



IF Digitally Controlled Variable-Gain Amplifier

MAX2027

General Description

The MAX2027 high-performance, digitally controlled variable-gain amplifier is designed for use from 50MHz to 400MHz.

The device integrates a digitally controlled attenuator and a high-linearity IF amplifier in one package. Targeted for IF signal chains to adjust gain either dynamically or as a one-time channel gain setting, the MAX2027 is ideal for applications requiring high performance. The attenuator provides 23dB of attenuation range with $\pm 0.2\text{dB}$ accuracy.

The MAX2027 is available in a thermally enhanced 20-pin TSSOP-EP package and operates over the -40°C to $+85^{\circ}\text{C}$ temperature range.

Applications

Cellular Base Stations
Receiver Gain Control
Transmitter Gain Control
Broadband Systems
Automatic Test Equipment
Terrestrial Links

Features

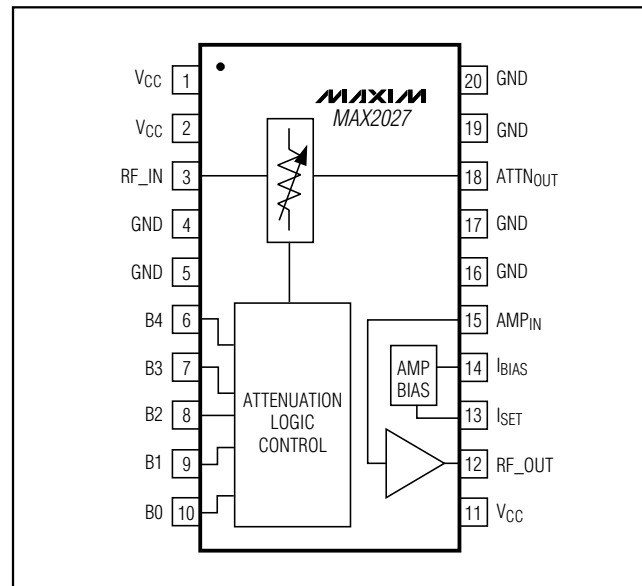
- ◆ 50MHz to 400MHz Frequency Range
- ◆ Variable Gain: -8dB to +15dB
- ◆ Output IP3: 40dBm (at All Gain Settings and 50MHz)
- ◆ Noise Figure: 4.7dB at Maximum Gain
- ◆ Digitally Controlled Gain with 1dB Resolution and $\pm 0.2\text{dB}$ Accuracy

Ordering Information

| PART | TEMP RANGE | PIN-PACKAGE |
|--------------|--|--------------|
| MAX2027EUP-T | -40°C to $+85^{\circ}\text{C}$ | 20 TSSOP-EP* |

*EP = exposed pad.

Pin Configuration/ Functional Diagram



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ABSOLUTE MAXIMUM RATINGS

All Pins (except B0–B4)
 to GND -0.3V to +5.5V
 Input Voltage Levels (B0–B4) -0.3V to ($V_{CC} + 0.5V$)
 RF Input Signal 20dBm
 Continuous Power Dissipation ($T_A = +70^\circ\text{C}$)
 20-Pin TSSOP-EP
 (derate 21.7mW/ $^\circ\text{C}$ above $+70^\circ\text{C}$) 1.7W

Operating Temperature Range -40°C to $+85^\circ\text{C}$
 Junction Temperature $+150^\circ\text{C}$
 Storage Temperature Range -65°C to $+165^\circ\text{C}$
 Lead Temperature (soldering, 10s) $+300^\circ\text{C}$

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

DC ELECTRICAL CHARACTERISTICS

(Typical application circuit, $V_{CC} = +4.75V$ to $+5.25V$, $GND = 0V$. No RF signals applied, and RF input and output ports are terminated with 50Ω . $R1 = 825\Omega$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$. Typical values are at $V_{CC} = +5V$ and $T_A = +25^\circ\text{C}$, unless otherwise noted.) (Notes 1, 2)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|-------------------------------|-----------|------------|----------------|-----|------|---------------|
| SUPPLY | | | | | | |
| Supply Voltage | V_{CC} | | 4.75 | 5 | 5.25 | V |
| Supply Current | I_{CC} | | | 60 | 70 | mA |
| I_{SET} Current | I_{SET} | | | 0.9 | | mA |
| CONTROL INPUTS/OUTPUTS | | | | | | |
| Control Bits | | Parallel | | 5 | | Bits |
| Input Logic High | | (Note 3) | $V_{CC} - 0.5$ | | | V |
| Input Logic Low | | | | | 0.5 | V |
| Input Leakage Current | | | -2 | | +2 | μA |

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AC ELECTRICAL CHARACTERISTICS

(Typical application circuit without matching, $V_{CC} = +4.75V$ to $+5.25V$, $GND = 0V$, max gain ($B0 = B1 = B2 = B3 = B4 = 0$), $R_1 = 825\Omega$, $P_{OUT} = 5dBm$, $f_{IN} = 50MHz$, 50Ω RF system impedance. Typical values are at $V_{CC} = +5V$ and $T_A = +25^\circ C$, unless otherwise noted.) (Notes 1, 2)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|----------------------------------|-----------|--|-----|-----------|-----|-------|
| Frequency Range | f_R | | 50 | | 400 | MHz |
| Gain | G | Max gain | | 15.3 | | dB |
| Noise Figure | NF | Max gain | | 4.7 | | dB |
| Minimum Reverse Isolation | | Max gain | | 22 | | dB |
| Output 1dB Compression Point | P_{1dB} | Max gain | | 20.6 | | dBm |
| 2nd-Order Output Intercept Point | OIP2 | $f_1 + f_2$, $f_1 = 50MHz$, $f_2 = 51MHz$, 5dBm/tone at RF_OUT | | 42 | | dBm |
| 3rd-Order Output Intercept Point | OIP3 | All gain conditions, 5dBm/tone at RF_OUT | | 40 | | dBm |
| 2nd Harmonic | $2f_{IN}$ | All gain conditions | | -42 | | dBc |
| 3rd Harmonic | $3f_{IN}$ | All gain conditions | | -68 | | dBc |
| RF Gain-Control Range | | | | 23 | | dB |
| Gain-Control Resolution | | | | 1 | | dB |
| Attenuation Absolute Accuracy | | Compared to the ideal expected attenuation | | ± 0.2 | | dB |
| Attenuation Relative Accuracy | | Between adjacent states | | ± 0.2 | | dB |
| Gain Drift Over Temperature | | $T_A = -40^\circ C$ to $+85^\circ C$ | | ± 0.1 | | dB |
| Gain Flatness Over 50MHz BW | | Peak-to-peak for all settings | | 0.3 | | dB |
| Attenuator Switching Time | | 50% control to 90% RF | | 40 | | ns |
| Input Return Loss | | $f_R = 50MHz$ to $150MHz$, all gain conditions | | 15 | | dB |
| Output Return Loss | | $f_R = 50MHz$ to $150MHz$, all gain conditions | | 15 | | dB |

Note 1: Guaranteed by design and characterization.

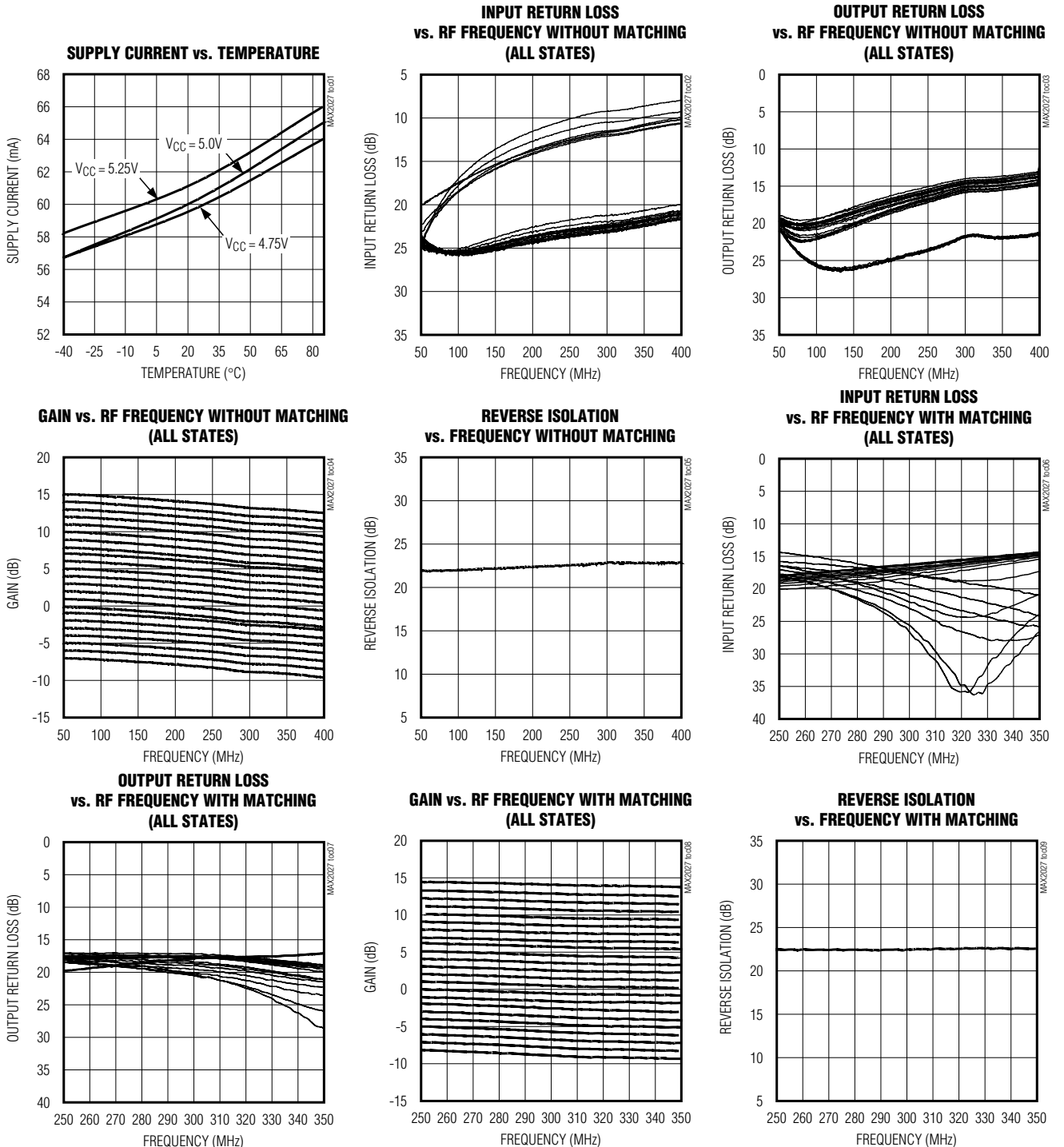
Note 2: All limits reflect losses of external components. Output measurements are taken at RF OUT using the typical application circuit.

Note 3: Device draws current in excess of the specified supply current when a digital input is driven with a voltage of $V_{IN} < V_{CC} - 0.5V$ or $V_{IN} > 0.5V$. This is due to the CMOS input stage crowbar current. Part may be damaged if operated in this condition for an extended period of time.

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Typical Operating Characteristics

(Typical application circuit, $V_{CC} = 5.0V$, max gain ($B0 = B1 = B2 = B3 = B4 = 0$), $P_{OUT} = 5dBm$, $R_1 = 825\Omega$, $T_A = +25^\circ C$, unless otherwise noted. External matching components for 300MHz in Table 2 are used for matched circuit.)



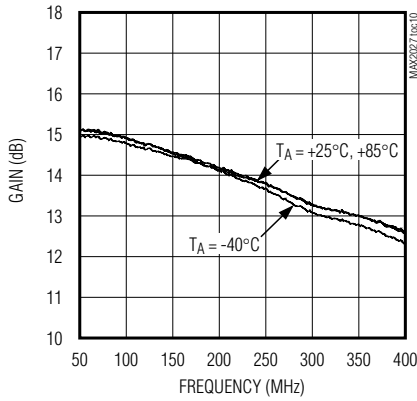
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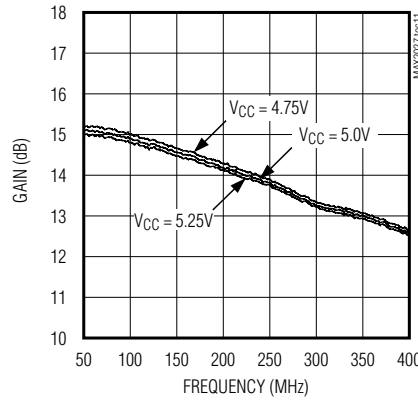
Typical Operating Characteristics (continued)

(Typical application circuit, $V_{CC} = 5.0V$, max gain ($B_0 = B_1 = B_2 = B_3 = B_4 = 0$), $P_{OUT} = 5dBm$, $R_1 = 825\Omega$, $T_A = +25^\circ C$, unless otherwise noted. External matching components for 300MHz in Table 2 are used for matched circuit.)

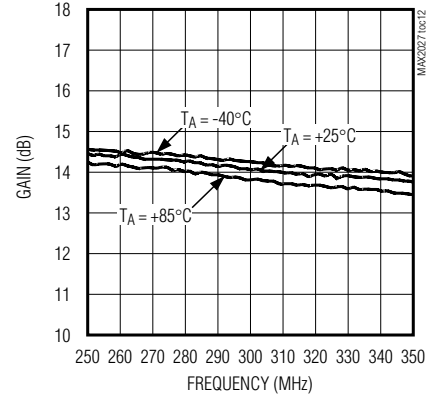
GAIN vs. FREQUENCY WITHOUT MATCHING



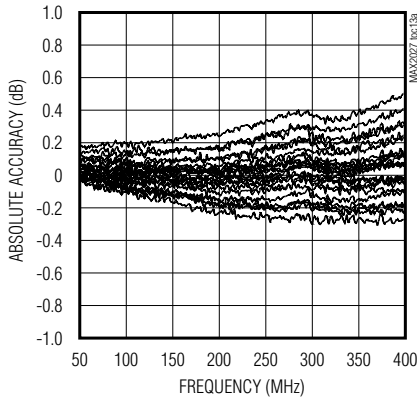
GAIN vs. FREQUENCY WITHOUT MATCHING



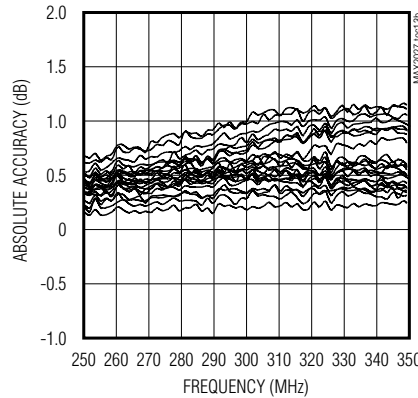
GAIN vs. FREQUENCY WITH MATCHING



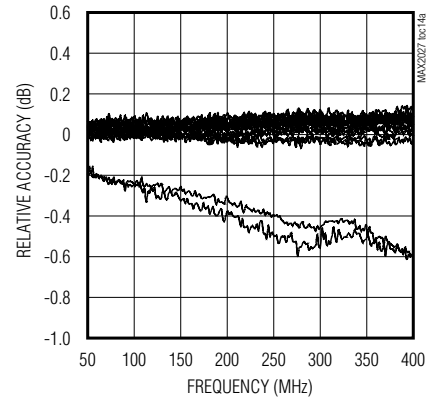
ATTENUATION ABSOLUTE ACCURACY WITHOUT MATCHING (ALL STATES)



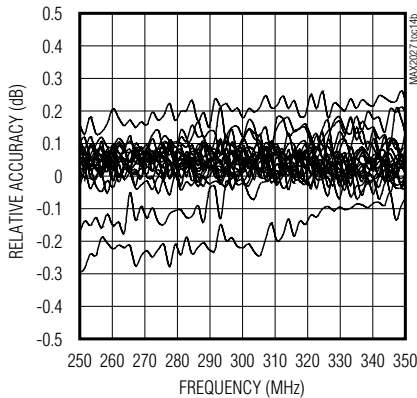
ATTENUATION ABSOLUTE ACCURACY WITH MATCHING (ALL STATES)



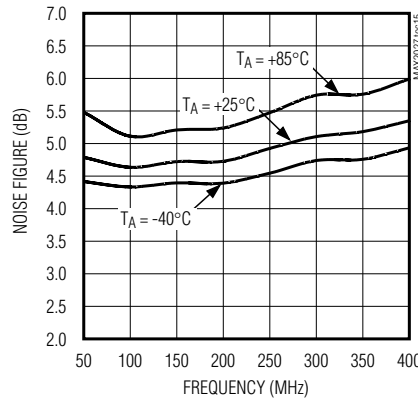
ATTENUATION RELATIVE ACCURACY WITHOUT MATCHING (ALL STATES)



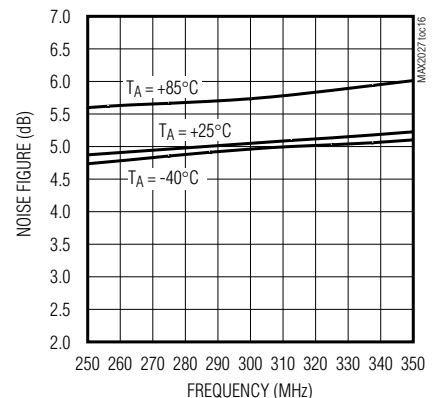
ATTENUATION RELATIVE ACCURACY WITH MATCHING (ALL STATES)



NOISE FIGURE vs. FREQUENCY WITHOUT MATCHING



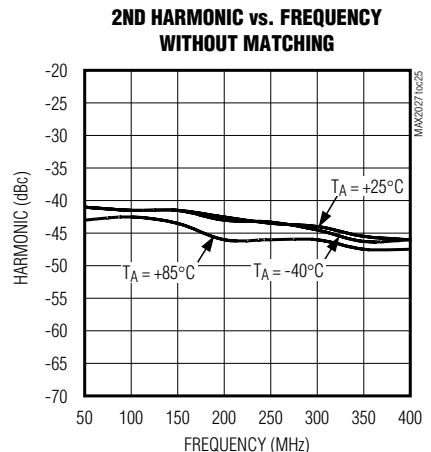
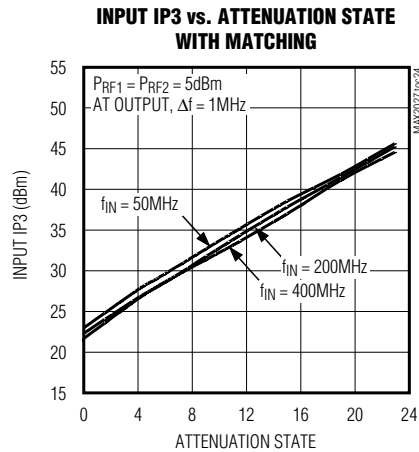
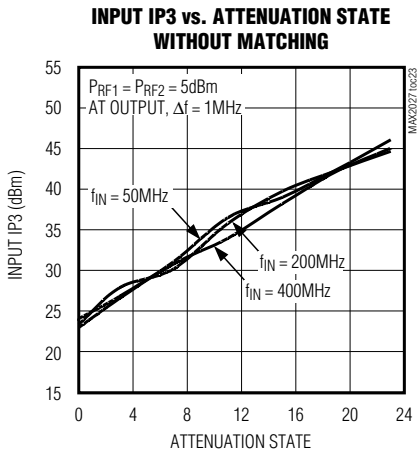
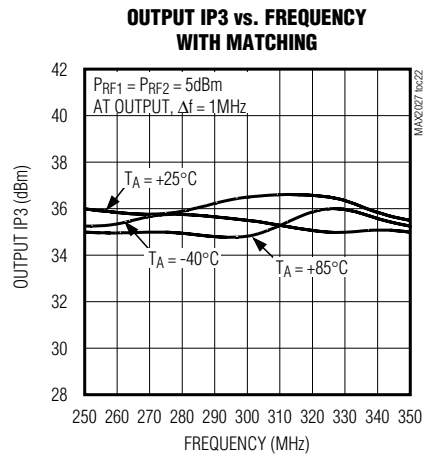
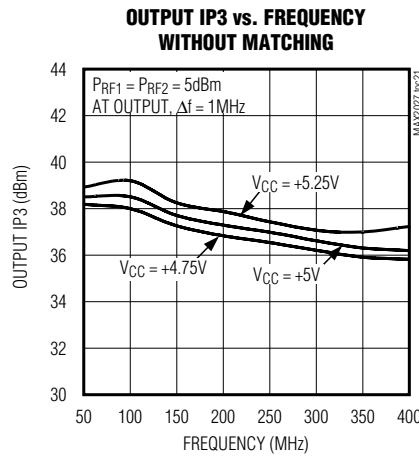
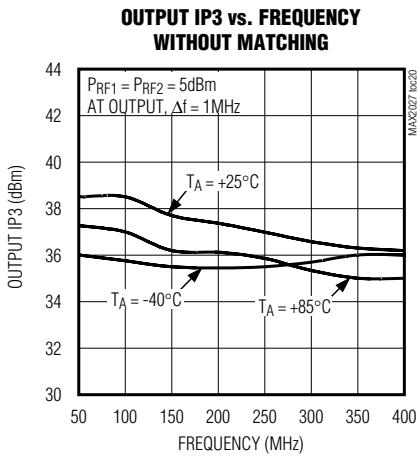
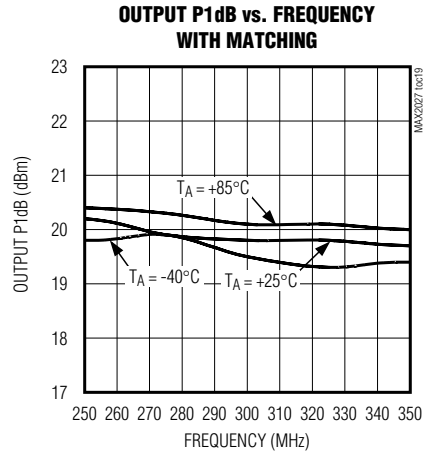
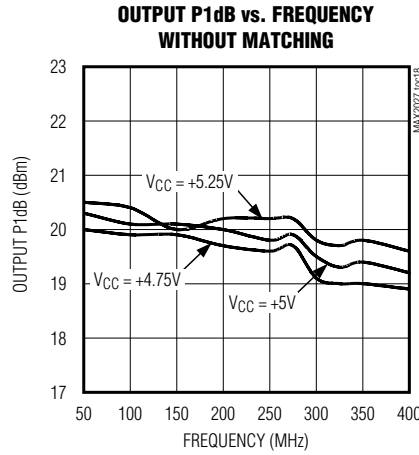
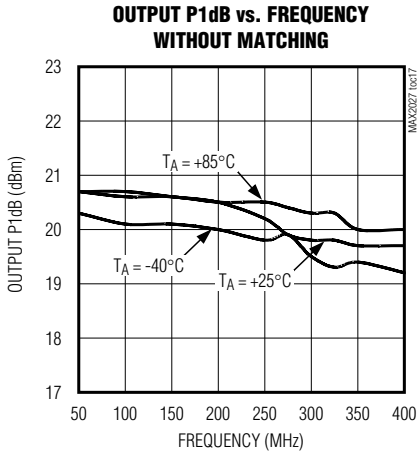
NOISE FIGURE vs. FREQUENCY WITH MATCHING



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Typical Operating Characteristics (continued)

(Typical application circuit, $V_{CC} = 5.0V$, max gain ($B0 = B1 = B2 = B3 = B4 = 0$), $P_{OUT} = 5dBm$, $R_1 = 825\Omega$, $T_A = +25^\circ C$, unless otherwise noted. External matching components for 300MHz in Table 2 are used for matched circuit.)

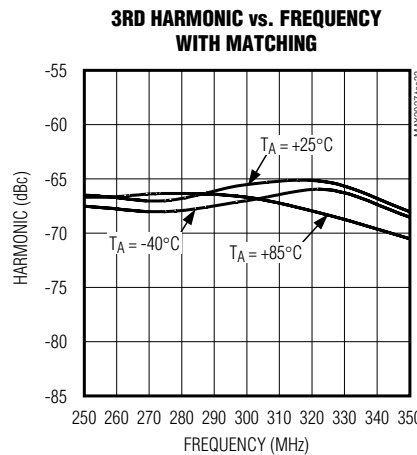
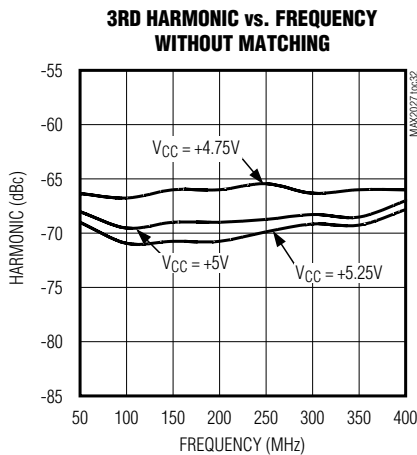
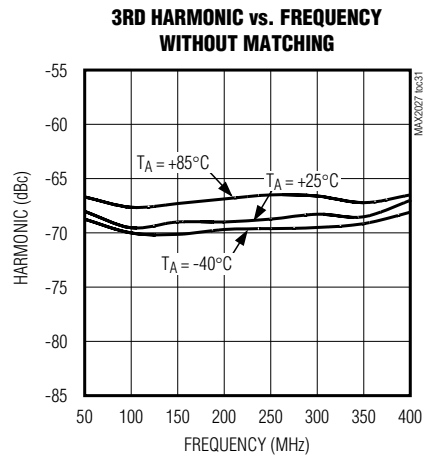
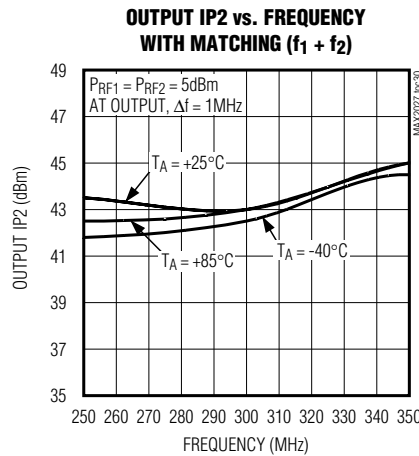
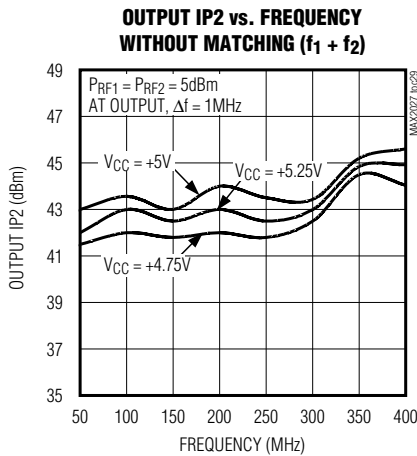
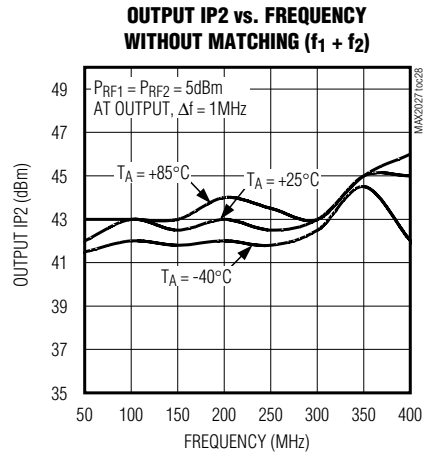
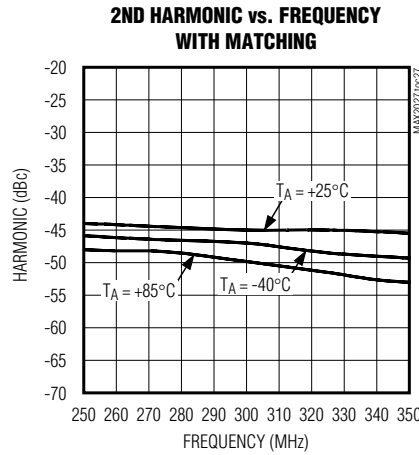
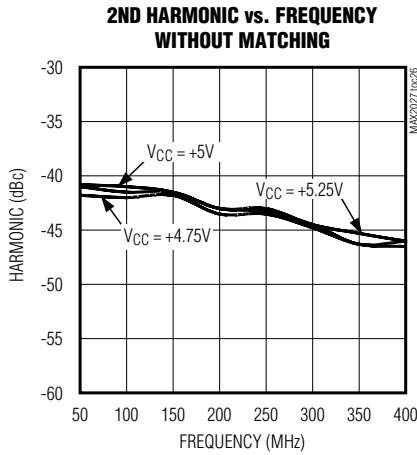


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Typical Operating Characteristics (continued)

(Typical application circuit, $V_{CC} = 5.0V$, max gain ($B0 = B1 = B2 = B3 = B4 = 0$), $P_{OUT} = 5dBm$, $R_1 = 825\Omega$, $T_A = +25^\circ C$, unless otherwise noted. External matching components for 300MHz in Table 2 are used for matched circuit.)



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Pin Description

| PIN | NAME | FUNCTION |
|--------------------------|---------------------|--|
| 1, 2, 11 | V _{CC} | Power Supply. Bypass to GND with capacitors as close to the pin as possible as shown in the typical application circuit (Figure 1). |
| 3 | RF_IN | Signal Input. See the typical application circuit for recommended component values. Requires an external DC-blocking capacitor. |
| 4, 5, 16, 17, 19, 20, EP | GND | Ground. Use low-inductance layout techniques on PC board. Solder the exposed pad evenly to the board ground plane. |
| 6–10 | B4–B0 | Gain-Control Bits. See Table 3 for gain setting. |
| 12 | RF_OUT | Signal Output. Requires an external pullup choke inductor (52mA typical current) to V _{CC} along with a DC-blocking capacitor (Figure 1). |
| 13 | I _{SET} | Connect an 825Ω resistor from I _{SET} to GND. |
| 14 | I _{BIAS} | Amplifier Bias. Connect to AMP _{IN} (pin 15) through a choke inductor (0.3mA typ). |
| 15 | AMP _{IN} | Amplifier Input. Requires a DC-coupling capacitor to allow biasing. |
| 18 | ATTN _{OUT} | Attenuator Output. Requires an external DC-blocking capacitor. |

Detailed Description

The MAX2027 is a high-performance, digitally controlled variable-gain amplifier for use in applications from 50MHz to 400MHz.

The MAX2027 incorporates a digital attenuator with a 23dB selectable attenuation range followed by a fixed-gain, high-linearity amplifier. The attenuator is digitally controlled through five logic lines: B0–B4. This on-chip attenuator provides up to 23dB of attenuation with ±0.2dB accuracy. The fixed-gain amplifier utilizes negative feedback to achieve high stability, gain, linearity, and wide bandwidth.

Applications Information

Input and Output Matching

The MAX2027 incorporates on-chip input and output matching for operation below 150MHz. Use a DC-blocking capacitor value of 1000pF for pins 3, 12, and 18 (see Figure 1). For operation above 150MHz, external matching improves performance. Table 1 and Table 2 provide recommended components for device operation.

Digitally Controlled Attenuator

The digital attenuator is controlled through five logic lines: B0, B1, B2, B3, and B4. Table 3 lists the attenuation settings. The input and output of this attenuator require external DC-blocking capacitors. This attenuator insertion loss is 2dB when the attenuator is set to 0dB (B0 = B1 = B2 = B3 = B4 = 0).

Table 1. Suggested Components of Typical Application Circuit

| COMPONENT | VALUE | SIZE |
|-------------------------|----------|------|
| C1, C3, C4, C6, C7, C10 | 1000pF | 0603 |
| C2, C5 | 100pF | 0603 |
| R1 | 825Ω ±1% | 0603 |
| R2–R6 | 47kΩ | 0603 |
| L1 | 330nH | 0805 |
| L2 | 680nH | 1008 |

Table 2. Suggested Matching Components

| FREQUENCY | COMPONENT | VALUE | SIZE |
|-----------|-----------|-------|------|
| 200MHz | L3, L4 | 18nH | 0603 |
| | C8, C9 | 8pF | 0603 |
| 250MHz | L3, L4 | 15nH | 0603 |
| | C8, C9 | 8pF | 0603 |
| 300MHz | L3, L4 | 11nH | 0603 |
| | C8, C9 | 7pF | 0603 |
| 400MHz | L3, L4 | 10nH | 0603 |
| | C8, C9 | 5pF | 0603 |

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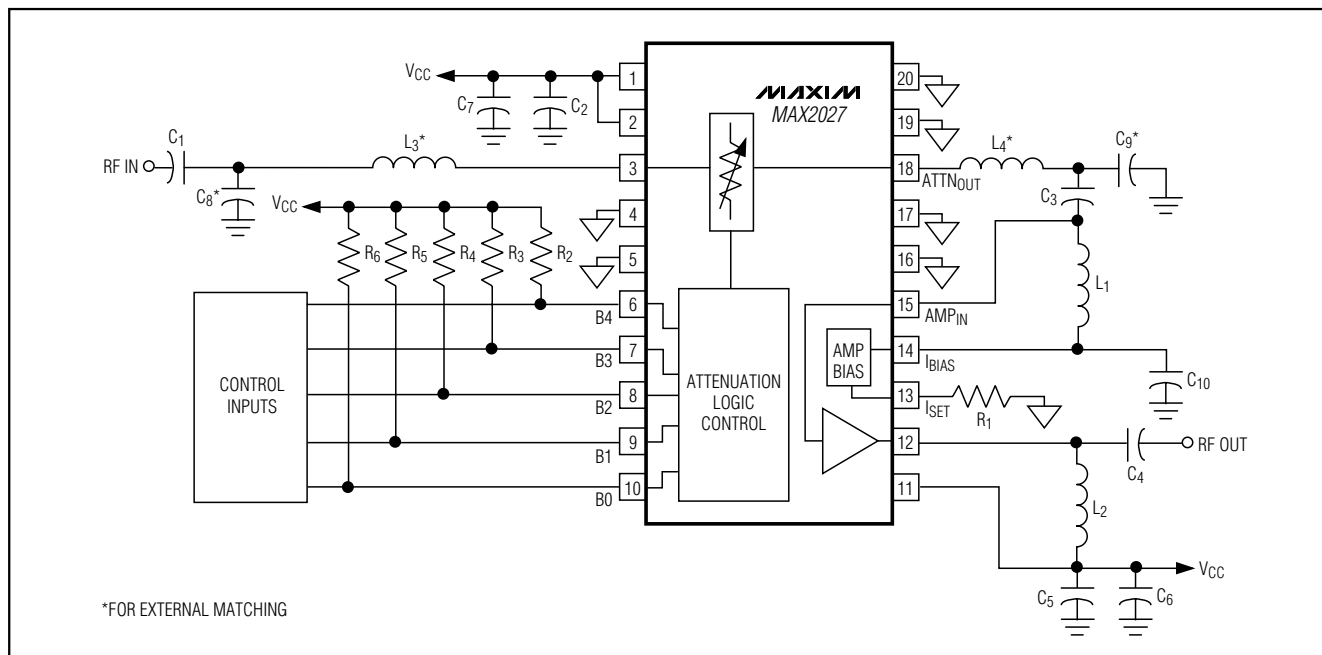


Figure 1. Typical Application Circuit

Fixed-Gain Amplifier

The MAX2027 integrates a fixed-gain amplifier in a negative feedback topology. This fixed-gain amplifier is optimized for a frequency range of operation from 50MHz to 400MHz with a high-output third-order intercept point (OIP3). The bias current is chosen to optimize the IP₃ of the amplifier. When R₁ is 825Ω, the current consumption is 60mA while exhibiting a typical 40dBm output IP₃ at 50MHz.

Choke Inductor

The fixed-gain amplifier output port requires an external pullup choke inductor to V_{CC}. At the input, connect a bias inductor of 330nH from AMP_{IN} (pin 15) to IBIAS (pin 14). At the output, connect a 680nH choke inductor from RF_OUT (pin 12) to V_{CC} (pin 11) to provide bias current to the amplifier.

Layout Considerations

A properly designed PC board is an essential part of any RF/microwave circuit. Keep RF signal lines as short as possible to reduce losses, radiation, and induc-

tance. For the best performance, route the ground pin traces directly to the exposed pad under the package. Solder the exposed pad on the bottom of the device package evenly to the board ground plane to provide a heat transfer path along with RF grounding.

Power-Supply Bypassing

Proper voltage-supply bypassing is essential for high-frequency circuit stability. Bypass each V_{CC} pin with a 1000pF and 100pF capacitor. Connect the 100pF capacitor as close to V_{CC} pins as possible.

Exposed Pad RF/Thermal Considerations

The exposed paddle (EP) of the MAX2027's 20-pin TSSOP-EP package provides a low thermal-resistance path to the die. It is important that the PC board on which the MAX2027 is mounted be designed to conduct heat from the EP. In addition, provide the EP with a low-inductance path to electrical ground. The EP should be soldered to a ground plane on the PC board, either directly or through an array of plated via holes.

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Table 3. Attenuation Setting vs. Gain-Control Bits

| ATTENUATION 2dB MINIMUM INSERTION LOSS | B4 | B3* | B2 | B1 | B0 |
|--|----|-----|----|----|----|
| 0 | 0 | 0 | 0 | 0 | 0 |
| 1 | 0 | 0 | 0 | 0 | 1 |
| 2 | 0 | 0 | 0 | 1 | 0 |
| 3 | 0 | 0 | 0 | 1 | 1 |
| 4 | 0 | 0 | 1 | 0 | 0 |
| 5 | 0 | 0 | 1 | 0 | 1 |
| 6 | 0 | 0 | 1 | 1 | 0 |
| 7 | 0 | 0 | 1 | 1 | 1 |
| 8 | 0 | 1 | 0 | 0 | 0 |
| 9 | 0 | 1 | 0 | 0 | 1 |
| 10 | 0 | 1 | 0 | 1 | 0 |
| 11 | 0 | 1 | 0 | 1 | 1 |
| 12 | 0 | 1 | 1 | 0 | 0 |
| 13 | 0 | 1 | 1 | 0 | 1 |
| 14 | 0 | 1 | 1 | 1 | 0 |
| 15 | 0 | 1 | 1 | 1 | 1 |
| 16 | 1 | X | 0 | 0 | 0 |
| 17 | 1 | X | 0 | 0 | 1 |
| 18 | 1 | X | 0 | 1 | 0 |
| 19 | 1 | X | 0 | 1 | 1 |
| 20 | 1 | X | 1 | 0 | 0 |
| 21 | 1 | X | 1 | 0 | 1 |
| 22 | 1 | X | 1 | 1 | 0 |
| 23 | 1 | X | 1 | 1 | 1 |

*Enabling B4 disables B3, and the minimum attenuation is 16dB.

Chip Information
TRANSISTOR COUNT: 325

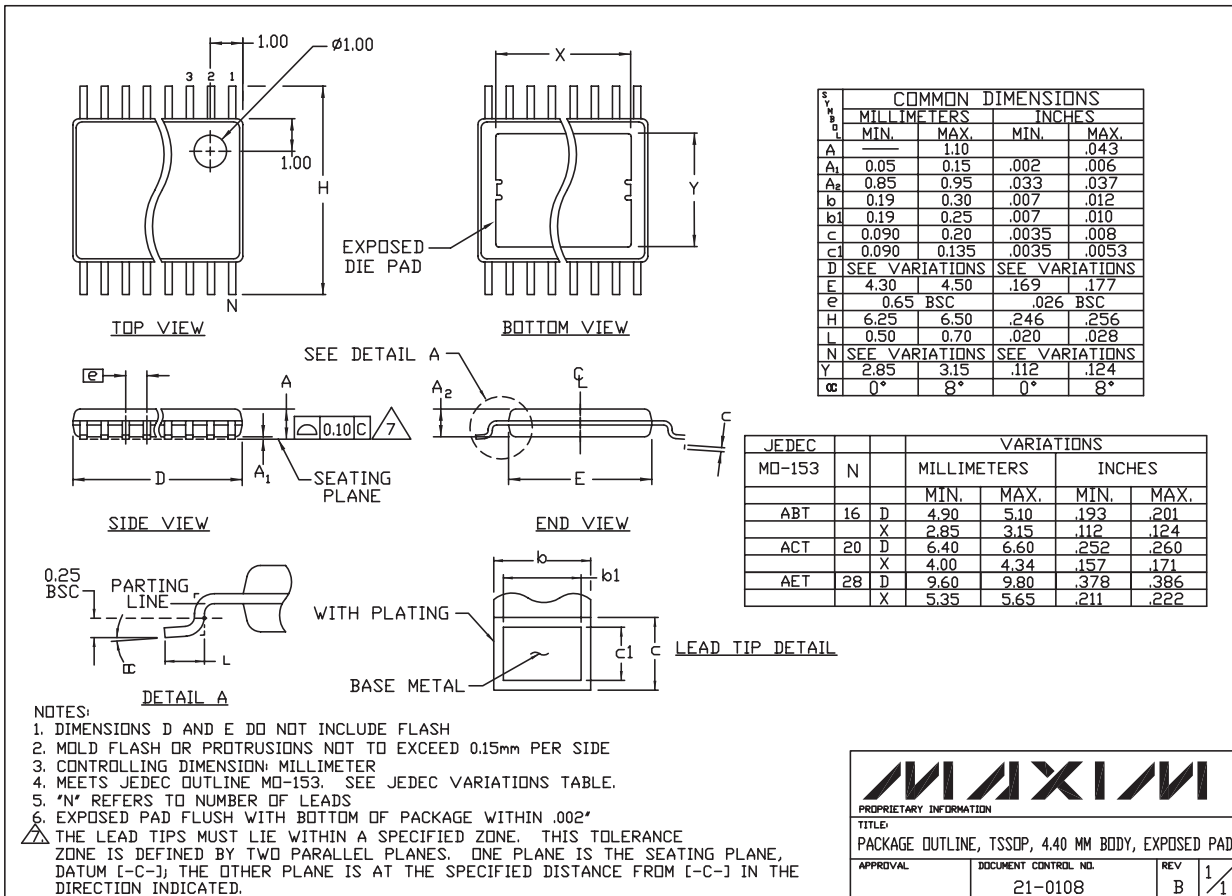
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Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to www.maxim-ic.com/packages.)

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TSSOP, 4.0 EXP PADS, EPS



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