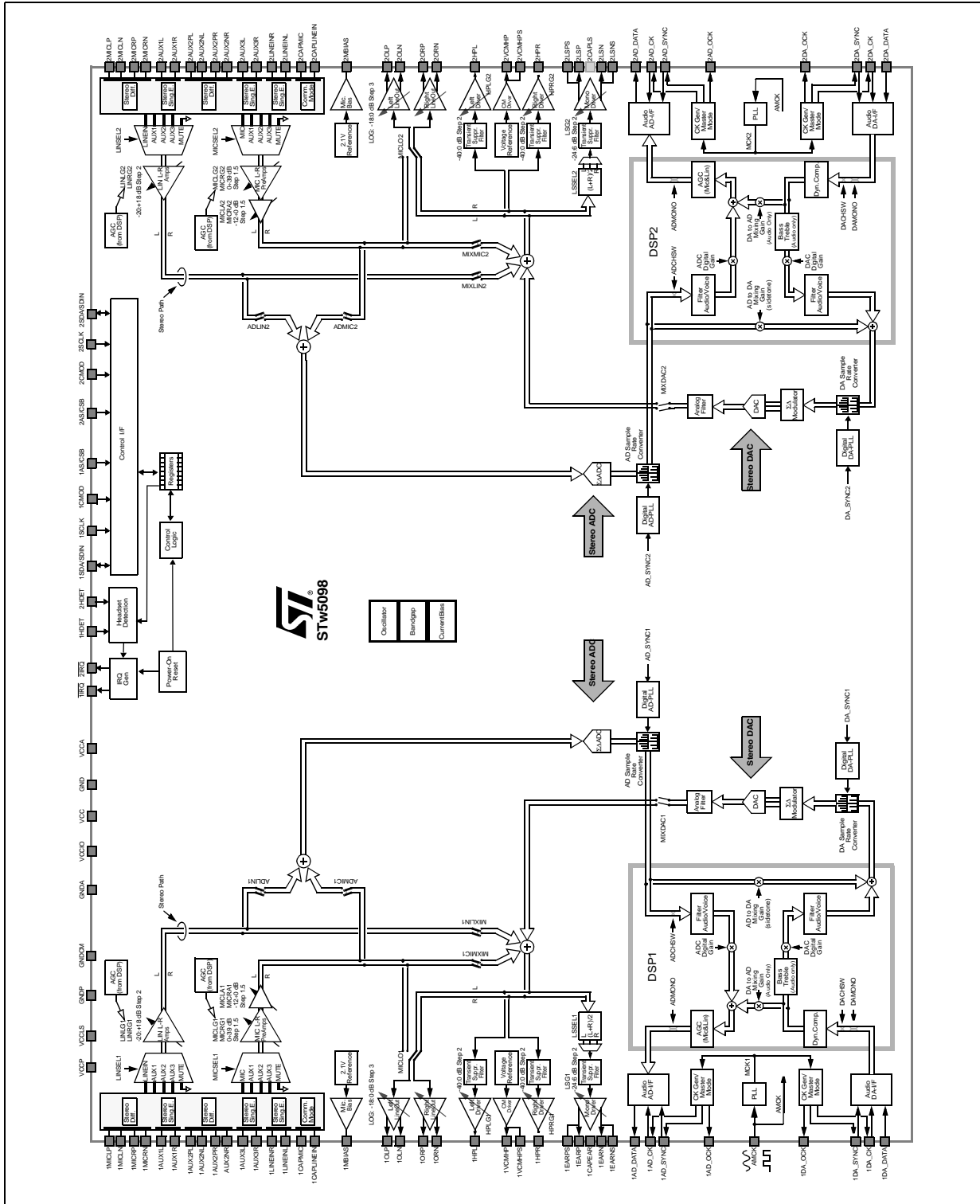
Position	Type	Pin name	Description
K8	AO	1EARNs	EARPS, EARNs (sense) pins must be connected on the application board to EARP, EARN pins respectively. The connection must be as close as possible to the pins.
K9	P	VCCLS	Power supply pins for the mono differential output driver. Operating range: from $V_{CCA}$ to 5.5V
K10	AO	1ORP	Audio differential line out amplifier for left and right channels. This outputs can drive up to 1k $\Omega$ resistive load. Can be used as single ended output.
K11	P	GNDP	Ground pin for the left, right and mono-differential output drivers. GNDP and GNDA must be connected together.
L1	P	VCCP	Power supply pin for the left and right output drivers (headphones and line-out). Operating range: from $V_{CCA}$ to 3.3V
L2	P	GNDP	Ground pin for the left, right and mono-differential output drivers. GNDP and GNDA must be connected together.
L3	AO	1VCMHPS	VCMHPS (sense) pin must be connected on the application board to VCMHP pin. The connection must be as close as possible to the pins.
L4	AO	2VCMHP	Common mode voltage headphones output. The negative pins of headphones left and right speakers can be connected to this pin to avoid decoupling capacitors.
L5	AO	2LSPS	LSPS, LSNS (sense) pins must be connected on the application board to LSP, LSN pins respectively. The connection must be as close as possible to the pins.
L6	AO	2LSP	Analog differential loudspeaker amplifier output for Left channel or Right channel or the sum of both. This output can drive 50nF (with series resistor) or directly an earpiece transducer of 8 $\Omega$ ; It can deliver up to 500mW.
L7	AI	2CAPLS	A capacitor can be connected between this node and ground
L8	AO	2LSN	Analog differential loudspeaker amplifier output for Left channel or Right channel or the sum of both. This output can drive 50nF (with series resistor) or directly an earpiece transducer of 8 $\Omega$ Can deliver up to 500mW.
L9	AO	2LSNS	LSPS, LSNS (sense) pins must be connected on the application board to LSP, LSN pins respectively. The connection must be as close as possible to the pins.
L10	P	VCCP	Power supply pin for the left and right output drivers (headphones and line-out). Operating range: from $V_{CCA}$ to 3.3V
L11	AO	2HPR	Audio single ended headphones amplifier outputs for left and right channels. The outputs can drive 50nF (with series resistor) or directly an earpiece transducer of 16 $\Omega$

**Type definitions**

AI	-	Analog input
AO	-	Analog output
AIO	-	Analog input output
DI	-	Digital input
DO	-	Digital output
DIO	-	Digital input output
DIOD	-	Digital input output open drain
P	-	Power supply or ground

# 3 Block diagram

Figure 2. STw5098 block diagram





## 4 Functional description

### 4.1 Naming convention

The STw5098 is composed of two identical entities, with their respective set of control registers.

Regarding the pin labelling, a pin name preceded by 1 refers to entity 1 and a pin name preceded by 2 refers to entity 2 (ie.g. 1SCLK, 2SCLK). In the following sections, no distinction is made between the two entities when it is not relevant. Consequently, the 1 and 2 prefixes for entities 1 and 2 respectively are omitted. The same naming convention applies to the control registers (CRxxx).

### 4.2 Power supply

STw5098 can have different supply voltages for different blocks, to optimize performance, power consumption and connectivity. See [Section 9.2 on page 59](#) for voltage definition.

The correct sequence to apply supply voltage is to set first (and unset last) the digital I/O supply ( $V_{CCIO}$ ). The other supply voltages can be set in any order and can be disconnected individually, if needed. Disconnection does not cause any harm to the device and no extra current is pulled from any supply during this operation. Moreover if a voltage conflict is detected, like  $V_{CCA} < V_{CC}$  (not allowed), simply all blocks connected to  $V_{CCA}$  are set to power down and no extra current is pulled from supply.

When  $V_{CCIO}$  is set and  $V_{CC}$  (digital supply) is not set, all the digital output pins are in high impedance state, while the digital inputs are disconnected to avoid power consumption for any input voltage value between GND and  $V_{CCIO}$ . Before  $V_{CC}$  is disconnected the device has to be reset (SWRES bit in CR30).

When the analog supply ( $V_{CCA}$ ) is set and  $V_{CC}$  is not set, all the analog inputs are in high impedance state.

The two sets of control registers are powered by VCC pins (digital supply) so if these pins are disconnected all the information stored in control registers is lost. When the digital supply voltage is set, a power-on-reset (POR) circuit sets all the registers content to the default value and then generates IRQ signals writing 1 in bits PORMSK end POREV in CR31 and CR32 respectively for both entities.

All supplies must be on during operation.

## 4.3 Device programming

STw5098 can be programmed by writing Control Registers with SPI or I<sup>2</sup>C compatible control interface (both slave). The interface is always active, there is no need to have the master clock running to program the device registers. The control interfaces of each entity can be operated independently either in SPI or I2C modes.

The choice between the two interfaces for each entity is done via their input pins 1CMOD and 2CMOD (CMOD):

1. CMOD connected to GND: I<sup>2</sup>C compatible mode selected  
The device address is selected with AS pin:

AS/CSB connected to GND: chip address 00110101(35hex) for reading, 00110100 (34hex) for writing

AS/CSB connected to V<sub>CCIO</sub>: chip address 00110111(37hex) for reading, 00110110 (36hex) for writing

When this mode is selected control registers are accessed through pins:

SCLK (clock)

SDA (serial data out/in, open drain)

2. CMOD connected to V<sub>CCIO</sub>: SPI compatible mode selected  
When this mode is selected control registers are accessed through:  
AS/CSB (chip select, active low)  
SCLK (clock)  
SDIN (serial data in)  
AD\_OCK or DA\_OCK or IRQ (serial data out, if selected)

**Device Programming: I<sup>2</sup>C.** The I<sup>2</sup>C Control Interface timing is shown in [Section 6.1 on page 50](#). The interface has an internal counter that keeps the current address of the control register to be read or written. At each write access of the interface the address counter is loaded with the data of the *register address* field. The value in the address counter is increased after each data byte read or write. It is possible to access the interface in 2 modes: single-byte mode in which the address and data of a single register are specified, and multi-byte mode in which the address of the first register to be written or read is specified and all the following bytes exchanged are the data of successive registers starting from the one specified (in multi-byte mode the internal address counter restart from register 0 after the last register 36). Using the multi-byte mode it is possible to write or read all the registers with a single access to the device on the I<sup>2</sup>C bus. This applies to both entities of the device.

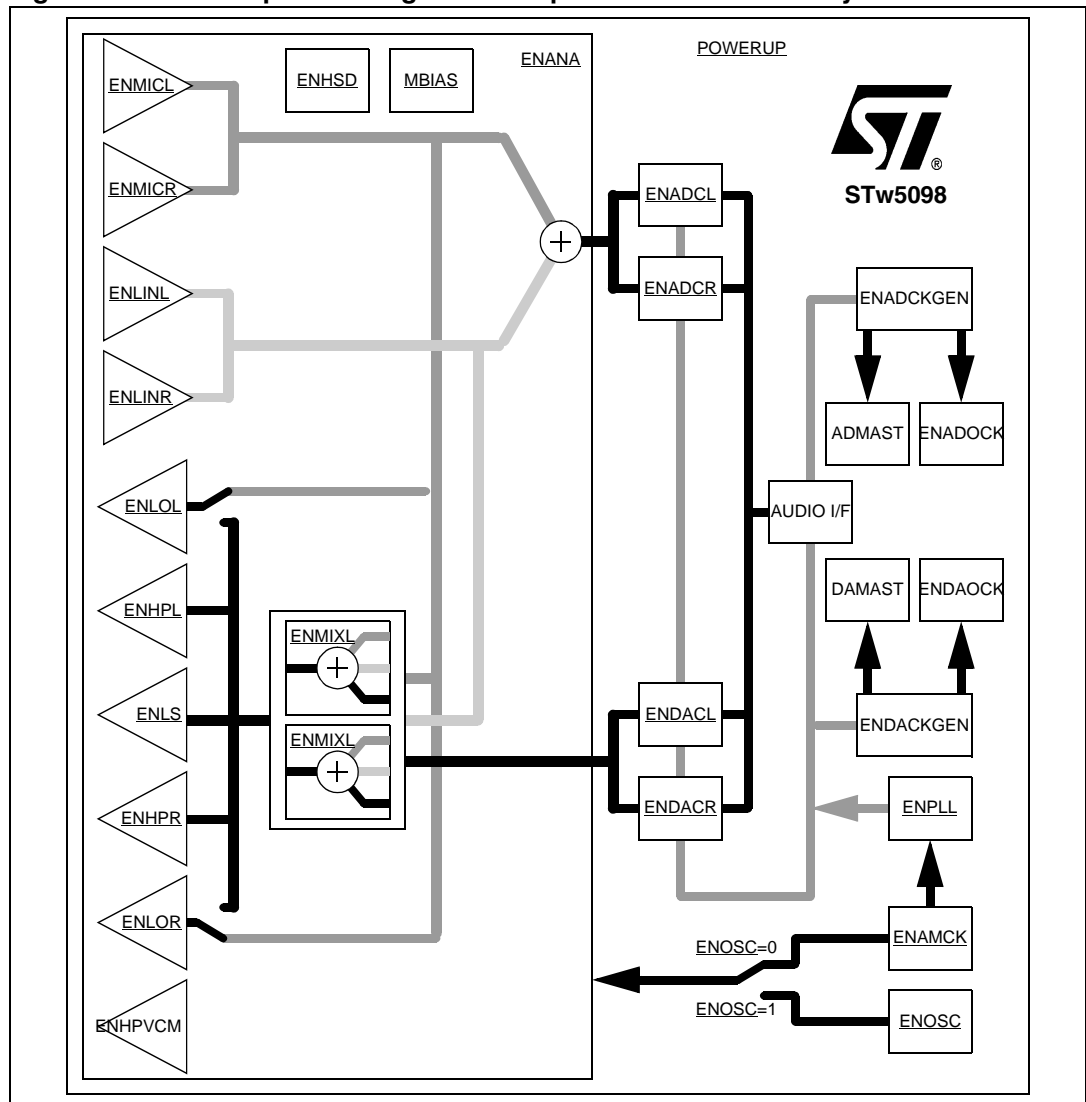
**Device Programming: SPI.** The SPI Control Interface timing is shown in section [Section 6.2 on page 51](#). Bits SPIOSEL (SPI Output Select) in CR33 control the out pin selection for serial data out (none, AD\_OCK, DA\_OCK or IRQ), while bit SPIOHIZ=1 in CR33 selects the high impedance state of serial data out pin when idle. The first bit sent on SDIN, after AS/CSB falling edge, sets the interface for writing (SDIN=1) or reading (SDIN=0), then a 7-bit Control Register address follows.

If the interface is set for writing then the last 8 bits on SDIN are written in the control register. If the interface is set for reading then after the 7 bit address STw5098 sends out 8 bits data on the pin selected with bits SPIOSEL in CR33, while bits present at SDIN pin are ignored. If SPIOSEL=00 (no out pin selected) the reading access on SPI interface can still be useful to clear the IRQ event bits in CR32.

### 4.4 Power up

STw5098 internal blocks can individually be switched on and off according to the user needs. A general power-up bit is present at bit 7 of CR0. The output drivers should always be powered up after the general power up. See the following drawing to select the needed block for the desired function. A fast-settling function is activated to quickly charge external capacitors when the device is switched on (CAPLS, CAPLINEIN and CAPMIC).

**Figure 3. Power up block diagram: example shown for one entity**



### 4.5 Master clock

Master clock is applied to both entities. The master clock pin (AMCK) accepts any frequency from 4 MHz to 32 MHz. The 4-32 MHz range is divided in sub-ranges that have to be programmed in bits CKRANGE in CR30. The jitter and spectral properties of this clock have a direct impact on the DAC and ADC performance because it is used to directly or by integer division drive the continuous-time to sampled-time interfaces.

Note that AMCK clock does not need to have any relation to any other digital or analog input or output.

AMCK can be either a square wave or a sinewave, bit AMCKSIN in CR30 selects the proper input mode. When a sinewave is used as input, AMCK pin must be decoupled with a capacitor. Specification for sinusoid input can be found in [Section 10.2 on page 62](#).

The AMCK clock is not needed when only analog functions are used. For this purpose an internal oscillator with no external components can be used to operate the device (see [Section 4.14 on page 25](#)).

## 4.6 Data rates

STw5098 supports any data rate in 2 ranges: 8 kHz to 48 kHz and 88 kHz to 96 kHz. The range is selected with bits DA96K and AD96K in CR29 for AD and DA paths respectively.

*Note:* When AD96K=1 it is required to have DA96K=1.

The rates are fully independent in A/D and D/A paths. Moreover the rates do not have to be specified to the device and they can change on the fly, within one range, while data is flowing.

The 2 audio data interfaces (for A/D and D/A) can independently operate in master or slave modes.

## 4.7 Clock generators and master mode function

STw5098 provides 4 internal clock generators that can drive, if needed, the audio interfaces (master mode), and/or two independent master clocks.

The AMCK clock input frequency is internally raised via a PLL on each entity to obtain a clock (MCK) in the range 32 MHz to 48 MHz. The ratio MCK/AMCK is defined in CR30 (see MCKCOEFF in [Section 4.7 on page 20](#)).

MCK is used to obtain, by fractional division, the oversampled clock (OCK), word clock (SYNC) and bit clock (CK), that will therefore have edges aligned with MCK (the OCK period can have jitter of 1 MCK period).

The frequency of OCK, SYNC and CK is set with DAOCKF in CR21/20 for DA interface, and ADOCKF in CR24/23 for AD interface.

The ratio between OCK and SYNC clocks is selected with bit DAOCK512 in CR22 for DA interface and bit ADOCK512 in CR25 for AD interface. The ratio between CK and SYNC clocks depends on the selected interface format (see [Audio digital interfaces](#) paragraph below). Note that SPI format can only be slave.

The ADOCK and DAOCK output clocks are activated by bits ENADOCK and ENDAOCK respectively, while master mode generation is activated with two bits: first ADMAST (DAMAST) sets ADSYNC and ADCK (DASYNC and DACK) pins as outputs, then ADMASTGEN (DAMASTGEN) generates the SYNC and CK clocks. The logical value at SYNC and CK pins before data generation depends on the interface selected format.

See description of CR20 to CR25 for further details.

## 4.8 Audio digital interfaces

Four separate audio data interfaces are provided for AD and DA paths to have maximum flexibility in communicating with other devices. The 4 interfaces can have different rates and can work in different formats and modes (i.e an AD interface can be 8 kHz PCM slave while a DA is 44.1 kHz I<sup>2</sup>S master).

The pins used by the interfaces are:

AD\_SYNC, AD\_CK and AD\_DATA for AD paths word clock, bit clock and data, respectively, and

DA\_SYNC, DA\_CK and DA\_DATA for DA paths word clock, bit clock and data, respectively.

Data is exchanged with MSB first and left channel data first in all formats. Data word-length is selected with bits DAWL in CR26 and ADWL in CR27. AD\_DATA pin, outside the selected time slot, is in the impedance condition selected by bit ADHIZ in CR28 in all data formats except right aligned format.

In the following paragraphs SYNC, CK and DATA will be used when the distinction between AD and DA is not relevant. When Master Mode is selected (bits DAMAST and ADMAST in CR22 and CR25 respectively) the SYNC and CK clocks are generated internally. In addition, an oversampled clock can be generated for each interface (AD\_OCK and DA\_OCK). The clock is available in Slave Mode also, if needed.

The AD and DA interfaces can also be used as a single bidirectional interface when they are configured with the same format (Delayed, DSP, etc.) and AD\_SYNC is connected to DA\_SYNC and DA\_CK to AD\_CK. Master Mode is still available selecting ADMAST or DAMAST (not both).

The interfaces features are controlled with control registers CR26, CR27 and CR28.

Supported operating formats:

- **Delayed format (I<sup>2</sup>S compatible)** (DAFORM or ADFORM =000): the Audio Interface is I<sup>2</sup>S compatible ([Figure 9 on page 54](#)). The number of CK periods within one SYNC period is not relevant, as long as enough CK periods are used to transfer the data and the maximum frequency limit specified for bit clock is not exceeded. CK can be either a continuous clock or a sequence of bursts. In master mode there are 32 CK periods per SYNC period (that means 16 CK periods per channel) when the word length is 16 bit, while there are 64 CK periods per SYNC period (or 32 CK periods per channel) when word length is 18bit or higher. Bits ADSYNCP, DASYNCP and ADCKP, DACKP affect the interface format inverting the polarity of SYNC and CK pins respectively.
- **Left aligned format** (DAFORM or ADFORM =001): this format is equivalent to delayed format without the 1 bit clock delay at the beginning of each frame ([Figure 9 on page 54](#)).
- **Right aligned format** (DAFORM or ADFORM =010): this format is equivalent to delayed format, except that the audio data is right aligned and that the number of CK periods is fixed to 64 for each SYNC period ([Figure 9 on page 54](#)).
- **DSP format** (DAFORM or ADFORM =011) in this format the audio interface starting from a frame sync pulse on SYNC receives (DA) or sends (AD) the left and right data one after the other ([Figure 10 on page 55](#)). The number of CK periods within one SYNC period is not relevant, as long as enough CK periods are used to transfer the data and the maximum frequency limit specified for bit clock is not exceeded. CK can be either a continuous clock or a sequence of bursts. In Master Mode there are 32 CK periods per SYNC period when the word length is 16 bit, while there are 64 CK periods per SYNC period when word length is 18bit or higher. Bit CKP (ADCKP and DACKP)

affects the interface format inverting the polarity of CK pin. Bit SYNCP (ADSYNCP and DASYNCP) switches between delayed (SYNCP=0) and non delayed (SYNCP=1) formats.

DSP format is suited to interface with a multi-channel serial port.

- **SPI format** (DAFORM or ADFORM =100) in this format left and right data is received with separate data burst. Every burst is identified with a low level on SYNC signal ([Figure 10 on page 55](#)). There is no timing difference between the left and right data burst: the two channels are identified by the startup order: the first burst after AD path or DA path power-up identifies the left channel data, the second one is the Right channel data, then left and right data repeat one after the other. CK must have 16 periods per channel in case of 16 bit data word and 32 periods per channel in case of 18 bit to 32 bit data word.  
The SPI interface can be configured as a single-channel (mono) interface with bit SPIM (ADSPIM and DASPIM). The mono interface always exchanges the left channel sample.  
SPI-format can only be slave: if Master Mode is selected the CK and SYNC pins are set to 0. Bit CKP (ADCKP and DACKP) affects the interface format inverting the polarity of CK pin.
- **PCM format** (DAFORM or ADFORM =111): this format is monophonic, as it can only receive (DA) and transmit (AD) single channel data ([Figure 10 on page 55](#)). It is mainly used when voice filters are selected. If audio filters are used then the same sample is sent from DA-PCM interface to both channel of DA path, and the left channel sample from AD path is sent to AD-PCM interface. If in the AD path the right channel has to be sent to the PCM interface then the following must be set: ADRTOL=1 (CR27) and ENADCR=0 (CR1). In Master Mode the number of CK periods per SYNC period is between 16 and 512 (see DAPCMF in CR22 and ADPCMF in CR25 [Section 4.7 on page 20](#) for details). Bit CKP (ADCKP and DACKP) affects the interface format inverting the polarity of CK pin. Bit SYNCP (ADSYNCP and DASYNCP) switches between delayed (SYNCP=0) and non delayed (SYNCP=1) formats.

## 4.9 Analog inputs

Each entity of the STw5098 has a stereo Microphone preamplifier and a stereo Line In amplifier, with inputs selectable among 5: MIC (for Microphone preamplifiers only), LINEIN (for Line In amplifiers only) and 3 different AUX inputs (for Microphone and Line In amplifiers). The AUX inputs can be used simultaneously for Line In amplifiers and Microphone preamplifiers.

The following description is for one entity, it is similar for the other entity.

- **Microphone preamplifier:** it has a very low noise input, specifically designed for low amplitude signals. For this reason the preamplifier has a high input gain (up to 39 dB) keeping a constant 50 k $\Omega$  input impedance for the whole gain range. However it can also be used as line in preamplifier because it can accept a high dynamic input signal (up to 4 V<sub>pp</sub>). There are two separate gain and attenuation stages in order to improve the S/N ratio when the preamplifier output range is below full scale (volume control). The gain and attenuation controls are separate for left and right channel (CR3 and CR4 respectively). The Preamplifier input is selected with bits MICSEL in CR18, and it is disconnected when MICMUTE=1. If a single ended input is selected then the preamplifier uses the selected pin as the positive input and connects the negative input (for both left and right channels) to CAPMIC pin, which has to be connected through a capacitor to a low noise ground (typically the same reference ground of the input).

Each stereo Microphone preamplifier is powered up with bits ENMICL and ENMICR in CR1.

- **Line In amplifier:** each line in amplifier is designed for high level input signal. The input gain is in the range -20 dB up to 18 dB. The Line In amplifier input is selected with bits LINSEL in CR18, and it is disconnected when LINMUTE=1. If a single ended input is selected then the amplifier uses the selected pin as the positive input and connects the negative input (for both left and right channels) to CAPLINEIN pin, which has to be connected through a capacitor to a low noise ground (typically the same reference ground of the input).  
The stereo Line In amplifier is powered up with bits ENLINL and ENLINR in CR1.

## 4.10 Analog output drivers

Each entity of the STw5098 provides 3 different analog signal outputs and 1 common mode reference output. The description here below is for one entity.  $V_{CCP}$  and  $V_{CCL}$  are common for both entities.

- **Line out drivers:** it is a stereo differential output, it can be used as single-ended output just by using the positive or negative pin. It can drive 1 k $\Omega$  resistive load. The load can be connected between the positive and negative pins or between one pin and ground through a decoupling capacitor. The output gain is regulated with LOG bits in CR7, in the range 0 to -18 dB, simultaneously for left and right channels. When used as a single ended output the effective gain is 6 dB lower. It is muted with bit MUTELO in CR19. The input signal of this stereo output can come from the analog mixer or directly from MIC preamplifiers. The output Common Mode Voltage level is controlled with bits VCML in CR19. The supply voltage of line out drivers is  $V_{CCP}$ .  
The line out drivers are powered up with bits ENLOL and ENLOR in CR1. The output pins are in high impedance state with a 180k $\Omega$  pull-down resistor when the line out drivers are powered down.
- **Headphones drivers:** it is a stereo single ended output. It can drive 16 ohm resistive load and deliver up to 40 mW. The output gain is regulated with HPLG and HPRG bits in CR8 and CR9 respectively, with a range of -40 to 6 dB. It is muted with bit MUTEHP in CR19. The input signal of this stereo output comes from the analog mixer. The output common mode voltage is controlled with bits VCML in CR19. The supply voltage of headphones drivers is  $V_{CCP}$ .  
The headphones drivers are powered up with bits ENHPL and ENHPR in CR2. The output pins are in high impedance state when the headphones drivers are powered down.
- **Common mode voltage driver:** it is a single ended output with output voltage value selectable with bits VCML in CR19, from 1.2 V to 1.65 V in steps of 150 mV. The output voltage should be set to the value closest to  $V_{CCP}/2$  to optimize output drivers performance. The common mode voltage driver is designed to be connected to the common pin of stereo headphones, so that decoupling capacitors are not needed at HPL and HPR outputs. The supply voltage of the common mode voltage driver is  $V_{CCP}$ .  
The common mode voltage driver is powered up with bit ENHPVCM in CR2. The output pin is in high impedance state when the common mode voltage driver is powered down.



- **Loudspeaker driver (one entity only):** it is a monophonic differential output. It can drive 8  $\Omega$  resistive load and deliver up to 500 mW to the load. The output gain is regulated with LSG bits in CR7, in the range -24 to +6 dB. The input signal of the loudspeaker driver comes from the analog mixers: bits LSSEL in CR29 select left channel, right channel, (L+R)/2 (mono) or mute. The output common mode voltage is obtained with an internal voltage divider from  $V_{CCLS}$  and it is connected to CAPLS pin. The supply voltage of the loudspeaker driver is  $V_{CCLS}$ . The loudspeaker driver is powered up with bit ENLS in CR2. The output pin is in high impedance state when the loudspeaker driver is powered down.

Note: 1 Together with the LS driver, only a second power output is allowed among:  
 Ear (1EARP - 1EARN)  
 Headphones 1 (1HPL and 1HPR)  
 Headphones 2 (2HPL and 2HPR)

- **Earphone driver (one entity only):** it is a monophonic differential output. It can drive 32  $\Omega$  resistive load and deliver up to 125 mW to the load. The output gain is regulated with EARG bits in CR7, in the range -24 to +6 dB. The input signal of the loudspeaker driver comes from the analog mixers: bits EARSEL in CR29 select left channel, right channel, (L+R)/2 (mono) or mute. The output Common Mode Voltage is obtained with an internal voltage divider from  $V_{CCLS}$  and it is connected to CAPEAR pin. The supply voltage of the loudspeaker driver is  $V_{CCLS}$ . The loudspeaker driver is powered up with bit ENEAR in CR2. The output pin is in high impedance state when the loudspeaker driver is powered down.

Note: **Note on direct connection of  $V_{CCLS}$  to the battery:**  
 The voltage of batteries of handheld devices during charging is usually below 5.5 V, making  $V_{CCLS}$  supply pin suitable for a direct connection to the battery. In this case if STw5098 is delivering the maximum power to the load and the ambient temperature is above 70 °C then the simultaneous charging of the battery can overheat the device. A basic protection scheme is implemented in STw5098 (activated with bit LSLIM in CR19): it limits the maximum gain of the loudspeaker to -6 dB when  $V_{CCLS}$  is above 4.2 V, and it removes the limit for  $V_{CCLS}$  below 4.0 V. The loudspeaker gain is left unchanged if it is set below -6 dB with bits LSG. This event ( $V_{CCLS} > 4.2$  V) can generate, if enabled (bit VLMSK in CR31), an IRQ signal.

## 4.11 Analog mixers

STw5098 can send to the output drivers the sum of stereo audio signals from 3 different sources of each entity: DA path (bit MIXDAC in CR17), Microphone Preamplifiers (bit MIXMIC in CR17) and Line In Amplifiers (bit MIXLIN in CR17). The analog mixers do not have a gain control on the inputs, therefore the user should reduce the levels of the input signals within the analog signal range.

The stereo analog mixers are powered up with bits ENMIXL and ENMIXR in CR2.

## 4.12 AD paths

In each entity the AD path converts audio signals from Microphone Preamplifiers (selected with bit ADMIC in CR17) and Line In Amplifiers (bit ADLIN in CR17) inputs to digital domain. If both inputs are selected then the sum of the two is converted. After AD conversion the audio data is resampled with a sample rate converter and then processed with the internal DSP. Two different filters are selectable in the DSP (bit ADVOICE in CR29): stereo Audio



Filter, with DC offset removal and FIR image filtering; and a standard mono voice-channel filter (uses left channel input and feeds both channel output). The AD path includes a digital gain control (ADCLG, ADCRG in CR12 and CR13 respectively) in the range -57 to +8 dB. The maximum gain from Mic Preamplifier to AD interface is then 47 dB. When Audio filter is selected in both AD and DA paths then DA audio data can be summed to AD data and sent to the AD Audio Interface (see DA2ADG in CR15). Left and right channels can be independently switched on and off to save power, if needed (bits ENADCL and ENADCR in CR1)

## 4.13 DA paths

In each entity the DA path converts digital data from the digital audio interface to analog domain and feeds it to the analog mixer. Incoming audio data is processed with a DSP where different filters are selectable (bit DAVOICE in CR29): Audio filter, stereo, with FIR image filtering, bass and treble controls (bits BASS and TREBLE in CR14), de-emphasis filter; and a standard voice channel filter, mono (uses left channel input and feeds both channel output). A dynamic compression function is available for both audio and voice filters (bit DYNC in CR14). The DA path includes a digital gain control (DACLG, DACRG in CR10 and CR11 respectively) in the range -65 to 0 dB. AD to DA mixing (sidetone) can be enabled: see CR16 for details. Left and right channel can be independently switched on and off to save power, if needed (bits ENACL and ENACR in CR1).

## 4.14 Analog-only operations

Each entity from the STw5098 can operate without AMCK master clock if analog-only functions are used. It is possible to mix Microphone and Line In preamplifiers signals and listen through headphones, loudspeaker or send them to line-out. The analog-only operation is enabled with bit ENOSC in CR0. When ENOSC=1 the AD and DA paths cannot be used.

In Analog Mode, each of the two entities can handle two different stereo audio signals, so it can be used as a front end for an external voice codec that does not include microphone preamplifiers and power drivers: mic signal is sent through Microphone preamplifiers directly to line out drivers (Transmit path), while Receive signal is sent through Line In amplifiers to the selected power drivers.

## 4.15 Automatic Gain Control (AGC)

STw5098 provides a digital Automatic Gain Control in AD path for each entity. The circuit can control the input gain at MIC preamplifier, Line In amplifier or both (bits ENAGCMIC and ENAGCLIN in CR35). When one input is selected, the center gain value used for the input is fixed with bits MICLG, MICRG, LINLG and LINRG in CR3 to CR6 (like in normal operation), then the AGC circuit adds to all the gains a value in the range -10.5 dB to +10.5 dB (or, extended with bit AGCRANGE in CR35, -21 dB to 21 dB), in order to obtain an average level at the digital interface output in the range -6 dB to -30 dB (selected with bits AGCLEV in CR35). The AGC added gain acts directly in the input gain, to avoid input saturation and improve S/N ratio, so it cannot exceed the input gain range. When MIC and Line-In inputs are selected simultaneously the control is performed on the sum of the two, preserving the balance fixed with input gains. Different values for Attack and Decay constants can be selected, depending on the kind of signal the AGC has to control (i.e. voice, music). The

Attack and Decay time constants are related to the AD data rate (see bits AGCATT and AGCDEL in CR34).

### 4.16 Interrupt request: IRQ pins

On each entity of the STw5098, the interrupt request feature can signal to a control device the occurrence of particular events on each entity. Two control registers are used to choose the behavior of IRQ pin: the first is a Status/Event Register (CR32), where bits can represent the status of an internal function (i.e. a voltage is above or below a threshold) or an event (i.e. a voltage changed crossing a threshold); the second is a Mask Register (CR31) where if a bit in the mask is set to 1 then the corresponding bit in the Status/Event Register can affect IRQ pin status.

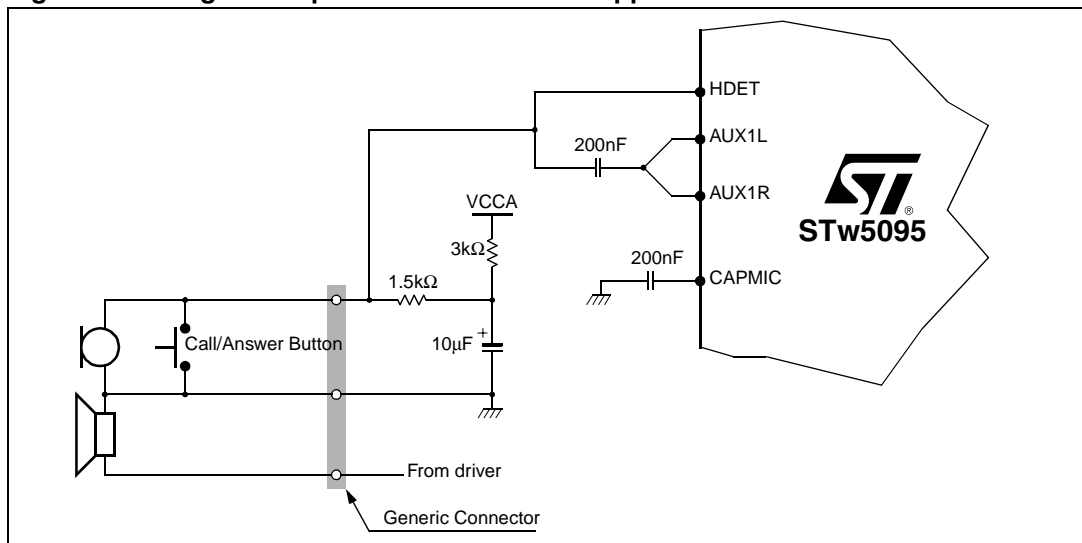
On each entity, the IRQ pin is always active low. At  $V_{CC}$  power up an interrupt request is generated by the Power-On-Reset circuit that sets to 1 bits PORMSK in CR31 and POREV in CR32. After this event the PORMSK bit should be cleared by the user and bit IRQCMOS in CR33 should be set according to the application (open drain or CMOS).

When an IRQ event occurs and SPI control interface is selected with no serial output pin it is still possible to identify the event (and relative status) that generated the interrupt request. This can be done by setting the IRQ mask/enable bits (in CR31) one at the time (with successive writings) and reading the IRQ pin status. A simple example of this is the headset plug-in detection: at first we set bit HSDETMSK=1 in CR31 (with all the other bits set to 0). If there is an interrupt request then we set HSDETMSK=0 and HSDETEN=1, so we can read the HSDET status at IRQ pin. Then we read CR32 to clear its content (even if no data is sent out).

### 4.17 Headset plug-in and push-button detection

Each entity of the STw5098 can detect the plug-in of a microphone connector and the press/release event of a call/answer push-button. An application example can be found below, while specifications can be found in [Section 10.4 on page 64](#).

**Figure 4. Plug-in and push-button detection application note**



## 4.18 Microphone biasing circuits

The Microphone Biasing Circuits can drive mono or stereo microphones and can switch them off when not needed in order to save the current used by the microphone biasing network on each entity. Two bits control the behavior of the microphone bias circuit: MBIAS in CR17 enables the circuit (fixed voltage at MBIAS pin), while bit MBIASPD in CR17 affects the behavior of MBIAS pin when the function is not enabled. In particular when MBIASPD=1 the MBIAS pin is pulled down, otherwise it is left in tristate mode. The specification for the microphone biasing circuits can be found in [Section 10.6 on page 64](#).

## 5 Control registers

### 5.1 Summary

Table 2. Control register summary

CR# (hex)	Description	D7	D6	D5	D4	D3	D2	D1	D0	Def.
CR0 (00h)	Supply & power control #1	POWER UP	ENANA	ENAMCK	ENOSC	ENPLL	ENHSD	A24V	D12V	0000 0000
CR1 (01h)	Power control #2	ENADCL	ENADCR	ENDACL	ENDACR	ENMICL	ENMICR	ENLINL	ENLINR	0000 0000
CR2 (02h)	Power control #3	ENLOL	ENLOR	ENHPL	ENHPR	ENHPVCM	1ENEAR 2ENLS	ENMIXL	ENMIXR	0000 0000
CR3 (03h)	Mic gain left	MICLA(2:0)			MICLG(4:0)				0000 0000	
CR4 (04h)	Mic gain right	MICRA(2:0)			MICRG(4:0)				0000 0000	
CR5 (05h)	Line in gain left	X	X	X	LINLG(4:0)				0000 1001	
CR6 (06h)	Line in gain right	X	X	X	LINRG(4:0)				0000 1001	
CR7 (07h)	LO gain & LS gain	X	LOG(2:0)			1EARG(3:0) 2LSG(3:0)		0000 0011		
CR8 (08h)	HPL gain	X	X	X	HPLG(4:0)				0000 0011	
CR9 (09h)	HPR gain	X	X	X	HPRG(4:0)				0000 0011	
CR10 (0Ah)	DAC digital gain left	X	X	DACLG(5:0)				0000 0000		
CR11 (0Bh)	DAC digital gain right	X	X	DACRG(5:0)				0000 0000		
CR12 (0Ch)	ADC digital gain left	X	X	ADCLG(5:0)				0000 1000		
CR13 (0Dh)	ADC digital gain right	X	X	ADCRG(5:0)				0000 1000		
CR14 (0Eh)	Bass/treble/de-emphasis	DYNC	TREBLE(2:0)			BASS(3:0)			0000 0000	
CR15 (0Fh)	DA to AD mixing gain	X	X	X	DA2ADG(4:0)				0000 0000	
CR16 (10h)	AD to DA mix/sidetone gain	X	X	AD2DAG(5:0)				0000 0000		
CR17 (11h)	Mixer switches & mic bias	MBIAS	M BIASPD	ADMIC	ADLIN	MIXMIC	MIXLIN	MIXDAC	MICLO	0000 0000

Table 2. Control register summary

CR# (hex)	Description	D7	D6	D5	D4	D3	D2	D1	D0	Def.
CR18 (12h)	Input switches	X	IN2VCM	LINMUTE	LINSEL(1:0)		MICMUTE	MICSEL(1:0)		0010 0100
CR19 (13h)	Drivers control	VCML(1:0)		X	MUTELO	MUTEHP	1EARLIM 2LSLIM	1EARSEL(1:0) 2LSSEL(1:0)		0101 1000
CR20 (14h)	DAOCK frequency LSB	DAOCKF(7:0)								0000 0000
CR21 (15h)	DAOCK frequency MSB	DAOCKF(15:8)								0000 0000
CR22 (16h)	DA clock generator control	X	X	DAMAST	DA MASTGEN	END AOCK	DAO CK512	DAPCMF(1:0)		0000 0000
CR23 (17h)	ADOCK frequency LSB	ADOCKF(7:0)								0000 0000
CR24 (18h)	ADOCK frequency MSB	ADOCKF(15:8)								0000 0000
CR25 (19h)	AD Clock generator control	X	X	ADMAST	AD MASTGEN	ENA DOCK	ADO CK512	ADPCMF(1:0)		0000 0000
CR26 (1Ah)	DAC data IF control	X	DAFORM(2:0)			DASPIM	DAWL(2:0)			0000 0000
CR27 (1Bh)	ADC data IF control	ADRTOL	ADFORM2:0)			ADSPIM	ADWL(2:0)			0000 0000
CR28 (1Ch)	DAC&ADC data IF control	AMC KINV	DACKP	DASYNCP	DAMONO	ADCKP	AD SYNCP	ADMONO	ADHIZ	0000 0000
CR29 (1Dh)	Digital filters control	X	DAVOICE	DA96K	RXNH	ADVOICE	AD96K	ADNH	TXNH	0000 0000
CR30 (1Eh)	Soft reset & AMCK range	SWRES	X	X	X	AMCKSIN	CKRANGE(2:0)			0000 0000
CR31 (1Fh)	Interrupt mask	VLSHEN	PUSH BEN	HSDTEN	VLSHMSK	PUSH BMSK	HSDET MSK	OVFMSK	PORMSK	0000 0000
CR32 (20h)	Interrupt status	VLSH	PUSHB	HSDET	VLSHEV	PUSHBEV	HSDETEVEV	OVFEV	POREV	0000 0000
CR33 (21h)	Misc. control	X	X	SPIOHIZ	SPIOSEL(1:0)		IRQCMOS	OVFDA	OVFAD	0000 0000
CR34 (22h)	AGC attack/decay coeff.	AGCATT(3:0)				AGCDEC(3:0)				0000 0000
CR35 (23h)	AGC control	X	ENA GCLIN	ENAG CMIC	AGC RANGE	AGCLEV(3:0)				0000 0000
CR36 (24h)	RESERVED	X	X	X	X	X	X	X	X	0000 0000

Note: X reserved, write zero

**Caution:** In the following [Section 5: Control registers](#), reference to each entity is omitted. Each entity of the STw5098 has the same register set.

## 5.2 Supply and power control

CR# (hex)	Description	D7	D6	D5	D4	D3	D2	D1	D0	Def.
CR0 (00h)	Supply & power control #1	POWER UP	ENANA	ENAMCK	ENOSC	ENPLL	ENHSD	A24V	D12V	0000 0000
CR1 (01h)	Power control #2	ENADCL	ENADCR	ENDACL	ENDACR	ENMICL	ENMICR	ENLINL	ENLINR	0000 0000
CR2 (02h)	Power control #3	ENLOL	ENLOR	ENHPL	ENHPR	ENH PVCM	ENLS	ENMIXL	ENMIXR	0000 0000

**Table 3. CR0 description**

Bits	Name	Val.	CR0 description	Def.
7	POWERUP	1 0	All the enabled analog and digital blocks are in power up All the device is in power down	0
6	ENANA	1 0	The analog blocks can be enabled All the analog blocks are in power down	0
5	ENAMCK	1 0	AMCK clock input pin is enabled AMCK clock input pin is disabled	0
4	ENOSC	1 0	The Internal oscillator is enabled. The analog blocks use oscillator clock The internal oscillator is in power down	0
3	ENPLL	1 0	The PLL is enabled The PLL is in power down	0
2	ENHSD	1 0	The headset plug-in detector is enabled The headset plug-in detector is disabled	0
1	A24V	1 0	Analog supply pins voltage range is $2.4V < V_{CCA} < 2.7V$ Analog supply pins voltage range is $2.7V < V_{CCA} < 3.3V$	0
0	D12V	1 0	Digital I/O pin voltage range is $1.2V < V_{CCIO} < 1.8V$ Digital I/O pin voltage range is $1.71V < V_{CCIO} < V_{CC}$	0

Table 4. CR1 description

Bits	Name	Value	CR1 description	Def.
7	ENADCL	1	The left channel A/D converter is enabled	0
		0	The left channel A/D converter is in power down	
6	ENADCR	1	The right channel A/D converter is enabled	0
		0	The right channel A/D converter is in power down	
5	ENDACL	1	The left channel D/A converter is enabled	0
		0	The left channel D/A converter is in power down	
4	ENDACR	1	The right channel D/A converter is enabled	0
		0	The right channel D/A converter is in power down	
3	ENMICL	1	The left channel microphone preamplifier is enabled	0
		0	The left channel microphone preamplifier is in power down	
2	ENMICR	1	The right channel microphone preamplifier is enabled	0
		0	The right channel microphone preamplifier is in power down	
1	ENLINL	1	The left channel line-in preamplifier is enabled	0
		0	The left channel line-in preamplifier is in power down	
0	ENLINR	1	The right channel line-in preamplifier is enabled	0
		0	The right channel line-in preamplifier is in power down	

Table 5. CR2 description

Bit #	Name	Value	CR2 Description	Def.
7	ENLOL	1	The left channel line out driver is enabled	0
		0	The left channel line out driver is in power down (default)	
6	ENLOR	1	The right channel line out driver is enabled	0
		0	The right channel line out driver is in power down (default)	
5	ENHPL	1	The left channel headphones driver is enabled	0
		0	The left channel headphones driver is in power down (default)	
4	ENHPR	1	The right channel headphones driver is enabled	0
		0	The right channel headphones driver is in power down (default)	
3	ENHPVCM	1	The headphones reference voltage generator is enabled	0
		0	The headphones reference voltage generator is in power down (def)	
2	1ENEAR	1	The 32Ω earphone amplifier is enabled	0
		0	The 32Ω earphone amplifier is in power down (default)	
	2ENLS	1	The 8Ω loudspeaker amplifier is enabled	0
		0	The 8Ω loudspeaker amplifier is in power down (default)	
1	ENMIXL	1	The left channel analog output mixer is enabled	0
		0	The left channel analog output mixer is in power down (default)	
0	ENMIXR	1	The right channel analog output mixer is enabled	0
		0	The right channel analog output mixer is in power down (default)	

### 5.3 Gains

CR# (hex)	Description	D7	D6	D5	D4	D3	D2	D1	D0	Def.
CR3 (03h)	Mic gain left	MICLA(2:0)			MICLG(4:0)				0000 0000	
CR4 (04h)	Mic gain right	MICRA(2:0)			MICRG(4:0)				0000 0000	
CR5 (05h)	Line in gain left	X	X	X	LINLG(4:0)				0000 1001	
CR6 (06h)	Line in gain right	X	X	X	LINRG(4:0)				0000 1001	
CR7 (07h)	LO gain & LS gain	X	LOG(2:0)			LSG(3:0)			0000 0011	
CR8 (08h)	HPL gain	X	X	X	HPLG(4:0)				0000 0011	
CR9 (09h)	HPR gain	X	X	X	HPRG(4:0)				0000 0011	
CR10 (0Ah)	DAC digital gain left	X	X	DACLG(5:0)				0000 0000		
CR11 (0Bh)	DAC digital gain right	X	X	DACRG(5:0)				0000 0000		
CR12 (0Ch)	ADC digital gain left	X	X	ADCLG(5:0)				0000 1000		
CR13 (0Dh)	ADC digital gain right	X	X	ADCRG(5:0)				0000 1000		

**Table 6. CR3 and CR4 description**

Bits	Name CR3 Name CR4	Value	CR3 and CR4 description	Def.
7-5	MICLA(2:0) MICRA(2:0)	000 001 010 ... 110 111	Left (CR3) and right (CR4) channels microphone attenuation 0.0 dB gain (default) -1.5 dB gain -3.0 dB gain ...step 1.5 dB -9.0 dB gain -12.0 dB gain	000
4-0	MICLG(4:0) MICRG(4:0)	00000 00001 00010 ... 11010	Left (CR3) and right (CR4) channels microphone gain 0.0 dB gain (default) 1.5 dB gain 3.0 dB gain ...step 1.5 dB 39.0 dB gain	00000



Table 7. CR5 and CR6 description

Bits	Name CR5 Name CR6	Value	CR5 and CR6 description	Def.
4-0	LINLG(4:0) LINRG(4:0)	00000	Left (CR5) and right (CR6) channels line in gain 18.0 dB gain	01001
		00001	16.0 dB gain	
		00010	14.0 dB gain	
		...	...step 2.0 dB	
		01001	0.0 dB gain (default)	
		...	...step 2.0 dB	
		10011	-20.0 dB gain	

Table 8. CR7 description

Bits	Name	Value	CR7 description	Def.
6-4	LOG(2:0)	000	Left and right channel line out drivers gain Gain to differential output                      Equivalent single-ended gain 18.0 dB gain (default)                      -24.0 dB gain (default)	000
		001	-15.0 dB gain                      -21.0 dB gain	
		010	-12.0 dB gain                      -18.0 dB gain	
		...	...step 3 dB                      ...step 3 dB	
		110	00 dB gain                      -6.0 dB gain	
3-0	1EARG(3:0)	0000	32Ω earphone gain/ 8Ω loudspeaker gain 6.0 dB gain	0011
	2LSG(3:0)	0001	4.0 dB gain	
		0010	2.0 dB gain	
		0011	0.0 dB gain (default)	
		...	...step 2.0 dB	
1111	-24.0 dB gain			

Table 9. CR8 and CR9 description

Bits	Name CR8 Name CR9	Value	CR8 and CR9 description	Def.
4-0	HPLG(4:0) HPRG(4:0)	00000	Left (CR8) and right (CR9) channels headphones driver gain 0.0 dB gain	00011
		00001	-2.0 dB gain	
		00010	-4.0 dB gain	
		00011	-6.0 dB gain (default)	
		...	...step 2.0 dB	
		10100	-40.0 dB gain	

Table 10. CR10 and CR11 description

Bits	Name CR10 Name CR11	Value	CR10 and CR11 description	Def.
5-0	DACLG(5:0) DACRG(5:0)		Left (CR10) and right (CR11) channels DAC digital gain	000000
		000000	0.0 dB gain (default)	
		000001	-1.0 dB gain	
		000010	-2.0 dB gain	
		000011	-3.0 dB gain	
		000100	-4.0 dB gain	
		000101	-5.0 dB gain	
		000110	-6.0 dB gain	
		000111	-7.0 dB gain	
		001000	-8.0 dB gain	
		001001	-9.0 dB gain	
		001010	-10.0 dB gain	
		001011	-11.0 dB gain	
		001100	-12.0 dB gain	
		001101	-13.0 dB gain	
		001110	-14.0 dB gain	
		001111	-15.0 dB gain	
		010000	-16.0 dB gain	
		010001	-17.0 dB gain	
		010010	-18.0 dB gain	
		010011	-20.0 dB gain	
		010100	-22.0 dB gain	
		010101	-24.0 dB gain	
		010110	-26.0 dB gain	
		010111	-28.0 dB gain	
		011000	-30.0 dB gain	
		011001	-32.0 dB gain	
		011010	-34.0 dB gain	
		011011	-36.0 dB gain	
		011100	-38.0 dB gain	
		011101	-41.0 dB gain	
		011110	-44.0 dB gain	
011111	-47.0 dB gain			
100000	-50.0 dB gain			
100001	-53.0 dB gain			
100010	-56.0 dB gain			
100011	-59.0 dB gain			
100100	-65.0 dB gain			
100101	-∞dB gain			

Table 11. CR12 and CR13 description

Bits	Name CR12 Name CR13	Value	CR12 and CR13 description	Def.
5-0	ADCLG(5:0) ACDRG(5:0)		Left (CR12) and right (CR13) channels ADC digital gain	001000
		000000	8.0 dB gain	
		000001	7.0 dB gain	
		000010	6.0 dB gain	
		000011	5.0 dB gain	
		000100	4.0 dB gain	
		000101	3.0 dB gain	
		000110	2.0 dB gain	
		000111	1.0 dB gain	
		001000	0.0 dB gain (default)	
		001001	-1.0 dB gain	
		001010	-2.0 dB gain	
		001011	-3.0 dB gain	
		001100	-4.0 dB gain	
		001101	-5.0 dB gain	
		001110	-6.0 dB gain	
		001111	-7.0 dB gain	
		010000	-8.0 dB gain	
		010001	-9.0 dB gain	
		010010	-10.0 dB gain	
		010011	-11.0 dB gain	
		010100	-12.0 dB gain	
		010101	-14.0 dB gain	
		010110	-16.0 dB gain	
		010111	-18.0 dB gain	
		011000	-20.0 dB gain	
		011001	-22.0 dB gain	
		011010	-24.0 dB gain	
		011011	-26.0 dB gain	
		011100	-28.0 dB gain	
		011101	-30.0 dB gain	
		011110	-33.0 dB gain	
		011111	-36.0 dB gain	
100000	-39.0 dB gain			
100001	-42.0 dB gain			
100010	-45.0 dB gain			
100011	-48.0 dB gain			
100100	-51.0 dB gain			
100101	-57.0 dB gain			
100110	-∞dB gain			

## 5.4 DSP control

CR# (hex)	Description	D7	D6	D5	D4	D3	D2	D1	D0	Def.
CR14 (0Eh)	Bass/treble/de-emphasis	DYNC	TREBLE(2:0)			BASS(3:0)				0000 0000
CR15 (0Fh)	DA to AD mixing gain	X	X	X	DA2ADG(4:0)				0000 0000	
CR16 (10h)	AD to DA mix/sidetone gain	X	X	AD2DAG(5:0)						0000 0000

**Table 12. CR14 description**

Bits	Name	Value	CR14 description	Def.
7	DYNC	1 0	Audio dynamic compression in D/A path is enabled Audio dynamic compression in D/A path is disabled	0
6-4	TREBLE(2:0)	011 010 001 000 111 110 101 100	Treble control in D/A path +6.0 dB treble gain +4.0 dB treble gain +2.0 dB treble gain 0.0 dB treble gain -2.0 dB treble gain -4.0 dB treble gain -6.0 dB treble gain De-emphasis filter enabled	000
3-0	BASS(3:0)	0101 0100 0011 0010 0001 0000 1111 1110 1101 1100 1011	Bass control in D/A path +12.5 dB bass gain +10.0 dB bass gain +7.5 dB bass gain +5.0 dB bass gain +2.5 dB bass gain 0.0 dB bass gain -2.5 dB bass gain -5.0 dB bass gain -7.5 dB bass gain -10.0 dB bass gain -12.5 dB bass gain	0000

Table 13. CR15 description

Bits	Name	Value	CR15 description	Def.
4-0	DA2ADG(4:0)*	00000	DA to AD mixing (Audio filter in D/A and A/D path selected)	00000
			DA to AD mixing disabled (default)	
		00001	+2.0 dB gain	
		00010	0.0 dB gain	
		00011	-2.0 dB gain	
		00100	-4.0 dB gain	
		00101	-6.0 dB gain	
		00110	-8.0 dB gain	
		00111	-10.0 dB gain	
		01000	-12.0 dB gain	
		01001	-14.0 dB gain	
		01010	-16.0 dB gain	
		01011	-18.0 dB gain	
		01100	-20.0 dB gain	
		01101	-22.0 dB gain	
		01110	-24.0 dB gain	
		01111	-26.0 dB gain	
		10000	-28.0 dB gain	
		10001	-30.0 dB gain	
		10010	-32.0 dB gain	
10011	-34.0 dB gain			
10100	-36.0 dB gain			
10101	-38.0 dB gain			
10110	-40.0 dB gain			

\* When Voice filter in D/A or A/D path is selected this function is disabled

Note:

D/A to A/D mixing is performed at AD data rate, so if A/D and D/A rates are different then asynchronous sampling artifacts may occur.

Table 14. CR16 description

Bits	Name	Value	CR16 description	Def.
5-0	AD2DAG(5:0)	000000	AD to DA mixing (sidetone) AD to DA mixing disabled (default)	000000
		000001	-1.0 dB gain	
		000010	-2.0 dB gain	
		000011	-3.0 dB gain	
		000100	-4.0 dB gain	
		000101	-5.0 dB gain	
		000110	-6.0 dB gain	
		000111	-7.0 dB gain	
		001000	-8.0 dB gain	
		001001	-9.0 dB gain	
		001010	-10.0 dB gain	
		001011	-11.0 dB gain	
		001100	-12.0 dB gain	
		001101	-13.0 dB gain	
		001110	-14.0 dB gain	
		001111	-15.0 dB gain	
		010000	-16.0 dB gain	
		010001	-17.0 dB gain	
		010010	-18.0 dB gain	
		010011	-19.0 dB gain	
		010100	-20.0 dB gain	
		010101	-21.0 dB gain	
		010110	-22.0 dB gain	
		010111	-23.0 dB gain	
		011000	-24.0 dB gain	
		011001	-25.0 dB gain	
		011010	-26.0 dB gain	
		011011	-27.0 dB gain	
		011100	-28.0 dB gain	
		011101	-29.0 dB gain	
		011110	-30.0 dB gain	
		011111	-31.0 dB gain	
		100000	-32.0 dB gain	
100001	-33.0 dB gain			
100010	-34.0 dB gain			
100011	-35.0 dB gain			
100100	-36.0 dB gain			
100101	-37.0 dB gain			
100110	-38.0 dB gain			
100111	-39.0 dB gain			
101000	-40.0 dB gain			
101001	-41.0 dB gain			
101010	-42.0 dB gain			

## 5.5 Analog functions

CR# (hex)	Description	D7	D6	D5	D4	D3	D2	D1	D0	Def.
CR17 (11h)	Mixer switches & Mic Bias	MBIAS	MBIASPD	ADMIC	ADLIN	MIXMIC	MIXLIN	MIXDAC	MICLO	0000 0000
CR18 (12h)	Input switches	X	IN2VCM	LINMUTE	LINSEL(1:0)		MICMUTE	MICSEL(1:0)		0010 0100
CR19 (13h)	Drivers control	VCML(1:0)		X	MUTELO	MUTEHP	LSLIM	LSSEL(1:0)		0101 1000

**Table 15. CR17 description**

Bits	Name	Value	CR17 description	Def.
7	MBIAS	1 0	Microphone Bias enabled (2.1V typ at MBIAS pin) Microphone Bias disabled	0
6	MBIASPD	1 0	MBIAS pin is pulled down when microphone bias is disabled MBIAS pin is in high impedance state when microphone Bias is disabled	0
5	ADMIC	1 0	Microphone preamplifiers are connected to AD path Microphone preamplifiers are not connected to AD path	0
4	ADLIN	1 0	Line in preamplifiers are connected to AD path Line in preamplifiers are not connected to AD path	0
3	MIXMIC	1 0	Microphone preamplifiers are connected to mixers Microphone preamplifiers are not connected to mixers	0
2	MIXLIN	1 0	Line in preamplifiers are connected to mixers Line in preamplifiers are not connected to mixers	0
1	MIXDAC	1 0	Stereo DAC path is connected to mixers Stereo DAC path is not connected to mixers	0
0	MICLO	1 0	Microphone preamplifiers are connected to line out drivers Mixers are connected to line out drivers	0

**Table 16. CR18 description**

Bits	Name	Value	CR18 description	Def.
6	IN2VCM	1 0	Unused analog input pins are biased to common mode voltage Unused analog input pins are in high impedance state	0
5	LINMUTE	1 0	Line in preamplifiers are muted Line in preamplifiers are not muted	1
4-3	LINSEL(1:0)	00 01 10 11	Input pins connected to line in preamplifiers (if LINMUTE=0) LINEIN (LINEINL, LINEINR) AUX1 (AUX1L, AUX1R) AUX2 (AUX2LP-AUX2LN, AUX2RP-AUX2RN) AUX3 (AUX3L, AUX3R)	00

Table 16. CR18 description

Bits	Name	Value	CR18 description	Def.
2	MICMUTE	1 0	Microphone preamplifiers are muted Microphone preamplifiers are not muted	1
1-0	MICSEL(1:0)	00 01 10 11	Input pins connected to microphone preamplifiers (if MICMUTE=0) MIC (MICLP-MICLN, MICRP-MICRN) AUX1 (AUX1L, AUX1R) AUX2 (AUX2LP-AUX2LN, AUX2RP-AUX2RN) AUX3 (AUX3L, AUX3R)	00

Table 17. CR19 description

Bits	Name	Value	CR19 Description	Def.
7-6	VCML(1:0)	00 01 10 11	Common mode voltage level for line out and headphones drivers 1.20 V 1.35 V (default) 1.50 V 1.65 V	01
4	MUTELO	1 0	Line out drivers are muted Line out drivers are not muted	1
3	MUTEHP	1 0	Headphones drivers (HP) are muted Headphones drivers (HP) are not muted	1
2	1EARLIM 2LSLIM	1 0	EAR/LS driver gain is limited when $V_{CCLS}$ is above 4.2V typ EAR/LS driver (LS) gain is not limited	0
1-0	1EARSEL(1:0) 2LSSEL(1:0)	00 01 10 11	Mute Loudspeaker driver (LS) is muted Right Right channel mixer only connected to loudspeaker driver Left Left channel mixer only connected to loudspeaker driver Mono (Left + Right)/2 channel mixers connected to loudspeaker driver	00



## 5.6 Digital audio interfaces master mode and clock generators

CR# (hex)	Description	D7	D6	D5	D4	D3	D2	D1	D0	Def.
CR20 (14h)	DAOCK frequency LSB	DAOCKF(7:0)								0000 0000
CR21 (15h)	DAOCK frequency MSB	DAOCKF(15:8)								0000 0000
CR22 (16h)	DA clock generator control	X	X	DAMAST	DA MASTGEN	END OCK	DAO CK512	DAPCMF(1:0)		0000 0000
CR23 (17h)	ADOCK frequency LSB	ADOCKF(7:0)								0000 0000
CR24 (18h)	ADOCK frequency MSB	ADOCKF(15:8)								0000 0000
CR25 (19h)	AD clock generator control	X	X	ADMAST	AD MASTGEN	ENA DOCK	ADO CK512	ADPCMF(1:0)		0000 0000

**Table 18. CR21-20 and CR24-23 description**

Bits	Name CR21-20 Name CR24-23	Value	CR21-20 and CR24-23 Description	Def.
15-0	DAOCKF(15:0) ADOCKF(15:0)	K	<p>The following formulas can be used to obtain the value of K for the desired FS or OCK respectively in the clock generator</p> $K(\text{FS}) = \text{round}\left(2^{25} \frac{\text{FS}}{\text{AMCK} \cdot \text{MCKCOEFF}}\right)$ $K(\text{OCK}) = \text{round}\left(2^{25} \frac{\text{OCK}}{\text{AMCK} \cdot \text{MCKCOEFF} \cdot \text{OSR}}\right)$ <p>FS: Data rate (DA_SYNC or AD_SYNC frequency in master mode)  OCK: Oversampled clock frequency (DA_OCK or AD_OCK)  AMCK: Input master clock frequency  MCKCOEFF: See CR30 for definition  OSR: See bit 2 in CR22 and CR25</p>	0000h

Note: CR21-20 and CR24-23 are meaningful in master mode only.

**Table 19. CR22 and CR25 description**

Bits	Name CR22 (Name CR25)	Value	CR22 and CR25 description	Def.
5	DAMAST (ADMAST)	1 0	DA (AD) Audio interface is in master mode (low impedance output) DA (AD) Audio interface is in slave mode (high impedance input)	0
4	DAMASTGEN (ADMASTGEN)	1 0	DA (AD) Master generator is enabled DA (AD) Master generator is disabled	0
3	ENDAOCK (ENADOCK)	1 0	DA_OCK (AD_OCK) output clock is enabled DA_OCK (AD_OCK) output clock is disabled	0

Table 19. CR22 and CR25 description

Bits	Name CR22 (Name CR25)	Value	CR22 and CR25 description	Def.
2	DAOCK512 (ADOCK512)	1 0	Definition of DA_OSR (AD_OSR) DA_OCK/DA_SYNC (AD_OCK/AD_SYNC) ratio in master mode is 512 da_ock/da_sync (ad_ock/ad_sync) ratio in master mode is 256	0
1-0	DAPCMF(1:0) (ADPCMF(1:0))	00 00 01 10 11 11	DA_CK/DA_SYNC (AD_CK/AD_SYNC) Ratio in PCM master mode - 16 when CR26 DAWL=000 (CR27 ADWL=000) - 32 when CR26 DAWL≠000 (CR27 ADWL≠000) - 64 - 128 - 256 when CR22 DAOCK512=0 (CR25 ADOCK512=0) - 512 when CR22 DAOCK512=1 (CR25 ADOCK512=1)	00

## 5.7 Digital audio interfaces

CR# (hex)	Description	D7	D6	D5	D4	D3	D2	D1	D0	Def.
CR26 (1Ah)	DAC data IF control	X	DAFORM(2:0)			DASPIM	DAWL(2:0)			0000 0000
CR27 (1Bh)	ADC data IF control	ADRTOL	ADFORM2:0)			ADSPIM	ADWL(2:0)			0000 0000
CR28 (1Ch)	DAC&ADC data IF control	AMCKINV	DACKP	DASYNCP	DAMONO	ADCKP	AD SYNCP	ADMONO	ADHIZ	0000 0000

**Table 20. CR26 description**

Bits	Name	Value	CR26 Description	Def.
6-4	DAFORM(2:0)	000	DA audio interface format selection Delayed format (I <sup>2</sup> S compatible)	000
		001	Left aligned format	
		010	Right aligned format	
		011	DSP format	
		100	SPI format	
		111	PCM format (uses left channel)	
3	DASPIM	1	DA interface in SPI mode receives one word for both channels	0
		0	DA interface in SPI mode receives two words (alternated, left channel first)	
2-0	DAWL(2:0)	000	DA interface word length 16 bit	000
		001	18 bit	
		010	20 bit	
		011	24 bit	
		100	32 bit	

**Table 21. CR27 description**

Bits	Name	Value	CR27 description	Def.
7	ADRTOL	1	AD right channel sent to PCM I/F (must set ENADCR=0 in CR1)	0
		0	Normal operation	
6-4	ADFORM(2:0)	000	AD audio interface format selection Delayed format (I <sup>2</sup> S compatible)	000
		001	Left aligned format	
		010	Right aligned format	
		011	DSP format	
		100	SPI format	
		111	PCM format (sends out left channel)	

Table 21. CR27 description (continued)

Bits	Name	Value	CR27 description	Def.
3	ADSPIM	1	AD interface in SPI mode sends one channel (left)	0
		0	AD interface in SPI mode sends two channels (alternated, left first)	
2-0	ADWL(2:0)	000	AD interface word length 16 bit	000
		001	18 bit	
		010	20 bit	
		011	24 bit	
		100	32 bit	

Table 22. CR28 description

Bits	Name	Value	CR28 description	Def.
7	AMCKINV	1	AMCK is inverted	0
		0	AMCK is not inverted	
6	DACKP	1	DA Bit clock pin (DA_CK) polarity is inverted	0
		0	DA Bit clock pin (DA_CK) polarity is not inverted	
5	DASYNCP	1	DSP and PCM formats in DA interface Non delayed format	0
			0	
		1	Delayed, left-aligned, right-aligned and SPI formats in DA interface DA sync pin (DA_SYNC) polarity is inverted	
			0	
4	DAMONO	1	Mono mode: (L+R)/2 from Audio Interface is used on both DAC channels	0
		0	Stereo mode	
3	ADCKP	1	AD Bit clock pin (AD_CK) polarity is inverted	0
		0	AD Bit clock pin (AD_CK) polarity is not inverted	
2	ADSYNCP	1	DSP and PCM formats in AD interface Non delayed format	0
			0	
		1	Delayed, left-aligned, right-aligned and SPI formats in AD interface DA sync pin (DA_SYNC) polarity is inverted	
			0	
1	ADMONO	1	Mono mode: (L+R)/2 from ADC is sent to both channels in the Audio interface	0
		0	Stereo mode	
0	ADHIZ	1	AD data pin (AD_DATA) is in high impedance state when no data is available	0
		0	AD data pin (AD_DATA) is forced to 0 when no data is available	

## 5.8 Digital filters, software reset and master clock control

CR# (hex)	Description	D7	D6	D5	D4	D3	D2	D1	D0	Def.
CR29 (1Dh)	Digital filters control	X	DAVOICE	DA96K	RXNH	ADVOICE	AD96K	ADNH	TXNH	0000 0000
CR30 (1Eh)	Soft reset & AMCK range	SWRES	X	X	X	AMCKSIN	CKRANGE(2:0)			0000 0000

**Table 23. CR29 description**

Bits	Name	Value	CR29 description	Def.
6	DAVOICE	1	DA path voice RX filter is enabled (single channel, left used)	0
		0	DA path voice filters are enabled	
5	DA96K	1	DA path data rate is in the range 88 kHz to 96 kHz	0
		0	DA path data rate is in the range 8 kHz to 48 kHz	
4	RXNH	1	DA path high pass voice RX filter is disabled	0
		0	DA path high pass voice RX filter is enabled (300Hz @ 8kHz rate)	
3	ADVOICE	1	AD path voice TX filter is enabled (single channel, left used)	0
		0	AD path audio filters are enabled	
2	AD96K	1	AD path data rate is in the range 88 kHz to 96 kHz	0
		0	AD path data rate is in the range 8 kHz to 48 kHz	
1	ADNH	1	AD path audio DC filter is disabled	0
		0	AD path audio DC filter is enabled	
0	TXNH	1	AD path high pass voice TX filter is disabled	0
		0	AD path high pass voice TX filter is enabled (300Hz @ 8kHz rate)	

**Table 24. CR30 description**

Bits	Name	Value	CR30 description	Def.	
7	SWRES	1	Software reset: All registers content is reset to the default value	0	
		0	Control Register content is left unchanged		
3	AMCKSIN	1	Signal at AMCK pin is a sinusoid	0	
		0	Signal at AMCK pin is a square wave		
2-0	CKRANGE(2:0)	000	AMCK range	000	
			4.0 MHz to 6.0 MHz		MCKCOEFF
		001	6.0 MHz to 8.0 MHz		8.0
		010	8.0 MHz to 12.0 MHz		6.0
		011	12.0 MHz to 16.0 MHz		4.0
		100	16.0 MHz to 24.0 MHz		3.0
101	24.0 MHz to 32.0 MHz	2.0			
			1.5		

## 5.9 Interrupt control and control interface SPI out mode

CR# (hex)	Description	D7	D6	D5	D4	D3	D2	D1	D0	Def.
CR31 (1Fh)	Interrupt mask	VLSHEN	PUSH BEN	HSDeten	VLSHMSK	PUSH BMSK	HSDet MSK	OVFMSK	PORMSK	0000 0000
CR32 (20h)	Interrupt status	VLSH	PUSHB	HSDet	VLSHEV	PUSHBEV	HSDeteV	OVFEV	POREV	0000 0000
CR33 (21h)	Misc. control	x	X	SPIOHIZ	SPIOSEL(1:0)		IRQCMOS	OVFDA	OVFAD	0000 0000

**Table 25. CR31 description**

Bits	Name	Value	CR31description	Def.
7	VLSHEN	1 0	VLSH status can be seen at IRQ output VLSH status is masked	0
6	PUSHBEN	1 0	PUSHB status can be seen at IRQ output PUSHB status is masked	0
5	HSDeten	1 0	HSDet status can be seen at IRQ output HSDet status is masked	0
4	VLSHMSK	1 0	VLSH event can be seen at IRQ output VLSH event is masked	0
3	PUSHBMSK	1 0	PUSHB event can be seen at IRQ output PUSHB event is masked	0
2	HSDetMSK	1 0	HSDet event can be seen at IRQ output HSDet event is masked	0
1	OVFMSK	1 0	OVF event can be seen at IRQ output OVF event is masked	0
0	PORMSK	1 0	POR event can be seen at IRQ output POR event is masked	0

Note: Value at IRQ pin is:

$$\text{IRQ} = \begin{cases} (1 \text{ or } Z) & \text{when } (\text{CR31} \ \& \ \text{CR32}) = 00 \text{ hex} \\ 0 & \text{when } (\text{CR31} \ \& \ \text{CR32}) \neq 00 \text{ hex} \end{cases}$$

**Table 26. CR32 description**

Bits	Name	Read only	CR32 description	Def.
7	VLSH*	1 0	V <sub>CCLS</sub> is above 4.2 V V <sub>CCLS</sub> is below 4.0 V	0
6	PUSHB*	1 0	Headset Button is pressed Headset Button is released	0
5	HSDet*	1 0	Headset Connector is inserted Headset Connector is not inserted	0

**Table 26. CR32 description (continued)**

Bits	Name	Read only	CR32 description	Def.
4	VLSHEV	1 0	VLSH bit has changed VLSH bit has not changed	0
3	PUSHBEV	1 0	Headset Button Status has changed Headset Button Status has not changed	0
2	HSDETEV	1 0	Headset Connector Status has changed Headset Connector Status has not changed	0
1	OVFEV	1 0	An Audio Data overflow has occurred in DSP No Audio Data overflow has occurred in DSP	0
0	POREV	1 0	Device was reset by power-on-reset Device was not reset by power-on-reset	0

Note: content of bits 4 to 0 in CR32 is cleared after reading, while it is left unchanged if accessed for writing.

\*Bits 7 to 5 represent the status when the Control register is read, not when the event occurred.

**Table 27. CR33 description**

Bits	Name	Val.	CR33 description	Def.
5	SPIOHIZ	1 0	SPI control interface out pin is set to high impedance state when inactive SPI control interface out pin is set to zero when inactive	0
4-3	SPIOSEL(1:0)	00 01 10 11	Out pin selection for SPI control interface No output. Control registers cannot be read in SPI mode SPI output sent to IRQ pin SPI output sent to DA_OCK pin SPI output sent to AD_OCK pin	00
2	IRQCMOS	1 0	IRQ interrupt request pin is set to CMOS (active low) IRQ interrupt request pin is set to pull down	0
1	OVFDA	1 0	An overflow (saturation) occurred in DA path No overflow occurred in DA channel	0
0	OVFAD	1 0	An overflow (saturation) occurred in AD path No overflow occurred in AD channel	0

Note: content of bits 1 to 0 in CR33 is cleared after reading, while it is left unchanged if accessed for writing.

## 5.10 AGC

CR# (hex)	Description	D7	D6	D5	D4	D3	D2	D1	D0	Def.
CR34 (22h)	AGC attack/decay coeff.	AGCATT(3:0)				AGCDEC(3:0)				0000 0000
CR35 (23h)	AGC control	x	ENAG CLIN	ENAG CMIC	AGC RANGE	AGCLEV(3:0)				0000 0000

Table 28. CR 34 description

Bits	Name	Value	CR 34 description		Def.
7-4	AGCATT(3:0)		AGC attack time constant; FS=AD data rate		0000
		0000	Audio filter in AD path 4096 / FS	Voice filter in AD path 8192 / FS	
		0001	2048 / FS	4096 / FS	
		0010	1365 / FS	2731 / FS	
		0011	1024 / FS	2048 / FS	
		0100	683 / FS	1365 / FS	
		0101	512 / FS	1024 / FS	
		0110	341 / FS	683 / FS	
		0111	256 / FS	512 / FS	
		1000	171 / FS	341 / FS	
		1001	128 / FS	256 / FS	
		1010	85 / FS	171 / FS	
		1011	64 / FS	128 / FS	
		1100	43 / FS	85 / FS	
		1101	32 / FS	64 / FS	
		3-0	AGCDEC(3:0)		
0000	Audio filter in AD path 65536 / FS			Voice filter in AD path 131072 / FS	
0001	32768 / FS			65536 / FS	
0010	21845 / FS			43691 / FS	
0011	16384 / FS			32768 / FS	
0100	10923 / FS			21845 / FS	
0101	8192 / FS			16384 / FS	
0110	5461 / FS			10923 / FS	
0111	4096 / FS			8192 / FS	
1000	2731 / FS			5461 / FS	
1001	2048 / FS			4096 / FS	
1010	1365 / FS			2731 / FS	
1011	1024 / FS			2048 / FS	
1100	683 / FS			1365 / FS	
1101	512 / FS			1024 / FS	
1110	341 / FS			683 / FS	
1111	256 / FS	512 / FS			



Table 29. CR 35 description

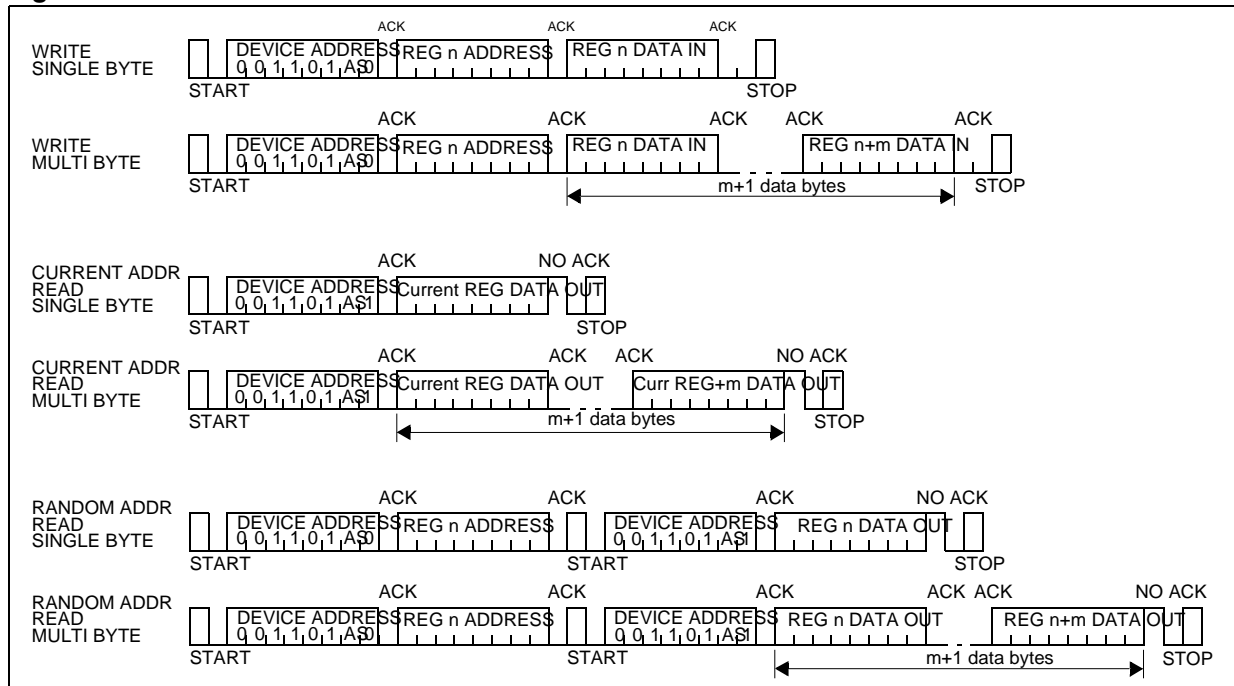
Bits	Name	Value	CR35 description	Def.
6	ENAGCLIN	1 0	AGC control on AD path acts on Line In Gain AGC control on AD path does not act on Line In Gain	0
5	ENAGCMIC	1 0	AGC control on AD path acts on Mic Gain AGC control on AD path does not act on Mic Gain	0
4	AGCRANGE	1 0	AGC action range is -21.0 dB to +21.0 dB AGC action range is -10.5 dB to +10.5 dB	0
3-0	AGCLEV(3:0)	0000 0001 0010 0011 0100 0101 0110 0111 1000 1001	AGC requested output level -30.0 dB gain -30.0 dB gain -27.0 dB gain -24.0 dB gain -21.0 dB gain -18.0 dB gain -15.0 dB gain -12.0 dB gain -9.0 dB gain -6.0 dB gain	0000

## 6 Control interface and master clock

Unless specified, the following description applies to both entities.

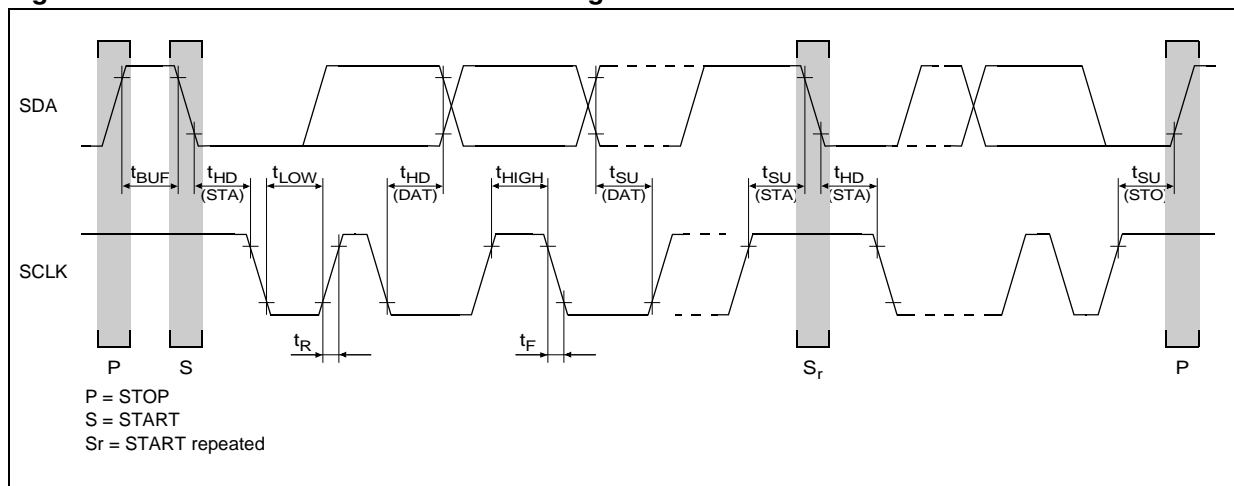
### 6.1 Control interface I<sup>2</sup>C mode

Figure 5. Control interface I<sup>2</sup>C format



Note: CMOD pin tied to GND

Figure 6. Control interface: I<sup>2</sup>C format timing

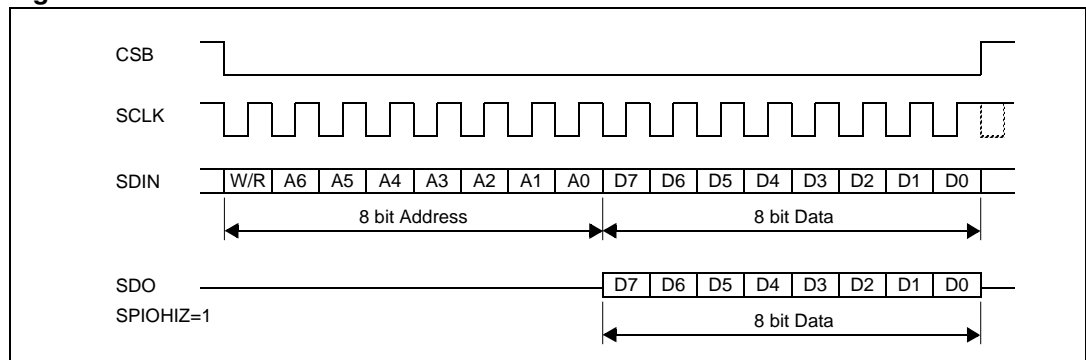


**Table 30. Control interface timing with I<sup>2</sup>C format**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
f <sub>SCL</sub>	Clock frequency				400	kHz
t <sub>HIGH</sub>	Clock pulse width high		600			ns
t <sub>LOW</sub>	Clock pulse width low		1300			ns
t <sub>R</sub>	SDA and SCLK rise time				1000	ns
t <sub>F</sub>	SDA and SCLK fall time				300	ns
t <sub>HD:STA</sub>	Start condition hold time		600			ns
t <sub>SU:STA</sub>	Start condition setup time		600			ns
t <sub>HD:DAT</sub>	Data input hold time		0			ns
t <sub>SU:DAT</sub>	Data input setup time		250			ns
t <sub>SU:STO</sub>	Stop condition setup time		600			ns
t <sub>BUF</sub>	Bus free time		1300			ns

## 6.2 Control interface SPI mode

**Figure 7. Control interface SPI format<sup>(a)</sup>**



a. CMOD pin tied to V<sub>CCIO</sub>; SDO pin position selected with bits SPIOSEL in CR33.

Figure 8. Control interface: SPI format timing

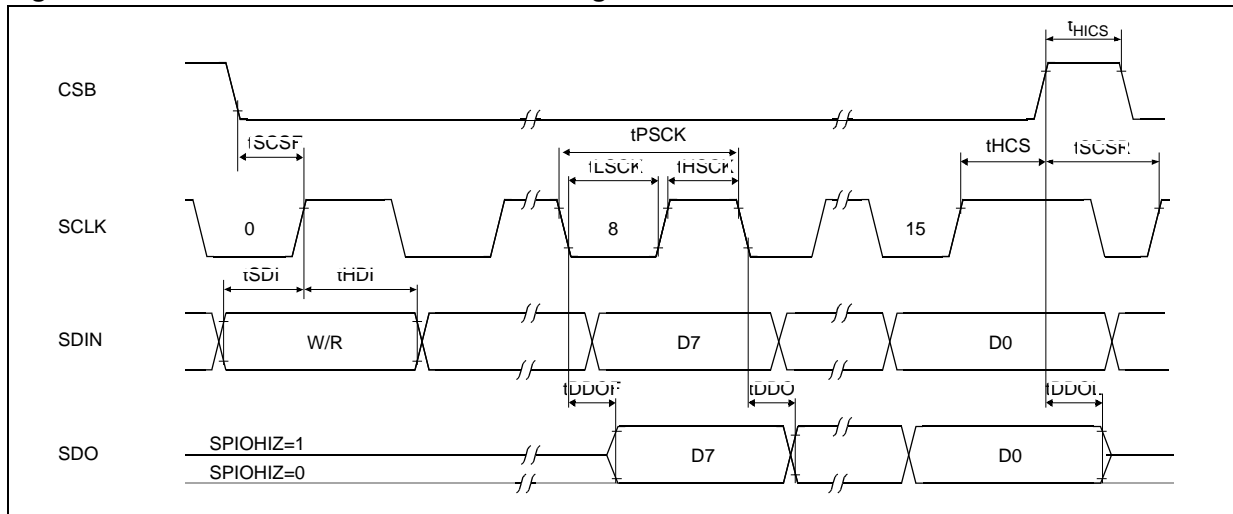


Table 31. Control interface signal timing with SPI format

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$t_{HCS}$	CSB pulse width high		80			ns
$t_{SCSR}$	Setup time CSB rising edge to SCLK rising edge		20			ns
$t_{SCSF}$	Setup time CSB falling edge to SCLK rising edge		20			ns
$t_{HCS}$	Hold time CSB rising edge from SCLK rising edge		20			ns
$t_{SDI}$	Setup time SDIN to SCLK rising edge		20			ns
$t_{HDI}$	Hold time SDIN from SCLK rising edge		20			ns
$t_{DDOF}$	SDO first Delay time from SCLK falling edge				30	ns
$t_{DDO}$	SDO Delay time from SCLK falling edge				20	ns
$t_{DDOL}$	SDO Delay time from CSB rising edge				30	ns
$t_{PCK}$	Period of SCK		100			ns
$t_{HSCK}$	SCK pulse width high	Measured from $V_{IH}$ to $V_{IH}$	40			ns
$t_{LSCK}$	SCK pulse width low	Measured from $V_{IL}$ to $V_{IL}$	40			ns

## 6.3 Master clock timing

Table 32. AMCK timing

Symbol	Parameter	AMCK range	Min.	Typ.	Max.	Unit
$t_{CKDC}$	AMCK duty cycle	4 MHz-8 MHz	45		55	%
		8 MHz-32 MHz	40		60	%

# 7 Audio interfaces

Information included in the following section is valid for both entities.

**Figure 9. Audio interfaces formats: delayed, left and right justified**

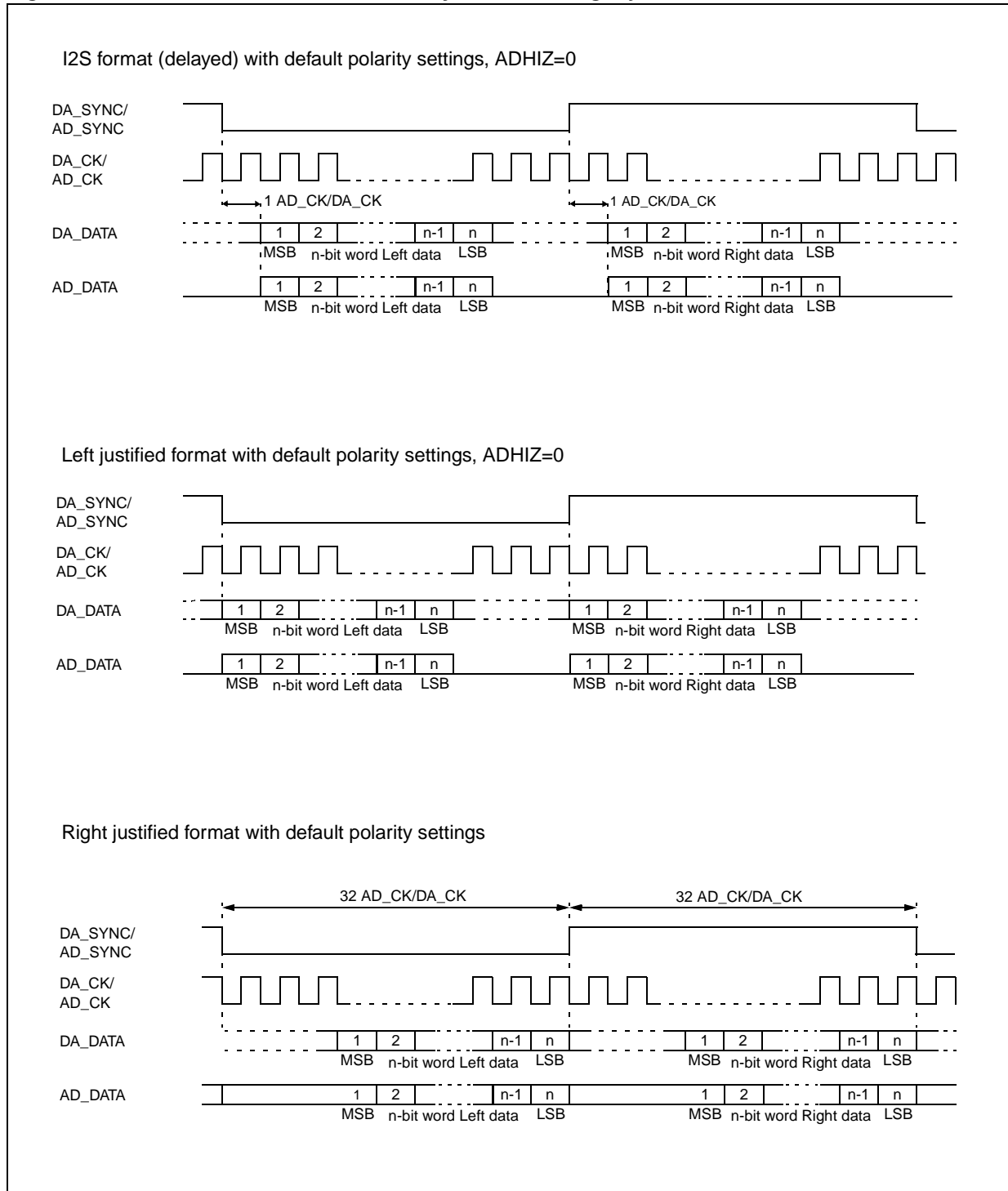


Figure 10. Audio interfaces formats: DSP, SPI and PCM

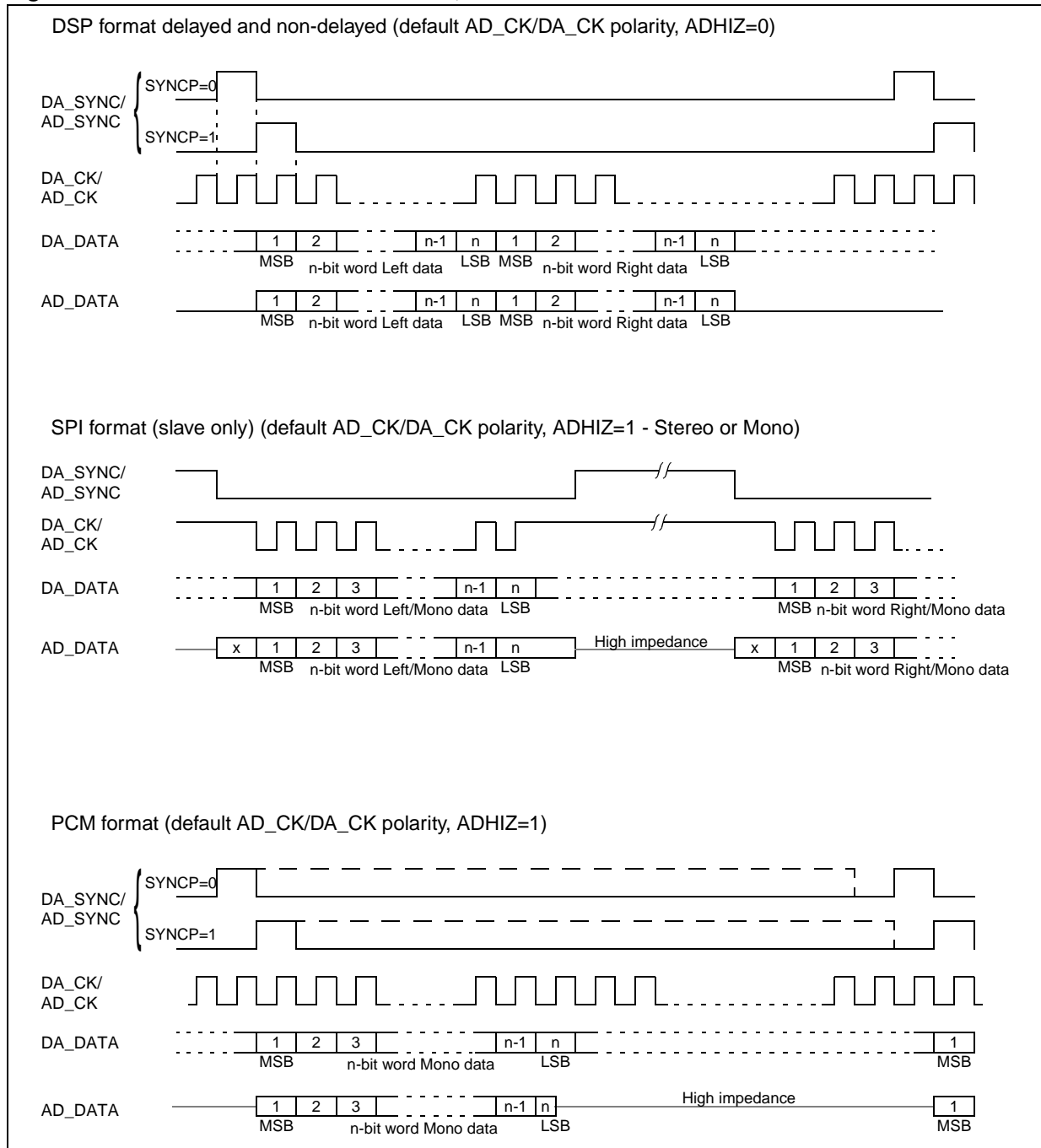


Figure 11. Audio interface timings: master mode

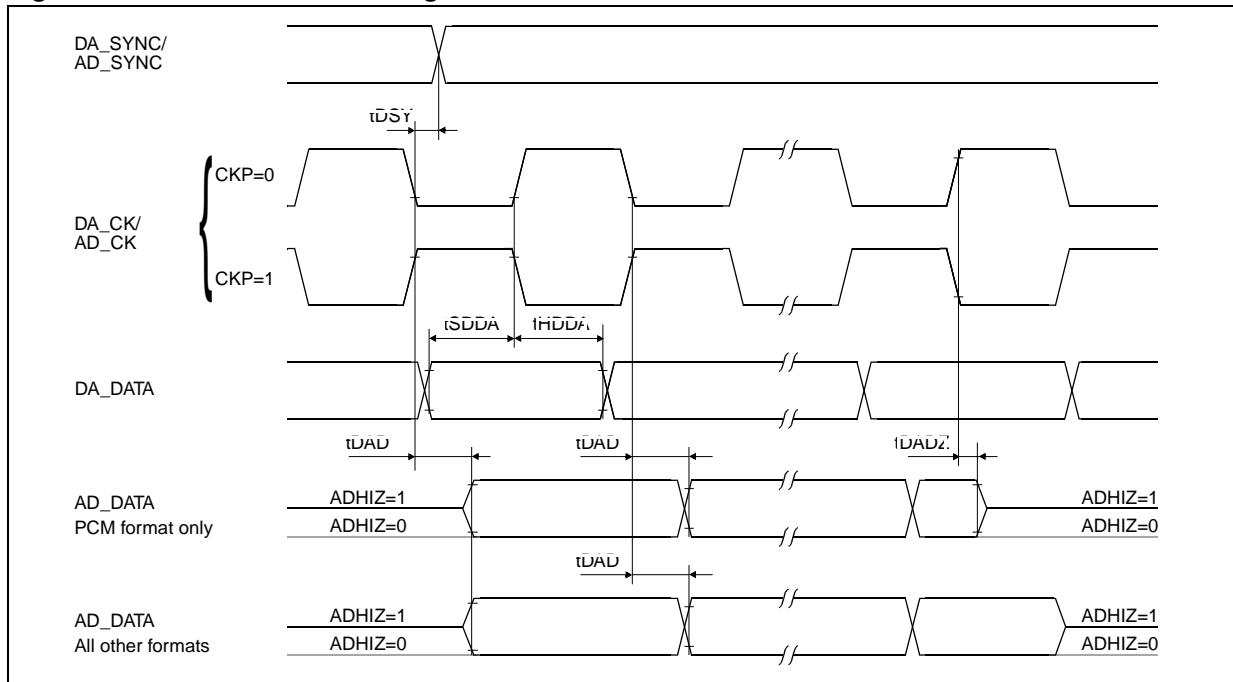


Figure 12. Audio interface timing: slave mode

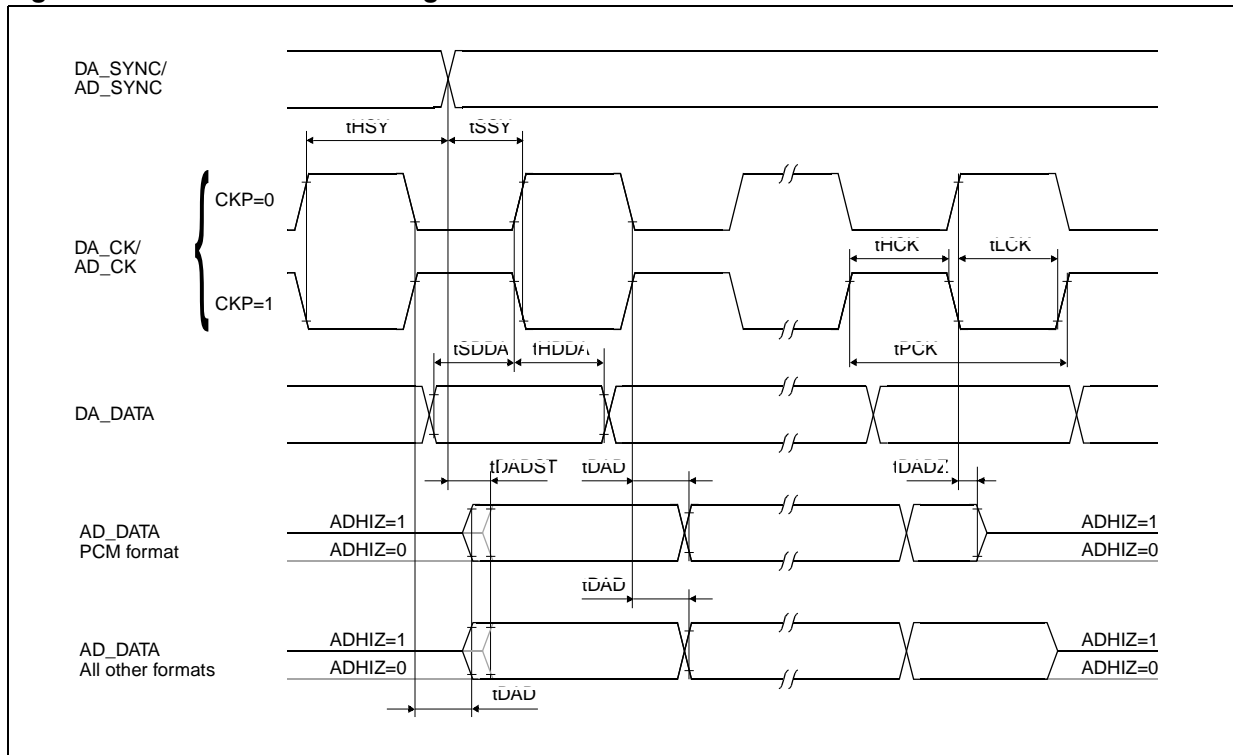




Table 33. Audio interface signal timings

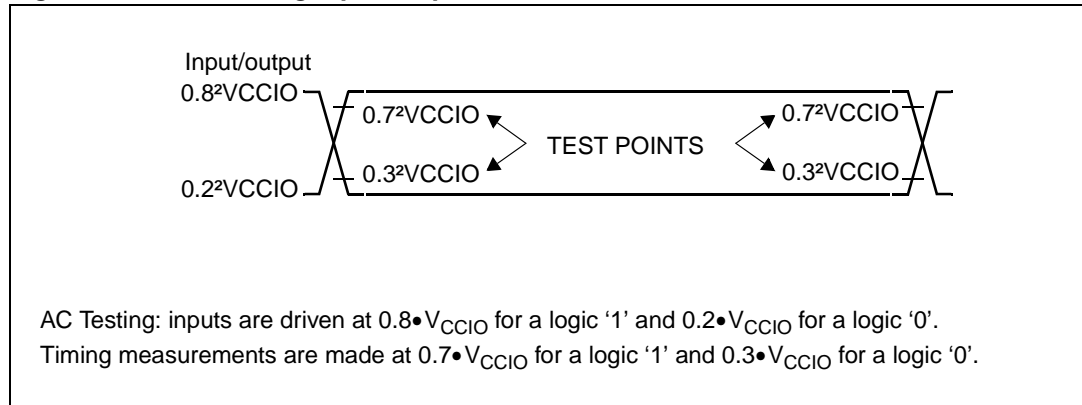
Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$t_{DSY}$	Delay of AD_SYNC/DA_SYNC edge from AD_CK/DA_CK active edge	Master Mode			10	ns
$t_{SDDA}$	Setup time DA_DATA to DA_CK active edge		10			ns
$t_{HDDA}$	Hold time DA_DATA from DA_CK active edge		10			ns
$t_{DAD}$	Delay of AD_DATA edge from AD_CK active edge				30	ns
$t_{DADST}$	Delay of the first AD_DATA edge from AD_SYNC active edge	AD_SYNC active edge comes after AD_CK active edge			30	ns
$t_{DADZ}$	Delay of AD_DATA high impedance from AD_SYNC inactive edge	PCM format	10		50	ns
$t_{SSY}$	Setup time AD_SYNC/DA_SYNC to AD_CK/DA_CK active edge	Slave Mode	20			ns
$t_{HSY}$	Hold time AD_SYNC/DA_SYNC from AD_CK/DA_CK active edge	Slave Mode	20			ns
$t_{PCK}$	Period of AD_CK/DA_CK	Slave Mode	100			ns
$t_{HCK}$	AD_CK/DA_CK pulse width high	Measured from $V_{IH}$ to $V_{IH}$	40			ns
$t_{LCK}$	AD_CK/DA_CK pulse width low	Measured from $V_{IL}$ to $V_{IL}$	40			ns

## 8 Timing specifications

Information included in this section is valid for both entities.

Unless otherwise specified,  $V_{CCIO} = 1.71V$  to  $2.7V$ ,  $T_{amb} = -30^{\circ}C$  to  $85^{\circ}C$ , max capacitive load  $20\text{ pF}$ ; typical characteristics are specified at  $V_{CCIO} = 2.4\text{ V}$ ,  $T_{amb} = 25^{\circ}C$ ; all signals are referenced to GND, see Note below figure for timing definitions.

**Figure 13. A.C. testing input-output waveform**



- Note:** A signal is valid if it is above  $V_{IH}$  or below  $V_{IL}$  and invalid if it is between  $V_{IL}$  and  $V_{IH}$ . For the purpose of this specification the following conditions apply (see [Figure 13](#) above):
- All input signal are defined as:  $V_{IL} = 0.2 \cdot V_{CCIO}$ ,  $V_{IH} = 0.8 \cdot V_{CCIO}$ ,  $t_R < 10ns$ ,  $t_F < 10ns$ .
  - Delay times are measured from the inputs signal valid to the output signal valid.
  - Setup times are measured from the data input valid to the clock input invalid.
  - Hold times are measured from the clock signal valid to the data input invalid.

**Note:** All timing specifications subject to change.

## 9 Operative ranges

### 9.1 Absolute maximum ratings

**Table 34. Absolute maximum ratings**

Parameter	Value	Unit	
$V_{CC}$ or $V_{CCIO}$ to GND	-0.5 to 3.6	V	
$V_{CCA}$ or $V_{CCP}$ to GND	-0.5 to 5	V	
$V_{CCLS}$ to GND	-0.5 to 7	V	
Voltage at analog inputs ( $V_{CCA} \leq 3.3V$ )	GND-0.5 to $V_{CCA}+0.5$	V	
Maximum power delivered to the load from LSP/N	500	mW	
Peak current at HPR,HPL	100	mA	
Current at $V_{CCP}$ , $V_{CCLS}$ , GNDP	350	mA	
Current at any digital output	50	mA	
Voltage at any digital input ( $V_{CCIO} \leq 2.7V$ ); limited at $\pm 50mA$	GND-0.5 to $V_{CCIO}+0.5$	V	
Storage temperature range	-65 to 150	°C	
Operating temperature range <sup>(1)</sup>	-30 to 85	°C	
Electrostatic discharge voltage (Vesd)	Human body model <sup>(2)</sup>	-2 to +2	kV
	Charge device model <sup>(3)</sup>	-500 to +500	V

1. in some operating conditions the temperature can be limited to 70 °C. See loudspeaker driver description from [Section 4.10](#) for details.
2. HBM tests have been performed in compliance with JESD22-A114-B and ESD STM 5.1-2001.HBM
3. CDM tests have been performed in compliance with CDM ANSI-ESDSTM5.3.1-1999

### 9.2 Operative supply voltage

**Table 35. Operative supply voltage**

Symbol	Parameter	Condition	Min.	Max.	Unit
$V_{CC}$	Digital supply		1.71	2.7	V
$V_{CCA}$	Analog supply Note: $V_{CCA} \geq V_{CC}$	A24V=0 (bit 1 in CR0)	2.7	3.3	V
		A24V=1 (bit 1 in CR0)	2.4	2.7	V
$V_{CCIO}$	Digital I/O supply	D12V=0 (bit 0 in CR0)	1.71	$V_{CC}$	V
		D12V=1 (bit 0 in CR0)	1.2	1.8	V
$V_{CCP}$	Stereo power drivers supply		$V_{CCA}$	3.3	V
$V_{CCLS}$	Mono power driver supply		$V_{CCA}$	5.5	V
$V_G$	Single supply voltage range	$V_{CC}=V_{CCA}=V_{CCIO}=V_{CCP}=V_{CCLS}$ A24V=1 (bit 1 in CR0)	2.4	2.7	V

### 9.3 Power dissipation

Unless otherwise specified,  $V_{CCP} = V_{CCLS} = V_{CCA} = 2.7V$  to  $3.3V$ ,  $V_{CCIO} = V_{CC} = 1.71V$  to  $2.7V$ ,  $T_{amb} = -30^{\circ}C$  to  $85^{\circ}C$ , all analog outputs not loaded; typical characteristics are specified at  $V_{CCIO} = V_{CC} = 1.8V$ ,  $V_{CCP} = V_{CCLS} = V_{CCA} = 2.7V$ ,  $T_{amb} = 25^{\circ}C$ .

**Table 36. Power dissipation**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
POFF	Power Down Dissipation	No Master Clock AMCK=13MHz		0.8		$\mu W$
				5.8		$\mu W$
PAD	Stereo ADC power			52.6		mW
PDA	Stereo DAC power			46.6		mW
PDAAD	Stereo ADC+DAC power			93.8		mW
PAA	Stereo Analog Path power			27.6		mW

### 9.4 Typical power dissipation by entity

$T_{amb} = 25^{\circ}C$ ; Analog Supply:  $V_{CCP} = V_{CCLS} = V_{CCA} = 2.7V$ ;  
digital supply:  $V_{CCIO} = V_{CC} = 1.8V$ .  
Full scale signal in every path,  $20k\Omega$  load at analog outputs.

#### No master clock

**Table 37. Typical power dissipation, no master clock**

N.	Function	CR0-CR2 setting	Other settings	Supply	Current	Power
1	Power Down	CR0=0x00 CR1=0x00 CR2=0x00		Analog: Digital: <b>Total:</b>	0.02 $\mu A$ 0.20 $\mu A$	0.05 $\mu W$ 0.36 $\mu W$ <b>0.41 <math>\mu W</math></b>
2	Stereo analog path (Mic-LO)	CR0=0xD0 CR1=0x0C CR2=0xC0	MICLO=1 MICSEL=2	Analog: Digital: <b>Total:</b>	4.3 mA 2.0 $\mu A$	11.6 mW 0.0 mW <b>11.6 mW</b>
3	Stereo analog path (Mic-Mixer-LO)	CR0=0xD0; CR1=0x0C; CR2=0xC3	MIXMIC=1 MICSEL=2	Analog: Digital: <b>Total:</b>	5.4 mA 2.0 $\mu A$	14.6 mW 0.0 mW <b>14.6 mW</b>

## Master clock AMCK = 13 MHz

Table 38. Typical power dissipation with master clock AMCK = 13 MHz

N.	Function	CR0-CR2 setting	Other settings	Supply	Current	Power
4	Power Down	CR0=0x00 CR1=0x00 CR2=0x00		Analog: Digital: <b>Total:</b>	0.02 $\mu$ A 2.20 $\mu$ A	0.05 $\mu$ W 3.96 $\mu$ W <b>4.01 <math>\mu</math>W</b>
5	Stereo ADC	CR0=0xE8 CR1=0xCC CR2=0x00	MICSEL=1 ADMIC=1	Analog: Digital: <b>Total:</b>	7.9 mA 2.8 mA	21.3 mW 5.0 mW <b>26.3 mW</b>
6	Stereo DAC	CR0=0xE8 CR1=0x30 CR2=0x33	MIXDAC=1	Analog: Digital: <b>Total:</b>	6.1 mA 3.8 mA	16.5 mW 6.8 mW <b>23.3 mW</b>
7	Stereo analog path (Mic-LO)	CR0=0xE8 CR1=0x0C CR2=0xC0	MICLO=1 MICSEL=2	Analog: Digital: <b>Total:</b>	4.8 mA 0.8 mA	13.0 mW 1.4 mW <b>13.8 mW</b>
8	Stereo ADC Stereo DAC	CR0=0xE8 CR1=0xFC CR2=0x33	MICSEL=2 ADMIC=1 MIXDAC=1	Analog: Digital: <b>Total:</b>	13.5 mA 5.8 mA	36.5 mW 10.4 mW <b>46.9 mW</b>
9	Stereo ADC Stereo DAC Stereo analog path	CR0=0xE8 CR1=0xFF CR2=0xF3	LINSEL=2; MICSEL=2 ADLIN=1; MIXDAC=1 MICLO=1	Analog: Digital: <b>Total:</b>	15.2 mA 5.8 mA	41.0 mW 10.4 mW <b>51.4 mW</b>
10	Voice TX+RX	CR0=0xE8 CR1=0xA8 CR2=0x06	MICSEL=2; LSMODE=2 ADMIC=1 MIXDAC=1 ADVOICE=1 DAVOICE=1	$V_{CCA}, V_{CCP}$ : $V_{CCLs}$ : Digital <b>Total:</b>	6.8 mA 1.3 mA 2.5 mA	18.4 mW 5.5 mW 4.5 mW <b>28.4 mW</b>

## 10 Electrical characteristics

Unless otherwise specified,  $V_{CCIO} = 1.71V$  to  $2.7V$ ,  $T_{amb} = -30^{\circ}C$  to  $85^{\circ}C$ ; typical characteristic are specified at  $V_{CCIO} = 2.0V$ ,  $T_{amb} = 25^{\circ}C$ ; all signals are referenced to GND.

### 10.1 Digital interfaces

**Table 39. Digital interfaces specifications**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$V_{IL}$	Input low voltage	All digital inputs	DC		$0.3 \cdot V_{CCIO}$	V
			AC		$0.2 \cdot V_{CCIO}$	V
$V_{IH}$	Input high voltage	All digital inputs,	DC	$0.7 \cdot V_{CCIO}$		V
			AC	$0.8 \cdot V_{CCIO}$		V
$V_{OL}$	Output low voltage	All digital outputs	$I_L = 10\mu A$		0.1	V
			$I_L = 2\mu A$		0.4	V
$V_{OH}$	Output high voltage	All digital outputs	$I_L = 10\mu A$	$V_{CCIO}-0.1$		V
			$I_L = 2\mu A$	$V_{CCIO}-0.4$		V
$I_{IL}$	Input low current	Any digital input, GND < $V_{IN}$ < $V_{IL}$	-1		1	$\mu A$
$I_{IH}$	Input high current	Any digital input, $V_{IH} < V_{IN} < V_{CCIO}$	-1		1	$\mu A$
$I_{OZ}$	Output current in high impedance (Tristate)	Tristate outputs	-1		1	$\mu A$

Note: See [Figure 13: A.C. testing input-output waveform on page 58](#).

### 10.2 AMCK with sinusoid input

**Table 40. AMCK with sinusoid input specifications**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$C_{AMCK}$	Minimum External Capacitance	AMCKSIN=1, see CR30	100			pF
$V_{AMCK}$	AMCK sinusoidal voltage swing	AMCKSIN=1, see CR30	0.5		$V_{CCIO}$	$V_{PP}$

## 10.3 Analog interfaces

Information below is for each entity.

**Table 41. Analog interface specifications**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$I_{MIC}$	MIC input leakage	$GND < V_{MIC} < V_{CCA}$	-100		+100	$\mu A$
$R_{MIC}$	MIC input resistance		30	50		$k\Omega$
$R_{LIN}$	Line in input resistance		30			$k\Omega$
$R_{LHP}$	Headphones (HP) drivers load resistance	HPL, HPR to GNDP or VCMHP	14.4	16/32		$\Omega$
$R_{LEAR}$	Earphone (EAR) drivers load resistance	1 EARP to 1EARN	30	32		$\Omega$
$R_{LLS}$	Loudspeaker (LS) drivers load resistance	2LSP to 2LSN	6.4	8		$\Omega$
$C_{LHP}$	Headphones (HP) drivers load capacitance	HPL, HPR to GNDP or VCMHP			50 50*	pF nF
$C_{LEAR}$	Earphone (EAR) drivers load capacitance	1 EARP to 1EARN			50 50*	pF nF
$C_{LLS}$	Loudspeaker (LS) drivers load capacitance	2LSP to 2LSN			50 50*	pF nF
$V_{OFFLS}$	Differential offset voltage at 2LSP, 2LSN	$R_L = 50\Omega$	-50		+50	mV
$V_{OFFEAR}$	Differential offset voltage at 1EARP, 1EARN	$R_L = 50\Omega$	-50		+50	mV
$R_{LOL}$	Line out (OL) diff./single-ended driver load resistance	OLP/ORP to OLN/ORN or OLP/ORP to GND (decoupled)	1			$k\Omega$

\* with series resistor

## 10.4 Headset plug-in and push-button detector

Information below is for each entity.

**Table 42. Headset plug-in and push-button detector specifications**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
HD <sub>VL</sub>	Plug-in detected	Voltage at HDET			V <sub>CCA</sub> -1	V
HD <sub>VH</sub>	Plug-in undetected	Voltage at HDET	V <sub>CCA</sub> -0.5			V
HD <sub>H</sub>	Plug-in detector hysteresis			100		mV
PB <sub>VL</sub>	Push-button pressed	Voltage at HDET			0.5	V
PB <sub>VH</sub>	Push-button released	Voltage at HDET	1			V
PB <sub>D</sub>	Push-button de-bounce time		15		50	ms

## 10.5 Microphone bias

Information below is for each entity.

**Table 43. Microphone bias specifications**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
V <sub>MBIAS</sub>	MBIAS output voltage		1.95	2.1	2.25	V
I <sub>MBIAS</sub>	MBIAS output current	From MBIAS to ground			1.1	mA
R <sub>MBIAS</sub>	MBIAS output load		3.5			kΩ
C <sub>MBIAS</sub>	MBIAS output capacitance				150	pF
PSR <sub>MB4</sub> PSR <sub>MB20</sub>	MBIAS power supply rejection	f<4kHz f<20kHz	60 50			dB dB

## 10.6 Power supply rejection ratio

**Table 44. Power supply rejection ratio specifications**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
PSR <sub>L20</sub> PSR <sub>L200</sub>	PSRR V <sub>CCLS</sub>	Each output (LSP, LSN) f<20kHz f<200kHz		65 47		dB dB
PSR <sub>PH</sub> PSR <sub>POS</sub> PSR <sub>POD</sub>	PSRR V <sub>CCP</sub>	Headphones f<20kHz Line out single ended f<20kHz Line out differential f<20kHz		65 65 65		dB dB dB
PSR <sub>AM</sub> PSR <sub>AL</sub>	PSRR V <sub>CCA</sub>	Mic input f<20kHz Line In f<20kHz		50 50		dB dB



## 10.7 LS and EAR gain limiter

Information below is for each entity.

**Table 45. LS and EAR gain limiter**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
VLS <sub>LIMH</sub>	High voltage at V <sub>CCLS</sub> (VLSH=1)	V <sub>CCLS</sub> raising		4.2		V
VLS <sub>LIML</sub>	Low voltage at V <sub>CCLS</sub> (VLSH=0)	V <sub>CCLS</sub> falling		4.0		V
VLS <sub>LIMD</sub>	V <sub>CCLS</sub> Hysteresis			200		mV

Note: See CR32 for VLSH definition. See Loudspeaker driver description in [Section 4.10](#) for details.

# 11 Analog input/output operative ranges

Information included in this section applies to both entities.

## 11.1 Analog levels

**Table 46. Reference full scale analog levels**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
	0dBFS level	$2.7V < V_{CCA} < 3.3V$		12 4		$\text{dBV}_{pp}$ $V_{pp}$
	0dBFS level low voltage mode	$2.4V < V_{CCA} < 2.7V$		10 3.18		$\text{dBV}_{pp}$ $V_{pp}$

## 11.2 Microphone input levels

Analog supply range:  $2.7V < V_{CCA} < 3.3V$

**Table 47. Microphone input levels, absolute levels at pins connected to preamplifiers**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
	Overload level, single ended	MIC gain = 0 to 6dB		707 2 -6		$\text{mV}_{RMS}$ $V_{pp}$ dBFS
	Overload level, single ended, versus MIC gain	MIC gain > 6dB	-(MIC_Gain)			dBFS
	Overload level, differential	MIC gain = 0dB		1.41 4 0		$\text{mV}_{RMS}$ $V_{pp}$ dBFS
	Overload level, differential, versus MIC gain	MIC gain > 0dB	-(MIC_Gain)			dBFS

Note: When  $2.4V < V_{CCA} < 2.7V$ , voltage values are reduced by 2dB.

**Table 48. Microphone input levels, absolute levels at pins connected to the line-in amplifiers**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
	Overload level, single ended	Line in gain from -20dB to 6dB		707 2 -6		$\text{mV}_{RMS}$ $V_{pp}$ dBFS
	Overload level (single ended) versus line in gain	Line in gain > 6dB	-(Line_In_Gain)			dBFS
	Overload level (differential)	Line in gain from -20dB to 0dB		1.41 4 0		$\text{mV}_{RMS}$ $V_{pp}$ dBFS

**Table 48. Microphone input levels, absolute levels at pins connected to the line-in amplifiers**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
	Overload level (differential) versus line in gain	Line in gain > 0dB		-(Line_In_Gain)		dBFS

Note: When  $2.4\text{ V} < V_{CCA} < 2.7\text{ V}$ , the values are reduced by 2dB

### 11.3 Line output levels

Analog supply range:  $2.7\text{ V} < V_{CCA} < 3.3\text{ V}$

**Table 49. Absolute levels at OLP/OLN, ORP/ORN**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
	Output level, single ended	0 dB gain Full scale digital input		707 2 -6		$mV_{RMS}$ $V_{pp}$ dBFS
	Output level, differential	0 dB gain Full scale digital input		1.41 4 0		$mV_{RMS}$ $V_{pp}$ dBFS

Note: When  $2.4\text{ V} < V_{CCA} < 2.7\text{ V}$ , the values are reduced by 2dB

### 11.4 Power output levels HP

Analog supply range:  $2.7\text{ V} < V_{CCA} < 3.3\text{ V}$

**Table 50. Absolute levels at HPL - HPR**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
	Output level	-6dB gain Full scale digital input		707 2 -6		$mV_{RMS}$ $V_{pp}$ dBFS
	Max output power <sup>(1)</sup>	16 $\Omega$ load $V_{CCP} > 3.2\text{ V}$	40			mW

1. In some operating conditions the maximum output power can be limited. See "[Section 9.1: Absolute maximum ratings](#)" and "loudspeaker driver" description from [Section 4.10: Analog output drivers](#) for details.

Note: When  $2.4\text{ V} < V_{CCA} < 2.7\text{ V}$ , the values are reduced by 2dB

### 11.5 Power output levels LS and EAR

Analog supply range:  $2.7\text{ V} < V_{CCA} < 3.3\text{ V}$

Table 51. Absolute levels at 1EARP-1EARN and 2LSP - 2LSN

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
	Output level	0 dB gain Full scale digital input		1.41 4 0		$V_{RMS}$ $V_{pp}$ dBFS
	Max EAR output power	32 $\Omega$ load $V_{CCLS} > 4V$	125			mW
	Max LS output power <sup>(1)</sup>	8 $\Omega$ load $V_{CCLS} > 4V$	500			mW

1. In some operating conditions the maximum output power can be limited. See "[Section 9.1: Absolute maximum ratings](#)" and "loudspeaker driver" description from [Section 4.10: Analog output drivers](#) for details.

Note: When  $2.4 V < V_{CCA} < 2.7 V$ , the values are reduced by 2dB

## 12 Stereo audio ADC specifications

Information included in this section applies to both entities. Typical measures at  $V_{CCA}=V_{CCP}=V_{CCLS}=2.7V$ ;  $V_{CCIO}=V_{CC}=1.8V$ ;  $T_{amb}=25^{\circ}C$ ; 13 MHz AMCK

**Table 52. Stereo audio ADC specifications**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
ADN	Resolution				20	Bits
ADDRM ADDRLI	Dynamic range	20Hz to 20kHz, A-weighted Measured at -60dBFS MIC input, 21dB gain Line-In, 0dB gain	87 89	91 93		dB dB
ADSNA ADSN	Signal to noise ratio	Max level at MIC input, 21dB gain A-weighted Unweighted (20 Hz to 20 kHz)		90 86		dB dB
	Input referred ADC noise	A-weighted Mic input 0dB gain Mic input 21dB gain Mic input 39dB gain Line in input 0dB gain Line in input 18dB gain		37 3.3 1.9 30 7.5		$\mu V$ $\mu V$ $\mu V$ $\mu V$ $\mu V$
ADTHD	Total harmonic distortion	Max level at MIC input, 21dB gain		0.001	0.003	%
	Deviation from linear phase	Measurement bandwidth 20Hz to 20kHz, $F_s=48kHz$ . Combined digital and analog filter characteristics			1	Deg
ADf <sub>PB</sub>	Passband	Combined digital and analog filter characteristics AD96K=0	0		0.45Fs	kHz
	Passband ripple	Combined digital and analog filter characteristics AD96K=0			0.2	dB
ADf <sub>SB</sub>	Stopband	Combined digital and analog filter characteristics AD96K=0	0.55Fs			kHz
	Stopband Attenuation	Measurement bandwidth up to 3.45Fs. Combined digital and analog filter characteristics, AD96K=0	60			dB
ADt <sub>gd</sub>	Group delay	Audio filters, 96kHz FS Audio filters, 48kHz FS Audio filters, 8kHz FS		0.11 0.4 2.6		ms ms ms
	Interchannel isolation			90		dB
	Interchannel gain mismatch				0.2	dB
	Gain error				0.5	dB

Note: When  $2.4V < V_{CCA} < 2.7V$ , the values are reduced by 2dB

## 13 Stereo audio DAC specifications

Information included in this section applies to both entities.

Typical measures at  $V_{CCA}=V_{CCP}=V_{CCLs}=2.7V$ ;  $V_{CCIO}=V_{CC}=1.8V$ ;  $T_{amb}=25^{\circ}C$ ; 13MHz AMCK

**Table 53. Stereo audio DAC specifications**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit		
DAN	Resolution				20	Bits		
DADR	Dynamic range	20Hz to 20kHz, A-weighted. Measured at -60dBFS	90	95		dB		
		Differential line out					93	dB
		Single-ended line out					94	dB
		HPL/HPR to GND or VCMHP LSP-LSN					94	dB
DASNA DASN	Signal to noise ratio	2V <sub>pp</sub> output HPL, HPR gain set to -6dB, 16Ω load		94		dB		
		A-weighted Unweighted (20 Hz to 20 kHz)					90	dB
DATHDL	Total harmonic distortion Worst case load	2V <sub>pp</sub> output HPL, HPR gain set to -6dB, 16Ω load		0.02	0.04	%		
DATHD	Total harmonic distortion	2V <sub>pp</sub> output, HPL, HPR gain set to -6dB, 1kΩ load		0.004		%		
	Deviation from linear phase	Measurement bandwidth 20Hz to 20kHz, F <sub>s</sub> = 48kHz. Combined digital and analog filter characteristics			1	Deg		
DA <sub>fPB</sub>	Passband	Combined digital and analog filter characteristics, DA96K=0	0		0.45F <sub>s</sub>	kHz		
	Passband ripple	Combined digital and analog filter characteristics, DA96K=0			0.2	dB		
DA <sub>fSB</sub>	Stopband	Combined digital and analog filter characteristics, DA96K=0	0.55F <sub>s</sub>			kHz		
	Stopband attenuation	Measurement bandwidth up to 3.45F <sub>s</sub> . Combined digital and analog filter characteristics, DA96K=0	50			dB		
TSF	Transient suppression filter cut-off frequency		15		23	Hz		
	Out of band noise	Measurement bandwidth 20 kHz to 100 kHz. Zero input signal		-85		dBr		

Table 53. Stereo audio DAC specifications (continued)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
DA <sub>tgd</sub>	Group delay	Audio filters, 96kHz FS		0.09		ms
		Audio filters, 48kHz FS		0.4		ms
		Audio filters, 8kHz FS		2.6		ms
	Interchannel isolation	2Vpp output HPR, HPL unloaded		100		dB
		HPR, HPL with 16Ω to VCMHP		60		dB
	Interchannel gain mismatch				0.2	dB
	Gain error				0.5	dB
SUT	Startup time from power up	FS=48 kHz		1		ms
		Line out HPL/R out		10		ms

Note: When  $2.4\text{ V} < V_{CCA} < 2.7\text{ V}$ , values are reduced by 2 dB

## 14 AD to DA mixing (sidetone) specifications

Information included in this section applies to both entities.

Typical measures at  $V_{CCA}=V_{CCP}=V_{CCLS}=2.7\text{V}$ ;  $V_{CCIO}=V_{CC}=1.8\text{V}$ ;  $T_{amb}=25^\circ\text{C}$ ; 13MHz AMCK.

Table 54. AD to DA mixing (sidetone) specifications

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
STDEL	AD to DA mixing (sidetone) delay	Valid for audio and voice filters		5	10	μs

## 15 Stereo analog-only path specifications

Information included in this section applies to both entities.

Measured at differential line-out, ENOSC=1, No master clock.

Typical measures at  $V_{CCA}=V_{CCP}=V_{CCLS}=2.7V$ ;  $V_{CCIO}=V_{CC}=1.8V$ ;  $T_{amb}=25^{\circ}C$

**Table 55. Stereo analog-only path specifications**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
AADRM AADRLI	Dynamic range	20Hz to 20kHz, A-weighted. Measured at -60dBFS MIC input, 21dB gain Line-In, 0dB gain	90 90	95 97		dB dB
AASNA AASN	Signal to noise ratio	Max level at line-in input, 0dB gain, A-weighted Unweighted (20 Hz to 20 kHz)		97 94		dB dB
AATHD	Total harmonic distortion	1kHz @ 0dBFS MIC input, 21dB gain Line-in input, 0dB gain		0.003 0.004	0.01 0.02	% %

Note: When  $2.4V < V_{CCA} < 2.7V$ , the values are reduced by 2dB.



## 16 ADC (TX) & DAC (RX) specifications with voice filters selected

Information included in this section applies to both entities.

Typical measures at  $V_{CCA}=V_{CCP}=V_{CCL}=2.7V$ ;  $V_{CCIO}=V_{CC}=1.8V$ ;  $T_{amb}=25^{\circ}C$ ; 13MHz  
AMCK

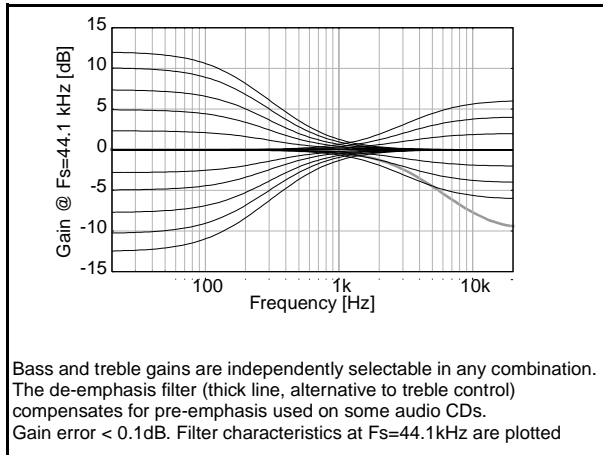
**Table 56. ADC (TX) & DAC (RX) specifications with voice filters selected**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
TXDR RXDR	Dynamic range	300Hz to 3.4kHz; 1kHz @ -60dBFS TX Path, MIC input, 21dB gain RX Path, LS Output, 0dB gain	86 83	89 86		dB dB
TXSN RXSN	Signal to noise ratio	300Hz to 3.4kHz; 1kHz @ 0dBFS TX Path, MIC input, 21dB gain RX Path, LS and EAR outputs, 0dB gain		88 86		dB dB
THD	THD	1kHz @ 0dBFS TX Path, MIC input, 21dB gain RX Path, LS and EAR outputs, 0dB gain		<0.001 0.005		% %
TXG	TX gain mask	f=60Hz			-30	dB
		f=100Hz			-24	dB
		f=200Hz			-6	dB
		f=300Hz	-1.5		0.5	dB
		f=400Hz-3000Hz	-0.5		0.5	dB
		f=3400Hz	-1.5		0.0	dB
		f=4000H			-14	dB
		f=4600Hzz f=8000Hz			-35 -47	dB dB
RXG	RX gain mask	f=60Hz			-20	dB
		f=100Hz			-12	dB
		f=200Hz			-2	dB
		f=300Hz	-1.5		0.5	dB
		f=400Hz-3000Hz	-0.5		0.5	dB
		f=3400Hz	-1.5		0.0	dB
		f=4000Hz			-14	dB
		f=5000Hz			-50	dB
	RX out of band noise	Measurement bandwidth 4kHz to 100kHz. Zero input signal		-85		dB <sub>r</sub>
	Group delay	TX path		0.32		ms
RX path			0.28		ms	

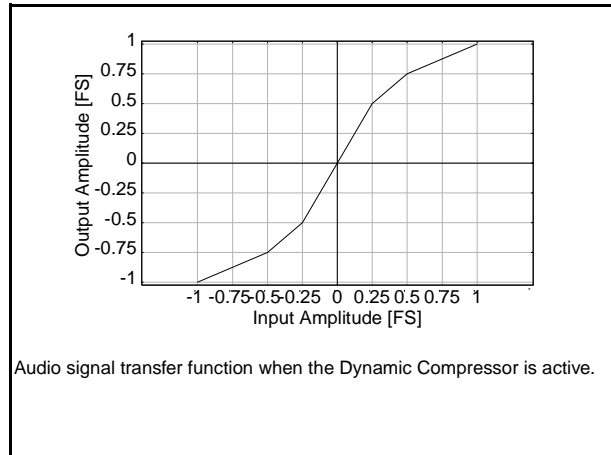
Note: When  $2.4V < V_{CCA} < 2.7V$ , the values are reduced by 2dB

# 17 Typical performance plots

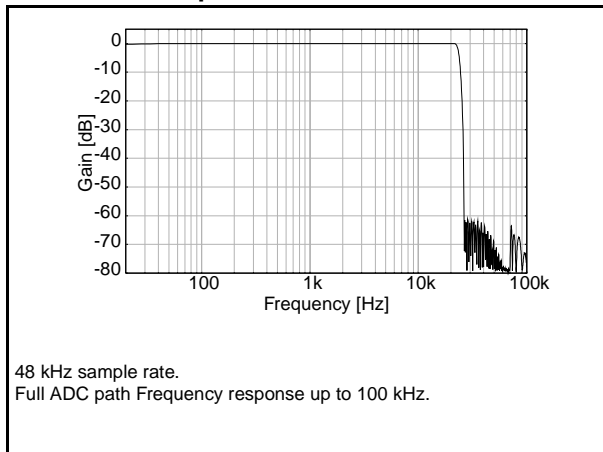
**Figure 14. Bass treble control, de-emphasis filter**



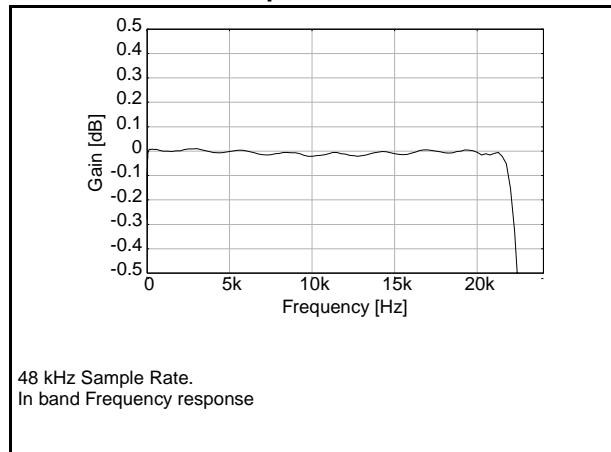
**Figure 15. Dynamic compressor transfer function**



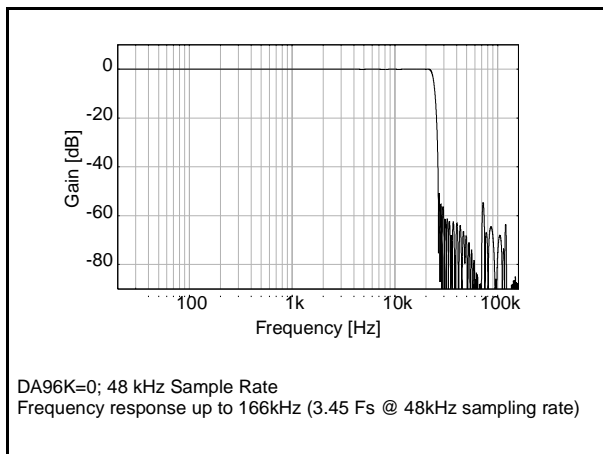
**Figure 16. ADC audio path measured filter response**



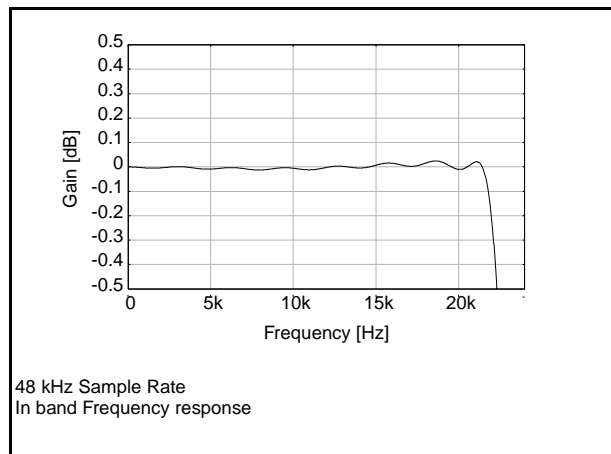
**Figure 17. ADC in band audio path measured filter response**



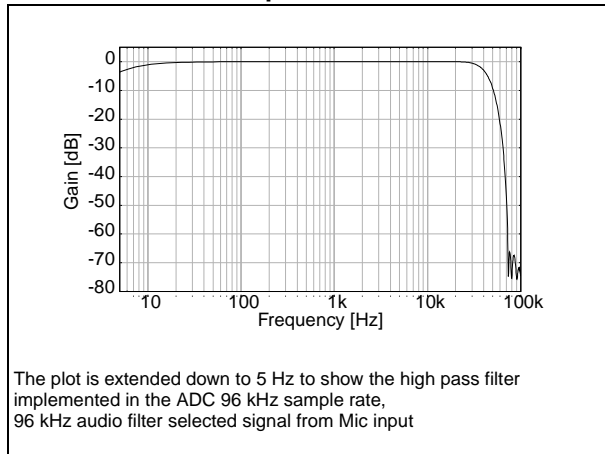
**Figure 18. DAC digital audio filter characteristics**



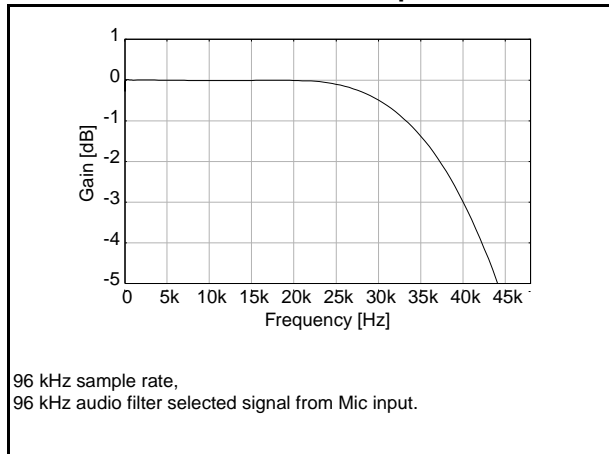
**Figure 19. DAC in band digital audio filter characteristics**



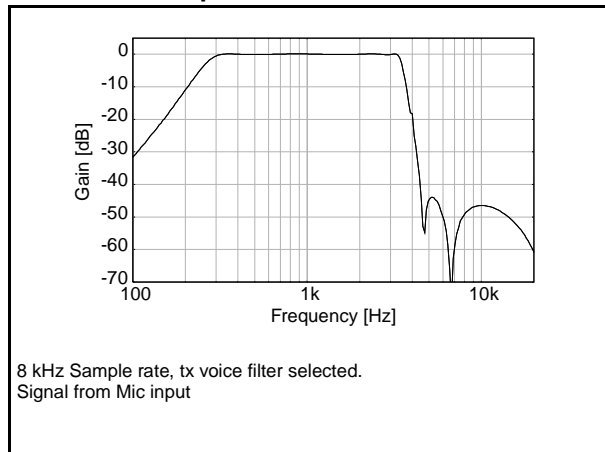
**Figure 20. ADC 96 kHz audio path measured filter response**



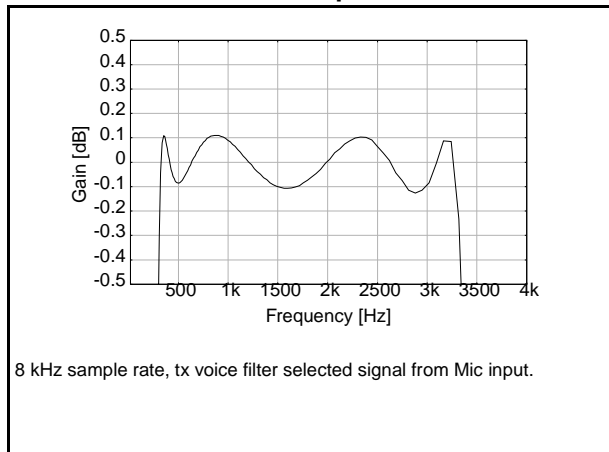
**Figure 21. ADC 96 kHz audio in-band measured filter response**



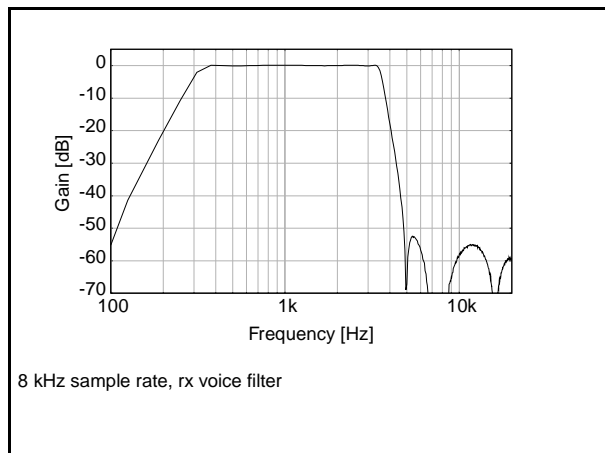
**Figure 22. ADC voice TX path measured filter response**



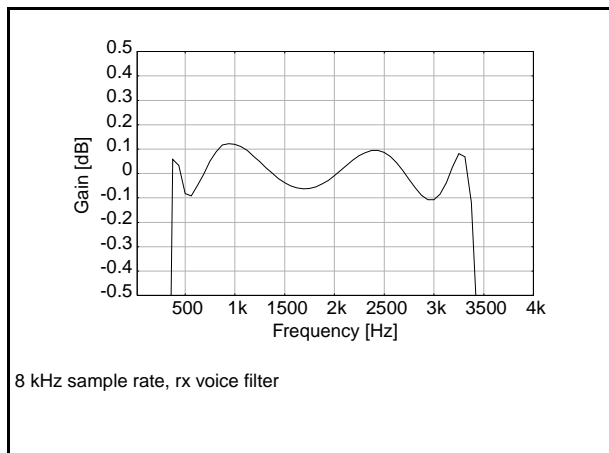
**Figure 23. ADC voice TX path measured in-band filter response**



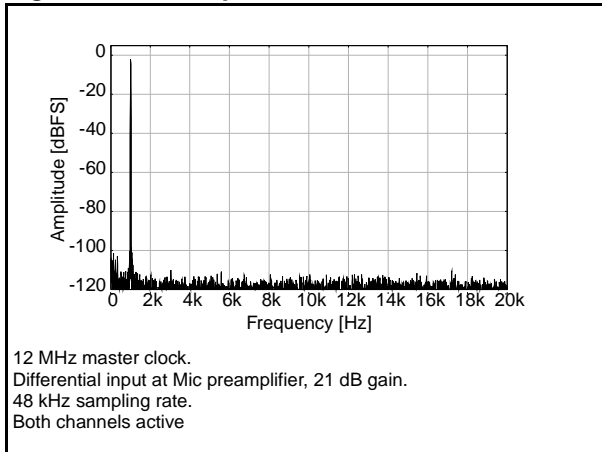
**Figure 24. DAC voice (RX) digital filter characteristics**



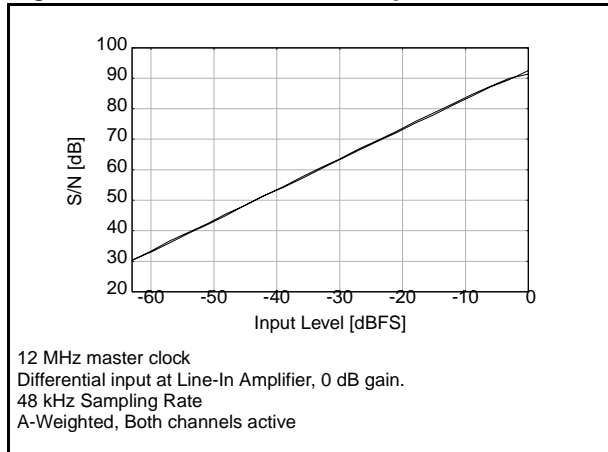
**Figure 25. DAC voice (RX) in-band digital filter characteristics**



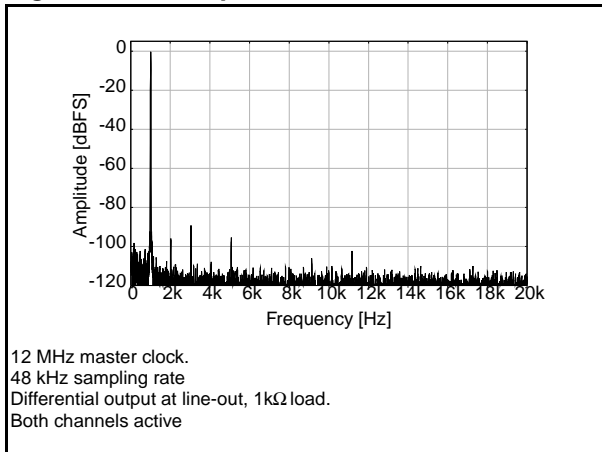
**Figure 26. ADC path FFT**



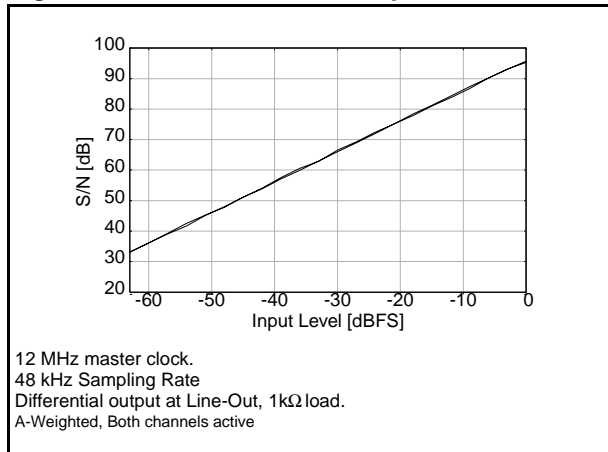
**Figure 27. ADC S/N versus input-level**



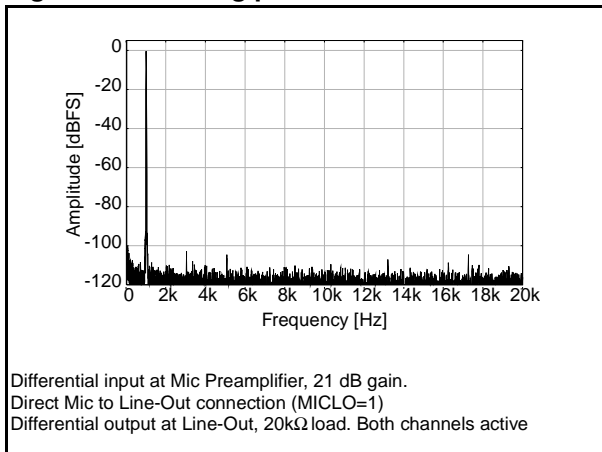
**Figure 28. DAC path FFT**



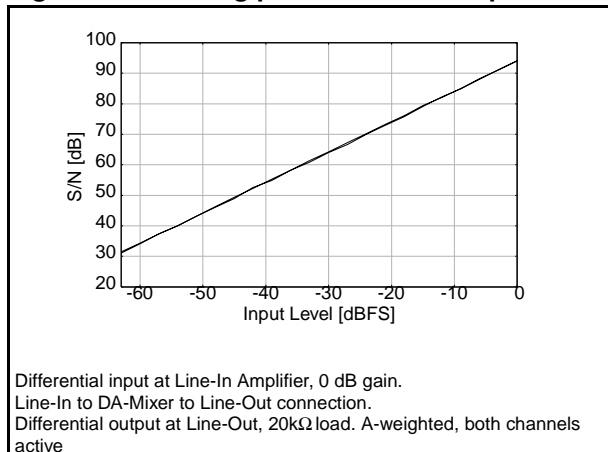
**Figure 29. DAC S/N versus input-level**



**Figure 30. Analog path FFT**



**Figure 31. Analog path S/N versus input-level**



## 18 Package mechanical data

In order to meet environmental requirements, ST offers these devices in ECOPACK® packages. These packages have a Lead-free second level interconnect. The category of second Level Interconnect is marked on the package and on the inner box label, in compliance with JEDEC Standard JESD97. The maximum ratings related to soldering conditions are also marked on the inner box label. ECOPACK is an ST trademark. ECOPACK specifications are available at: [www.st.com](http://www.st.com).

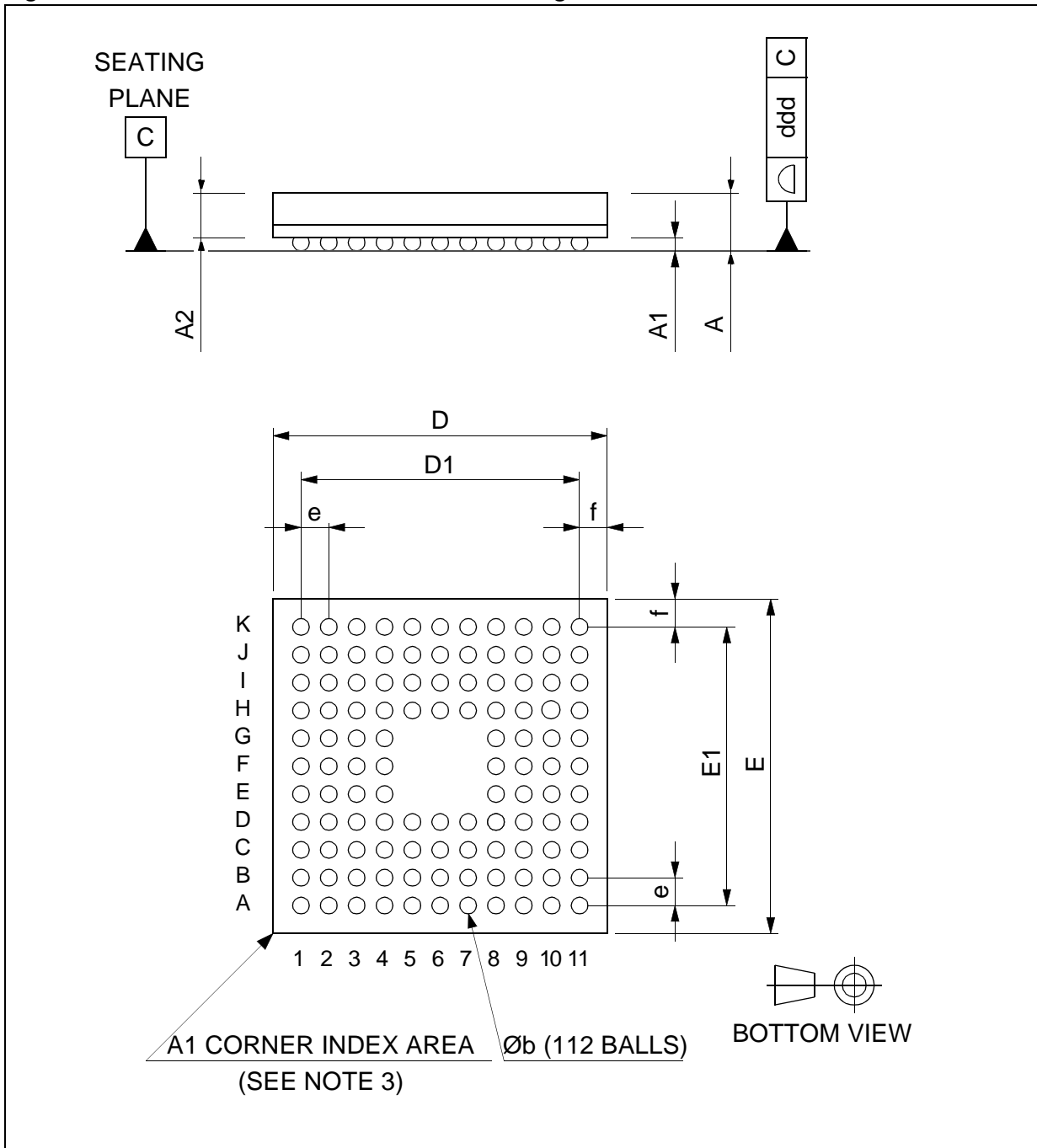
## 18.1 LFBGA 6x6x1.4

**Table 57. Dimensions of LFBGA 6x6x1.4 112 4R11x11. 0.5**

Reference	Databook (mm)			Drawing (mm)			Notes
	Min.	Typ.	Max.	Min.	Typ.	Max.	
A			1.40			1.26	<a href="#">Note 1</a>
A1	0.15			0.16	0.21	0.26	
A2		0.985		0.93	0.985	1.04	
A3		0.20		0.16	0.20	0.24	
A4			0.80	0.77	0.785	0.80	
b	0.25	0.30	0.35	0.25	0.30	0.35	<a href="#">Note 2</a>
D	5.85	6.00	6.15	5.90	6.00	6.10	
D1		5.00			5.00		
E	5.85	6.00	6.15	5.90	6.00	6.10	
E1		5.00			5.00		
e		0.50			0.50		
F		0.50			0.50		
ddd			0.08			0.08	
eee			0.15			0.15	<a href="#">Note 4</a>
fff			0.05			0.05	<a href="#">Note 5</a>

- Note:**
- 1 *LFBGA stands for Low Profile Fine Pitch Ball Grid Array.*  
 - Low profile: the total profile height (Dim A) is measured from the seating plane to the top of the component. The maximum total package height is calculated as follows:  
 $A_{2Typ} + A_{1Typ} + \sqrt{(A_1^2 + A_3^2 + A_4^2 \text{tolerancevalues})}$ . Fine pitch:  $e < 1.0$  mm pitch
  - 2 *The typical ball diameter before mounting is 0.30 mm*
  - 3 *The tolerance of position that controls the location of the pattern of balls with respect to datum A and B. For each ball there is a cylindrical tolerance zone eee perpendicular to datum C and located on true position with respect to datum A and B as defined by e. The axis perpendicular to datum C of each ball must lie within this tolerance zone.*
  - 4 *The tolerance of position that controls the location of the balls within the matrix with respect to each other. For each ball there is a cylindrical tolerance zone fff perpendicular to datum C and located on true position as defined by e. The axis perpendicular to datum C of each ball must lie within this tolerance zone. Each tolerance zone fff in the array is contained entirely in the respective zone eee above.*  
*The axis of each ball must lie simultaneously in both tolerance zones.*
  - 5 *The terminal A1 corner must be identified on the top surface by using a corner chamfer, ink or metallized markings, or other feature of package body or integral heatslug. A distinguishing feature is allowable on the bottom surface of the package to identify the terminal A1 corner. Exact shape of each corner is optional.*

Figure 32. LFBGA 6x6x1.4 112 4R11x11 0.5 drawing



## 18.2 VFBGA 5x5x1.0

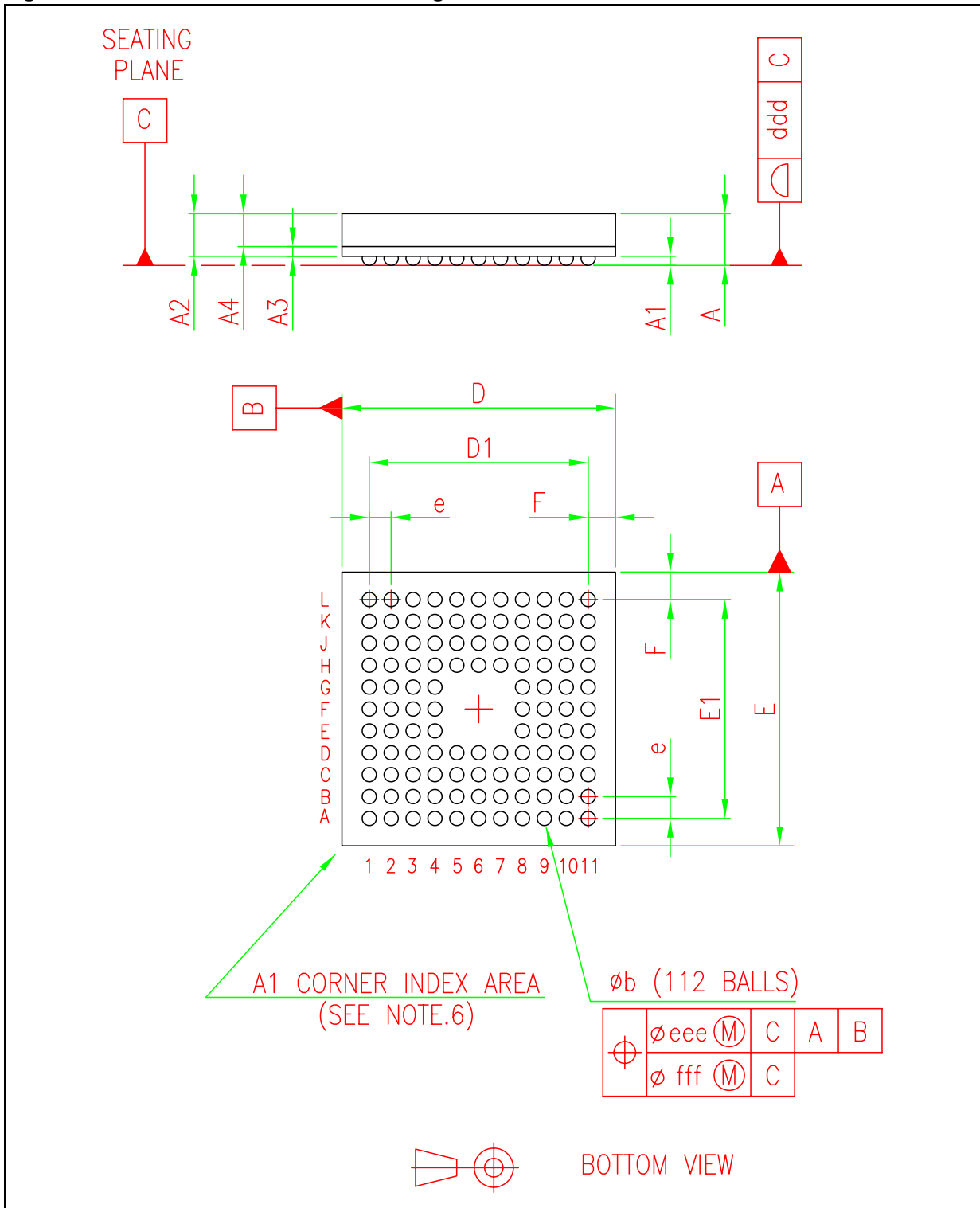
**Table 58. Dimensions of VFBGA 5x5x1.0 112 balls 0.4 mm pitch**

Reference	Databook (mm)			Drawing (mm)			Notes
	Min.	Typ.	Max.	Min.	Typ.	Max.	
A			1.00			0.99	<a href="#">Note 1</a>
A1	0.125			0.125	0.165	0.205	
A2		0.765		0.71	0.765	0.82	
A3		0.18		0.14	0.18	0.22	
A4			0.60	0.57	0.585	0.60	
b	0.22	0.26	0.30	0.22	0.26	0.30	<a href="#">Note 2</a>
D	4.95	5.00	5.05	4.95	5.00	5.05	
D1		4.00			4.00		
E	4.95	5.00	5.05	4.95	5.00	5.05	
E1		4.00			4.00		
e		0.40			0.40		<a href="#">Note 3</a>
F		0.50			0.50		
ddd			0.08			0.08	
eee			0.13			0.13	<a href="#">Note 4</a>
fff			0.04			0.04	<a href="#">Note 5</a>

- Note:**
- 1 VFBGA stands for Very thin Profile Fine Pitch Ball Grid Array.  
The maximum total package height is calculated by the following methodology:  
 $A2Typ + A1Typ + \sqrt{(A1^2 + A3^2 + A4^2 \text{tolerance values})}$ .  
Very thin profile:  $0.80\text{mm} < A \leq 1.00\text{mm}$  Max/Fine pitch:  $e < 1.0\text{ mm}$
  - 2 The typical ball diameter before mounting is 0.25 mm
  - 3 VFBGA with 0.40mm ball pitch is not yet registered into JEDEC publications.
  - 4 The tolerance of position that controls the location of the pattern of balls with respect to datum A and B. For each ball there is a cylindrical tolerance zone eee perpendicular to datum C and located on true position with respect to datum A and B as defined by e. The axis perpendicular to datum C of each ball must lie within this tolerance zone.
  - 5 The tolerance of position that controls the location of the balls within the matrix with respect to each other. For each ball there is a cylindrical tolerance zone fff perpendicular to datum C and located on true position as defined by e. The axis perpendicular to datum C of each ball must lie within this tolerance zone. Each tolerance zone fff in the array is contained entirely in the respective zone eee above.  
The axis of each ball must lie simultaneously in both tolerance zones.
  - 6 The terminal A1 corner must be identified on the top surface by using a corner chamfer, ink or metallized markings, or other feature of package body or integral heatslug. A distinguishing feature is allowable on the bottom surface of the package to identify the terminal A1 corner. Exact shape of each corner is optional.



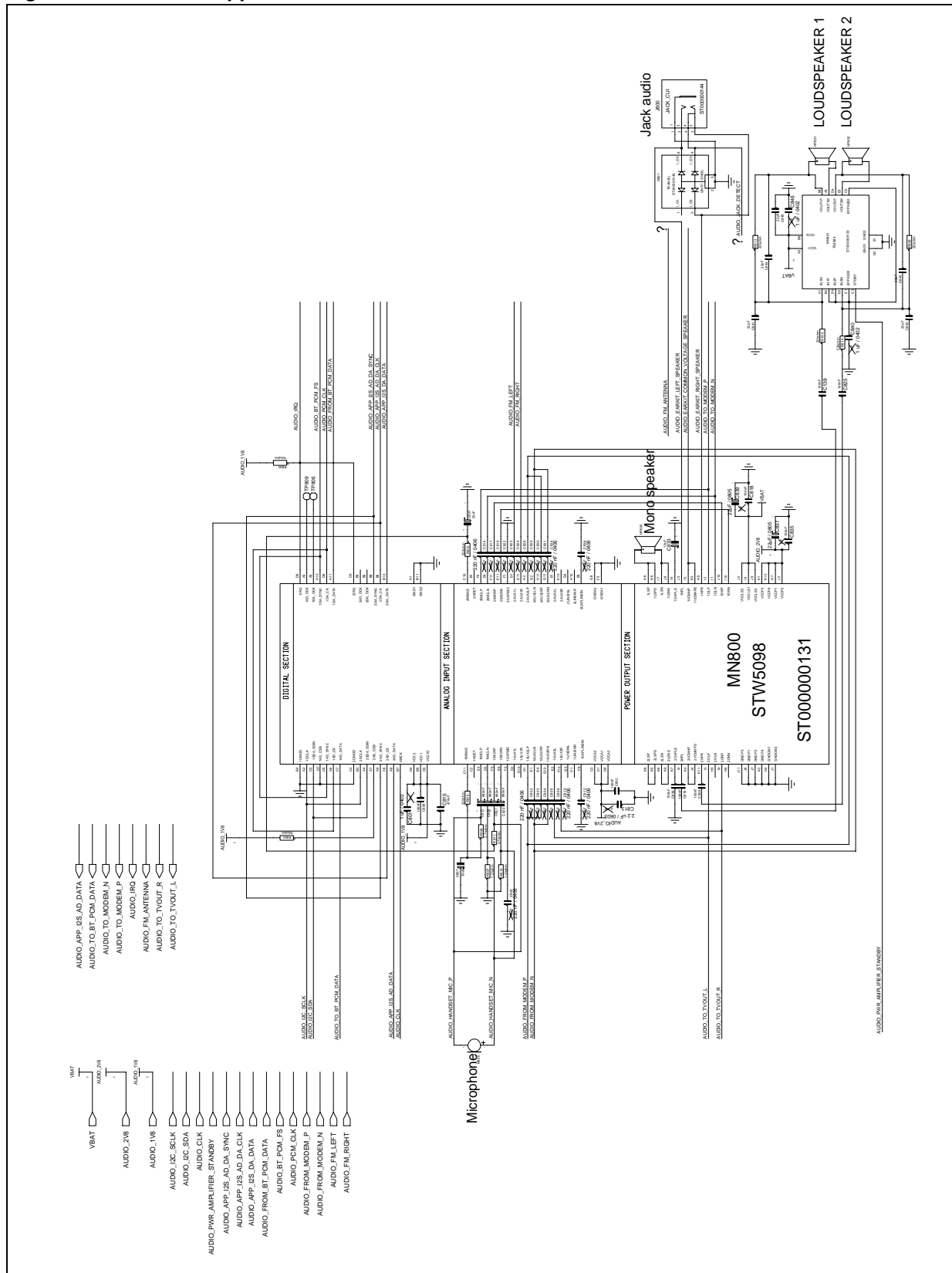
Figure 33. VFBGA 5x5x1.0 112 0.4 drawing



## 19 Application schematics

See [Figure 34: STw5098 application schematics](#).

Figure 34. STw5098 application schematics



## 20 Ordering information

**Table 59. Order codes**

Part Number	Package	Packing
STw5098	LFBGA 6x6x1.4, 0.5 mm pitch, 112 pins	Tray
STw5098T	LFBGA 6x6x1.4, 0.5 mm pitch, 112 pins	Tape and reel
STw5098BBLR/LF	VFBGA 5x5x1.0, 0.4 mm pitch, 112 pins	Tray
STw5098BBLT/LF	VFBGA 5x5x1.0, 0.4 mm pitch, 112 pins	Tape and reel

## 21 Revision history

**Table 60. Document revision history**

Date	Revision	Changes
24-Apr-2007	1	Initial release.

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