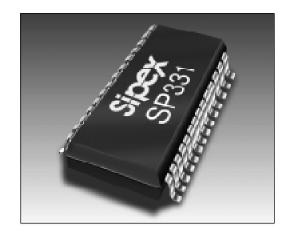


Programmable RS-232/RS-485 Transceiver

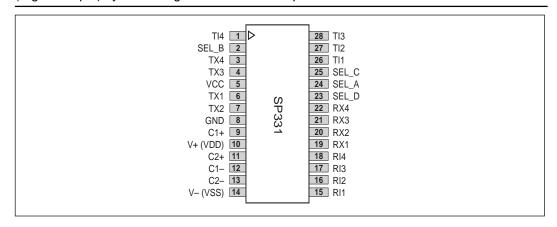
- +5V Only Operation
- Software Programmable RS-232 or RS-485 Selection
- Four RS-232 Transceivers in RS-232 Mode
- Two RS-485 Full-Duplex Transceivers in RS-485 Mode
- Two RS-232 Transceivers and One RS-485 Transceiver in Dual Mode
- Self-Testing Loopback Mode
- Full Driver Tri-State (Hi-Z) Control
- Ideal for RS-232 to RS-485 conversion



DESCRIPTION...

The **SP331** is a programmable RS-232 and/or RS-485 transceiver IC. The **SP331** contains four drivers and four receivers when selected in RS-232 mode; and two drivers and two receivers when selected in RS-485 mode. The **SP331** also contains a dual mode which has two RS-232 drivers/receivers plus one differential RS-485 driver/receiver.

The RS-232 transceivers can typically operate at 230kbps while adhering to the RS-232 specifications. The RS-485 transceivers can operate up to 10Mbps while adhering to the RS-485 specifications. The **SP331** includes a self-test loopback mode where the driver outputs are internally configured to the receiver inputs. This allows for easy diagnostic serial port testing without using an external loopback plug. The RS-232 and RS-485 drivers can be disabled (High-Z output) by controlling a set of four select pins.



ABSOLUTE MAXIMUM RATINGS

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

V _{CC}	+7V
Storage Temperature	65°C to +150°C
Power Dissipation	
28-pin Plastic DIP	1000mW
28-pin Plastic SOIC	1000mW

Package Derating: 28-pin Plastic DIP	
ø,,	40 °C/W
28-pin Plastic SOIC	
ø _{.JA}	40 °C/W

SPECIFICATIONS

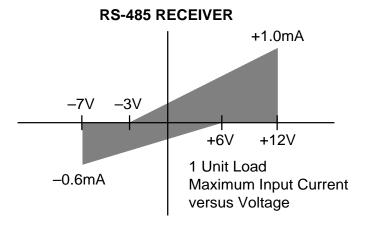
Typically 25°C @ Vcc = +5V unless otherwise noted.

	MIN.	TYP.	MAX.	UNITS	CONDITIONS
LOGIC INPUTS					
V_IL			0.8	Volts	
V _{IH}	2.0			Volts	
LOGIC OUTPUTS					
V _{OL}			0.4	Volts	I _{OUT} = -3.2mA
V _{OH}	2.4			Volts	I _{OUT} = 1.0mA
RS-232 DRIVER					
DC Characteristics					
HIGH Level Output	+5.0		+15	Volts	$R_L=3k\Omega$, $V_{IN}=0.8V$
LOW Level Output	-15.0		-5.0	Volts	$R_{I}^{L}=3k\Omega$, $V_{IN}^{IN}=2.0V$
Open Circuit Voltage	-15		+15	Volts	
Short Circuit Current			±100	mA	$V_{OUT} = 0V$
Power Off Impedance	300			Ω	$V_{cc}^{001} = 0V, V_{out} = \pm 2.0V$
AC Characteristics					
Slew Rate			30	V/µs	$R_1 = 3k\Omega$, $C_1 = 50pF$
				.,	V _{CC} = +5.0V, T _A @ +25°C
Transition Time			1.5	μs	$R_L=3k\Omega$, $C_L=2500pF$;
				·	between ±3V, T _△ @ +25°C
Maximum Data Rate	120	235		kbps	$R_1 = 3k\Omega$, $C_1 = 2500pF$
Propagation Delay					
t _{PHL}		2	8	μs	Measured from 1.5V of V _{IN}
t _{PLH}		2	8	μs	to 50% of V_{OUT} ; $R_L=3k\Omega$
RS-232 RECEIVER					
DC Characteristics					
HIGH Threshold		1.7	3.0	Volts	
LOW Threshold	0.8	1.2		Volts	
Receiver Open Circuit Bias			+2.0	Volts	
Input Impedance	3	5	7	kΩ	$V_{IN} = +15V \text{ to } -15V$
AC Characteristics					
Maximum Data Rate	120	235		kbps	
Propagation Delay					
t _{PHL}		0.25	1	μs	Measured from 50% of V _{IN}
t _{PLH}		0.25	1	μs	to 1.5V of V _{OUT} .
RS-485 DRIVER					
DC Characteristics					
Open Circuit Voltage			6.0	Volts	
Differential Output	1.5	1	5.0	Volts	$R_1 = 54\Omega$, $C_1 = 50pF$

Typically 25°C @ Vcc = +5V unless otherwise noted.

Typically 25°C @ Vcc = +5V unless otherw	MIN.	TYP.	MAX.	UNITS	CONDITIONS
RS-485 DRIVER					
Balance			±0.2	Volts	$ V_{\tau} - \overline{V_{\tau}} $
Common-Mode Output			3.0	Volts	
Output Current	28.0			mA	$R_L=54\Omega$
Short Circuit Current			±250	mA	Terminated in –7V to +10V
AC Characteristics					
Maximum Data Rate	10			Mbps	$R_1 = 54\Omega$
Output Transition Time	. •	30	50	ns	Rise/fall time, 10%–90%
Propagation Delay					See Figures 2 & 4
t _{PHL}		80	120	ns	$R_{DIFF} = 54\Omega, C_{L1} = C_{L2} = 100pF$
t _{PLH}		80	120	ns	$R_{DIFF} = 54\Omega, C_{L1} = C_{L2} = 100pF$
Driver Output Skew		10	20	ns	per Figure 4, t _{SKEW} = t _{DPLH} - t _{DPHL}
RS-485 RECEIVER					
DC Characteristics					
Inputs Common Mode Range	-7.0		+12.0	Volts	
Receiver Sensitivity	7.0	±0.2	±0.3	Volts	$-7V \le V_{CM} \le +12V$
Input Impedance	12	15		kΩ	$-7V \le V_{CM} \le +12V$
					Civi
AC Characteristics					
Maximum Data Rate	10			Mbps	Con Figures 2 8 6
Propagation Delay		130	200	ns	See Figures 2 & 6
t _{PHL} t _{PLH}		130	200	ns	${ m R_{DIFF}}$ =54 Ω , ${ m C_{L1}}$ =C $_{L2}$ =100pF ${ m R_{DIFF}}$ =54 Ω , ${ m C_{L1}}$ =C $_{L2}$ =100pF
Differential Receiver Skew		10	20	ns	$t_{\text{DIFF}} = 121, \ \theta_{11} = \theta_{12} = 100 \text{ f}$ $t_{\text{DIFF}} = 11, \ \text{L} = 100 \text{ f}$ $t_{\text{DIFF}} = 54\Omega,$
					$t_{SKEW} = t_{PLH} - t_{PHL} ; R_{DIFF} = 54\Omega,$ $C_{L1} = C_{L2} = 100pF$
ENABLE TIMING					
RS-485 Driver					
Enable Time Enable to Low		00	150	20	See Figures 3 & 5
Enable to Low Enable to High		90 90	150 150	ns ns	C_L =15pF, S_1 Closed C_1 =15pF, S_2 Closed
Disable Time		00	100	110	See Figures 3 & 5
Disable From Low		80	120	ns	C _L =15pF, S ₁ Closed
Disable From High		80	120	ns	C _L =15pF, S ₂ Closed
BOWED DECLIBERATION					
POWER REQUIREMENTS	. 4 75			\/o!+-	
Supply Voltage V _{CC} Supply Current I _{CC}	+4.75		+5.25	Volts	
No Load (T _x Disabled)		10	15	mA	SEL A → SEL D = "0001"
No Load (RS-232 Mode)		15	30	mA	SEL_A → SEL_D = "0000"
No Load (RS-485 Mode)		7	20	mA	SEL_A ⇒ SEL_D = "1100"
ENVIRONMENTAL					
Operating Temperature	0		. 70		
Commercial (C) Industrial (E)	0 –40		+70 +85	°C °C	
Storage Temperature	-40 -65		+150	ي ي	
	30				

RECEIVER INPUT GRAPH



TEST CIRCUITS

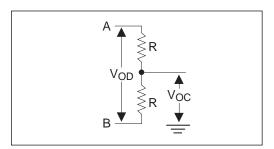


Figure 1. Driver DC Test Load Circuit

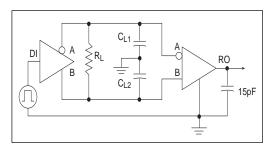


Figure 2. Driver/Receiver Timing Test Circuit

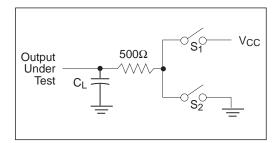


Figure 3. Driver Timing Test Load #2 Circuit

SWITCHING WAVEFORMS

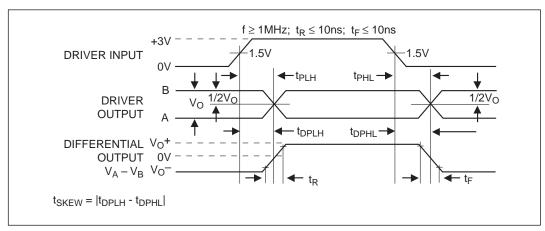


Figure 4. Driver Propagation Delays

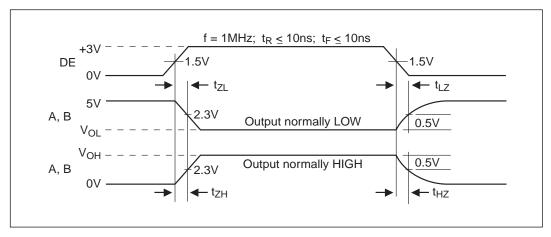


Figure 5. Driver Enable and Disable Times

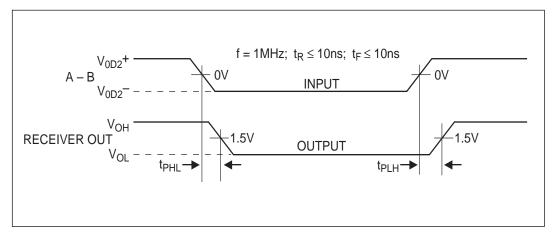


Figure 6. Receiver Propagation Delays

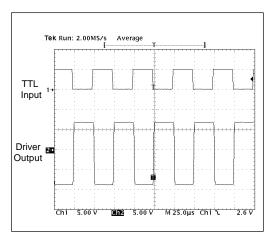


Figure 7. Typical RS-232 Driver Output

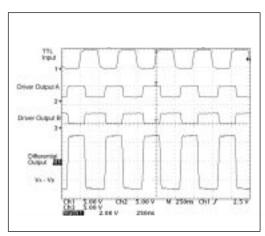


Figure 8. Typical RS-485 Driver Output

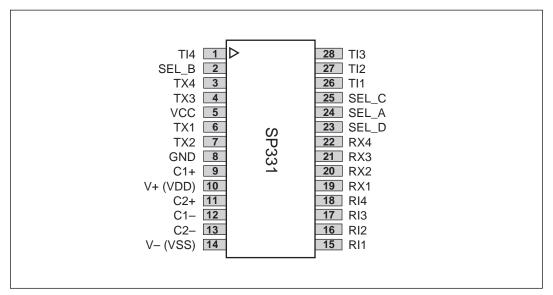


Figure 9. SP331 Pinout

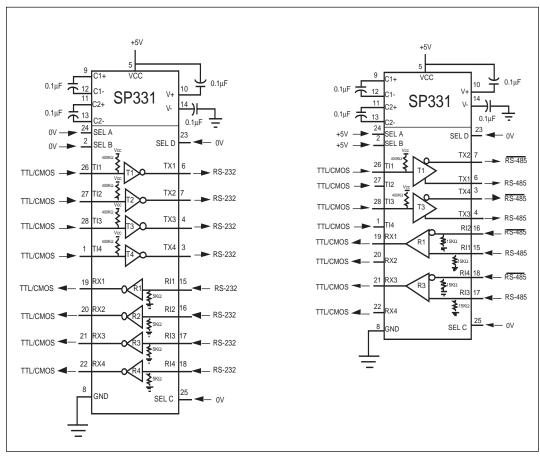


Figure 10. Typical Operating Circuit

FUNCTION TABLE FOR SELECT PINS

<u>A</u>	<u>B</u>	<u>C</u>	<u>D</u>	MODE	<u>FUNCTION</u>
0	0	0	0	RS-232	All four RS-232 drivers active
0	0	0	1	RS-232	All four RS-232 drivers tri-state
0	0	1	0	RS-232	All four RS-232 drivers tri-state
0	0	1	1	RS-232	RS-232 (4ch) Loopback
0	1	0	0	RS-232/RS-485	T1 and T2 active RS-232; T3 tri-state RS-485
0	1	0	1	RS-232/RS-485	T1 and T2 tri-state RS-232; T3 active RS-485
0	1	1	0	RS-232/RS-485	T1 and T2 active RS-232; T3 tri-state RS-485
0	1	1	1	RS-232/RS-485	RS-232 (2ch) / RS-485 (1ch) Loopback
1	0	0	0	RS-485/RS-232	T1 active RS-485; T2 and T3 active RS-232
1	0	0	1	RS-485/RS-232	T1 tr-state RS-485; T3 active RS-232; T4 active RS232
1	0	1	0	RS-485/RS-232	All RS-485 and RS-232 drivers tri-state
1	0	1	1	RS-485/RS-232	RS-485 (1ch) / RS-232 (2ch) Loopback
1	1	0	0	RS-485	T1 and T3 active RS-485
1	1	0	1	RS-485	T1 tri-state RS-485; T3 active RS-485
1	1	1	0	RS-485	T1 active RS-485; T3 tri-state RS-485
1	1	1	1	RS-485	RS-485 (2ch) Loopback

Table 1. Mode Function Table. (Refer to Control Logic Confirmations for Block Diagrams)

THEORY OF OPERATION

The **SP331** is made up of four separate circuit blocks — the charge pump, drivers, receivers, and decoder. Each of these circuit blocks is described in more detail below.

Charge-Pump

The charge pump is a **Sipex**–patented design (U.S. 5,306,954) and uses a unique approach compared to older less efficient designs. The charge pump still requires four external capacitors, but uses a four–phase voltage shifting technique to attain symmetrical 10V power supplies. *Figure 15(a)* shows the waveform found on the positive side of capcitor C2, and *Figure 15(b)* shows the negative side of capcitor C2. There is a free–running oscillator that controls the four phases of the voltage shifting. A description of each phase follows.

Phase 1

— V_{SS} charge storage —During this phase of the clock cycle, the positive side of capacitors C_1 and C_2 are initially charged to +5V. C_1^+ is then switched to ground and charge on C_1^- is transferred to C_2^- . Since C_2^+ is connected to

+5V, the voltage potential across capacitor C_2 is now 10V.

Phase 2

— V_{SS} transfer — Phase two of the clock connects the negative terminal of C_2 to the V_{SS} storage capacitor and the positive terminal of C_2 to ground, and transfers the generated –l0V to C_3 . Simultaneously, the positive side of capacitor C_1 is switched to +5V and the negative side is connected to ground.

Phase 3

— V_{DD} charge storage — The third phase of the clock is identical to the first phase — the charge transferred in C_1 produces –5V in the negative terminal of C_1 , which is applied to the negative side of capacitor C_2 . Since C_2^+ is at +5V, the voltage potential across C_2 is 10V.

Phase 4

— V_{DD} transfer — The fourth phase of the clock connects the negative terminal of C_2 to ground and transfers the generated l0V across C_2 to C_4 , the V_{DD} storage capacitor. Again,

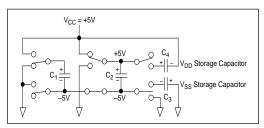


Figure 11. Charge Pump Phase 1.

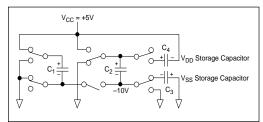


Figure 12. Charge Pump Phase 2.

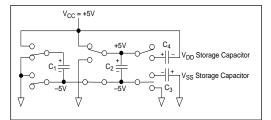


Figure 13. Charge Pump Phase 3.

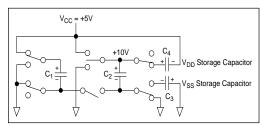


Figure 14. Charge Pump Phase 4.

simultaneously with this, the positive side of capacitor C_1 is switched to +5V and the negative side is connected to ground, and the cycle begins again.

Since both V+ and V⁻ are separately generated from V_{CC} in a no–load condition, V+ and V⁻ will be symmetrical. Older charge pump approaches that generate V⁻ from V+ will show a decrease in the magnitude of V⁻ compared to V+ due to the inherent inefficiencies in the design.

The clock rate for the charge pump typically operates at 15kHz. The external capacitors must be 0.1µF with a 16V breakdown rating.

External Power Supplies

For applications that do not require +5V only, external supplies can be applied at the V+ and V^- pins. The value of the external supply voltages must be no greater than $\pm 10V$. The current drain for the $\pm 10V$ supplies is used for RS-232. For the RS-232 driver the current requirement will be 3.5mA per driver. The external power supplies should provide a power supply sequence of : $\pm 10V$, then $\pm 5V$, followed by $\pm 10V$.

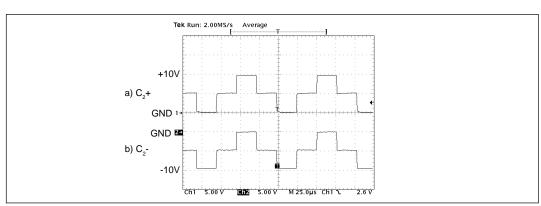


Figure 15. Charge Pump Waveforms

Drivers

The **SP331** has four independent RS-232 singleended drivers and two differential RS-485 drivers. Control for the mode selection is done via a four-bit control word. The drivers are prearranged such that for each mode of operation the relative position and functionality of the drivers are set up to accommodate the selected interface mode. As the mode of the drivers is changed, the electrical characteristics will change to support the requirements of clock, data, and control line signal levels. Unused driver inputs can be left floating; however, to ensure a desired state with no input signal, pull-up resistors to +5V or pull-down resistors to ground are suggested. Since the driver inputs are both TTL or CMOS compatible, any value resistor less than $100k\Omega$ will suffice.

When in RS-232 mode, the single-ended RS-232 drivers produce compliant RS-232E and ITU V.28 signals. Each of the four drivers output single-ended bipolar signals in access of ± 5 V with a full load of 3k Ω and 2500pF applied as specified. These drivers can also operate at least 120kbps.

When programmed to RS-485 mode, the differential RS-485 drivers produce complaint RS-485 signals. Each RS-485 driver outputs a unipolar signal on each output pin with a magnitude of at least 1.5V while loaded with a worst case of 54Ω between the driver's two output pins. The signal levels and drive capability of the RS-485 drivers allow the drivers to also comply with RS-422 levels. The transmission rate for the differential drivers is 10Mbps.

Receivers

The **SP331** has four single-ended receivers when programmed for RS-232 mode and two differential receivers when programmed for RS-485 mode.

Control for the mode selection is done via a 4–bit control word, as in the drivers. As the operating mode of the receivers is changed, the electrical characteristics will change to support the requirements of the appropriate serial standard. Unused receiver inputs can be left floating

without causing oscillation. To ensure a desired state of the receiver output, a pull–up resistor of $100k\Omega$ to +5V should be connected to the inverting input for a logic low, or the non–inverting input for a logic high. For single-ended receivers, a pull–down resistor to ground of $5k\Omega$ is internally connected, which will ensure a logic high output.

The RS-232 receiver has a single–ended input with a threshold of 0.8V to 2.4V. The RS-232 receiver has an operating voltage range of $\pm 15V$ and can receive signals up to 120kbps. RS-232 receivers are used in RS-232 mode for all signal types include data, clock, and control lines of the RS-232 serial port.

The differential RS-485 receiver has an input impedance of $15k\Omega$ and a differential threshold of $\pm 200 mV$. Since the characteristics of an RS-422 receiver are actually subsets of RS-485, the receivers for RS-422 requirements are identical to the RS-485 receivers. All of the differential receivers can receive data up to 10 Mbps.

Select Mode Pins

Similar to our SP500 family of multiprotocol products, the **SP331** has the ability to change the configuration of the drivers and receivers via a 4-bit switch. Referring to *Table 1*; RS-232 mode, RS-485 mode, or two different combinations of RS-232/RS-485 can be configured using the SEL_A and SEL_B pins. The drivers can be put into tri-state mode by using the SEL_C and SEL_D pins. All receivers remain active during any tri-state condition of the drivers.

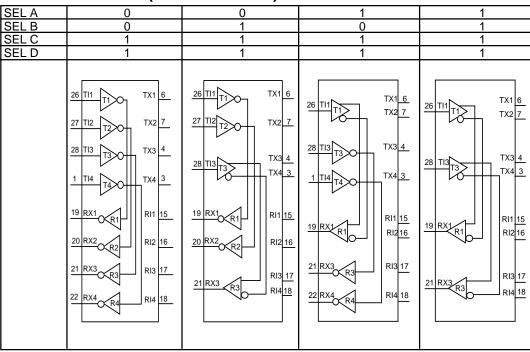
Loopback Mode

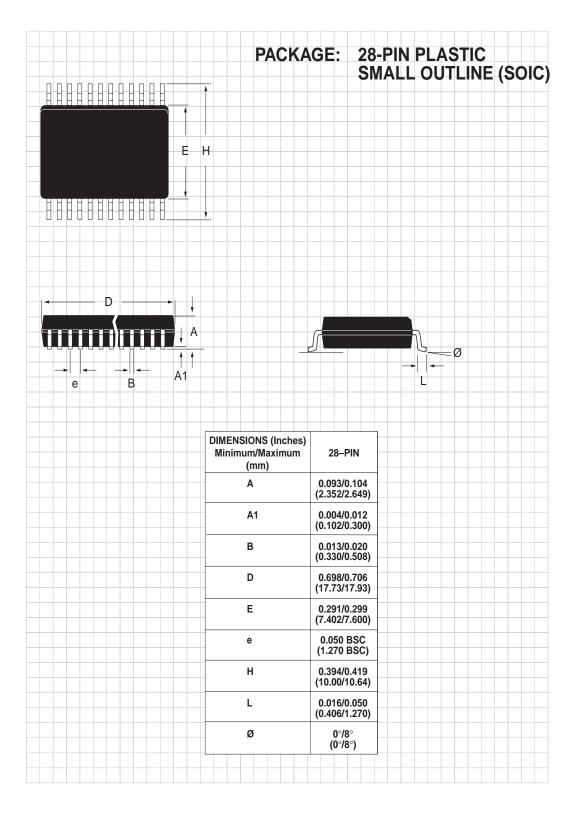
Loopback is invoked by asserting "xx11" into the select pins. In RS-232/RS-485 or RS-485/RS-232 loopback mode, the RS-232 driver outputs loop back into the RS-232 receiver inputs and the RS-485 differential driver loops back into the RS-485 receiver. During loopback, the driver outputs and receiver inputs are disconnected from the outside world. The driver outputs are in tri-state and the receiver inputs are disabled. The input impedance of the receivers during loopback is approximately $15 \mathrm{k}\Omega$ to ground.

SP331 CONTROL LOGIC CONFIGURATION (Refer to Table 1)

SEL A	0	0	0	0	0	0	1	1	1	1	1	1
SEL B	0	0	0	1	1	1	0	0	0	1	1	1
SEL C	0	0	1	0	0	1	0	0	1	0	0	1
SEL D	0	1	0	0	1	0	0	1	0	0	1	0
SEL D	26 TI1 27 TI2 28 TI3 1 TI4 19 RX1 20 RX2 21 RX3 22 RX4		TX1 6 TX2 7 TX3 4 TX4 3 RRI1 15 RRI2 16 RRI3 17 RRI4 18	26 TI1 27 TI2 28 TI3 19 RX1 20 RX2 21 RX3		TX1 6 TX2 7 TX3 4 TX4 3 RI1 15 RI2 16 RI3 17 RI4 18	28 TI3 1 TI4 19 RX1 21 RX3 22 RX4		TX1 6 TX2 7 TX3 4 TX4 3 RI1 15 RI2 16 RI3 17	26 TI1 28 TI3 19 RX1 21 RX3		TX1 6 TX2 7 TX3 4 TX4 3 RI1 15 RI2 16 RI3 17 RI4 18

SP331 LOOPBACK (Refer to Table 1)





ORDERING INFORMATION							
Model	Temperature Range	Package Types					
SP331CT	0°C to +70°C	28-pin Plastic SOIC					
SP331ET	-40°C to +85°C						

Please consult the factory for pricing and availability on a Tape-On-Reel option.



SIGNAL PROCESSING EXCELLENCE

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