

DUAL RETRIGGERABLE MONOSTABLE MULTIVIBRATOR WITH RESET

FEATURES

- DC triggered from active HIGH or active LOW inputs
- Retriggerable for very long pulses up to 100% duty factor
- Direct reset terminates output pulse
- Schmitt-trigger action on all inputs except for the reset input
- Output capability: standard (except for nREXT/CEXT)
- I_{CC} category: MSI

GENERAL DESCRIPTION

The 74HC/HCT123 are high-speed Si-gate CMOS devices and are pin compatible with low power Schottky TTL (LSTTL). They are specified in compliance with JEDEC standard no. 7A.

The 74HC/HCT123 are dual retriggerable monostable multivibrators with output pulse width control by three methods. The basic pulse time is programmed by selection of an external resistor (REXT) and capacitor (CEXT). The external resistor and capacitor are normally connected as shown in Fig. 6.

Once triggered, the basic output pulse width may be extended by retriggering the gated active LOW-going edge input (nA) or the active HIGH-going edge input (nB). By repeating this process, the output pulse period (nQ = HIGH, nQ = LOW) can be made as long as desired. Alternatively an output delay can be terminated at any time by a LOW-going edge on input nRD, which also inhibits the triggering.

(continued on next page)

SYMBOL	PARAMETER	CONDITIONS	TYPICAL		UNIT
			HC	HCT	
t _{PHL} / t _{PLH}	propagation delay nA, nB to nQ, nQ nRD to nQ, nQ	C _L = 15 pF V _{CC} = 5 V R _{EXT} = 5 kΩ C _{EXT} = 0 pF	26 20	26 23	ns ns
C _I	input capacitance		3.5	3.5	pF
C _{PD}	power dissipation capacitance per monostable	notes 1 and 2	54	56	pF

GND = 0 V; T_{amb} = 25 °C; t_r = t_f = 6 ns

Notes

1. C_{PD} is used to determine the dynamic power dissipation (P_D in μW):

$$P_D = C_{PD} \times V_{CC}^2 \times f_i + \sum (C_L \times V_{CC}^2 \times f_o) + 0.75 \times C_{EXT} \times V_{CC}^2 \times f_o + D \times 16 \times V_{CC}$$

where:

f_i = input frequency in MHz

f_o = output frequency in MHz

D = duty factor in %

Σ(C_L × V_{CC}² × f_o) = sum of outputs

C_L = output load capacitance in pF

V_{CC} = supply voltage in V

C_{EXT} = timing capacitance in pF

2. For HC the condition is V_I = GND to V_{CC}
For HCT the condition is V_I = GND to V_{CC} - 1.5 V

PACKAGE OUTLINES

16-lead DIL; plastic (SOT38Z).

16-lead mini-pack; plastic (SO16; SOT109A).

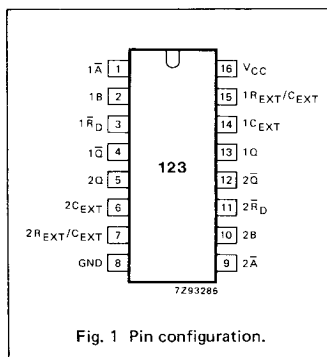


Fig. 1 Pin configuration.

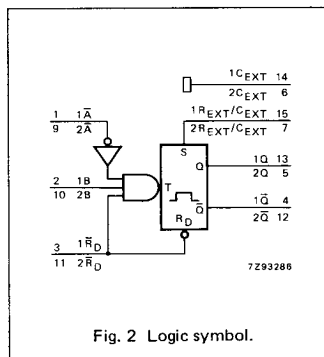


Fig. 2 Logic symbol.

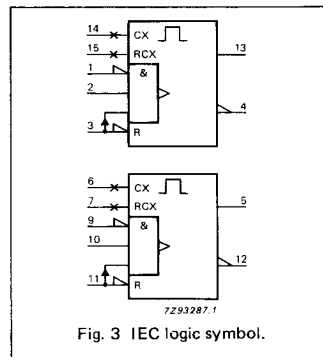


Fig. 3 IEC logic symbol.

PIN DESCRIPTION

PIN NO.	SYMBOL	NAME AND FUNCTION
1, 9	$1\bar{A}, 2\bar{A}$	trigger inputs (negative-edge triggered)
2, 10	1B, 2B	trigger inputs (positive-edge triggered)
3, 11	$1\bar{R}_D, 2\bar{R}_D$	direct reset LOW and trigger action at positive edge
4, 12	$1\bar{Q}, 2\bar{Q}$	outputs (active LOW)
7	$2R_{EXT}/C_{EXT}$	external resistor/capacitor connection
8	GND	ground (0 V)
13, 5	1Q, 2Q	outputs (active HIGH)
14, 6	$1C_{EXT}, 2C_{EXT}$	external capacitor connection
15	$1R_{EXT}/C_{EXT}$	external resistor/capacitor connection
16	VCC	positive supply voltage

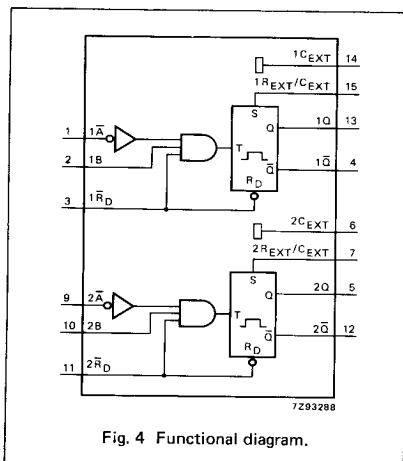


Fig. 4 Functional diagram.

GENERAL DESCRIPTION (Cont'd)

An internal connection from $n\bar{R}_D$ to the input gates makes it possible to trigger the circuit by a positive-going signal at input $n\bar{R}_D$ as shown in the function table.

Figures 7 and 8 illustrate pulse control by retriggering and early reset. The basic output pulse width is essentially determined by the values of the external timing components R_{EXT} and C_{EXT} . For pulse widths, when $C_{EXT} < 10\,000\text{ pF}$, see Fig. 9.

When $C_{EXT} > 10\,000\text{ pF}$, the typical output pulse width is defined as:

$$t_W = 0.45 \times R_{EXT} \times C_{EXT} \text{ (typ.)},$$

where, t_W = pulse width in ns;

R_{EXT} = external resistor in k Ω ;

C_{EXT} = external capacitor in pF.

Schmitt-trigger action in the $n\bar{A}$ and nB inputs, makes the circuit highly tolerant to slower input rise and fall times.

The '123' is identical to the '423' but can be triggered via the reset input.

FUNCTION TABLE

INPUTS			OUTPUTS	
$n\bar{R}_D$	$n\bar{A}$	nB	nQ	$n\bar{Q}$
L	X	X	L	H
X	H	X	L*	H*
X	X	L	L*	H*
H	L	↑	⌊	⌋
H	↓	H	⌊	⌋
↑	L	H	⌊	⌋

H = HIGH voltage level

L = LOW voltage level

X = don't care

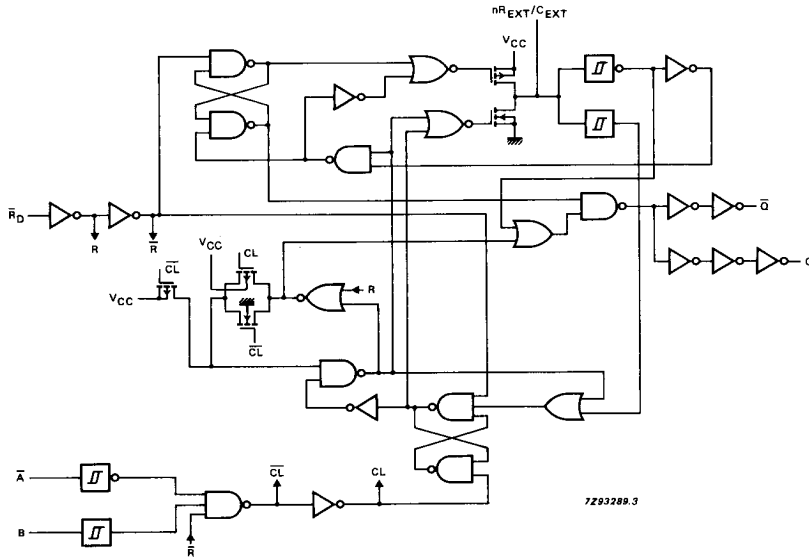
↑ = LOW-to-HIGH transition

↓ = HIGH-to-LOW transition

⌊ = one HIGH level output pulse

⌋ = one LOW level output pulse

* If the monostable was triggered before this condition was established, the pulse will continue as programmed.



(1) For minimum noise generation,
it is recommended to ground pins 6 ($2C_{EXT}$)
and 14 ($1C_{EXT}$) externally to pin 8 (GND).

Fig. 5 Logic diagram.

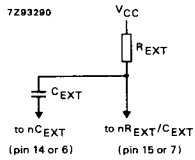


Fig. 6 Timing component connections.

DC CHARACTERISTICS FOR 74HC

For the DC characteristics see chapter "HCMOS family characteristics", section "Family specifications".

Output capability: standard (except for nR_{EXT}/C_{EXT})

I_{CC} category: MSI

AC CHARACTERISTICS FOR 74HC

$GND = 0\text{ V}$; $t_r = t_f = 6\text{ ns}$; $C_L = 50\text{ pF}$

SYMBOL	PARAMETER	T _{amb} (°C)							UNIT	TEST CONDITIONS	
		74HC								V _{CC} V	WAVEFORMS/NOTES
		+25			−40 to +85		−40 to +125				
		min.	typ.	max.	min.	max.	min.	max.			
t _{PHL}	propagation delay nR _D , nA, nB to nQ		83 30 24	255 51 43		320 64 54		385 77 65	ns	2.0 4.5 6.0	C _{EXT} = 0 pF; R _{EXT} = 5 kΩ
t _{PLH}	propagation delay nR _D , nA, nB to nQ		83 30 24	255 51 43		320 64 54		385 77 65	ns	2.0 4.5 6.0	C _{EXT} = 0 pF; R _{EXT} = 5 kΩ
t _{PHL}	propagation delay nR _D to nQ (reset)		66 24 19	215 43 37		270 54 46		325 65 55	ns	2.0 4.5 6.0	C _{EXT} = 0 pF; R _{EXT} = 5 kΩ
t _{PLH}	propagation delay nR _D to nQ (reset)		66 24 19	215 43 37		270 54 46		325 65 55	ns	2.0 4.5 6.0	C _{EXT} = 0 pF; R _{EXT} = 5 kΩ
t _{THL} / t _{TLH}	output transition time		19 7 6	75 15 13		95 19 16		110 22 19	ns	2.0 4.5 6.0	
t _W	trigger pulse width nA = LOW	100 20 17	8 3 2		125 25 21		150 30 26		ns	2.0 4.5 6.0	Fig. 7
t _W	trigger pulse width nB = HIGH	100 20 17	17 6 5		125 25 21		150 30 26		ns	2.0 4.5 6.0	Fig. 7
t _W	reset pulse width nR _D = LOW	100 20 17	14 5 4		125 25 21		150 30 26		ns	2.0 4.5 6.0	Fig. 8
t _W	output pulse width nQ = HIGH nQ = LOW		450		—		—		μs	5.0	C _{EXT} = 100 nF; R _{EXT} = 10 kΩ; Figs 7 and 8
t _W	output pulse width nQ = HIGH nQ = LOW		75		—		—		ns	5.0	C _{EXT} = 0 pF; R _{EXT} = 5 kΩ; note 1; Figs 7 and 8
t _{rt}	retrigger time nA, nB		26		—		—		ns	5.0	C _{EXT} = 0 pF; R _{EXT} = 5 kΩ; note 2; Fig. 7
R _{EXT}	external timing resistor	10 2		1000 1000	—		—		kΩ	2.0 5.0	Fig. 9
C _{EXT}	external timing capacitor	no limits							pF	5.0	Fig. 9; note 3

DC CHARACTERISTICS FOR 74HCT

For the DC characteristics see chapter "HCMOS family characteristics", section "Family specifications".

Output capability: standard (except for nREXT/CEXT)

I_{CC} category: MSI

Note to HCT types

The value of additional quiescent supply current (ΔI_{CC}) for a unit load of 1 is given in the family specifications. To determine ΔI_{CC} per input, multiply this value by the unit load coefficient shown in the table below.

INPUT	UNIT LOAD COEFFICIENT
n $\bar{A}$, nB	0.35
n $\bar{R}_D$	0.50

AC CHARACTERISTICS FOR 74HCT

GND = 0 V; $t_r = t_f = 6$ ns; $C_L = 50$ pF

SYMBOL	PARAMETER	T _{amb} (°C)							UNIT	TEST CONDITIONS	
		74HCT								V _{CC} V	WAVEFORMS/NOTES
		+25			−40 to +85		−40 to +125				
		min.	typ.	max.	min.	max.	min.	max.			
t _{PHL}	propagation delay nR _D , nA, nB to nQ		30	51		64		77	ns	4.5	C _{EXT} = 0 pF; R _{EXT} = 5 kΩ
t _{PLH}	propagation delay nR _D , nA, nB to nQ		28	51		64		77	ns	4.5	C _{EXT} = 0 pF; R _{EXT} = 5 kΩ
t _{PHL}	propagation delay nR _D to nQ (reset)		27	46		58		69	ns	4.5	C _{EXT} = 0 pF; R _{EXT} = 5 kΩ
t _{PLH}	propagation delay nR _D to nQ (reset)		23	46		58		69	ns	4.5	C _{EXT} = 0 pF; R _{EXT} = 5 kΩ
t _{THL} / t _{TLH}	output transition time		7	15		19		22	ns	4.5	
t _W	trigger pulse width nA = LOW	20	3		25		30		ns	4.5	Fig. 7
t _W	trigger pulse width nB = HIGH	20	5		25		30		ns	4.5	Fig. 7
t _W	reset pulse width nR _D = LOW	20	7		25		30		ns	4.5	Fig. 8
t _W	output pulse width nQ = HIGH nQ = LOW		450		—		—		μs	5.0	C _{EXT} = 100 nF; R _{EXT} = 10 kΩ; Figs 7 and 8
t _W	output pulse width nQ = HIGH nQ = LOW		75		—		—		ns	5.0	C _{EXT} = 0 pF; R _{EXT} = 5 kΩ; note 1; Figs 7 and 8
t _{rt}	retrigger time nA, nB		40		—		—		ns	5.0	C _{EXT} = 0 pF; R _{EXT} = 5 kΩ; note 2; Fig. 7
R _{EXT}	external timing resistor	2		1000	—		—		kΩ	5.0	Fig. 9
C _{EXT}	external timing capacitor	no limits							pF	5.0	Fig. 9; note 3

Notes to AC characteristics

1. For other R_{EXT} and C_{EXT} combinations see Fig. 9.

If $C_{EXT} > 10 \text{ nF}$, the next formula is valid:

$$t_W = K \times R_{EXT} \times C_{EXT} \quad (\text{typ.})$$

where, t_W = output pulse width in ns;

R_{EXT} = external resistor in $k\Omega$; C_{EXT} = external capacitor in pF;

K = constant = 0.45 for $V_{CC} = 5.0 \text{ V}$ and 0.48 for $V_{CC} = 2.0 \text{ V}$.

The inherent test jig and pin capacitance at pins 15 and 7 (nR_{EXT}/C_{EXT}) is approximately 7 pF.

2. The time to retrigger the monostable multivibrator depends on the values of R_{EXT} and C_{EXT} .

The output pulse width will only be extended when the time between the active-going edges of the trigger input pulses meets the minimum retrigger time.

If $C_{EXT} > 10 \text{ pF}$, the next formula (at $V_{CC} = 5.0 \text{ V}$) for the set-up time of a retrigger pulse is valid:

$$t_{rt} = 35 + (0.11 \times C_{EXT}) + (0.04 \times R_{EXT} \times C_{EXT}) \quad (\text{typ.})$$

where, t_{rt} = retrigger time in ns;

C_{EXT} = external capacitor in pF;

R_{EXT} = external resistor in $k\Omega$.

The inherent test jig and pin capacitance at pins 15 and 7 (nR_{EXT}/C_{EXT}) is approximately 7 pF.

3. When the device is powered-up, initiate the device via a reset pulse, when $C_{EXT} < 50 \text{ pF}$.

AC WAVEFORMS

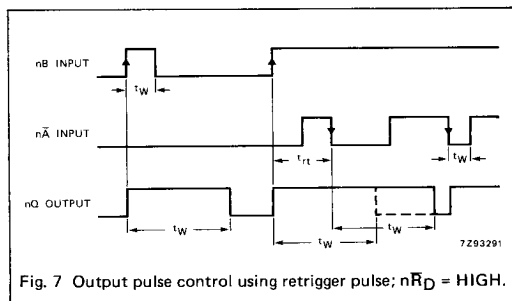


Fig. 7 Output pulse control using retrigger pulse; $n\bar{R}_D = \text{HIGH}$.

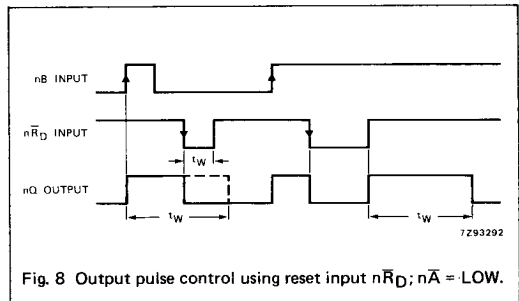


Fig. 8 Output pulse control using reset input $n\bar{R}_D$; $n\bar{A} = \text{LOW}$.

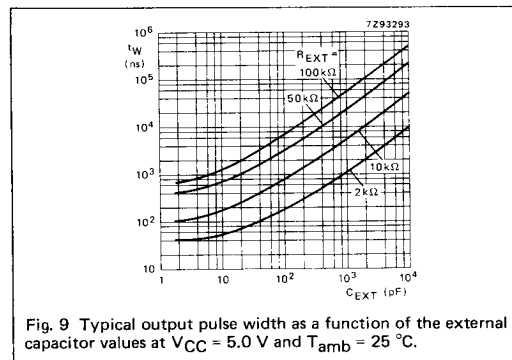


Fig. 9 Typical output pulse width as a function of the external capacitor values at $V_{CC} = 5.0 \text{ V}$ and $T_{amb} = 25^\circ \text{C}$.

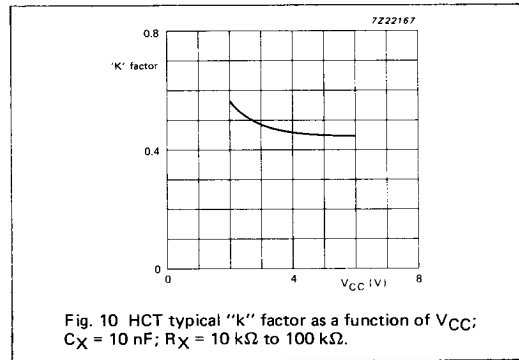


Fig. 10 HCT typical "k" factor as a function of V_{CC} ; $C_X = 10 \text{ nF}$; $R_X = 10 \text{ k}\Omega$ to $100 \text{ k}\Omega$.

APPLICATION INFORMATION

Power-up considerations

When the monostable is powered-up it may produce an output pulse, with a pulse width defined by the values of R_X and C_X , this output pulse can be eliminated using the circuit shown in Fig. 11.

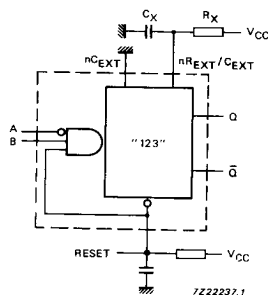


Fig. 11 Power-up output pulse elimination circuit.

Power-down considerations

A large capacitor (C_X) may cause problems when powering-down the monostable due to the energy stored in this capacitor. When a system containing this device is powered-down or a rapid decrease of V_{CC} to zero occurs, the monostable may sustain damage, due to the capacitor discharging through the input protection diodes. To avoid this possibility, use a damping diode (D_X) preferably a germanium or Schottky type diode able to withstand large current surges and connect as shown in Fig. 12.

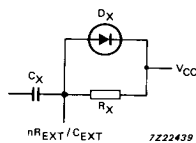


Fig. 12 Power-down protection circuit.