

## **TDA7275A**

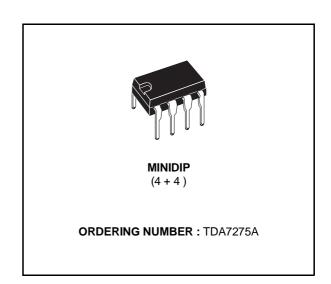
### MOTOR SPEED REGULATOR

- EXCELLENT VERSATILITY IN USE
- HIGH OUTPUT CURRENT (up to 1.5 A)
- LOW QUIESCENT CURRENT
- LOW REFERENCE VOLTAGE (1.32 V)
- EXCELLENT PARAMETERS STABILITY VER-SUS AMBIENT TEMPERATURE
- START/STOP FUNCTION (TTL levels)
- DUMP PROTECTION

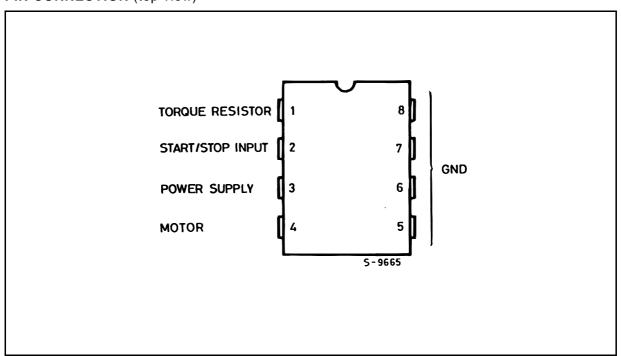
#### **DESCRIPTION**

The TDA7275A is a linear integrated circuit in minidip plastic package. It is intended for use as speed regulator for DC motors of record players, tape and cassette recorders.

The dump protection make it particularly suitable for car radio applications.

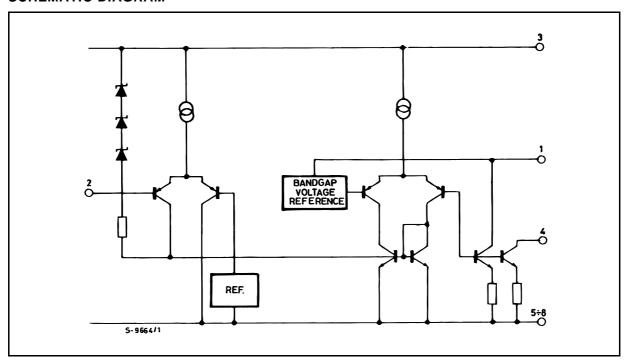


#### PIN CONNECTION (top view)



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#### **SCHEMATIC DIAGRAM**



#### **ABSOLUTE MAXIMUM RATINGS**

Symbol	Parameter	Value	Unit
Vs	Supply Voltage	19	V
Vs	Peak Supply Voltage (for 50ms)	45	V
I <sub>M</sub>	Maximum Output Current	1.5	Α
T <sub>op</sub>	Operating Temperature Range	-30 to +85	°C
P <sub>tot</sub>	Power Dissipation at T <sub>amb</sub> = 70°C	1	W
	at T <sub>pins</sub> = 70°C	4	W

#### THERMAL DATA

Symbol	Parameter	Value	Unit
R <sub>th j-amb</sub>	Thermal Resistance Junction-ambient	80	°C/W
R <sub>th j-pins</sub>	Max.	20	°C/W
	Thermal Resistance Junction -pins Max.		



# **ELECTRICAL CHARACTERISTICS** (Refer to test circuit, $V_S = 12V$ , $T_{amb} = 25^{\circ}C$ unless otherwise specified, refer to test circuit)

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
Vs	Supply Voltage Range		8		18	V
$V_{ref}$	Reference Voltage	I <sub>M</sub> = 0.1A	1.05	1.22	1.35	V
l <sub>q</sub> + l <sub>d</sub>	Total Quiescent Current	$I_{M} = 0.1 \text{mA}$		2		mA
l <sub>d</sub>	Quiescent Current	$I_{M} = 0.1 \text{mA}$		1		mA
I <sub>ms</sub>	Starting Motor Current	$\frac{\Delta V_{ref}}{V_{ref}} = -50\%$	1			А
$V_4$	Saturation Voltage	$I_{M} = 0.5A$		1.7	2	V
$K = I_M/I_T$	Reflection coefficient	$I_{M} = 0.1A$	18	20	22	-
$\frac{\Delta K/\Delta V_S}{K}$		$I_{M} = 0.1A$ $V_{S} = 8 \text{ to } 16V$		0.5		%/V
$\frac{\Delta K/\Delta I_{M}}{K}$		I <sub>M</sub> = 25 to 200mA		-0.05		%/mA
$\frac{\Delta K/\Delta T}{K}$		$I_{M} = 0.1A$ $T_{op} = -30 \text{ to } +85^{\circ}\text{C}$		0.02		%/°C
$\frac{\Delta V_{ref}/\Delta V_{S}}{V_{ref}}$	Line Regulation	I <sub>M</sub> = 0.1A V <sub>S</sub> = 8 to 16V		0.04		%/V
$\frac{\Delta V_{ref}/\Delta I_{M}}{V_{ref}}$	Load Regulation	I <sub>M</sub> = 25 to 200mA		-0.01		%/mA
$\frac{\Delta V_{ref}/\Delta T}{V_{ref}}$	Temperature Coefficient	$I_{M} = 0.1A$ $T_{op} = -30 \text{ to } +85^{\circ}\text{C}$		0.02		%/°C
V <sub>2</sub>	Motor "Stop" (Acc. Following data or grounded)			1		V
l <sub>2</sub>	Motor "Stop"	V2 = 1V		-0.05		mA
V <sub>2</sub>	Motor "Run" (Acc. Following data or open)			1.5		V
l <sub>2</sub>	Motor "Run"	V2 = 1.5V		-0.1		mA

Figure 1 : Test Circuit.

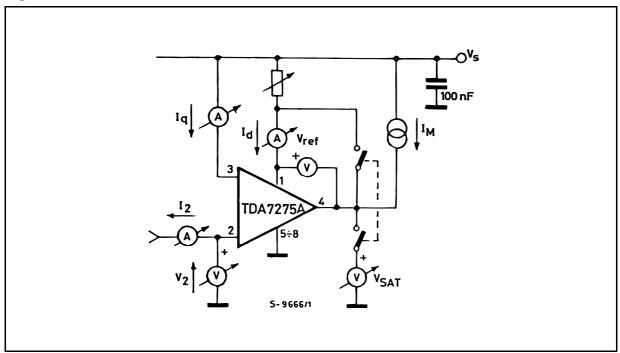
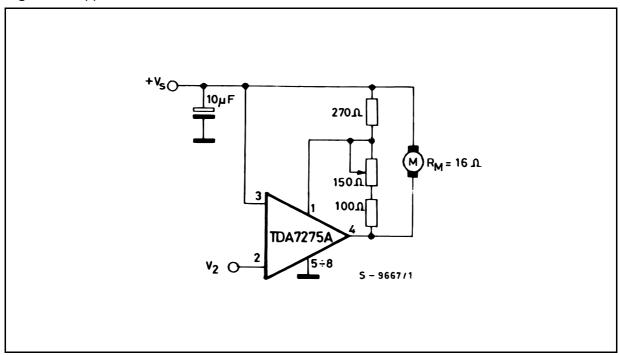


Figure 2: Application Circuit.



- $R_{Ttyp.}$  =  $K_{typ.}$   $R_{Mtyp.}$  if  $R_{T}$  >  $K_{min}$   $R_{Mmin}$  instability may accur.
- A diode across the motor could be necessary with certain kind of motor.

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Figure 3 : Quiescent Current vs. Supply voltage.

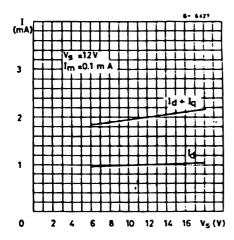
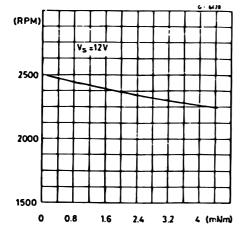
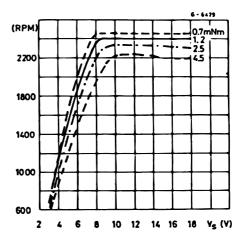


Figure 5 : Speed Variation vs. Torque ( $V_S = 12 \text{ V}$ ).

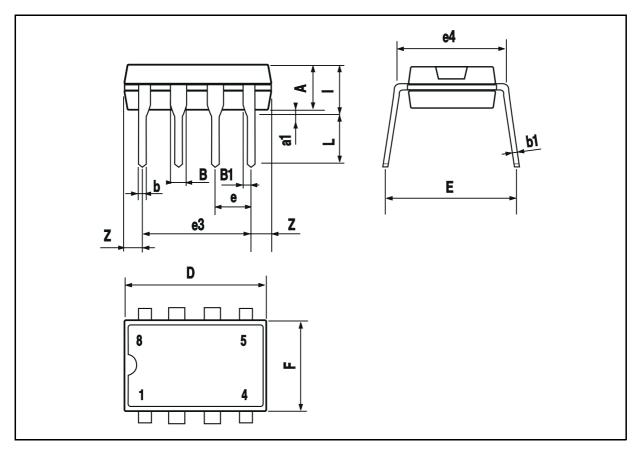


**Figure 4 :** Speed Variation vs. Supply Voltage.



#### MINIDIP PACKAGE MECHANICAL DATA

DIM.		mm			inch	
Diwi.	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
А		3.3			0.130	
a1	0.7			0.028		
В	1.39		1.65	0.055		0.065
B1	0.91		1.04	0.036		0.041
b		0.5			0.020	
b1	0.38		0.5	0.015		0.020
D			9.8			0.386
Е		8.8			0.346	
е		2.54			0.100	
e3		7.62			0.300	
e4		7.62			0.300	
F			7.1			0.280
I			4.8			0.189
L		3.3			0.130	
Z	0.44		1.6	0.017		0.063



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