DS04-29104-2E

ASSP DUAL REVERSIBLE MOTOR DRIVER

MB3863

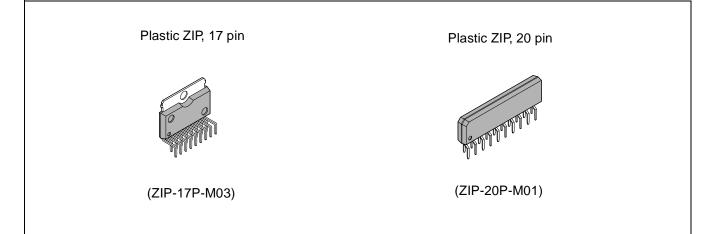
DESCRIPTION

The MB3863 is an IC motor driver with two independent reverse control functions. It drives motor drives of frontloading VCRs and auto-reverse cassette decks and stepping motors by reversible control at TTL and CMOS levels. A heat protection circuit is incorporated to prevent damage by overheating.

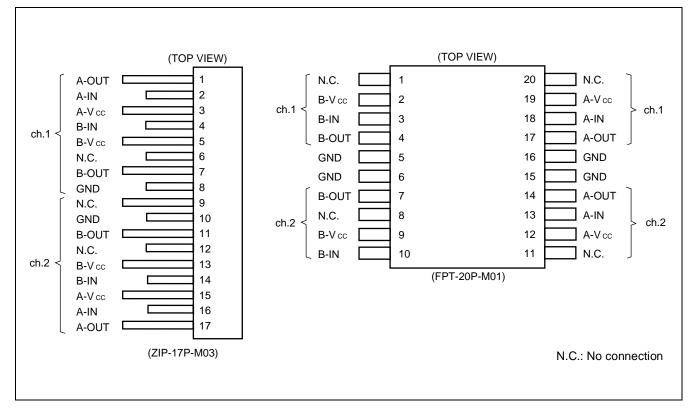
■ FEATURES

- Wide voltage range: Vcc = +4 to +36V
- Motor drive current: 500 mA (1.2 A for surge current)
- Two internal independent drivers
- Internal heat protection circuit
- Control at TTL and CMOS level
- Stand-by mode
- Brake function to stop motors
- Surge absorption diode
- Stepping motor application
- Symmetrical pin layout

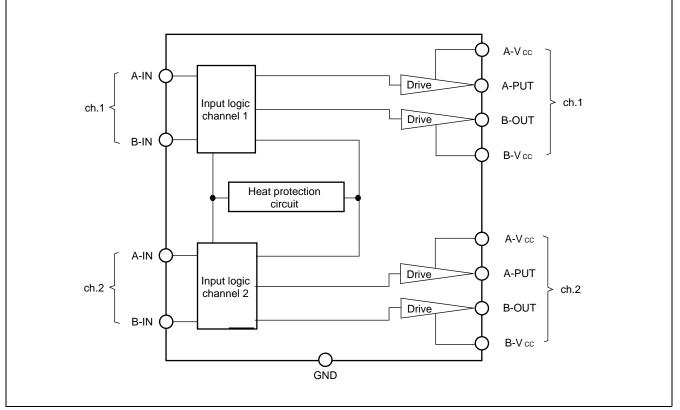
■ PACKAGE



■ PIN ASSIGNMENT



BLOCK DIAGRAM



■ ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Ratings	Unit
Supply Voltage	Vcc	+38	V
Output Current	lo	550	mA
Maximum Output Current (within 5 ms)	IOmax	1.2	A
	Da	6.5 (ZIP-17)	W
Allowable Loss	PD	1.6 (SOP-20)	VV V
Operating Temperature	Тор	-20 to +75	°C
Storage Temperature	Tstg	-55 to +150	°C

■ RECOMMENDED OPERATING CONDITIONS

Parameter		Symbol	Ratings	Unit
Supply Voltage		Vcc	+4 to +36	V
Output Current		lo	0 to 500	mA
Input Voltage	High level	Vін	2.4 to Vcc +0.3	V
input voltage	Low level	Vı∟	0 to 0.4	V

ELECTRICAL CHARACTERISTICS

				$(VCC = Z^2)$	$\pm v$, $v =$	2.4V, Ia =	= +25°C)
Parame	Conditions		Values				
Falalite		Symbol	Conditions	Min.	Тур.	Max.	Unit
Stand-by Supply Voltage		Icco	Vcc = +24V, $VIA = VIB = 0V$			100	μA
Supply Voltage		Icc1	lo = 0 mA		24	38	mA
		Icc2	lo = 500 mA	—	24	_	mA
		Іссз	IO = 0 mA, VIA = VIB = +2.4V	—	37	—	mA
	High level	Vон	lo = 500 mA	22.65	23	_	V
Output Voltage	Low level	Vol	lo = 500 mA		0.35	0.65	V
Saturated Output Voltage		VSAT	lo = 500 mA	—	1.35	2.00	V
Input Current		Т	VIN = +2.4V		250	400	μA
Surge Absorption Diode Voltage in Forward Direction		Iін Vf	lo = 1.2A	_	2.0	_	V

(Vcc = 24V, VIN = 2.4V, Ta = +25°C)

■ OPERATIONS

1. Forward and Reverse

Switching control mode A or B pairs Q2 and Q3, or Q1 and Q4, respectively, while reversing the supply current to the motor for each switching. When Q2 and Q3 are in use, B-OUT and A-OUT are High level and Low level, respectively. In this case, current flows B-OUT motor A-OUT, causing forward operation as described in the table below.

When Q1 and Q4 are in use, current flows in the reverse direction to the above flow, causing reverse motor operation.

2. Brake

Control mode C operates Q3 and Q4 while stopping Q1 and Q3.

Since A-OUT and B-OUT are held at Low level, both poles of the motor are short-circuited and the motor is stopped.

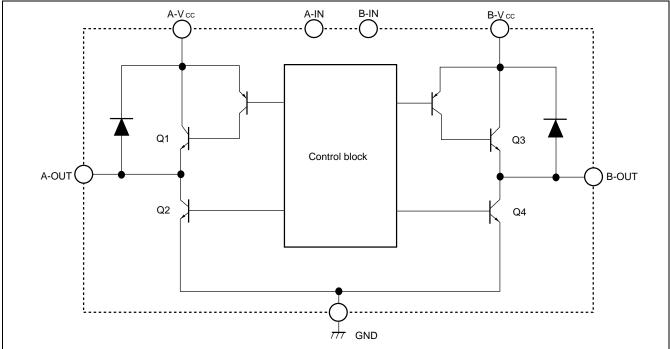
3. Stand-by

Control mode D turns Q1 to Q4 OFF and the motor has no current flow.

In this mode, the power current is less than 100 μ A.

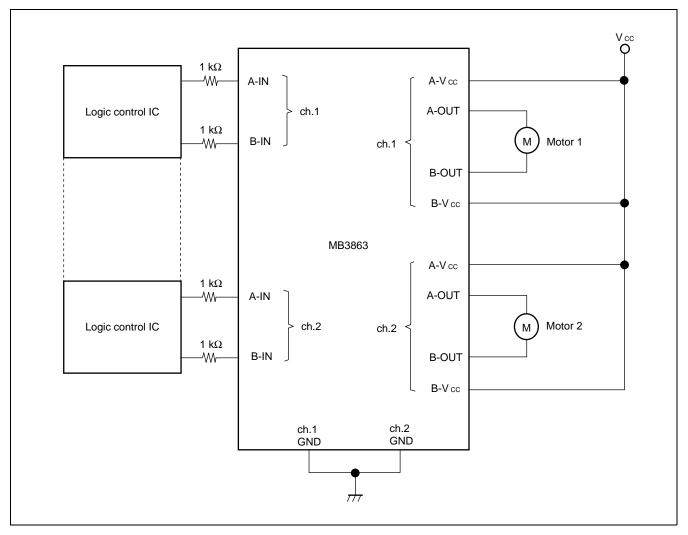
Mode	Mode Input mode*		Operation state of output transistor				State of output pin		Output operation mode
woue	A=IN	B=IN	Q1	Q2	Q3	Q4	A-OUT	B-OUT	Output operation mode
А	1	0	OFF	ON	ON	OFF	L	Н	Forward (Reverse)
В	0	1	ON	OFF	OFF	ON	Н	L	Reverse (Forward)
С	1	1	OFF	ON	OFF	ON	L	L	Brake
D	0	0	OFF	OFF	OFF	OFF	_	_	Open (High impedance)

* : Input mode: -1: +2.4V min. -0: +0.4V max.

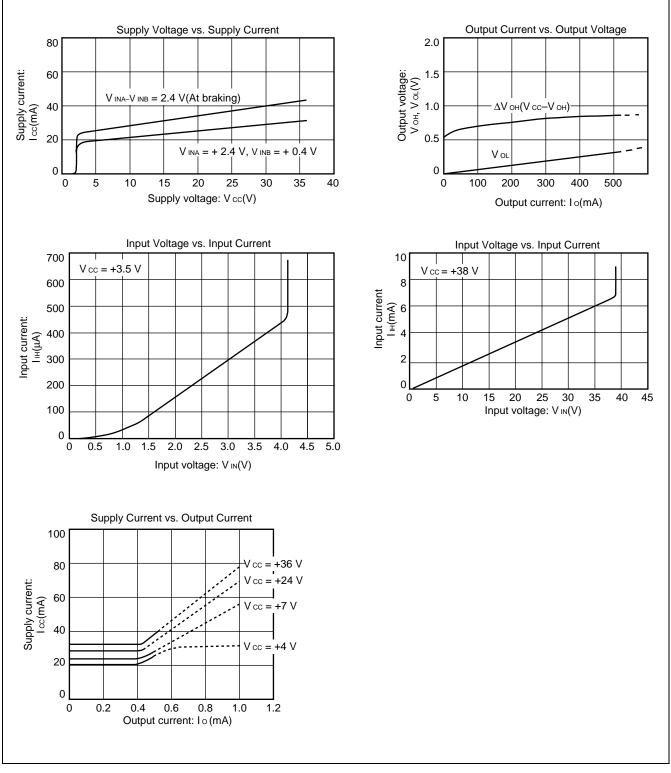


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■ TYPICAL CONNECTION



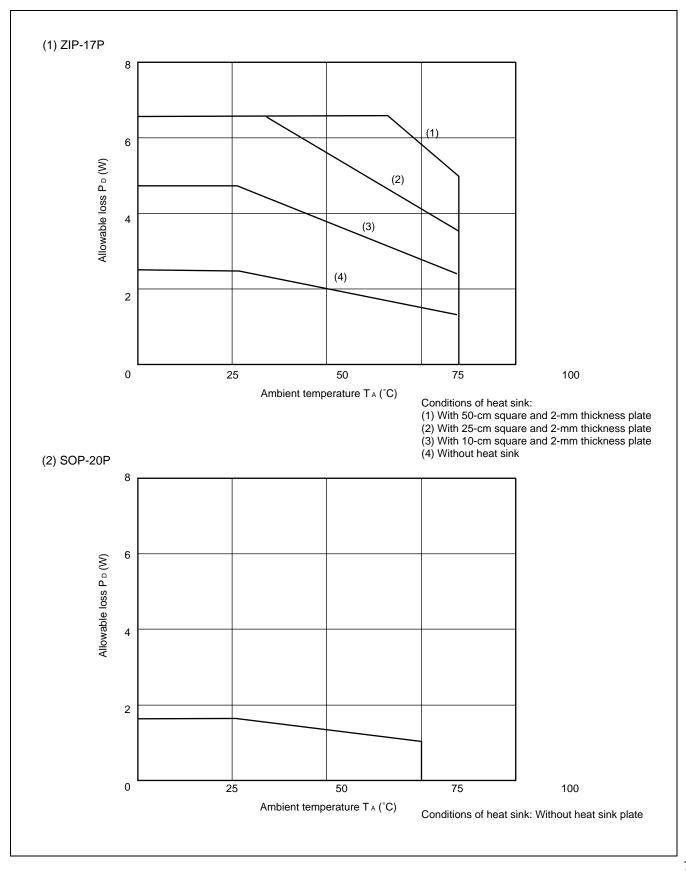
Note: If input voltage is applied when power is not supplied, over-current flows into the device via the input pins. In this case, connect a resistor of at least 1 k Ω in series with the input pins to prevent passage of a large current.



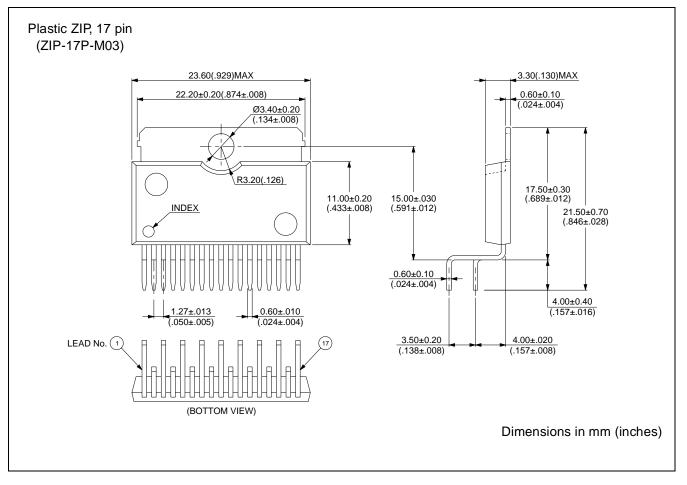
TYPICAL CHARACTERISTIC CURVES

Note: The above characteristic curves are at Ta = $+25^{\circ}C$

■ POWER DERATING CHARACTERISTICS

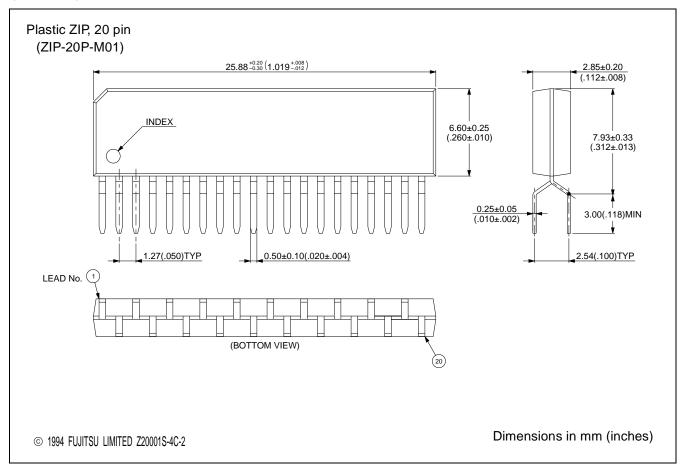


■ PACKAGE DIMENSIONS



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