

#### ABSOLUTE MAXIMUM RATINGS at $T_A = 25^{\circ}C$

Logic Supply Voltage, V <sub>DD</sub> 15 V
Driver Supply Voltage, V <sub>BB</sub> 60 V
Continuous Output Current,
I <sub>OUT</sub> 40 mA to +25 mA
Input Voltage Range,
$V_{\text{IN}}$
Package Power Dissipation,
P <sub>D</sub> See Graph
Operating Temperature Range,
T <sub>A</sub> 20°C to +85°C
Storage Temperature Range,
T <sub>S</sub> 55°C to +150°C

Designed primarily for use with vacuum-fluorescent displays, the UCN5811A smart power BiMOS II driver features low-output saturation voltages and high output switching speed. These devices contain CMOS shift registers, data latches, and control circuitry, and bipolar high-speed sourcing outputs with DMOS active pull-down circuitry. The high-speed shift register and data latches allow direct interface with microprocessor-based systems. A CMOS serial data output enables cascade connections in applications requiring additional drive lines.

The UCN5811A features 60 V and -40 mA output ratings, allowing it to be used in many other peripheral power driver applications. It can be used as an improved replacement tor the SN75512B. The Allegro devices do not require special power-up sequencing.

The UCN5811A has been designed with BiMOS II logic for improved data entry rates. With a 5 V supply, it will typically operate above 5 MHz. At 12 V, significantly higher speeds are obtained. Use of this device with TTL may require the use of appropriate pull-up resistors to ensure a proper input logic high.

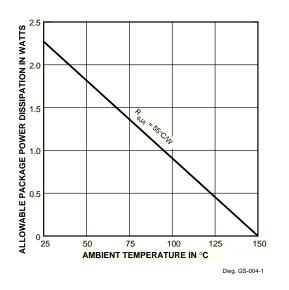
This device is supplied in a 20-pin plastic dual in-line package. It can be operated over the ambient temperature range of -20°C to +85°C. Copper lead frames and low output saturation voltages allow all outputs to be operated at 25 mA continuously at ambient temperatures of up to 76°C.

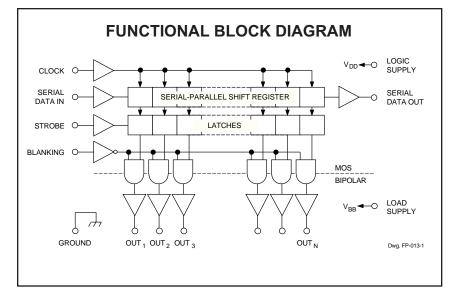
#### **FEATURES**

- To 3.3 MHz Data Input Rate
- Low-Power CMOS Logic and Latches
- High-Speed Source Drivers
- Active Pull-Downs
- Low-Output Saturation Voltages
- Improved Replacement for SN75512B

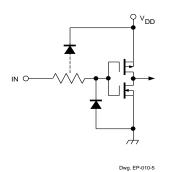
Always order by complete part number: **UCN5811A**.



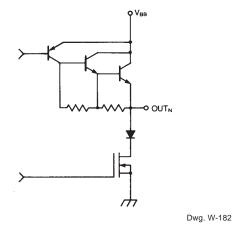




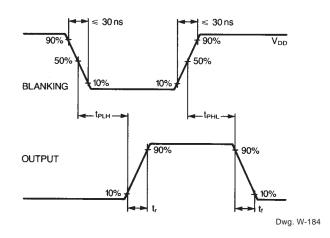
**TYPICAL INPUT CIRCUIT** 



**TYPICAL OUTPUT DRIVER** 



**TIMING WAVESHAPES** 



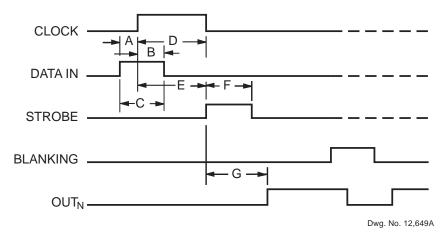
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### ELECTRICAL CHARACTERISTICS at $T_A$ = +25°C, $V_{BB}$ = 60 V (unless otherwise noted).

			Limits	s @ V <sub>DD</sub>	, = 5 V	Limits			
Characteristic	Symbol	Test Conditions	MIn.	Тур.	Max.	Min.	Тур.	Max.	Units
Output Leakage Current	I <sub>CEX</sub>	V <sub>OUT</sub> = 0 V, T <sub>A</sub> = +70°C	—	-5.0	-15	_	-5.0	-15	μA
Output Voltage	V <sub>OUT(H)</sub>	I <sub>OUT</sub> = -25 mA, V <sub>BB</sub> = 60 V	58	58.5	_	58	58.5	_	V
	V <sub>OUT(L)</sub>	I <sub>OUT</sub> = 1 mA	-	2.0	3.0	-		_	V
		I <sub>OUT</sub> = 2 mA	-	—	_	—	2.0	3.0	V
Output Pull-Down Current	I <sub>OUT(L)</sub>	$V_{OUT} = 10 \text{ V to } V_{BB}$	2.5	4.0		—		—	mA
		$V_{OUT} = 40 \text{ V to } V_{BB}$	-			15	18	—	mA
Input Voltage	V <sub>IN(1)</sub>		3.5		5.3	10.5		12.3	V
	V <sub>IN(0)</sub>		-0.3	_	+0.8	-0.3		+0.8	V
Input Current	I <sub>IN(1)</sub>	$V_{IN} = V_{DD}$	<b>—</b>	0.05	0.5	—	0.1	1.0	μΑ
	I <sub>IN(0)</sub>	V <sub>IN</sub> = 0.8 V	-	-0.05	-0.5		-1.0	-1.0	μA
Serial Data Output Voltage	V <sub>OUT(H)</sub>	I <sub>OUT</sub> = -200 μA	4.5	4.7		11.7	11.8	_	V
	V <sub>OUT(L)</sub>	I <sub>OUT</sub> = 200 μA	-	200	250	_	100	200	mV
Maximum Clock Frequency	f <sub>clk</sub>		3.3	5.0	—		7.5	_	MHz
Supply Current	I <sub>DD(H)</sub>	All Outputs High	-	3.0	5.0	—	15	20	mA
	I <sub>DD(L)</sub>	All Outputs Low	-	2.5	4.0		7.0	10	mA
	I <sub>BB(H)</sub>	Outputs High, No Load	-	7.5	12		7.5	12	mA
	I <sub>BB(L)</sub>	Outputs Low	—	10	100	_	10	100	μA
Blanking to Output Delay	t <sub>PHL</sub>	C <sub>L</sub> = 30 pF	—	300	550	—	125	150	ns
	t <sub>PLH</sub>	C <sub>L</sub> = 30 pF	-	250	450	—	170	200	ns
Output Fall Time	t <sub>f</sub>	C <sub>L</sub> = 30 pF	-	1000	1250	—	250	300	ns
Output Rise Time	t <sub>r</sub>	C <sub>L</sub> = 30 pF	-	150	170	—	150	170	ns

Negative current is defined as coming out of (sourcing) the specified device pin.



#### **TIMING CONDITIONS**

(T<sub>A</sub> = +25°C, V<sub>DD</sub> = 5 V, Logic Levels are V<sub>DD</sub> and Ground)

Α.	Minimum Data Active Time Before Clock Pulse (Data Set-Up Time)	.75 ns
В.	Minimum Data Active Time After Clock Pulse (Data Hold Time)	. 75 ns
С.	Minimum Data Pulse Width	150 ns
D.	Minimum Clock Pulse Width	150 ns
Е.	Minimum Time Between Clock Activation and Strobe	300 ns
F.	Minimum Strobe Pulse Width	100 ns
G.	Typical Time Between Strobe Activation and	
	Output Transistion	500 ns

Serial Data present at the input is transferred to the shift register on the logic "0" to logic "1" transition of the CLOCK input pulse. On succeeding CLOCK pulses, the registers shift data information towards the SERIAL DATA OUTPUT. The SERIAL DATA must appear at the input prior to the rising edge of the CLOCK input waveform.

Information present at any register is transferred to the respective latch when the STROBE is high (serial-to-parallel conversion). The latches will continue to accept new data as long as the STROBE is held high. Applications where the latches are bypassed (STROBE tied high) will require that the BLANKING input be high during serial data entry.

When the BLANKING input is high, the output source drivers are disabled (OFF); the DMOS sink drivers are ON, the information stored in the latches is not affected by the BLANKING input. With the BLANKING input low, the outputs are controlled by the state of their respective latches.

Serial		s	hift	Regi	ster	Conte	ents	Serial		Latch Contents				Output Contents						
Data Input	Clock Input		$I_2$	I <sub>3</sub>		I <sub>N-1</sub>	I <sub>N</sub>	Data Output	Strobe Input	I <sub>1</sub>	l <sub>2</sub>	I <sub>3</sub>	 I <sub>N-1</sub>	I <sub>N</sub>	Blanking	I <sub>1</sub>	l <sub>2</sub>	I <sub>3</sub>	I <sub>N-1</sub>	I <sub>N</sub>
н	Г	н	R <sub>1</sub>	$R_2$		R <sub>N-2</sub>	R <sub>N-1</sub>	R <sub>N-1</sub>												
L	<b>_</b>	L	R <sub>1</sub>	$R_2$		R <sub>N-2</sub>	R <sub>N-1</sub>	R <sub>N-1</sub>												
х	1	R <sub>1</sub>	$R_2$	$R_3$		R <sub>N-1</sub>	R <sub>N</sub>	R <sub>N</sub>												
		х	Х	Х		Х	Х	Х	L	R <sub>1</sub>	$R_2$	$R_3$	 R <sub>N-1</sub>	$R_N$						
		P <sub>1</sub>	$P_2$	P <sub>3</sub>		P <sub>N-1</sub>	P <sub>N</sub>	P <sub>N</sub>	Н	P <sub>1</sub>	$P_2$	P <sub>3</sub>	 P <sub>N-1</sub>	P <sub>N</sub>	L	P <sub>1</sub>	$P_2$	P <sub>3</sub>	P <sub>N-1</sub>	
P <sub>N</sub>			_	-						X	Х	X	 Х	Х	Н	L	L	L	L	L

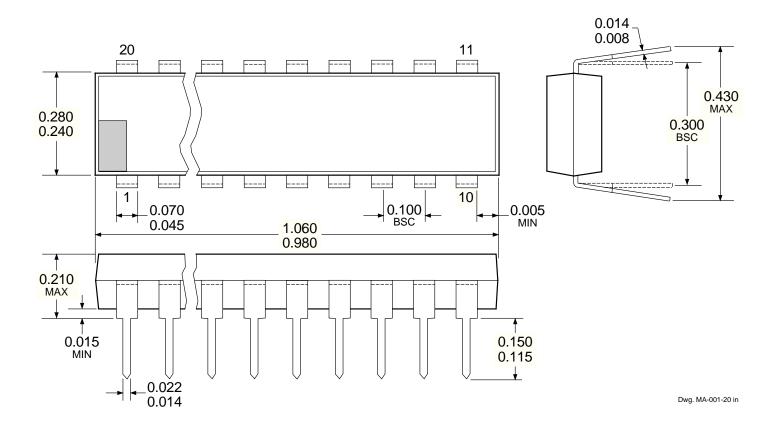
#### **TRUTH TABLE**

L = Low Logic Level H = High Logic Level X = Irrelevant P = Present State R = Previous State



#### UCN5811A

Dimensions in Inches (controlling dimensions)



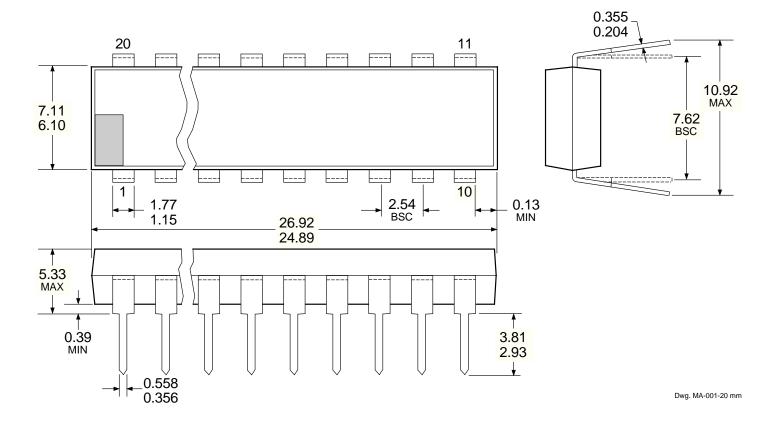
NOTES: 1. Exact body and lead configuration at vendor's option within limits shown.

2. Lead spacing tolerance is non-cumulative.

3. Lead thickness is measured at seating plane or below.

#### UCN5811A

Dimensions in Millimeters (for reference only)



NOTES: 1. Exact body and lead configuration at vendor's option within limits shown.

Lead spacing tolerance is non-cumulative.

3. Lead thickness is measured at seating plane or below.



115 Northeast Cutoff, Box 15036 Worcester, Massachusetts 01615-0036 (508) 853-5000 5811 *Bimos II 12-BIT Serial-Input, Latched Source Driver* 

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## BiMOS II (Series 5800) & DABiC IV (Series 6800) INTELLIGENT POWER INTERFACE DRIVERS SELECTION GUIDE

Function	Output F	Ratings *	Part Number †				
SER	IAL-INPUT LATCHED DR	IVERS	·				
8-Bit (saturated drivers)	-120 mA	50 V‡	5895				
8-Bit	350 mA	50 V	5821				
8-Bit	350 mA	80 V	5822				
8-Bit	350 mA	50 V‡	5841				
8-Bit	350 mA	80 V‡	5842				
9-Bit	1.6 A	50 V	5829				
10-Bit (active pull-downs)	-25 mA	60 V	5810-F and 6809/10				
12-Bit (active pull-downs)	-25 mA	60 V	5811 and 6811				
20-Bit (active pull-downs)	-25 mA	60 V	5812-F and 6812				
32-Bit (active pull-downs)	-25 mA	60 V	5818-F and 6818				
32-Bit	100 mA	30 V	5833				
32-Bit (saturated drivers)	100 mA	40 V	5832				
PARA	LLEL-INPUT LATCHED D	RIVERS					
4-Bit	350 mA	50 V‡	5800				
8-Bit	-25 mA	60 V	5815				
8-Bit	350 mA	50 V‡	5801				
SPE	ECIAL-PURPOSE FUNCT	IONS					
Unipolar Stepper Motor Translator/Driver	1.25 A	50 V‡	5804				
Addressable 28-Line Decoder/Driver	450 mA	30 V	6817				

\* Current is maximum specified test condition, voltage is maximum rating. See specification for sustaining voltage limits. Negative current is defined as coming out of (sourcing) the output.

† Complete part number includes additional characters to indicate operating temperature range and package style.

‡ Internal transient-suppression diodes included for inductive-load protection.

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