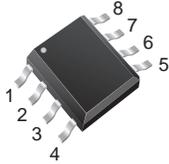


Adjustable Precision Shunt Regulators

SO-8


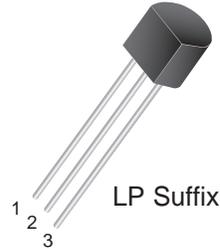
S Suffix

SOT-23


U Suffix

SOT-89


X Suffix

TO-92


LP Suffix

Features

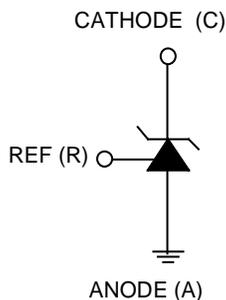
- Programmable Output Voltage to 30V
- Precision Reference Voltage
 GS431B: 2.495V \pm 0.5%
 TL431A: 2.495V \pm 1.0%
 TL431: 2.495V \pm 1.6%
- Sink Current Capability: 200mA.
- Minimum Cathode Current for Regulation: 250 μ A
- Equivalent Full-Range Temperature Coefficient: 50 ppm/ $^{\circ}$ C
- Fast Turn-On Response
- Low Dynamic Output Impedance: 0.08 Ω
- Low Output Noise

Description

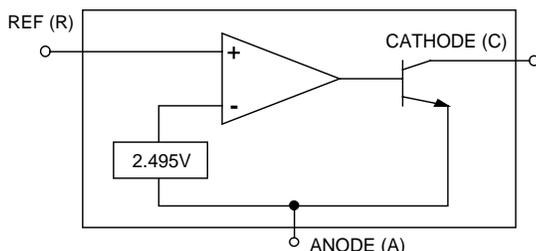
The GS431B/TL431A/TL431 are 3-terminal adjustable precision shunt regulators with guaranteed temperature stability over the applicable extended commercial temperature range. The output voltage may be set at any level greater than 2.495V (V_{REF}) up to 30V merely by selecting two external resistors that act as a voltage divider network. These devices have a typical output impedance of 0.08 Ω . Active output circuitry provides very sharp turn-on characteristics, making these devices excellent improved replacements for zener diodes in many applications.

The precise \pm 0.5% reference voltage tolerance of the GS431B makes it possible in many applications to avoid the use of a variable resistor, consequently saving cost and eliminating drift and reliability problems associated with it.

Symbol



Block Diagram



Applications

- Voltage Monitor
- Delay Timer
- Constant-Current Source/Sink
- High-Current Shunt Regulator
- Crow Bar
- Over-Voltage/Under-Voltage Protection

Mechanical Data

Case: SO-8, SOT-23, SOT-89, TO-92

High temperature soldering guaranteed:

260 $^{\circ}$ C/10 seconds at terminals

Case outlines are on the back pages

Vishay
formerly General Semiconductor

Ordering Information

GS431B_{lxx}

Package code

SO-8: S
TO-92: LP
SOT-89: X
SOT-23: U-1/U-2

U-1: Pin 1, Cathode
Pin 2, V_{ref}
Pin 3, Anode

U-2: Pin 1, V_{ref}
Pin 2, Cathode
Pin 3, Anode

TL431_{xlxx}

Tolerance

Default: 1.6%
A: 1.0%

Package code

SO-8: S
TO-92: LP
SOT-89: X
SOT-23: U-1/U-2

Marking Information

SOT-23

GS431B,	(U-1)	DAxxxx*
TL431A,	(U-1)	DBxxxx
TL431,	(U-1)	DCxxxx
GS431B,	(U-2)	DDxxxx
TL431A,	(U-2)	DExxxx
TL431,	(U-2)	DGxxxx

*Last two digits denote datecode

SO-8	<p>Top View</p> <p>Cathode 1 8 Ref Anode 2 7 Anode Anode 3 6 Anode NC 4 5 NC</p>
SOT-23 (U-1)	<p>Top View</p> <p>1. Cathode 2. V_{ref} 3. Anode</p>
SOT-23 (U-2)	<p>Top View</p> <p>1. V_{ref} 2. Cathode 3. Anode</p>
SOT-89	<p>Top View</p> <p>1. V_{ref} 2. Anode (tab) 3. Cathode</p>
TO-92	<p>Top View</p> <p>1. V_{ref} 2. Anode 3. Cathode</p>



Absolute Maximum Ratings $T_A = 25^\circ\text{C}$ unless otherwise noted.

Parameter	Symbol	Value	Unit	
Cathode voltage	V_Z	30	V	
Continuous cathode current	I_Z	-10 to 250	mA	
Reference Input Current Range	I_{REF}	-0.05 to 10	mA	
Operating Temperature Range	T_{oper}	-40 to 85	$^\circ\text{C}$	
Junction Temperature	T_J	150	$^\circ\text{C}$	
Lead Temperature	T_L	260	$^\circ\text{C}$	
Storage Temperature	T_{stg}	-65 to 150	$^\circ\text{C}$	
Thermal Resistance	$R_{\theta JA}$	TO-92 Package SOT-23 Package SO-8 Package SOT-89 Package	115 310 163 120	$^\circ\text{C/W}$

Electrical Characteristics $T_A = 25^\circ\text{C}$ unless otherwise noted.

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit	
Reference Voltage	V_{REF}	$V_Z = V_{REF}$ $I_L = 10\text{mA}$ (Fig. 1) $T_A = 25^\circ\text{C}$	GS431B	2.482	2.495	2.508	V
			TL431A	2.470	2.495	2.520	
			TL431	2.455	2.495	2.535	
		$V_Z = V_{REF}$ $I_L = 10\text{mA}$ (Fig. 1) $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$	GS431B	2.475	-	2.520	
			TL431A	2.445	-	2.545	
			TL431	2.43	-	2.56	
Deviation of reference Input voltage over temperature ⁽¹⁾	ΔV_{REF}	$V_Z = V_{REF}$ $I_L = 10\text{mA}$	$T_A = 0^\circ\text{C}$ to 70°C	-	9.0	20	mV
			$T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (Fig. 1)	-	15.0	50	
Ratio of the change in reference voltage to the change in cathode voltage	$\frac{\Delta V_{REF}}{\Delta V_Z}$	$I_Z = 10\text{mA}$ (Fig. 2)	$V_Z = V_{REF} \sim 10\text{V}$	-	0.5	2.0	mV/V
			$V_Z = 10\text{V} \sim 30\text{V}$	-	0.35	1.5	
Reference input current	I_{REF}	$R_1 = 10\text{K}\Omega$, $R_2 = \infty$ $I_L = 10\text{mA}$ (Fig. 2)	$T_A = 25^\circ\text{C}$	-	0.8	3.5	μA
			$T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$	-	-	4.5	
Deviation of reference input current over temperature	αI_{REF}	$R_1 = 10\text{K}\Omega$, $R_2 = \infty$ $I_L = 10\text{mA}$ $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (Fig. 2)	-	0.3	1.2	μA	
Minimum cathode current for regulation	$I_{Z(MIN)}$	$V_Z = V_{REF}$ (Fig. 1)	-	0.25	0.5	mA	
Off-state current	$I_{Z(OFF)}$	$V_Z = 30\text{V}$, $V_{REF} = 0\text{V}$ (Fig 3)	-	0.1	1.0	μA	
Dynamic output impedance ⁽²⁾	R_Z	$V_Z = V_{REF}$, $f = 1.0\text{KHz}$ $\Delta I_Z = 1.0\text{mA}$ to 50mA	-	0.08	0.3	Ω	

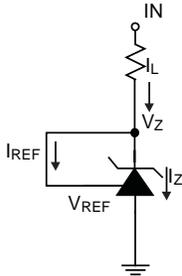
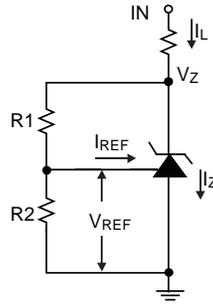


Fig. 1 Test Circuit for $V_Z = V_{REF}$



Note: $V_Z = V_{REF}(1 + R_1/R_2) + I_{REF}R_1$

Fig. 2 Test Circuit for $V_Z > V_{REF}$

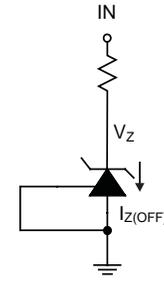
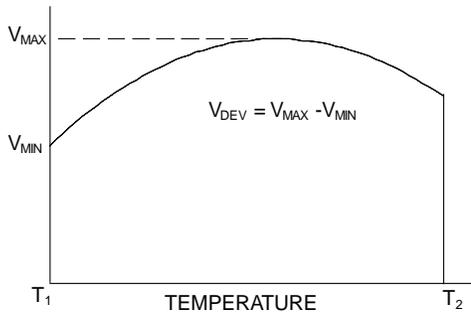


Fig. 3 Test Circuit for off-state current

Note 1. Deviation of reference input voltage, ΔV_{REF} , is defined as the maximum variation of the reference input voltage over the full temperature range.



The average temperature coefficient of the reference input voltage, αV_{REF} is defined as:

$$\alpha V_{REF} \frac{\text{ppm}}{^\circ\text{C}} = \frac{\pm \left[\frac{V_{MAX} - V_{MIN}}{V_{REF}(\text{at } 25^\circ\text{C})} \right] 10^6}{T_2 - T_1} = \frac{\pm \left[\frac{V_{DEV}}{V_{REF}(\text{at } 25^\circ\text{C})} \right] 10^6}{T_2 - T_1}$$

Where:

$T_2 - T_1$ = full temperature change.

The slope can be positive or negative depending on whether V_{MAX} or V_{MIN} occurs at the lower ambient temperature.

Example: $\Delta V_{REF} = 9.0\text{mV}$, $V_{REF} = 2495\text{mV}$,
 $T_2 - T_1 = 70^\circ\text{C}$, slope is positive.

$$\alpha V_{REF} = \frac{\left[\frac{9.0\text{mV}}{2495\text{mV}} \right] 10^6}{70^\circ\text{C}} = 50\text{ppm}/^\circ\text{C}$$

Note 2. The dynamic output impedance, R_Z , is defined as:

$$R_Z = \frac{\Delta V_Z}{\Delta I_Z}$$

When the device is programmed with two external resistors, R_1 and R_2 , (see Fig. 2), the dynamic output impedance of the overall circuit, is defined as:

$$r_Z = \frac{\Delta V_Z}{\Delta I_Z} \approx R_Z \left[1 + \frac{R_1}{R_2} \right]$$

Typical Performance Characteristics

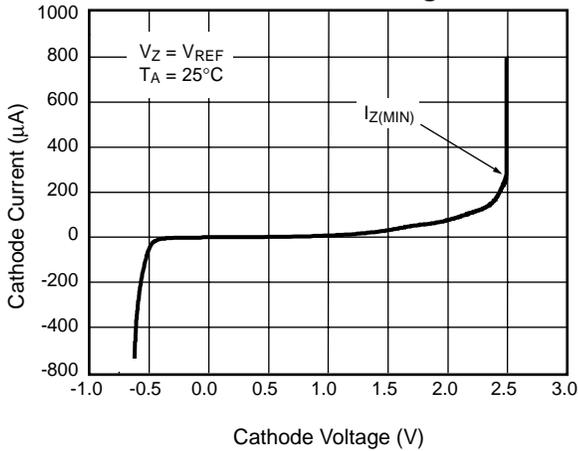
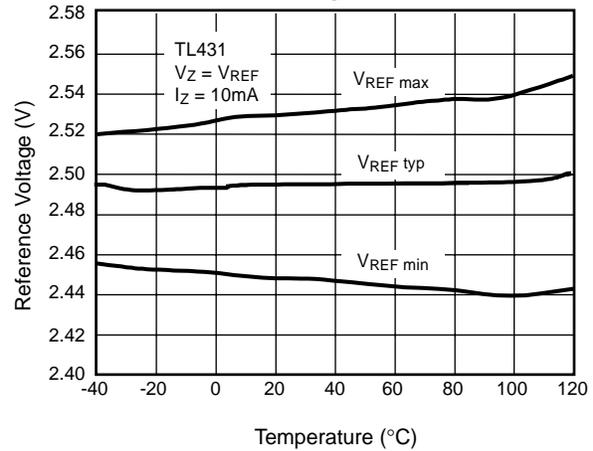
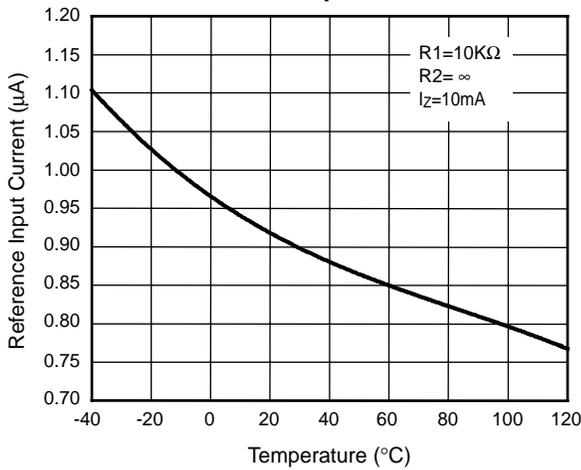
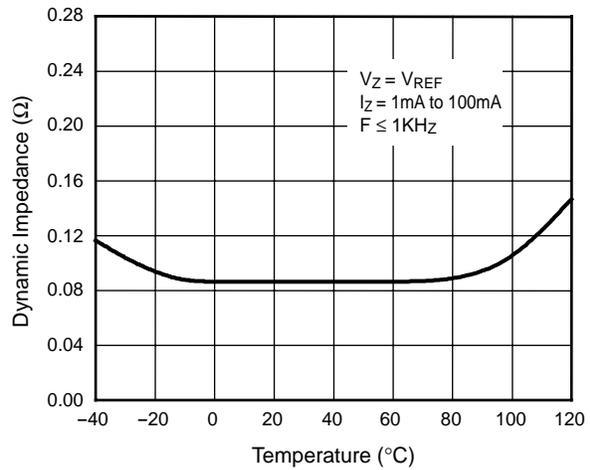
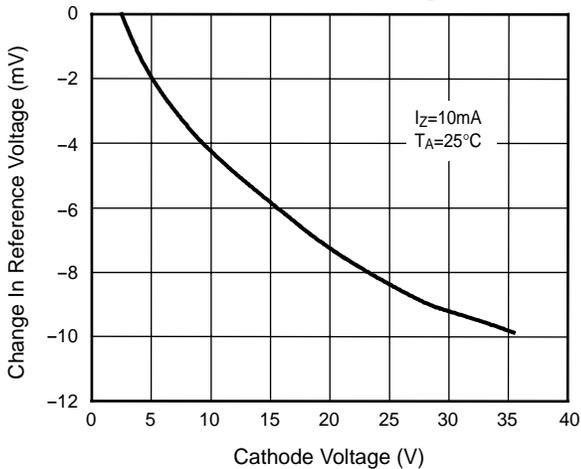
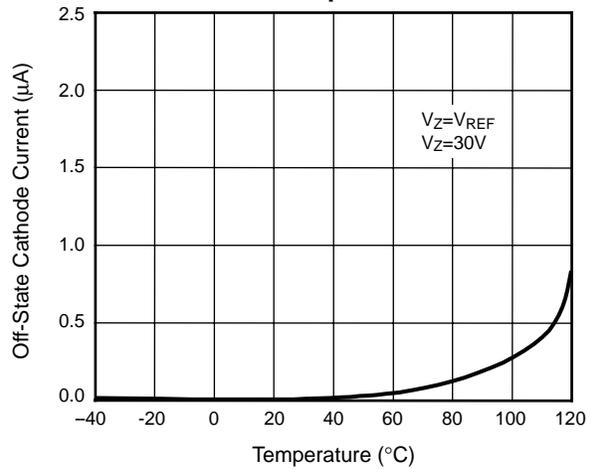
Fig. 4 – Cathode Current vs. Cathode Voltage

Fig. 5 – Reference Voltage vs. Temperature

Fig. 6 – Reference Input Current vs. Temperature

Fig. 7 – Dynamic Impedance vs. Temperature

Fig. 8 – Change in Reference Voltage vs. Cathode Voltage

Fig. 9 – Off-State Cathode Current vs. Temperature


Fig. 10 – Small Signal Voltage Amplification vs. Frequency

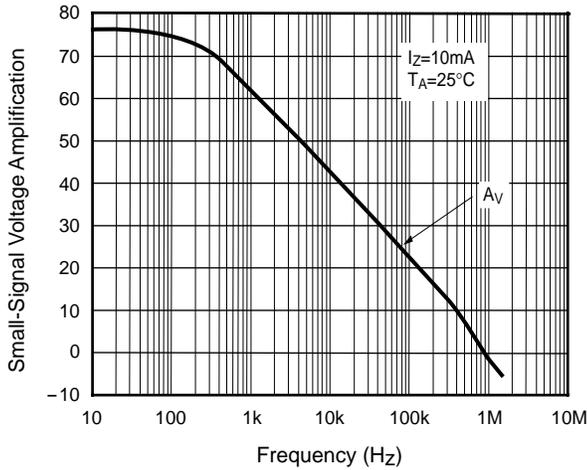


Fig. 11 – Test Circuit Frequency Response

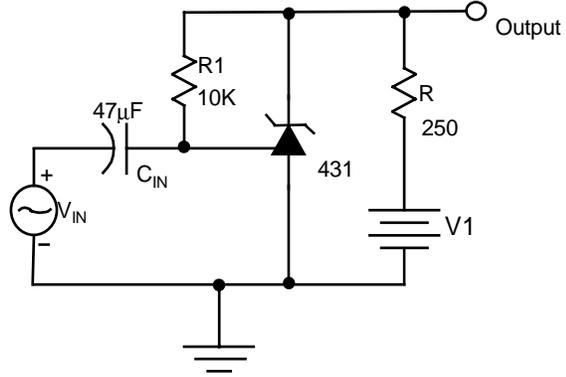


Fig. 12 – Pulse Response

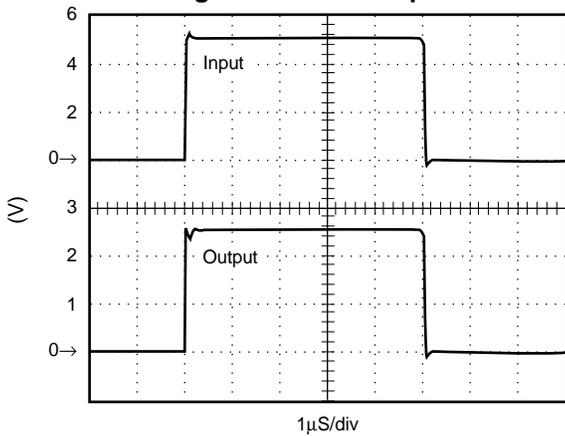


Fig. 13 – Test Circuit For Pulse

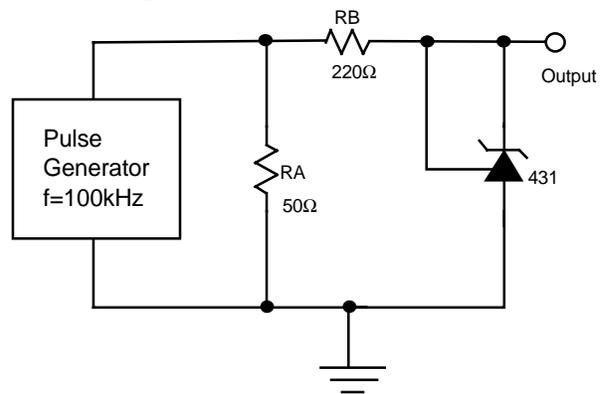


Fig. 14 – Dynamic Impedance vs.

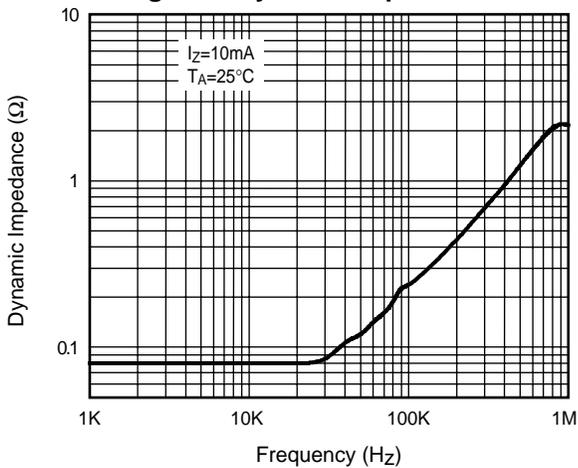
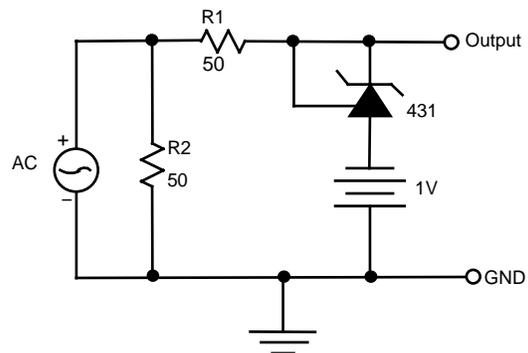
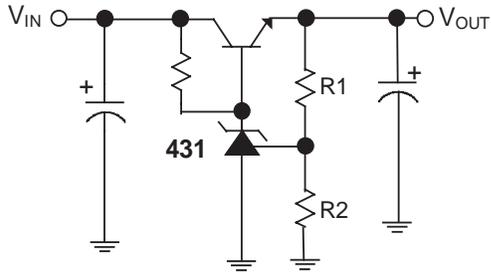


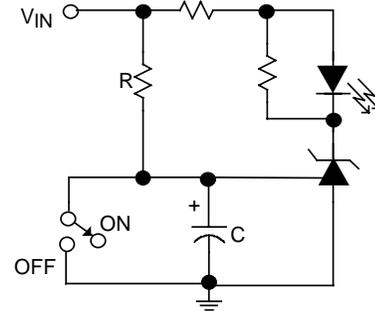
Fig. 15 – Test Circuit for Dynamic



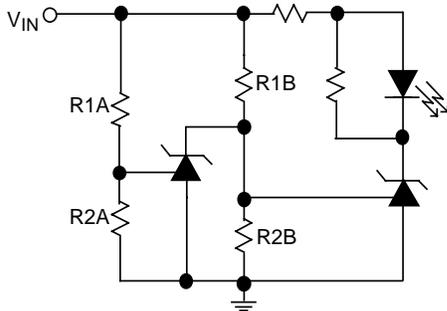
Application Examples

Fig. 16 – Typical Application Circuit


$$V_{OUT} = (1 + R1/R2) \times V_{REF}$$

Precision Regulator
Fig. 17 – Delay Timer


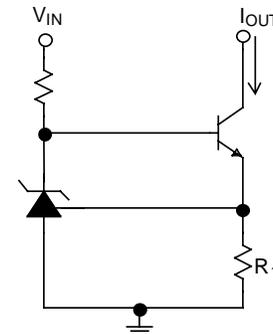
$$\text{Delay} = R \times C \times n \left(\frac{V_{IN}}{V_{IN} - V_{REF}} \right)$$

Fig. 18 – Voltage Monitor


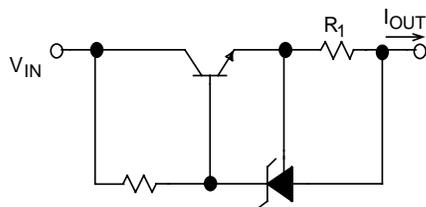
LED on when Low Limit < V_{IN} < High Limit

Low Limit $\cong V_{REF} (1 + R1B/R2B)$

High Limit $\cong V_{REF} (1 + R1A/R2A)$

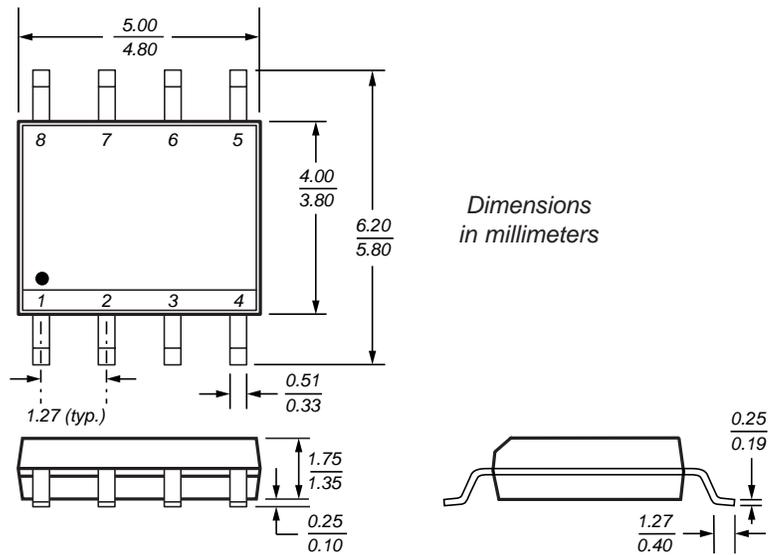
Fig. 19 – Constant-Current Sink


$$I_{OUT} = V_{REF} / R_1$$

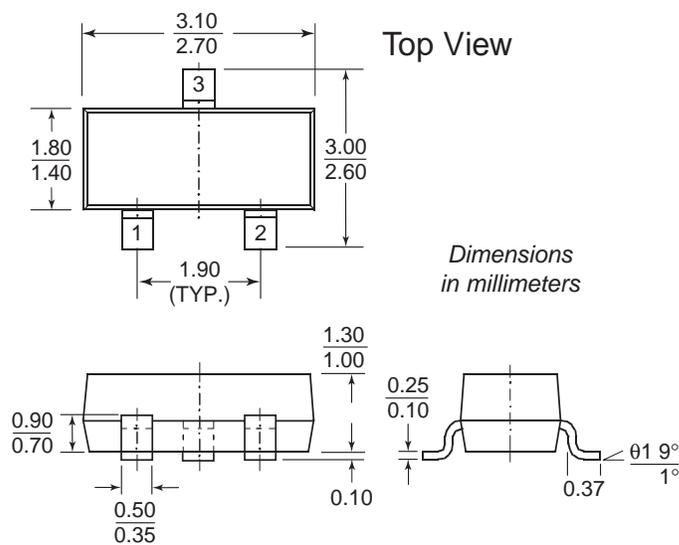
Fig. 20 – Current Limiter or Current Source


$$I_{OUT} = V_{REF} / R_1$$

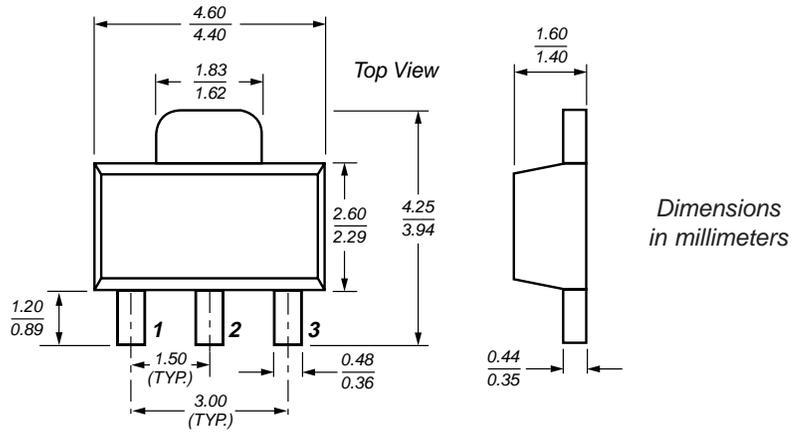
SO-8 Case Outline



SOT-23 Case Outline



SOT-89 Case Outline



TO-92 Case Outline

