
HN27C4096ACP Series

262144-word × 16-bit CMOS One Time Programmable ROM

HITACHI

ADE-203-240B (Z)

Rev. 2.0

Jun. 22, 1995

Description

The Hitachi HN27C4096ACP is a 4-Mbit one time programmable ROM, featuring high speed and low power dissipation. Fabricated on advanced fine process and high speed circuitry technique, the HN27C4096ACP makes high speed access time possible. Therefore, it is suitable for 16-bit microcomputer systems using high speed microcomputer such as the 80286 and 68020. The HN27C4096ACP offers high speed programming using page programming mode. This device is packaged in a 44-pin plastic leaded chip carrier (PLCC). Therefore, this device cannot be rewritten.

Features

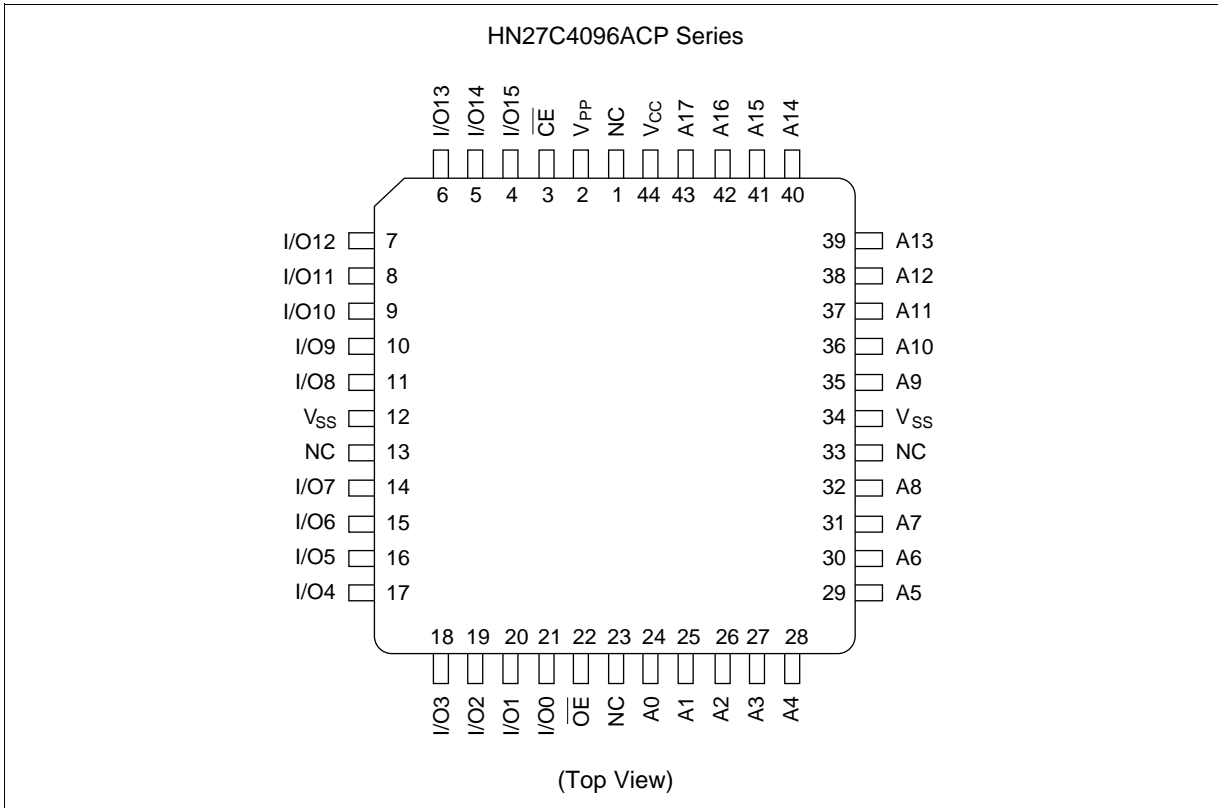
- High speed
 - Access time: 120 ns/150 ns (max)
- Low power dissipation
 - Standby mode: 5 μ W (typ)
 - Active mode: 35 mW/MHz (typ)
- Fast high reliability page programming, fast high-reliability programming and option programming
 - Programming voltage: +12.5 V D.C.
 - Program time: 3.5 sec (min) (Theoretical in Page programming)
- Inputs and outputs TTL compatible during both read and program modes
- Pin arrangement: 44-pin PLCC JEDEC standard
- Device identifier mode: Manufacturer code and device code
- Fully compatible with the HN27C4096CP Series

Ordering Information

Type No.	Access Time	Package
HN27C4096ACP-12	120 ns	44-pin PLCC (CP-44)
HN27C4096ACP-15	150 ns	

HN27C4096ACP Series

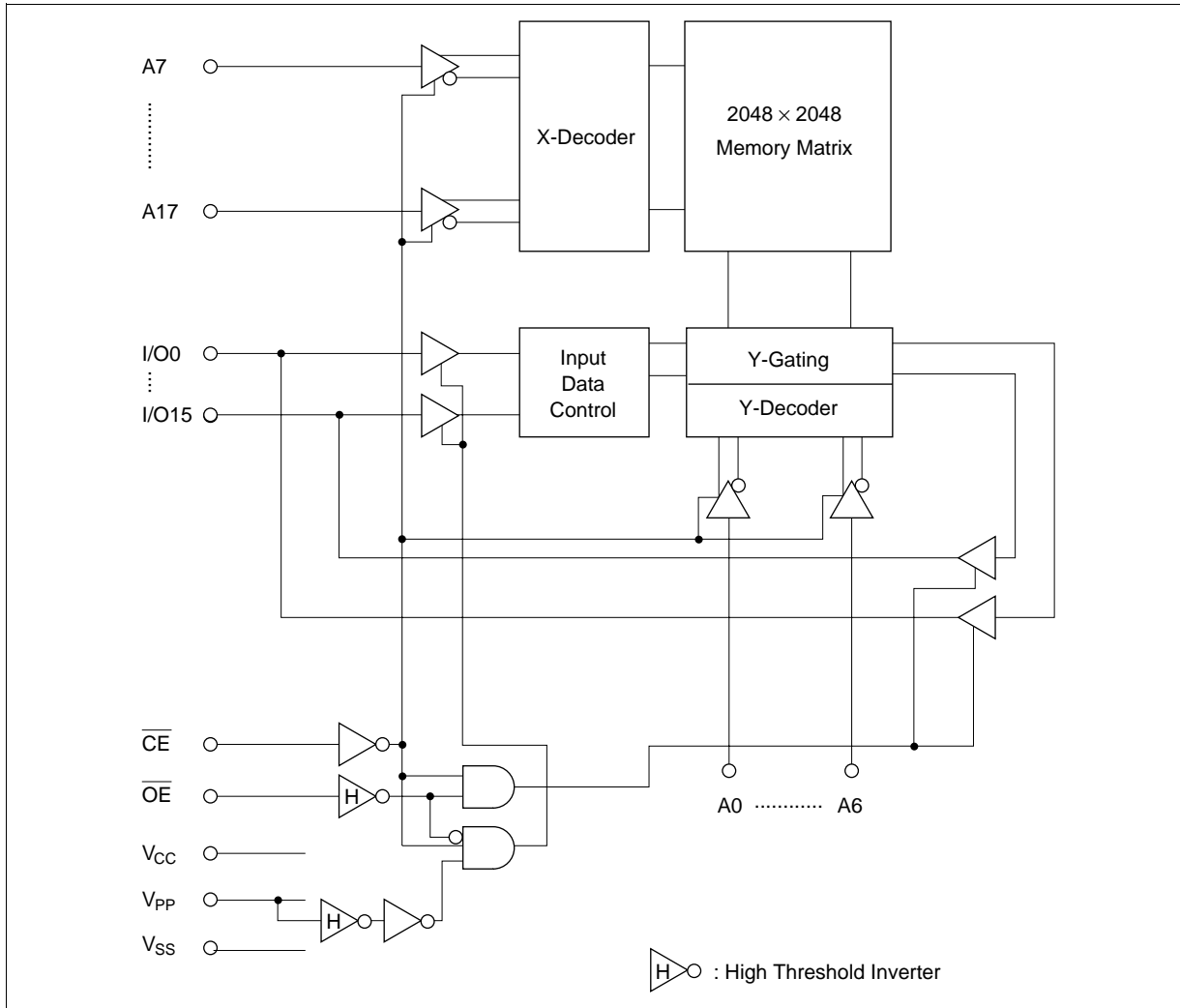
Pin Arrangement



Pin Description

Pin Name	Function
A0 – A17	Address
I/O0 – I/O15	Input/output
\overline{CE}	Chip enable
\overline{OE}	Output enable
V_{CC}	Power supply
V_{PP}	Programming power supply
V_{SS}	Ground

Block Diagram



Mode Selection

Mode	Pin	\overline{CE} (3)	\overline{OE} (22)	A9 (35)	V_{PP} (2)	V_{CC} (44)	I/O (4 – 11, 14 – 21)
Read		V_{IL}	V_{IL}	X	$V_{SS} - V_{CC}$	V_{CC}	Dout
Output disable		V_{IL}	V_{IH}	X	$V_{SS} - V_{CC}$	V_{CC}	High-Z
Standby		V_{IH}	X	X	$V_{SS} - V_{CC}$	V_{CC}	High-Z
Page program	Page program set	V_{IH}	V_H^{*2}	X	V_{PP}	V_{CC}	High-Z
	Page data latch	V_{IL}	V_H^{*2}	X	V_{PP}	V_{CC}	Din
	Page program	V_{IL}	V_{IH}	X	V_{PP}	V_{CC}	High-Z
	Page program verify	V_{IH}	V_{IL}	X	V_{PP}	V_{CC}	Dout
	Page program reset	V_{IH}	V_{IH}	X	V_{CC}	V_{CC}	High-Z
Word program	Program	V_{IL}	V_{IH}	X	V_{PP}	V_{CC}	Din
	Program verify	V_{IH}	V_{IL}	X	V_{PP}	V_{CC}	Dout
	Optional verify	V_{IL}	V_{IL}	X	V_{PP}	V_{CC}	Dout
	Program inhibit	V_{IH}	V_{IH}	X	V_{PP}	V_{CC}	High-Z
Identifier		V_{IL}	V_{IL}	V_H^{*2}	$V_{SS} - V_{CC}$	V_{CC}	Code

- Notes: 1. X: Don't care.
 2. V_H : 12.0 V \pm 0.5 V

Absolute Maximum Ratings

Parameter	Symbol	Value	Unit	Notes
All input and output voltages	V_{in} , V_{out}	-0.6 ² to +7.0	V	1, 2
Voltage on pin A9 and \overline{OE}	V_{ID}	-0.6 ² to +13.0	V	2
V_{PP} voltage	V_{PP}	-0.6 to +13.5	V	1
V_{CC} voltage	V_{CC}	-0.6 to +7.0	V	1
Operating temperature range	T_{opr}	0 to +70	°C	
Storage temperature range	T_{stg}	-55 to +125	°C	3
Storage temperature under bias	T_{bias}	-20 to +80	°C	

- Notes: 1. Relative to V_{SS} .
 2. V_{in} , V_{out} , V_{ID} min = -2.0 V for pulse width \leq 20 ns.
 3. Storage temperature range of device before programming.

Capacitance ($T_a = 25^\circ\text{C}$, $f = 1\text{ MHz}$)

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions
Input capacitance	Cin	—	—	12	pF	Vin = 0 V
Output capacitance	Cout	—	—	20	pF	Vout = 0 V

Read Operation
DC Characteristics ($V_{CC} = 5\text{ V} \pm 10\%$, $V_{PP} = V_{SS}$ to V_{CC} , $T_a = 0$ to $+70^\circ\text{C}$)

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions
Input leakage current	I_{LI}	—	—	2	μA	Vin = 5.5 V
Output leakage current	I_{LO}	—	—	2	μA	Vout = 5.5 V/0.45 V
V_{PP} current	I_{PP1}	—	1	20	μA	$V_{PP} = 5.5\text{ V}$
Standby V_{CC} current	I_{SB1}	—	—	1	mA	$\overline{CE} = V_{IH}$
	I_{SB2}	—	1	20	μA	$\overline{CE} = V_{CC} \pm 0.3\text{ V}$
Operating V_{CC} current	I_{CC1}	—	—	30	mA	Iout = 0 mA, f = 1 MHz
	I_{CC2}	—	—	90	mA	Iout = 0 mA, f = 8.4 MHz
Input voltage	V_{IL}	-0.3^{*1}	—	0.8	V	
	V_{IH}	2.2	—	$V_{CC} + 1^{*2}$	V	
Output voltage	V_{OL}	—	—	0.45	V	$I_{OL} = 2.1\text{ mA}$
	V_{OH}	2.4	—	—	V	$I_{OH} = -400\ \mu\text{A}$

Notes: 1. V_{IL} min = -1.0 V for pulse width $\leq 50\text{ ns}$.

V_{IL} min = -2.0 V for pulse width $\leq 20\text{ ns}$.

2. V_{IH} max = $V_{CC} + 1.5\text{ V}$ for pulse width $\leq 20\text{ ns}$.

If V_{IH} is over the specified maximum value, read operation cannot be guaranteed.

HN27C4096ACP Series

AC Characteristics ($V_{CC} = 5\text{ V} \pm 10\%$, $V_{PP} = V_{SS}$ to V_{CC} , $T_a = 0$ to $+70^\circ\text{C}$)

Test Conditions

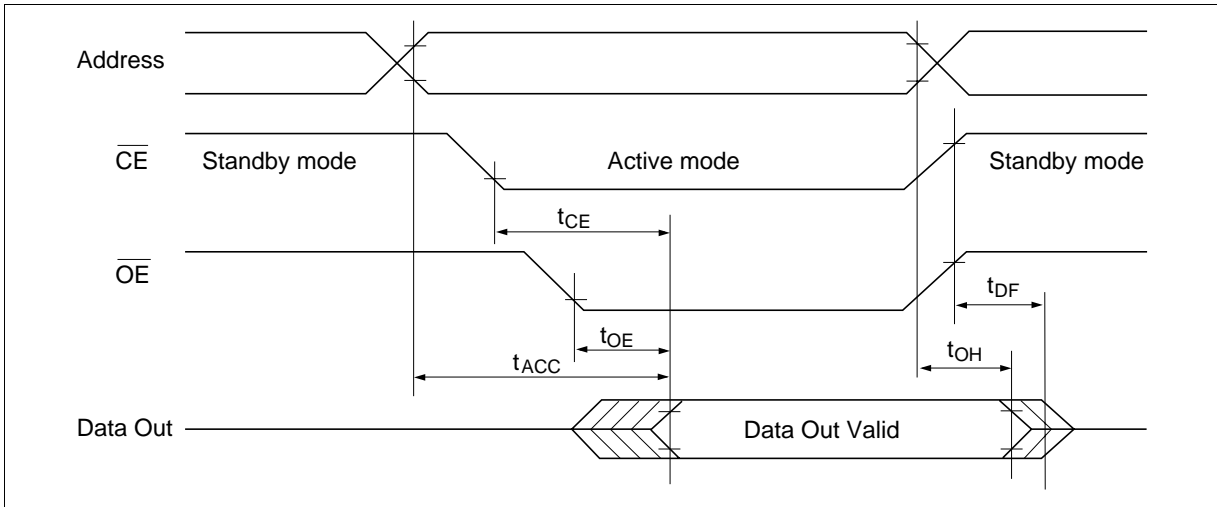
- Input pulse levels: 0.45 to 2.4 V
- Input rise and fall time: $\leq 10\text{ ns}$
- Output load: 1 TTL Gate + 100 pF
- Reference levels for measuring timing: 0.8 V, 2.0 V

HN27C4096ACP

Parameter	Symbol	-12		-15		Unit	Test Conditions
		Min	Max	Min	Max		
Address to output delay	t_{ACC}	—	120	—	150	ns	$\overline{CE} = \overline{OE} = V_{IL}$
\overline{CE} to output delay	t_{CE}	—	120	—	150	ns	$\overline{OE} = V_{IL}$
\overline{OE} to output delay	t_{OE}	—	60	—	70	ns	$\overline{CE} = V_{IL}$
\overline{OE} high to output float ^{*1}	t_{DF}	0	40	0	50	ns	$\overline{CE} = V_{IL}$
Address to output hold	t_{OH}	5	—	5	—	ns	$\overline{CE} = \overline{OE} = V_{IL}$

Note: 1. t_{DF} is defined as the time at which the output achieves the open circuit condition and data is no longer driven.

Read Timing Waveform



Fast High-Reliability Page Programming

This device can be applied the high performance page programming algorithm shown in the following flowchart. This algorithm allows to obtain faster programming time without any voltage stress to the device nor deterioration in reliability of programmed data.

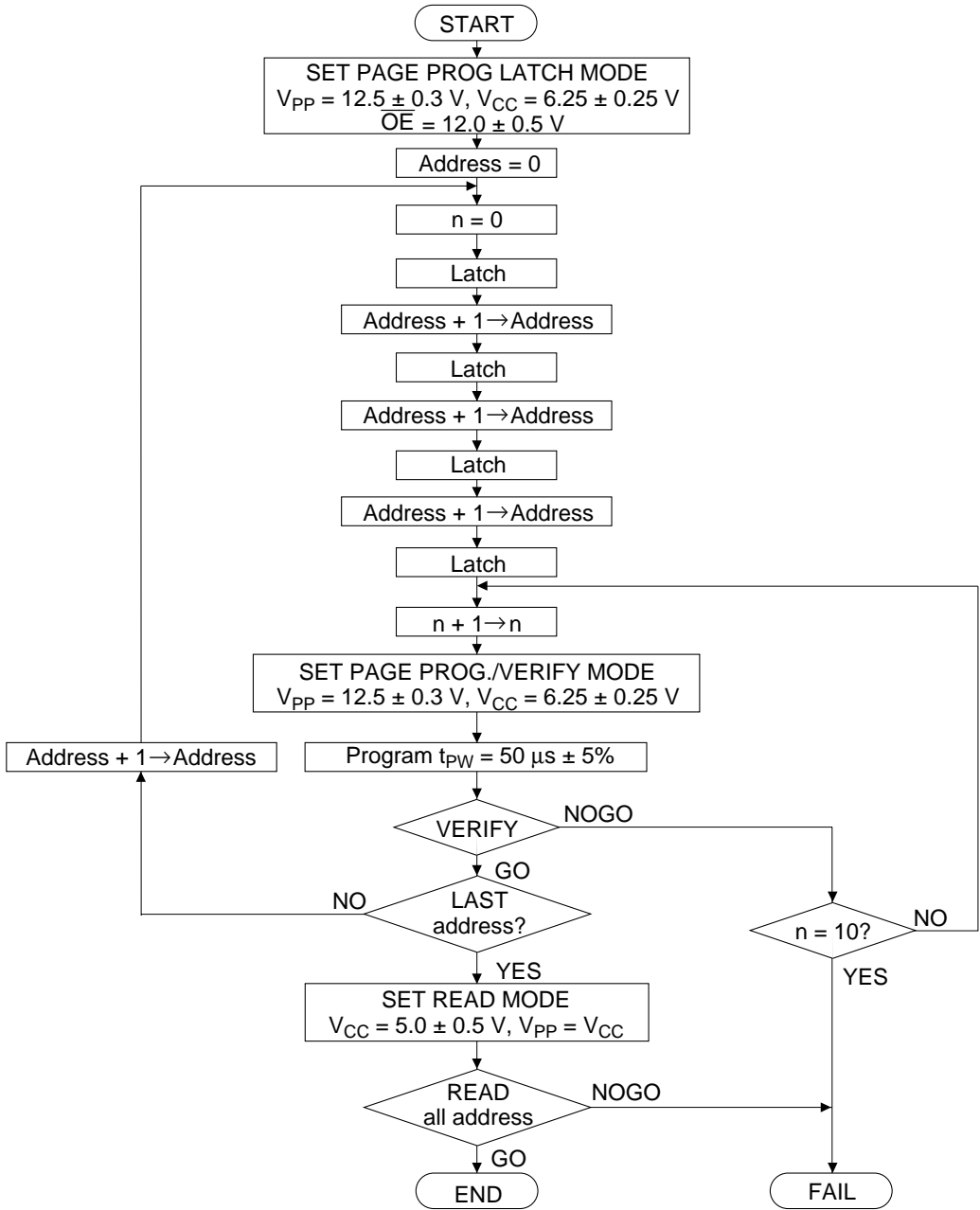
Page Program Set

Apply 12 V to $\overline{\text{OE}}$ pin after applying 12.5 V to V_{PP} to set a page program mode.

The device operates in a page program mode until reset.

Page Program Reset

Set V_{PP} to V_{CC} level or less to reset a page program mode.



Fast High-Reliability Page Programming Flowchart

DC Characteristics ($V_{CC} = 6.25 \text{ V} \pm 0.25 \text{ V}$, $V_{PP} = 12.5 \text{ V} \pm 0.3 \text{ V}$, $T_a = 25^\circ\text{C} \pm 5^\circ\text{C}$)

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions
Input leakage current	I_{LI}	—	—	2	μA	$V_{in} = 6.5 \text{ V}/0.45 \text{ V}$
Output voltage during verify	V_{OL}	—	—	0.45	V	$I_{OL} = 2.1 \text{ mA}$
	V_{OH}	2.4	—	—	V	$I_{OH} = -400 \mu\text{A}$
Operating V_{CC} current	I_{CC}	—	—	50	mA	
Input voltage	V_{IL}	-0.1^{15}	—	0.8	V	
	V_{IH}	2.2	—	$V_{CC} + 0.5^{16}$	V	
	V_H	11.5	12.0	12.5	V	
V_{PP} supply current	I_{PP}	—	—	70	mA	$\overline{CE} = V_{IL}$

- Notes:
- V_{CC} must be applied simultaneously or before V_{PP} and removed simultaneously or after V_{PP} .
 - V_{PP} must not exceed 13 V including overshoot.
 - An influence may be had upon device reliability if the device is installed or removed while $V_{PP} = 12.5 \text{ V}$.
 - Do not alter V_{PP} either V_{IL} to 12.5 V or 12.5 V to V_{IL} when $\overline{CE} = \text{low}$.
 - $V_{IL} \text{ min} = -0.6 \text{ V}$ for pulse width $\leq 20 \text{ ns}$.
 - If V_{IH} is over the specified maximum value, programming operation cannot be guaranteed.

HN27C4096ACP Series

AC Characteristics ($V_{CC} = 6.25 \text{ V} \pm 0.25 \text{ V}$, $V_{PP} = 12.5 \text{ V} \pm 0.3 \text{ V}$, $T_a = 25^\circ\text{C} \pm 5^\circ\text{C}$)

Test Conditions

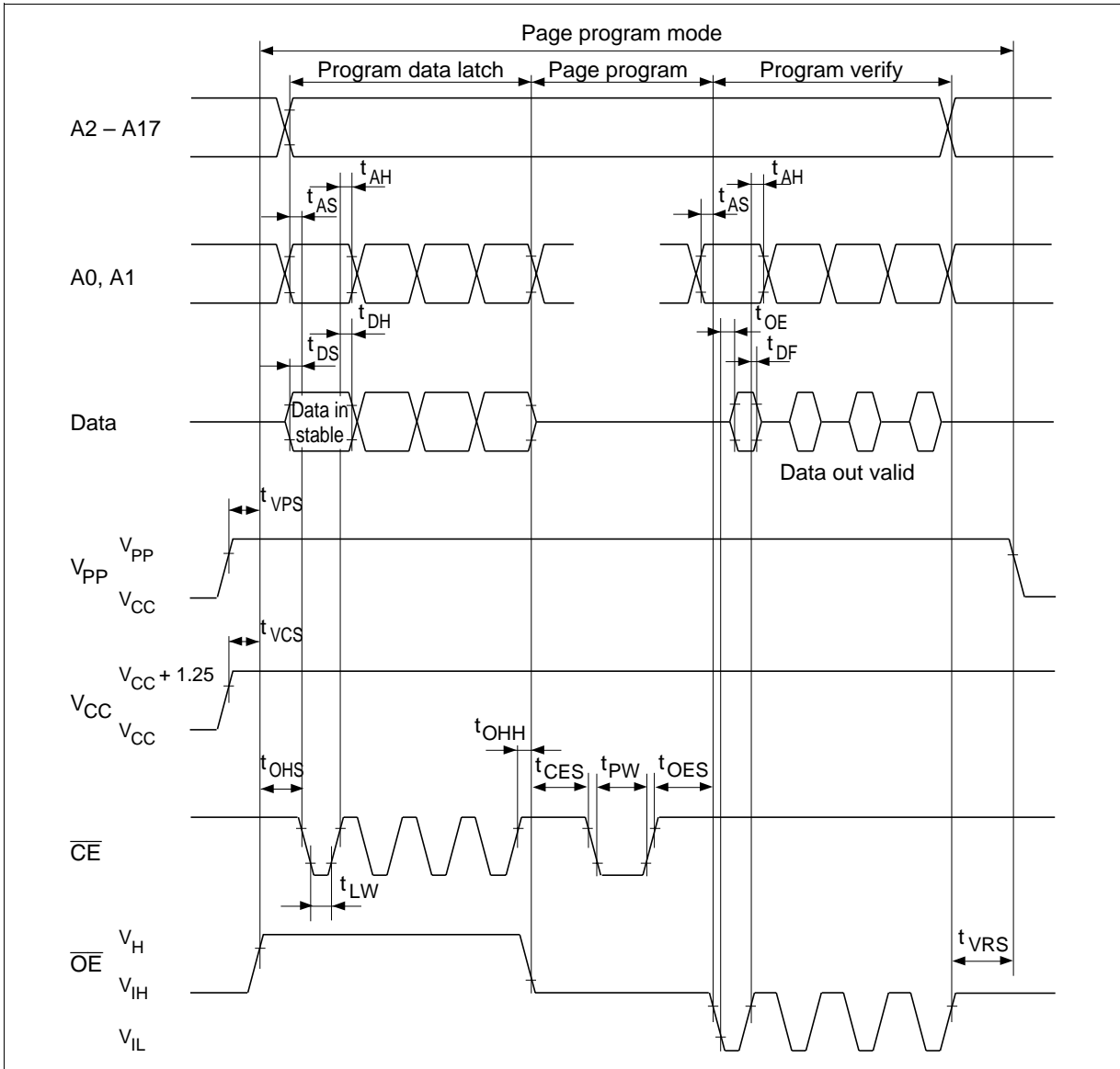
- Input pulse levels: 0.45 to 2.4 V
- Input rise and fall time: $\leq 20 \text{ ns}$
- Reference levels for measuring timing: Inputs: 0.8 V, 2.0 V,
Outputs: 0.8 V, 2.0 V

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions
Address setup time	t_{AS}	2	—	—	μs	
$\overline{\text{OE}}$ setup time	t_{OES}	2	—	—	μs	
Data setup time	t_{DS}	2	—	—	μs	
Address hold time	t_{AH}	0	—	—	μs	
Data hold time	t_{DH}	2	—	—	μs	
$\overline{\text{OE}}$ high to output float delay	t_{DF}^{*1}	0	—	130	ns	
V_{PP} setup time	t_{VPS}	2	—	—	μs	
V_{CC} setup time	t_{VCS}	2	—	—	μs	
$\overline{\text{CE}}$ programming pulse width	t_{PW}	47.5	50.0	52.5	μs	
$\overline{\text{CE}}$ setup time	t_{CES}	2	—	—	μs	
Data valid from $\overline{\text{OE}}$	t_{OE}	0	—	150	ns	
$\overline{\text{CE}}$ pulse width during data latch	t_{LW}	1	—	—	μs	
$\overline{\text{OE}} = V_H$ setup time	t_{OHS}	2	—	—	μs	
$\overline{\text{OE}} = V_H$ hold time	t_{OHH}	2	—	—	μs	
V_{PP} hold time ^{*2}	t_{VRS}	1	—	—	μs	

Notes: 1. t_{DF} is defined as the time at which the output achieves the open circuit condition and data is no longer driven.

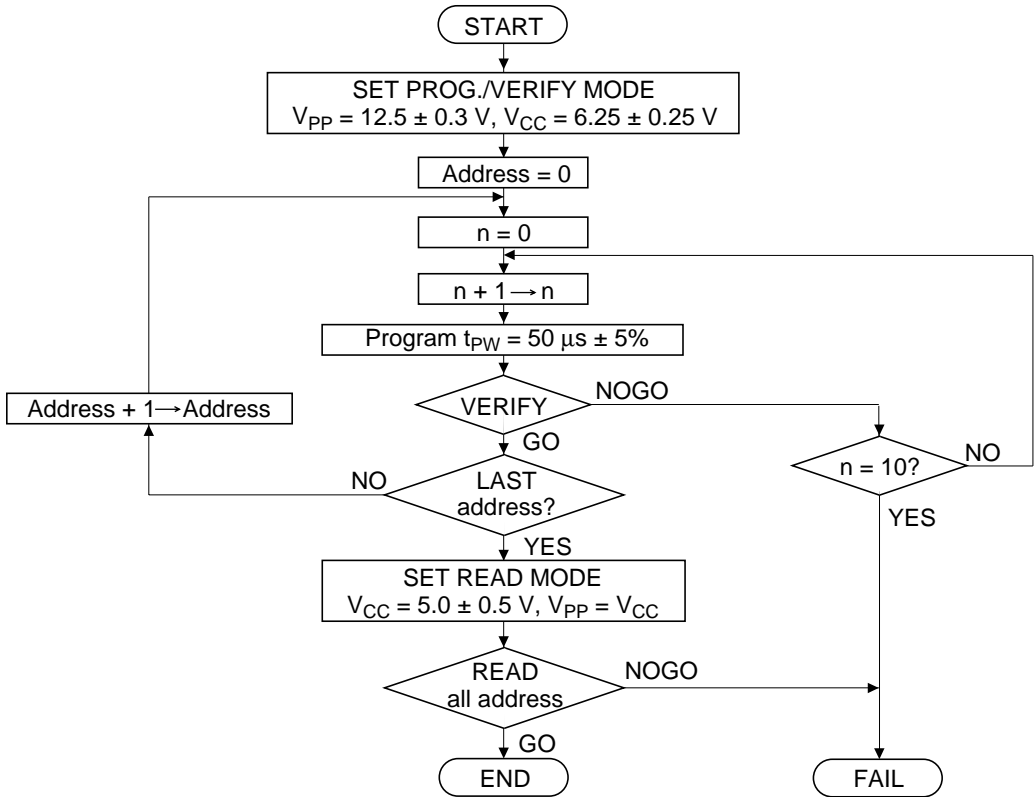
2. Page program mode will be reset when V_{PP} is set to V_{CC} or less.

Fast High-Reliability Page Programming Timing Waveform



Fast High-Reliability Programming

This device can be applied the fast high-reliability programming algorithm shown in the following flowchart. This algorithm allows to obtain faster programming time without any voltage stress to the device nor deterioration in reliability of programmed data.



Fast High-Reliability Programming Flowchart

DC Characteristics ($V_{CC} = 6.25 \text{ V} \pm 0.25 \text{ V}$, $V_{PP} = 12.5 \text{ V} \pm 0.3 \text{ V}$, $T_a = 25^\circ\text{C} \pm 5^\circ\text{C}$)

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions
Input leakage current	I_{LI}	—	—	2	μA	$V_{in} = 6.5 \text{ V}/0.45 \text{ V}$
V_{PP} supply current	I_{PP}	—	—	40	mA	$\overline{CE} = V_{IL}$
Operating V_{CC} current	I_{CC}	—	—	50	mA	
Input voltage	V_{IL}	-0.1^{15}	—	0.8	V	
	V_{IH}	2.2	—	$V_{CC} + 0.5^{16}$	V	
Output voltage	V_{OL}	—	—	0.45	V	$I_{OL} = 2.1 \text{ mA}$
	V_{OH}	2.4	—	—	V	$I_{OH} = -400 \mu\text{A}$

- Notes:
- V_{CC} must be applied simultaneously or before V_{PP} and removed simultaneously or after V_{PP} .
 - V_{PP} must not exceed 13 V including overshoot.
 - An influence may be had upon device reliability if the device is installed or removed while $V_{PP} = 12.5 \text{ V}$.
 - Do not alter V_{PP} either V_{IL} to 12.5 V or 12.5 V to V_{IL} when $\overline{CE} = \text{low}$.
 - V_{IL} min = -0.6 V for pulse width $\leq 20 \text{ ns}$.
 - If V_{IH} is over the specified maximum value, programming operation cannot be guaranteed.

AC Characteristics ($V_{CC} = 6.25 \text{ V} \pm 0.25 \text{ V}$, $V_{PP} = 12.5 \text{ V} \pm 0.3 \text{ V}$, $T_a = 25^\circ\text{C} \pm 5^\circ\text{C}$)

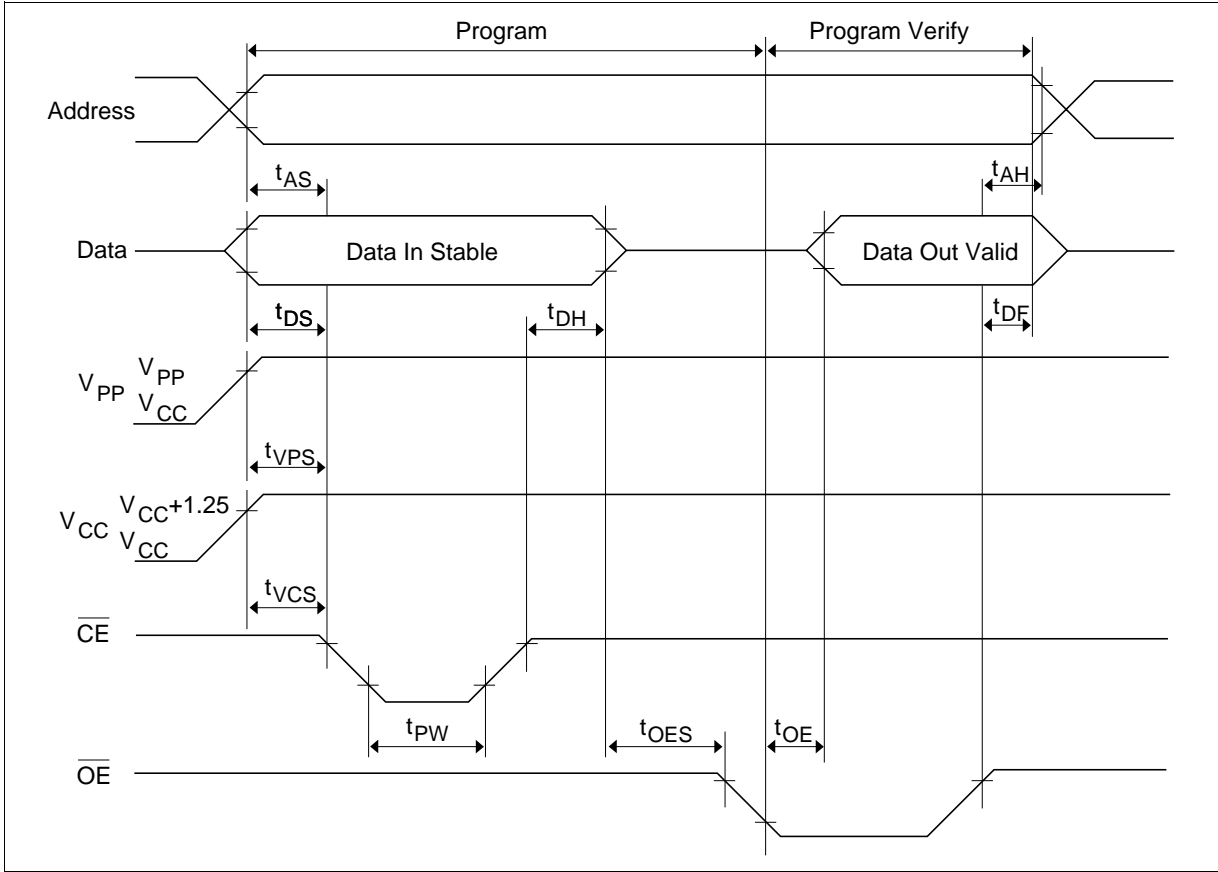
Test Conditions

- Input pulse levels: 0.45 to 2.4 V
- Input rise and fall time: $\leq 20 \text{ ns}$
- Reference levels for measuring timing: Inputs: 0.8 V, 2.0 V,
Outputs: 0.8 V, 2.0 V

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions
Address setup time	t_{AS}	2	—	—	μs	
\overline{OE} setup time	t_{OES}	2	—	—	μs	
Data setup time	t_{DS}	2	—	—	μs	
Address hold time	t_{AH}	0	—	—	μs	
Data hold time	t_{DH}	2	—	—	μs	
\overline{OE} to output float delay	t_{DF}^{*1}	0	—	130	ns	
V_{PP} setup time	t_{VPS}	2	—	—	μs	
V_{CC} setup time	t_{VCS}	2	—	—	μs	
\overline{CE} programming pulse width	t_{PW}	47.5	50.0	52.5	μs	
Data valid from \overline{OE}	t_{OE}	0	—	150	ns	

- Note: 1. t_{DF} is defined as the time at which the output achieves the open circuit condition and data is no longer driven.

Fast High-Reliability Programming Timing Waveform

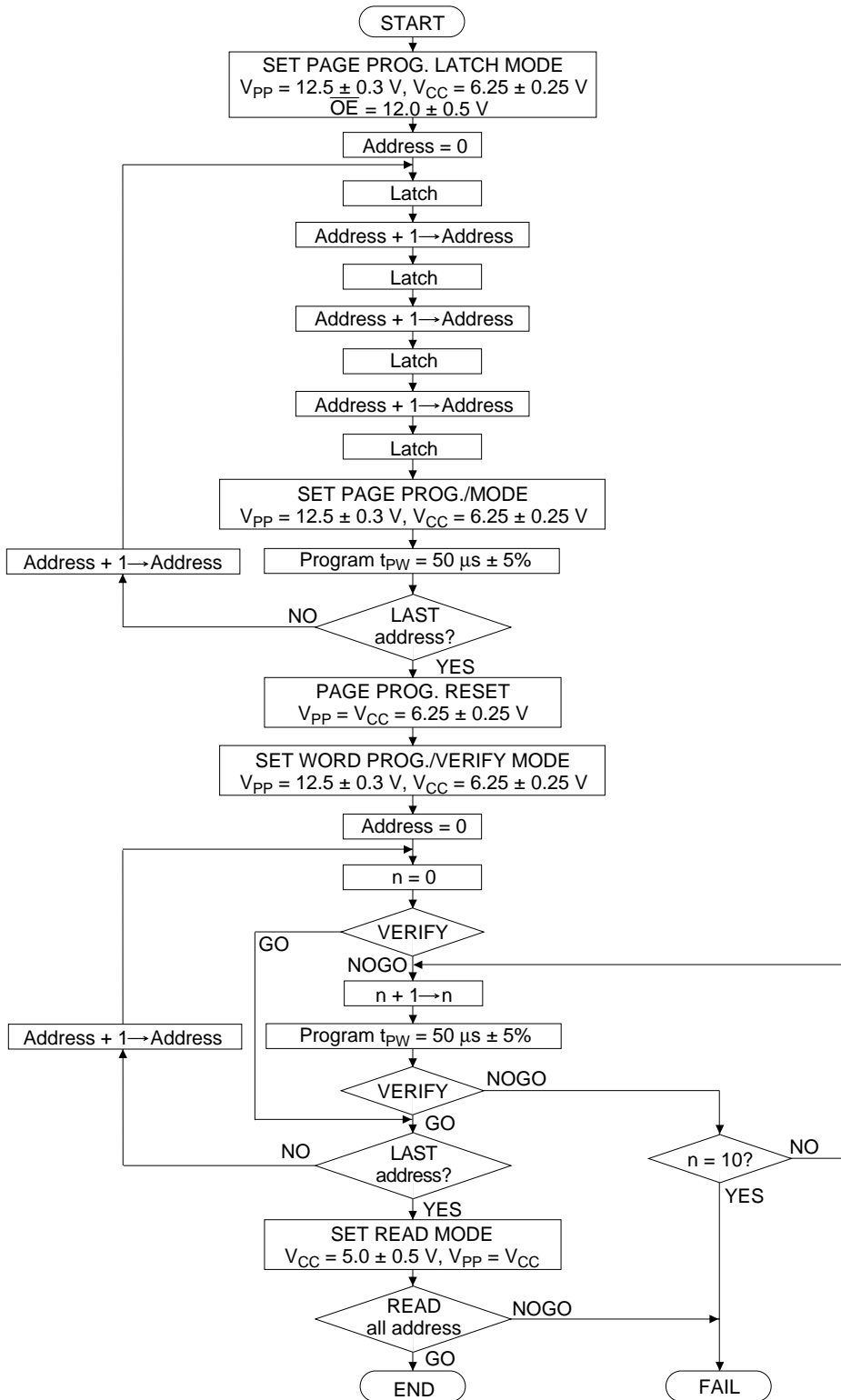


Optional Page Programming

This device can be applied the optional page programming algorithm shown in the following flowchart. This algorithm allows to obtain faster programming time without any voltage stress to the device nor deterioration in reliability of programmed data.

This programming algorithm is the combination of page programming and word verify. It can avoid the increase of programming verify time when a programmer with slow machine cycle is used, and shorten the total programming time.

Regarding the timing specifications for page programming and word verify, please refer to the specifications for fast high-reliability page programming and fast high-reliability programming.



Optional Page Programming Flowchart

HN27C4096ACP Series

DC Characteristics ($V_{CC} = 6.25 \text{ V} \pm 0.25 \text{ V}$, $V_{PP} = 12.5 \text{ V} \pm 0.3 \text{ V}$, $T_a = 25^\circ\text{C} \pm 5^\circ\text{C}$)

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions
Input leakage current	I_{LI}	—	—	2	μA	$V_{in} = 6.5 \text{ V}/0.45 \text{ V}$
Output voltage during verify	V_{OL}	—	—	0.45	V	$I_{OL} = 2.1 \text{ mA}$
	V_{OH}	2.4	—	—	V	$I_{OH} = -400 \mu\text{A}$
Operating V_{CC} current	I_{CC}	—	—	50	mA	
Input voltage	V_{IL}	-0.1^{*5}	—	0.8	V	
	V_{IH}	2.2	—	$V_{CC} + 0.5^{*6}$	V	
	V_H	11.5	12.0	12.5	V	
V_{PP} supply current	I_{PP}	—	—	70	mA	$\overline{CE} = V_{IL}$

- Notes:
1. V_{CC} must be applied simultaneously or before V_{PP} and removed simultaneously or after V_{PP} .
 2. V_{PP} must not exceed 13 V including overshoot.
 3. An influence may be had upon device reliability if the device is installed or removed while $V_{PP} = 12.5 \text{ V}$.
 4. Do not alter V_{PP} either V_{IL} to 12.5 V or 12.5 V to V_{IL} when $\overline{CE} = \text{low}$.
 5. $V_{IL} \text{ min} = -0.6 \text{ V}$ for pulse width $\leq 20 \text{ ns}$.
 6. If V_{IH} is over the specified maximum value, programming operation cannot be guaranteed.

AC Characteristics ($V_{CC} = 6.25 \text{ V} \pm 0.25 \text{ V}$, $V_{PP} = 12.5 \text{ V} \pm 0.3 \text{ V}$, $T_a = 25^\circ\text{C} \pm 5^\circ\text{C}$)

Test Conditions

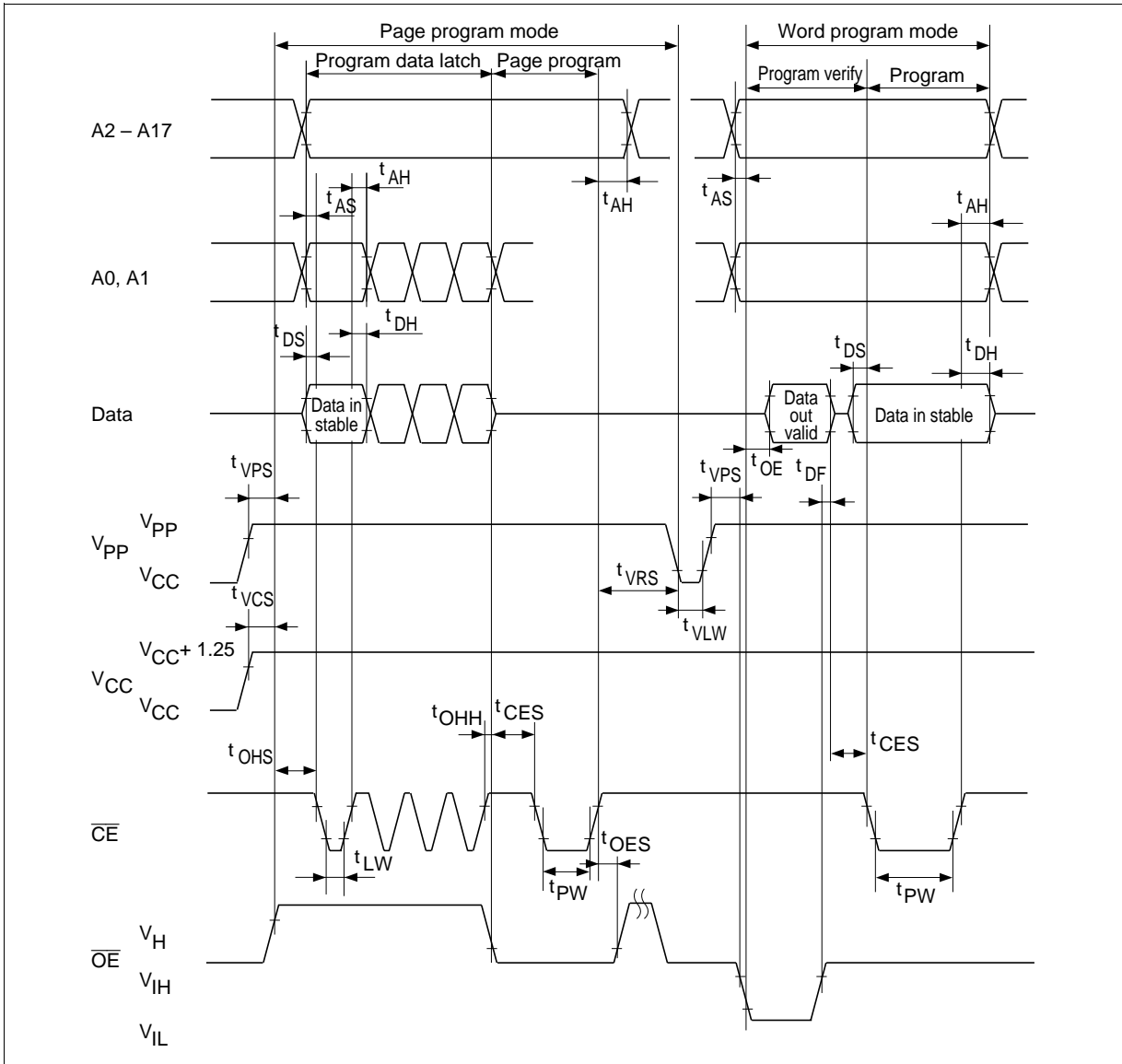
- Input pulse levels: 0.45 to 2.4 V
- Input rise and fall time: $\leq 20 \text{ ns}$
- Reference levels for measuring timing: Inputs: 0.8 V, 2.0 V,
Outputs: 0.8 V, 2.0 V

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions
Address setup time	t_{AS}	2	–	–	μs	
\overline{OE} setup time	t_{OES}	2	–	–	μs	
Data setup time	t_{DS}	2	–	–	μs	
Address hold time	t_{AH}	0	–	–	μs	
Data hold time	t_{DH}	2	–	–	μs	
\overline{OE} high to output float delay	t_{DF}^{*1}	0	–	130	ns	
V_{PP} setup time	t_{VPS}	2	–	–	μs	
V_{CC} setup time	t_{VCS}	2	–	–	μs	
\overline{CE} programming pulse width	t_{PW}	47.5	50.0	52.5	μs	
\overline{CE} setup time	t_{CES}	2	–	–	μs	
Data valid from \overline{OE}	t_{OE}	0	–	150	ns	
\overline{CE} pulse width during data latch	t_{LW}	1	–	–	μs	
$\overline{OE} = V_H$ setup time	t_{OHS}	2	–	–	μs	
$\overline{OE} = V_H$ hold time	t_{OHH}	2	–	–	μs	
Page programming reset time ^{*2}	t_{VLW}	1	–	–	μs	
V_{PP} hold time ^{*2}	t_{VRS}	1	–	–	μs	

Notes: 1. t_{DF} is defined as the time at which the output achieves the open circuit condition and data is no longer driven.

2. Page program mode will be reset when V_{PP} is set to V_{CC} or less.

Optional Page Programming Timing Waveform



Mode Description

Device Identifier Mode

The device identifier mode allows the reading out of binary codes that identify manufacturer and type of device, from outputs of OTPROM. By this mode, the device will be automatically matched its own corresponding programming algorithm, using programming equipment.

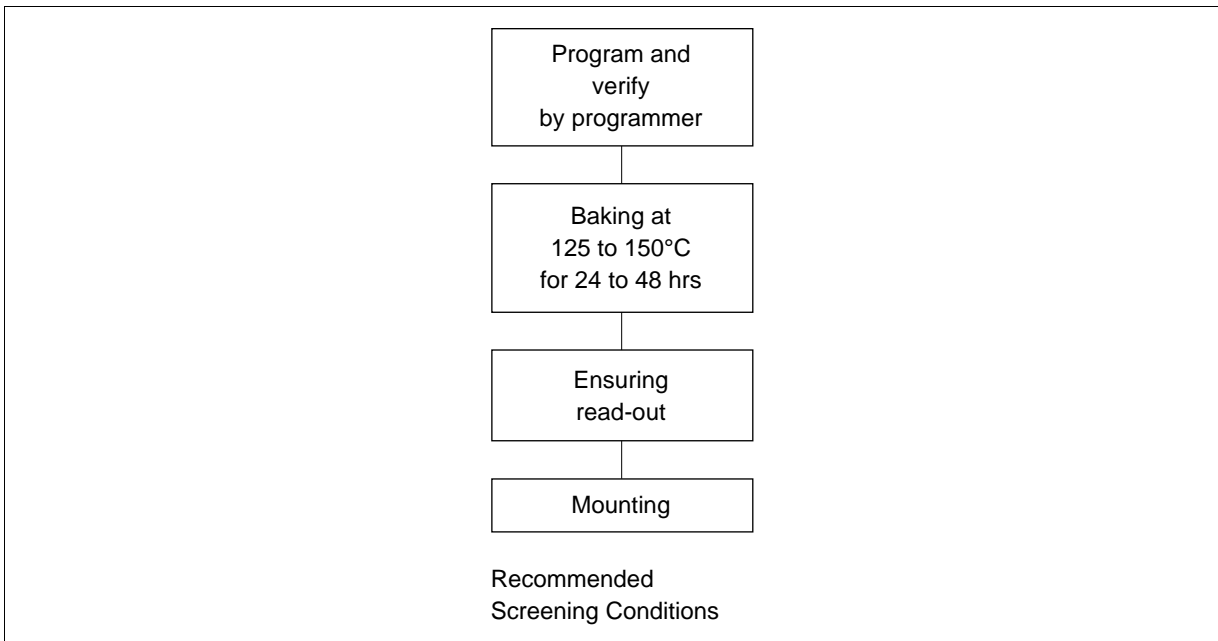
HN27C4096ACP Identifier Code

Identifier	A0 (24)	I/O8 – I/O15 (11) – (4)	I/O7 (14)	I/O6 (15)	I/O5 (16)	I/O4 (17)	I/O3 (18)	I/O2 (19)	I/O1 (20)	I/O0 (21)	Hex Data
Manufacturer code	V_{IL}	X	0	0	0	0	0	1	1	1	07
Device code	V_{IH}	X	1	0	1	0	0	0	1	0	A2

- Notes: 1. $V_{CC} = 5.0\text{ V} \pm 10\%$.
 2. $A9 = 12.0\text{ V} \pm 0.5\text{ V}$.
 3. A1 – A8, A10 – A17, \overline{CE} , $\overline{OE} = V_{IL}$.
 4. X: Don't care.

Recommended Screening Conditions

Before mounting, please make the screening (baking without bias) shown in the right.



HN27C4096ACP Series

Package Dimensions

HN27C4096ACP Series (CP-44)

Unit: mm

