

L9216A/G

Short-Loop Ringing SLIC with Ground Start

Introduction

The Agere Systems Inc. L9216 is a subscriber line interface circuit (SLIC) that is optimized for short-loop, power-sensitive applications. This device provides the complete set of line interface functionality, including power ringing needed to interface to a subscriber loop. This device has the capability to operate with a V_{cc} supply of 3.3 V or 5 V and is designed to minimize external components required at all device interfaces.

Features

- Onboard ringing generation
- Three ringing input options:
 - Sine wave
 - PWM
 - Logic level square wave
- Flexible V_{cc} options:
 - 5 V or 3.3 V V_{cc}
 - No -5 V required
- Battery switch to minimize off-hook power
- Eight operating states:
 - Scan mode for minimal power dissipation
 - Forward and reverse battery active
 - On-hook transmission states
 - Ground start (tip open)
 - Ring mode
 - Disconnect mode
- Ultralow on-hook power:
 - 27 mW scan mode
 - 41 mW active mode
- Two SLIC gain options to minimal external components in codec interface
- Loop start, ring trip, and ground start detectors
- Software-controllable dual current-limit option
- 28-pin PLCC package
- 48-pin MLCC package

Applications

- Voice over Internet Protocol (VoIP)
- Cable Modems
- Terminal Adapters (TA)
- Wireless Local Loop (WLL)
- *Telcordia Technologies*TM GR-909 Access
- Network Termination (NT)
- Key Systems

Description

This device is optimized to provide battery feed, ringing, and supervision on short-loop plain old telephone service (POTS) loops.

This device provides power ring to the subscriber loop through amplification of a low-voltage input. It provides forward and reverse battery feed states, on-hook transmission, a low-power scan state, ground start (tip open), and a forward disconnect state.

The device requires a V_{cc} and battery to operate. V_{cc} may be either a 5 V or a 3.3 V supply. The ringing signal is derived from the high-voltage battery. A battery switch is included to allow for use of a lower-voltage battery in the off-hook mode, thus minimizing short-loop off-hook power.

Loop closure, ring trip, and ground start detectors are available. The loop closure detector has a fixed threshold with hysteresis. The ring trip detector requires a single-pole filter, thus minimizing external components required.

The dc current limit is set and fixed by a logic controllable pin. Ground or open is applied to this pin set the current limit at the low or high value.

The device is offered with two gain options. This allows for an optimized codec interface, with minimal external components regardless of whether a first-generation or a programmable third-generation codec is used.

Table of Contents

Contents	Page	Contents	Page
Introduction.....	1	ac Applications	32
Features	1	ac Parameters.....	32
Applications.....	1	Codec Types.....	32
Description	1	First-Generation Codecs	32
Features	4	Third-Generation Codecs	32
Description.....	4	ac Interface Network	32
Architecture Diagram.....	7	Design Examples	34
Pin Information	8	First-Generation Codec ac Interface	
Operating States	10	Network—Resistive Termination	34
State Definitions	11	Example 1, Real Termination	34
Forward Active	11	First-Generation Codec ac Interface	
Reverse Active.....	11	Network—Complex Termination	37
Scan.....	11	Complex Termination Impedance Design	
On-Hook Transmission—Forward Battery	11	Example.....	37
On-Hook Transmission—Reverse Battery	11	ac Interface Using First-Generation Codec	37
Disconnect	11	Transmit Gain.....	38
Ring.....	11	Receive Gain.....	39
Ground Start	11	Hybrid Balance	39
Thermal Shutdown.....	12	Blocking Capacitors	40
Absolute Maximum Ratings (@ TA = 25 °C)	12	Third-Generation Codec ac Interface	
Electrical Characteristics	13	Network—Complex Termination	42
Test Configurations	20	Outline Diagrams.....	44
Applications	22	28-Pin PLCC	44
Power Control	22	48-Pin MLCC.....	45
dc Loop Current Limit.....	23	48-Pin MLCC, JEDEC MO-220 VKKD-2.....	46
Overhead Voltage	23	Ordering Information	47
Active Mode	23		
Scan Mode	23		
On-Hook Transmission Mode.....	23		
Ring Mode.....	24		
Loop Range	24		
Battery Reversal Rate.....	24		
Supervision.....	24		
Loop Closure.....	24		
Ring Trip	24		
Tip or Ring Ground Detector.....	24		
Power Ring	25		
Sine Wave Input Signal and Sine Wave			
Power Ring Signal Output	26		
PWM Input Signal and Sine Wave Power			
Ring Signal Output.....	28		
5 V Vcc Operation	29		
3.3 V Vcc Operation	30		
Square Wave Input Signal and Trapezoidal			
Power Ring Signal Output	30		

Table of Contents (continued)

Figures	Page	Tables	Page
Figure 1. Architecture Diagram	7	Table 1. Pin Descriptions	9
Figure 2. 28-Pin PLCC	8	Table 2. Control States	10
Figure 3. 48-Pin MLCC	8	Table 3. Supervision Coding	10
Figure 4. Basic Test Circuit	20	Table 4. Recommended Operating Characteristics	12
Figure 5. Metallic PSRR	21	Table 5. Thermal Characteristics	12
Figure 6. Longitudinal PSRR	21	Table 6. Environmental Characteristics	13
Figure 7. Longitudinal Balance	21	Table 7. 5 V Supply Currents	13
Figure 8. ac Gains	21	Table 8. 5 V Powering	13
Figure 9. Ringing Waveform Crest Factor = 1.6	25	Table 9. 3.3 V Supply Currents	14
Figure 10. Ringing Waveform Crest Factor = 1.2	25	Table 10. 3.3 V Powering	14
Figure 11. Ring Mode Typical Operation	26	Table 11. 2-Wire Port	15
Figure 12. RING _{IN} Operation	27	Table 12. Analog Pin Characteristics	16
Figure 13. L9215/16 Ringing Input Circuit Selection Table for Square Wave and PWM Inputs	28	Table 13. ac Feed Characteristics	17
Figure 14. Modulation Waveforms	29	Table 14. Logic Inputs and Outputs (V _{CC} = 5 V)	18
Figure 15. 5 V PWM Signal Amplitude	29	Table 15. Logic Inputs and Outputs (V _{CC} = 3.3 V) ..	18
Figure 16. Ringing Output on RING, with V _{CC} = 5 V	29	Table 16. Ground Start	18
Figure 17. 3.3 V PWM Signal Amplitude	30	Table 17. Ringing Specifications	19
Figure 18. Ringing Output on RING, with V _{CC} = 3.1 V	30	Table 18. Ring Trip	19
Figure 19. Square Wave Input Signal and Trapezoidal Power Ring Signal Output ...	30	Table 19. Typical Active Mode On- to Off-Hook Tip/Ring Current-Limit Transient Response	23
Figure 20. Crest Factor vs. Battery Voltage	31	Table 20. FB1 and FB2 Values vs. Typical Ramp Time	24
Figure 21. Crest Factor vs. R (k Ω)	31	Table 21. Onset of Power Ringing Clipping V _{CC} = 5 V, C _{input} = 0.47 μ F	27
Figure 22. ac Equivalent Circuit	35	Table 22. Onset of Power Ringing Clipping V _{CC} = 3.1 V, C _{input} = 0.47 μ F	27
Figure 23. Agere T7504 First-Generation Codec Resistive Termination	35	Table 23. Signal and Component Selection Chart ...	28
Figure 24. Interface Circuit Using First-Generation Codec (Blocking Capacitors Not Shown)	38	Table 24. Parts List L9216; Agere T7504 First- Generation Codec Resistive Termination; Nonmeter Pulse Application	36
Figure 25. ac Interface Using First-Generation Codec (Including Blocking Capacitors) for Complex Termination Impedance	40	Table 25. Parts List L9216; Agere T7504 First- Generation Codec Complex Termination; Meter Pulse Application	41
Figure 26. Agere T7504 First-Generation Codec Complex Termination	40	Table 26. Parts List L9216; Agere T8536 Third-Generation Codec ac and dc Parameters; Fully Programmable	43
Figure 27. Third-Generation Codec ac Interface Network; Complex Termination	42		

Features

- Onboard balanced ringing generation:
 - No ring relay
 - No bulk ring generator required
 - 15 Hz to 70 Hz ring frequency supported
 - Sine wave input-sine wave output
 - PWM input-sine wave output
 - Square wave input-trapezoidal output
- Power supplies requirements:
 - Vcc talk battery and ringing battery required
 - No -5 V supply required
 - No high-voltage positive supply required
- Flexible Vcc options:
 - 5 V or 3.3 V Vcc operation
 - 5 V or 3.3 V Vcc interchangeable and transparent to users
- Battery switch via logic control:
 - Minimize off-hook power dissipation
- Minimal external components required
- Eight operating states:
 - Forward active, V_{BAT2} applied
 - Polarity reversal active, V_{BAT2} applied
 - On-hook transmission, V_{BAT1} applied
 - On-hook transmission polarity reversal, V_{BAT1} applied
 - Ground start
 - Scan
 - Forward disconnect
 - Ring mode
- Unlatched parallel data control interface
- Ultralow SLIC power:
 - Scan 37 mW (V_{CC} = 5 V)
 - Forward/reverse active 54 mW (V_{CC} = 5 V)
 - Scan 27 mW (V_{CC} = 3.3 V)
 - Forward/reverse active 41 mW (V_{CC} = 3.3 V)
- Supervision:
 - Loop start, fixed threshold with hysteresis
 - Ring trip, single-pole ring trip filtering, fixed threshold as a function of battery voltage
 - Ring current for ground start applications, user-adjustable threshold
- Adjustable current limit:
 - 25 mA or 40 mA via ground or open to control input
- Overhead voltage:
 - Clamped typically <51 V differentially
 - Clamped maximum <56.5 V single-ended
- Thermal shutdown protection with hysteresis
- Longitudinal balance:
 - *Telcordia Technologies* GR-909 balance
- ac interface:
 - Two SLIC gain options to minimize external components required for interface to first- or third-generation codecs
 - Sufficient dynamic range for direct coupling to codec output
- 28-pin PLCC/48-pin MLCC package
- 90 V CBIC-S technology

Description

The L9216 is designed to provide battery feed, ringing, and supervision functions on short plain old telephone service (POTS) loops. This device is designed for ultralow power in all operating states.

The L9216 offers eight operating states. The device assumes uses of a lower-voltage talk battery, a higher-voltage ringing battery, and a V_{CC} supply.

The L9216 requires only a positive V_{CC} supply. No -5 V supply is needed. The L9216 can operate with a V_{CC} of either 5 V or 3.3 V, allowing for greater user flexibility. The choice of V_{CC} voltage is transparent to the user; the device will function with either supply voltage connected.

Two batteries are used:

1. A high-voltage ring battery (V_{BAT1}).
V_{BAT1} is a maximum -75 V. V_{BAT1} is used for power ring signal amplification and for scan, on-hook transmission, and ground start modes. This supply is current limited to approximately the maximum power ringing current, typically 50 mA.
2. A lower-voltage talk battery (V_{BAT2}).
V_{BAT2} is used for active mode powering.

Description (continued)

Forward and reverse battery active modes are used for off-hook conditions. Since this device is designed for short-loop applications, the lower-voltage V_{BAT2} is applied during the forward and reverse active states. Battery reversal is quiet, without breaking the ac path. Rate of battery reversal may be ramped to control switching time.

The magnitude of the overhead voltage in the forward and reverse active modes has a typical default value of 6.0 V, allowing for an undistorted signal of 3.14 dBm into 900 Ω . This overhead is fixed. The ring trip detector is turned off during active modes to conserve power.

Because on-hook transmission is not allowed in the scan mode, an on-hook transmission mode is defined. This mode is functionally similar to the active mode, except the tip ring voltage is derived from the higher V_{BAT1} rather than V_{BAT2} .

In the on-hook transmission modes with a primary battery whose magnitude is greater than a nominal 51 V, the magnitude of the tip to ground and ring to ground voltage is clamped at less than 56.5 V.

To minimize on-hook power, a low-power scan mode is available. In this mode, all functions except off-hook supervision are turned off to conserve power. On-hook transmission is not allowed in the scan mode.

In the scan mode with a primary battery whose magnitude is greater than a nominal 51 V, the magnitude of the tip to ground and ring to ground voltage is clamped at less than 56.5 V.

A forward disconnect mode is provided, where all circuits are turned off and power is denied to the loop.

The device offers a ring mode, in which a power ring signal is provided to the tip/ring pair. During the ring mode, a user-supplied low-voltage ring signal (ac-coupled) is input to the device's $RING_{IN}$ input. This signal is amplified to produce the power ring signal. This signal may be a sine wave or filtered square wave to produce a sine wave on trapezoidal output. Ring trip detector and common-mode current detector are active during the ring mode.

This feature eliminates the need for a separate external ring relay, associated external circuitry, and a bulk ringing generator. See the Applications section of this data sheet for more information.

The device offers a ground start mode. In this mode, the tip drive amplifier is turned off. The device presents a high impedance ($>100\text{ k}\Omega$) to PT and a current-limited battery (V_{BAT1}) to PR. V_{BAT1} is clamped to less than 56.5 V in this mode as PR. A ring current detector for ring ground detection is included for ground start applications. The threshold is user programmable via external resistors. See the Applications section of this data sheet for more information on supervision functions. Output pin RGDET indicates current flowing in the ring lead.

Both the ring trip and loop closure supervision functions are included. The loop closure has a fixed typical 10.5 mA on- to off-hook threshold in the active mode and a fixed 11.5 mA on- to off-hook threshold from the scan mode. In either case, there is a 2 mA hysteresis. The ring trip detector requires only a single-pole filter at the input, minimizing external components. The ring trip threshold at a given battery voltage is fixed. Typical ring trip threshold is 42.5 mA for a $-70\text{ V }V_{BAT1}$.

Upon reaching the thermal shutdown temperature, the device will enter an all-off mode. Upon cooling, the device will re-enter the state it was in prior to thermal shutdown. Hysteresis is built in to prevent oscillation.

Longitudinal balance is consistent with North American GR-909 requirements. Specifications are given in Table 12.

Data control is via a parallel unlatched control scheme.

The dc current limit is fixed to either 25 mA or 40 mA depending if ground or open is applied to the V_{PROG} current-limit programming pin. Programming accuracy is $\pm 8\%$.

Circuitry is added to the L9216 to minimize the inrush of current from the V_{CC} supply and to the battery supply during an on- to off-hook transition, thus saving in power supply design cost. See the Applications section of this data sheet for more information.

Overhead in the active modes (V_{BAT2} applied) is fixed to approximately 6.0 V is achieved. This is adequate for a 3.14 dBm overload into 900 Ω .

Transmit and receive gains have been chosen to minimize the number of external components required in the SLIC-codec ac interface, regardless of the choice of codec.

Description (continued)

The L9216 uses a voltage feed-current sense architecture; thus, the transmit gain is a transconductance. The L9216 transconductance is set via a single external resistor, and this device is designed for optimal performance with a transconductance set at 300 V/A.

The L9216 offers an option for a single-ended to differential receive gain of either 8 or 2. These options are mask programmable at the factory and are selected by choice of code.

A receive gain of 8 is more appropriate when choosing a first-generation type codec where termination impedance, hybrid balance, and overall gains are set by external analog filters. The higher gain is typically required for synthesization of complex termination impedance.

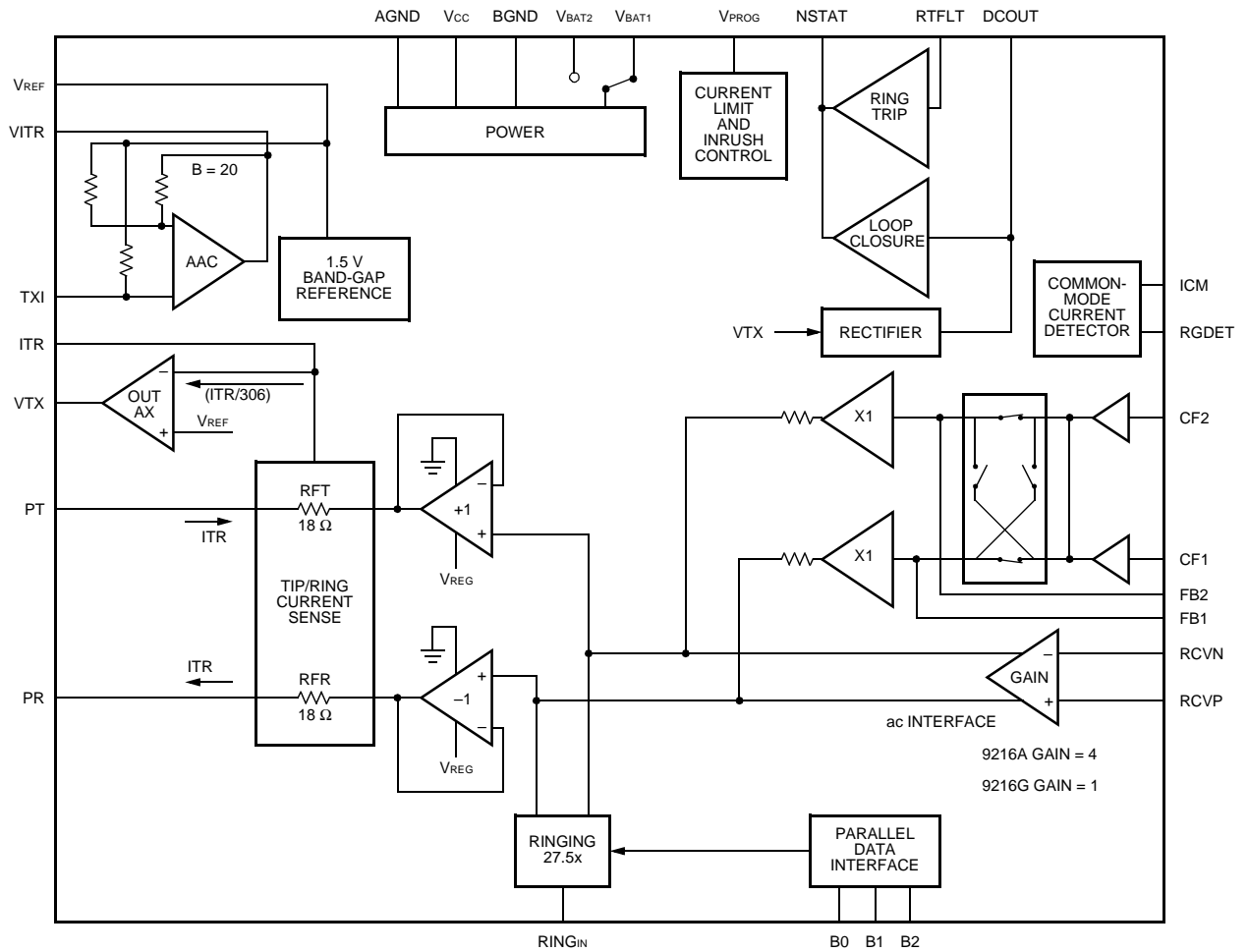
A receive gain of 2 is more appropriate when choosing a third-generation type codec. Third-generation codecs will synthesize termination impedance and set hybrid balance and overall gains. To accomplish these functions, third-generation codecs typically have both analog and digital gain filters. For optimal signal to noise

performance, it is best to operate the codec at a higher gain level. If the SLIC then provides a high gain, the SLIC output may be saturated causing clipping distortion of the signal at tip and ring. To avoid this situation, with a higher gain SLIC, external resistor dividers are used. These external components are not necessary with the lower gain offered by the L9216. See the Applications section of this data sheet for more information.

The L9216 is internally referenced to 1.5 V. This reference voltage is output at the V_{REF} output of the device. The SLIC output V_{TR} is also referenced to 1.5 V; therefore, it must be ac coupled to the codec input. However, the SLIC inputs RCVP/RCVN are floating inputs. If there is not feedback from RCVP/RCVN to V_{TR}, RCVP/RCVN may be directly coupled to the codec output. If there is feedback from RCVP/RCVN to V_{TR}, RCVP/RCVN must be ac coupled to the codec output.

The L9216 is packaged in a 28-pin PLCC package and an ultrasmall 48-pin MLCC package. Use L9216A for gain of eight applications and L9216G for gain of two applications.

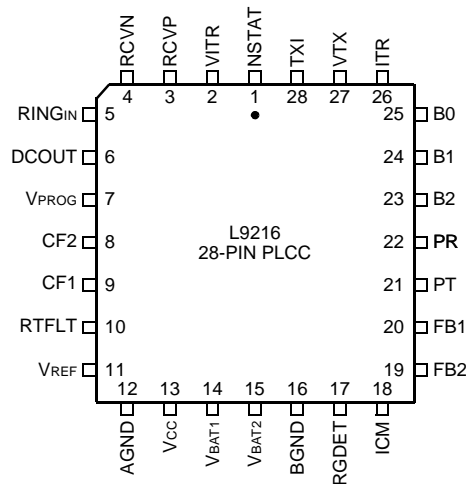
Architecture Diagram



12-3530.E (F)

Figure 1. Architecture Diagram

Pin Information



12-3558.d (F)

Figure 2. 28-Pin PLCC

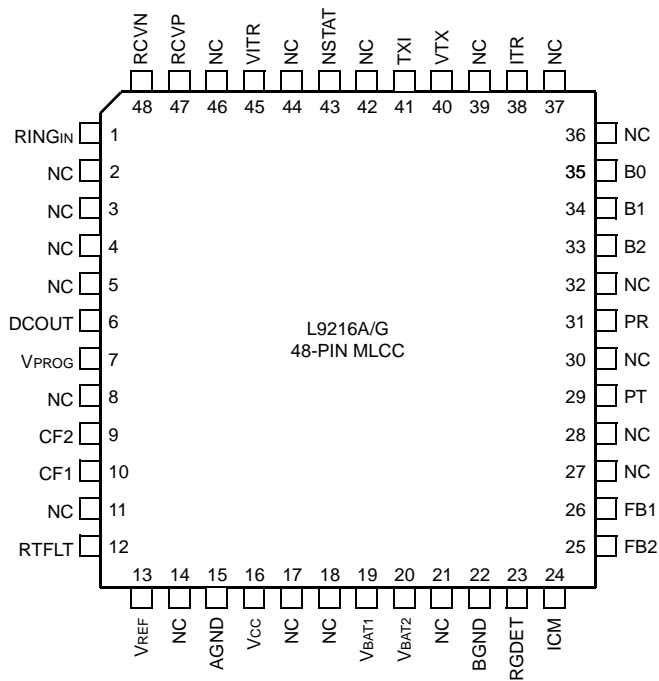


Figure 3. 48-Pin MLCC

Pin Information (continued)

Table 1. Pin Descriptions

28-Pin PLCC	48-Pin MLCC	Symbol	Type	Name/Function
1	43	NSTAT	O	Loop Closure Detector Output—Ring Trip Detector Output. When low, this logic output indicates that an off-hook condition exists or ringing is tripped.
2	45	VITR	O	Transmit ac Output Voltage. Output of internal AAC amplifier. This output is a voltage that is directly proportional to the differential ac tip/ring current.
3	47	RCVP	I	Receive ac Signal Input (Noninverting). This high-impedance input controls the ac differential voltage on tip and ring. This node is a floating input.
4	48	RCVN	I	Receive ac Signal Input (Inverting). This high-impedance input controls the ac differential voltage on tip and ring. This node is a floating input.
5	1	RINGIN	I	Power Ring Signal Input. ac-couple to a sine wave or lower crest factor low-voltage ring signal. The input here is amplified to provide the full power ring signal at tip and ring. This signal may be applied continuously, even during nonringing states.
6	6	DCOUT	O	dc Output Voltage. This output is a voltage that is directly proportional to the absolute value of the differential tip/ring current. This is used to set ring trip threshold.
7	7	VPROG	I	Current-Limit Program Input. Connect ground to this pin to set current-limit to 25 mA, float to this pin to set current limit to 40 mA.
8	9	CF2	—	Filter Capacitor. Connect a capacitor from this node to ground.
9	10	CF1	—	Filter Capacitor. Connect a capacitor from this node to CF2.
10	12	RTFLT	—	Ring Trip Filter. Connect this lead to DCOUT via a resistor and to AGND with a capacitor to filter the ring trip circuit to prevent spurious responses. A single-pole filter is needed.
11	13	VREF	O	SLIC Internal Reference Voltage. Output of internal 1.5 V reference voltage.
12	15	AGND	GND	Analog Signal Ground.
13	16	VCC	PWR	Analog Power Supply. User choice of 5 V or 3.3 V nominal power or supply.
14	19	VBAT1	PWR	Battery Supply 1. High-voltage battery.
15	20	VBAT2	PWR	Battery Supply 2. Lower-voltage battery.
16	22	BGND	GND	Battery Ground. Ground return for the battery supplies.
—	2, 3, 4, 5, 8, 11, 14, 17, 18, 21, 27, 28, 30, 32, 36, 37, 39, 42, 44, 46	NC	—	No Connection.
17	23	RGDET	O	Ring Ground Detect. When high, this open collector output indicates the presence of a ring ground or a tip ground. This supervision output may be used in ground key, ground start or common-mode fault detection applications.
18	24	ICM	I	Common-Mode Current Sense. To program tip or ring ground sense threshold, connect a resistor to Vcc and connect a capacitor to AGND to filter 50/60 Hz. If unused, the pin is connected to ground.

Pin Information (continued)

Table 1. Pin Descriptions (continued)

28-Pin PLCC	48-Pin MLCC	Symbol	Type	Name/Function
19	25	FB2	—	Polarity Reversal Slowdown Capacitor. Connect a capacitor from this node to ground for controlling rate of battery reversal. If ramped battery reversal is not desired, this pin is left open.
20	26	FB1	—	Polarity Reversal Slowdown Capacitor. Connect a capacitor from this node to ground for controlling rate of battery reversal. If ramped battery reversal is not desired, this pin is left open.
21	29	PT	I/O	Protected Tip. The output drive of the tip amplifier and input to the loop sensing circuit. Connect to loop through overvoltage and overcurrent protection.
22	31	PR	I/O	Protected Ring. The output drive of the ring amplifier and input to the loop sensing circuit. Connect to loop through overvoltage and overcurrent protection.
23	33	B2	I ^d	State Control Input. These pins have an internal 110 kΩ pull-down.
24	34	B1	I ^d	
25	35	B0	I ^d	
26	38	ITR	I	Transmit Gain. Input to AX amplifier. Connect a 4.75 kΩ resistor from this node to VTX to set transmit gain. Gain shaping for termination impedance with a first-generation codec is also achieved with a network from this node to VTX.
27	40	VTX	O	ac Output Voltage. Output of internal AX amplifier. The voltage at this pin is directly proportional to the differential tip/ring current.
28	41	TXI	I	ac/dc Separation. Input to internal AAC amplifier. Connect a 0.1 μF capacitor from this pin to VTX.

Operating States

Table 2. Control States

B0	B1	B2	State
1	1	0	Forward active
1	0	0	Reverse active
1	1	1	On-hook transmission forward battery
1	0	1	On-hook transmission reverse battery
0	0	1	Ground start
0	1	1	Scan
0	0	0	Disconnect, device will power up in this state
0	1	0	Ring

Table 3. Supervision Coding

NSTAT	RGDET
0 = off-hook or ring trip or TSD. 1 = on-hook and no ring trip and no TSD or DISCONNECT state.	0 = no ring or tip ground. 1 = ring or tip ground.

State Definitions

Forward Active

- Pin PT is positive with respect to PR.
- V_{BAT2} is applied to tip/ring drive amplifiers.
- Loop closure and common-mode detect are active.
- Ring trip detector is turned off to conserve power.
- Overhead is set to nominal 6.0 V for undistorted transmission of 3.14 dBm into 900 Ω .

Reverse Active

- Pin PR is positive with respect to PT.
- V_{BAT2} is applied to tip/ring drive amplifiers.
- Loop closure and common-mode detect are active.
- Ring trip detector is turned off to conserve power.
- Overhead is set to nominal 6.0 V for undistorted transmission of 3.14 dBm into 900 Ω .

Scan

- Except for loop closure, all circuits (including ring trip and common-mode detector) are powered down.
- On-hook transmission is disabled.
- Pin PT is positive with respect to PR, and V_{BAT1} is applied to tip/ring.
- The tip to ring on-hook differential voltage will be typically between -44 V and -51 V with a -70 V primary battery.

On-Hook Transmission—Forward Battery

- Pin PT is positive with respect to PR.
- V_{BAT1} is applied to tip/ring drive amplifiers.
- Supervision circuits, loop closure, and common-mode detect are active.
- Ring trip detector is turned off to conserve power.
- On-hook transmission is allowed.
- The tip-to-ring on-hook differential voltage will be typically between -41 V and -49 V with a -70 V primary battery.

On-Hook Transmission—Reverse Battery

- Pin PR is positive with respect to PT.
- V_{BAT1} is applied to tip/ring drive amplifiers.
- Supervision circuits, loop closure, and common-mode detect are active.
- Ring trip detector is turned off to conserve power.
- On-hook transmission is allowed.
- The tip-to-ring on-hook differential voltage will be typically between -41 V and -49 V with a -70 V primary battery.

Disconnect

- The tip/ring amplifiers and all supervision are turned off.
- The SLIC goes into a high-impedance state.
- NSTAT is forced high (on-hook).
- Device will power up in this state.

Ring

- Power ring signal is applied to tip and ring.
- Input waveform at RINGIN is amplified.
- Ring trip supervision and common-mode current supervision are active; loop closure is inactive.
- Overhead voltage is reduced to typically 4 V.
- Current is limited by saturation current of the amplifiers themselves, typically 100 mA at 125 °C.

Ground Start

- Tip drive amplifier is turned off.
- Device presents a high impedance (>100 k Ω) to pin PT.
- Device presents a clamped (<56.5 V) current-limited battery (V_{BAT1}) to PR.
- Output pin RGDET indicates current flowing in the ring lead.

Thermal Shutdown

- Not controlled via truth table inputs.
- NSTAT is forced low (off-hook) during this state.
- This mode is caused by excessive heating of the device, such as may be encountered in an extended power cross situation.

Absolute Maximum Ratings (@ T_A = 25 °C)

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only. Functional operation of the device is not implied at these or any other conditions in excess of those given in the operational sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect device reliability.

Parameter	Symbol	Min	Typ	Max	Unit
dc Supply (V _{CC})	—	-0.5	—	7.0	V
Battery Supply (V _{BAT1})	—	—	—	-80	V
Battery Supply (V _{BAT2})	—	—	—	V _{BAT1}	V
Logic Input Voltage	—	-0.5	—	V _{CC} + 0.5	V
Logic Output Voltage	—	-0.5	—	V _{CC} + 0.5	V
Operating Temperature Range	—	-40	—	125	°C
Storage Temperature Range	—	-40	—	150	°C
Relative Humidity Range	—	5	—	95	%
PT or PR Fault Voltage (dc)	V _P T, V _P R	V _{BAT} - 5	—	3	V
PT or PR Fault Voltage (10 x 1000 μs)	V _P T, V _P R	V _{BAT} - 15	—	15	V
Ground Potential Difference (BGND to AGND)	—	—	—	±1	V

Note: The IC can be damaged unless all ground connections are applied before, and removed after, all other connections. Furthermore, when powering the device, the user must guarantee that no external potential creates a voltage on any pin of the device that exceeds the device ratings. For example, inductance in a supply lead could resonate with the supply filter capacitor to cause a destructive overvoltage.

Table 4. Recommended Operating Characteristics

Parameter	Min	Typ	Max	Unit
5 V dc Supplies (V _{CC})	—	5.0	5.25	V
3 V dc Supplies (V _{CC})	3.13	3.3	—	V
High Office Battery Supply (V _{BAT1})	-60	-70	-75	V
Auxiliary Office Battery Supply (V _{BAT2})	-12	—	V _{BAT1}	V
Operating Temperature Range	-40	25	85	°C

Table 5. Thermal Characteristics

Parameter	Min	Typ	Max	Unit
Thermal Protection Shutdown (T _{Jc}) ¹	150	165	—	°C
28-pin PLCC Thermal Resistance Junction to Ambient (θ _{JA}) ² :				
Natural Convection 2S2P Board	—	35.5	—	°C/W
Natural Convection 2S0P Board	—	50.5	—	°C/W
Wind Tunnel 100 Linear Feet per Minute (LFPM) 2S2P Board	—	31.5	—	°C/W
Wind Tunnel 100 Linear Feet per Minute (LFPM) 2S0P Board	—	42.5	—	°C/W
48-pin MLCC Thermal Resistance Junction to Ambient (θ _{JA}) ^{1, 2}	—	38	—	°C/W

1. This parameter is not tested in production. It is guaranteed by design and device characterization.

2. Airflow, PCB board layers, and other factors can greatly affect this parameter.

Electrical Characteristics

Table 6. Environmental Characteristics

Parameter	Min	Typ	Max	Unit
Temperature Range	-40	—	85	°C
Humidity Range ¹	5	—	95 ¹	%RH

1. Not to exceed 26 grams of water per kilogram of dry air.

Table 7. 5 V Supply Currents

$V_{BAT1} = -70\text{ V}$, $V_{BAT2} = -21\text{ V}$, $V_{CC} = 5\text{ V}$.

Parameter	Min	Typ	Max	Unit
Supply Currents (scan state; no loop current):				
I _{VCC}	—	4.30	4.80	mA
I _{VBAT1}	—	0.24	0.35	mA
I _{VBAT2}	—	3	6	μA
Supply Currents (forward/reverse active; no loop current, with or without PPM, V _{BAT2} applied):				
I _{VCC}	—	5.95	7.0	mA
I _{VBAT1}	—	25	85	μA
I _{VBAT2}	—	1.2	1.40	mA
Supply Currents (on-hook transmission mode; no loop current, with or without PPM, V _{BAT1} applied):				
I _{VCC}	—	6.0	7.0	mA
I _{VBAT1}	—	1.5	1.9	mA
I _{VBAT2}	—	1.5	6	μA
Supply Currents (disconnect mode):				
I _{VCC}	—	2.7	3.75	mA
I _{VBAT1}	—	15	110	μA
I _{VBAT2}	—	3.5	25	μA
Supply Currents (ground start mode, no loop current):				
I _{VCC}	—	4.0	—	mA
I _{VBAT1}	—	0.24	—	mA
I _{VBAT2}	—	2	—	μA
Supply Currents (ring mode; no load):				
I _{VCC}	—	5.9	6.5	mA
I _{VBAT1}	—	1.8	2.2	mA
I _{VBAT2}	—	2	6	μA

Table 8. 5 V Powering

$V_{BAT1} = -70\text{ V}$, $V_{BAT2} = -21\text{ V}$, $V_{CC} = 5\text{ V}$.

Parameter	Min	Typ	Max	Unit
Power Dissipation (scan state; no loop current)	—	38	46	mW
Power Dissipation (forward/reverse active; no loop current, V _{BAT2} applied)	—	57	64	mW
Power Dissipation (on-hook transmission mode; no loop current, V _{BAT1} applied)	—	135	165	mW
Power Dissipation (disconnect mode)	—	14	23	mW
Power Dissipation (ground start mode)	—	37	—	mW
Power Dissipation (ring mode; no load)	—	156	184	mW

Electrical Characteristics (continued)

Table 9. 3.3 V Supply currents

$V_{BAT1} = -70\text{ V}$, $V_{BAT2} = -21\text{ V}$, $V_{CC} = 3.3\text{ V}$.

Parameter	Min	Typ	Max	Unit
Supply Currents (scan state; no loop current):				
I _{VCC}	—	3.2	3.6	mA
I _{VBAT1}	—	0.24	0.35	mA
I _{VBAT2}	—	3	6	μA
Supply Currents (forward/reverse active; no loop current, V _{BAT2} applied):				
I _{VCC}	—	4.8	5.7	mA
I _{VBAT1}	—	25	85	μA
I _{VBAT2}	—	1.2	1.4	mA
Supply Currents (on-hook transmission mode; no loop current, V _{BAT1} applied):				
I _{VCC}	—	4.9	5.7	mA
I _{VBAT1}	—	1.5	1.9	mA
I _{VBAT2}	—	1.5	6	μA
Supply Currents (disconnect mode):				
I _{VCC}	—	1.8	2.5	mA
I _{VBAT1}	—	8	110	μA
I _{VBAT2}	—	2	25	μA
Supply Currents (ground start mode, no loop current):				
I _{VCC}	—	3.1	—	mA
I _{VBAT1}	—	0.24	—	mA
I _{VBAT2}	—	2	—	μA
Supply Currents (ring mode; no load):				
I _{VCC}	—	4.70	5.4	mA
I _{VBAT1}	—	1.8	2.2	mA
I _{VBAT2}	—	2	6	μA

Table 10. 3.3 V Powering

$V_{BAT1} = -70\text{ V}$, $V_{BAT2} = -21\text{ V}$, $V_{CC} = 3.3\text{ V}$.

Parameter	Min	Typ	Max	Unit
Power Dissipation (scan state; no loop current)	—	27	36.5	mW
Power Dissipation (forward/reverse active; no loop current, V _{BAT2} applied)	—	42	53	mW
Power Dissipation (on-hook transmission mode; no loop current, V _{BAT1} applied)	—	121	151	mW
Power Dissipation (disconnect mode)	—	6.5	15	mW
Power Dissipation (ground start mode)	—	27	—	mW
Power Dissipation (ring mode; no loop current)	—	141	172	mW

Electrical Characteristics (continued)

Table 11. 2-Wire Port

Parameter	Min	Typ	Max	Unit
Tip or Ring Drive Current = dc + Longitudinal + Signal Currents	105	—	—	mA _p
Tip or Ring Drive Current = Ringing + Longitudinal	65	—	—	mA _p
Signal Current	10	—	—	mA _{rms}
Longitudinal Current Capability per Wire (Longitudinal current is independent of dc loop current.)	8.5	15	—	mA _{rms}
Ringing Current (R _{LOAD} = 1386 Ω + 40 μF)	29	—	—	mA _{rms}
Ringing Current Limit (R _{LOAD} = 100 Ω)	—	—	50	mA _p
dc Loop Current—I _{LIM} (V _{BAT2} applied, R _{LOOP} = 100 Ω):				
V _{PROG} = 0	—	25	—	mA
V _{PROG} = Open	—	40	—	mA
dc Current Variation	—	—	±8	%
dc Feed Resistance (does not include protection resistors)	—	50	—	Ω
Open Loop Voltages:				
Scan Mode:				
V _{BAT1} > 51 V V _{TIP} – V _{RING}	44	51	—	V
PR to Battery Ground	—	—	56.5	V
PT to Battery Ground	—	—	56.5	V
OHT Mode:				
V _{BAT1} > 51 V V _{TIP} – V _{RING}	41	49	—	V
PR to Battery Ground	—	—	56.5	V
PT to Battery Ground	—	—	56.5	V
Active Mode:				
PT – PR – V _{BAT2}	5.75	6.25	6.75	V
Ring Mode:				
PT – PR – V _{BAT1}	—	4	—	V

Electrical Characteristics (continued)

Table 11. 2-Wire Port (continued)

Parameter	Min	Typ	Max	Unit
Loop Closure Threshold: Active/On-hook Transmission Modes	—	10.5	—	mA
Scan Mode	—	11.5	—	mA
Loop Closure Threshold Hysteresis: V _{CC} = 5 V Active Mode	—	2	—	mA
V _{CC} = 3.3 V Active Mode	—	1	—	mA
V _{CC} = 5 V Ground Start Mode	—	6	—	mA
V _{CC} = 3.3 V Ground Start Mode	—	5	—	mA
Longitudinal to Metallic Balance at PT/PR Test Method: Q552 (11/96) Section 2.1.2 and <i>IEEE</i> [®] 455: 300 Hz to 600 Hz	52	—	—	dB
600 Hz to 3.4 kHz	52	—	—	dB
Metallic to Longitudinal (harm) Balance: 200 Hz to 1000 Hz	40	—	—	dB
100 Hz to 4000 Hz	40	—	—	dB
PSRR 500 Hz—3000 Hz: V _{BAT1} , V _{BAT2}	45	—	—	dB
V _{CC} (5 V operation)	35	—	—	dB

Table 12. Analog Pin Characteristics

Parameter	Min	Typ	Max	Unit
TXI (input impedance)	—	100	—	kΩ
Output Offset (VTX)	—	—	±10	mV
Output Offset (VITR)	—	—	100	mV
Output Drive Current (VTX)	±300	—	—	μA
Output Drive Current (VITR)	±10	—	—	μA
Output Voltage Swing: Maximum (VTX, VITR)	AGND	—	V _{CC}	V
Minimum (VTX)	AGND + 0.25	—	V _{CC} - 0.5	V
Minimum (VITR)	AGND + 0.35	—	V _{CC} - 0.4	V
Output Short-circuit Current	—	—	±50	mA
Output Load Resistance	10	—	—	kΩ
Output Load Capacitance	—	20	—	pF
RCVN and RCVP: Input Voltage Range (V _{CC} = 5 V)	0	—	V _{CC} - 0.5	V
Input Voltage Range (V _{CC} = 3.3 V)	0	—	V _{CC} - 0.3	V
Input Bias Current	—	0.05	—	μA
Differential PT/PR Current Sense (DCOUT): Gain (PT/PR to DCOUT)	—	67	—	V/A
Offset Voltage at I _{LOOP} = 0	-20	—	20	mV

Electrical Characteristics (continued)

Table 13. ac Feed Characteristics

Parameter	Min	Typ	Max	Unit
ac Termination Impedance ¹	150	600	1400	Ω
Total Harmonic Distortion (200 Hz—4 kHz) ² :				
Off-hook	—	—	0.3	%
On-hook	—	—	1.0	%
Transmit Gain (f = 1004 Hz, 1020 Hz, current limit) ³ : PT/PR Current to VITR	300 – 3%	300	300 + 3%	V/A
Receive Gain, f = 1004 Hz, 1020 Hz Open Loop:				
RCVP or RCVN to PT—PR (gain of 8 option, L9216A)	7.76	8	8.24	—
RCVP or RCVN to PT—PR (gain of 2 option, L9216G)	1.94	2	2.06	—
Gain vs. Frequency (transmit and receive) ² 600 Ω Termination, 1004 Hz, 1020 Hz Reference:				
200 Hz—300 Hz	–0.3	0	0.05	dB
300 Hz—3.4 kHz	–0.05	0	0.05	dB
3.4 kHz—20 kHz	–3.0	0	0.05	dB
20 kHz—266 kHz	—	—	2.0	dB
Gain vs. Level (transmit and receive) ² 0 dBV Reference: –55 dB to +3.0 dB	–0.05	0	0.05	dB
Idle-channel Noise (tip/ring) 600 Ω Termination:				
Psophometric	—	–82	–77	dBmp
C-Message	—	8	13	dBrnC
3 kHz Flat	—	—	20	dBrn
Idle-channel Noise (VTX) 600 Ω Termination:				
Psophometric	—	–82	–77	dBmp
C-Message	—	8	13	dBrnC
3 kHz Flat	—	—	20	dBrn

1. Set externally either by discrete external components or a third- or fourth-generation codec. Any complex impedance $R1 + R2 \parallel C$ between 150 Ω and 1400 Ω can be synthesized.
2. This parameter is not tested in production. It is guaranteed by design and device characterization.
3. VITR transconductance depends on the resistor from ITR to VTX. This gain assumes an ideal 4750 Ω, the recommended value. Positive current is defined as the differential current flowing from PT to PR.

Electrical Characteristics (continued)

Table 14. Logic Inputs and Outputs (V_{CC} = 5 V)

Parameter	Symbol	Min	Typ	Max	Unit
Input Voltages:					
Low Level	V _{IL}	-0.5	0.4	0.7	V
High Level	V _{IH}	2.0	2.4	V _{CC}	V
Input Current:					
Low Level (V _{CC} = 5.25 V, V _I = 0.4 V)	I _{IL}	—	—	±50	μA
High Level (V _{CC} = 5.25 V, V _I = 2.4 V)	I _{IH}	—	—	±50	μA
Output Voltages (open collector with internal pull-up resistor):					
Low Level (V _{CC} = 4.75 V, I _{OL} = 200 μA)	V _{OL}	0	0.2	0.4	V
High Level (V _{CC} = 4.75 V, I _{OH} = -20 μA)	V _{OH}	2.4	—	V _{CC}	V

Table 15. Logic Inputs and Outputs (V_{CC} = 3.3 V)

Parameter	Symbol	Min	Typ	Max	Unit
Input Voltages:					
Low Level	V _{IL}	-0.5	0.2	0.5	V
High Level	V _{IH}	2.0	2.5	V _{CC}	V
Input Current:					
Low Level (V _{CC} = 3.46 V, V _I = 0.4 V)	I _{IL}	—	—	±50	μA
High Level (V _{CC} = 3.46 V, V _I = 2.4 V)	I _{IH}	—	—	±50	μA
Output Voltages (open collector with internal 60 kΩ pull-up resistor):					
Low Level (V _{CC} = 3.13 V, I _{OL} = 200 μA)	V _{OL}	0	0.2	0.5	V
High Level (V _{CC} = 3.13 V, I _{OH} = -5 μA)	V _{OH}	2.2	—	V _{CC}	V

Table 16. Ground Start

Parameter	Min	Typ	Max	Unit
Tip Open Mode:				
Tip Input Impedance	150	—	—	kΩ
Detector Accuracy	—	—	20	%
Detection	50	—	—	ms

Electrical Characteristics (continued)

Table 17. Ringing Specifications

Parameter	Min	Typ	Max	Unit
RING _{IN} (This input is ac coupled through 0.47 μF.): Input Voltage Swing	0	—	V _{CC}	V
Input Impedance	—	100	—	kΩ
Ring Signal Isolation: PT/PR to VITR Ring Mode	—	60	—	dB
Ring Signal Isolation: RING _{IN} to PT/PR Nonring Mode	—	80	—	dB
Ringing Voltage (5 REN 1380 Ω + 40 μF load, 100 Ω loop, 2 x 50 Ω protection resistors, -70 V battery)	40	—	—	V _{rms}
Ringing Voltage (3 REN 2310 Ω + 24 μF load, 250 Ω loop, 2 x 50 Ω protection resistors, -70 V battery)	40	—	—	V _{rms}
Ring Signal Distortion: 5 REN 1380 Ω, 40 μF Load, 100 Ω Loop	—	3	—	%
3 REN 2310 Ω, 24 μF Load, 250 Ω Loop	—	3	—	%
Differential Gain: RING _{IN} to PT/PR—No Load	—	55	—	—

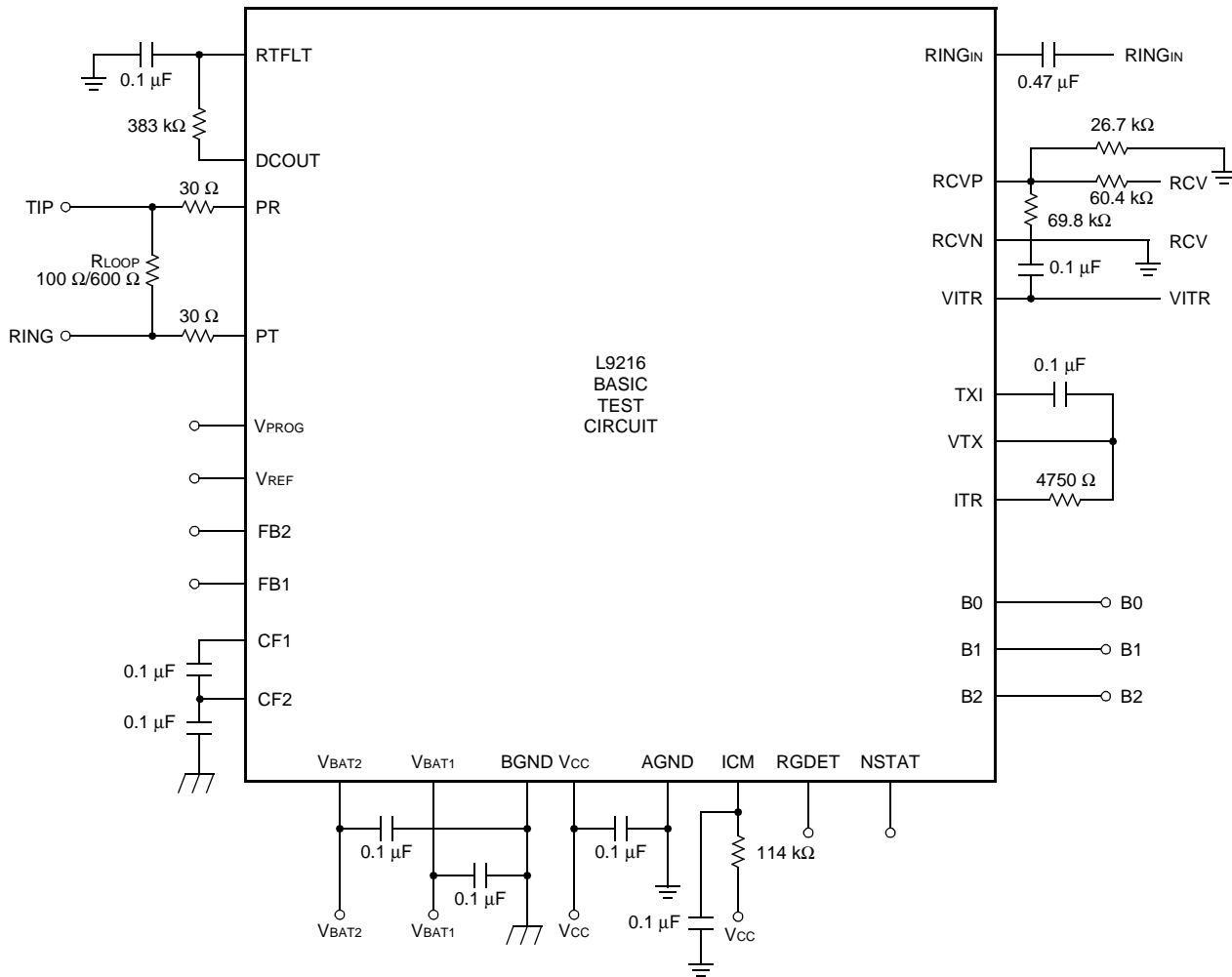
Table 18. Ring Trip

Parameter	Min	Typ	Max	Unit
Ring Trip (NSTAT = 0): Loop Resistance (total) High Battery	100	—	600	Ω
Ring Trip (NSTAT = 1): Loop Resistance (total) High Battery	—	—	10	kΩ
Trip Time (f = 20 Hz)	—	—	100	ms

Ringing will not be tripped by the following loads:

- 10 kΩ resistor in parallel with a 6 μF capacitor applied across tip and ring. Ring frequency = 17 Hz to 23 Hz.
- 100 Ω resistor in series with a 2 μF capacitor applied across tip and ring. Ring frequency = 17 Hz to 23 Hz.

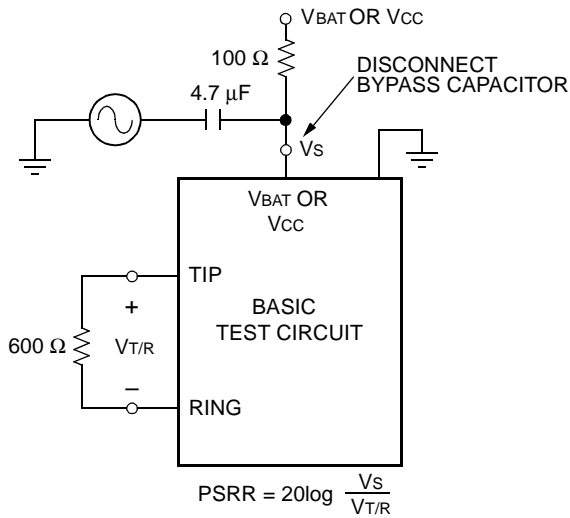
Test Configurations



12-3531.h (F)

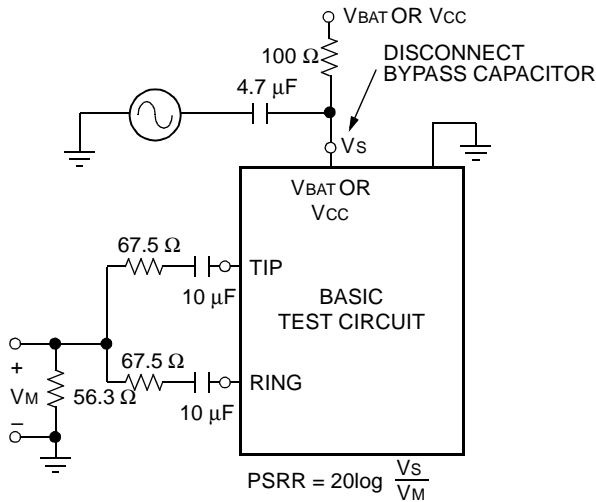
Figure 4. Basic Test Circuit

Test Configurations (continued)



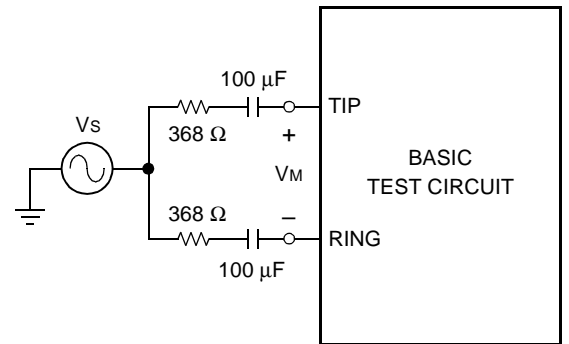
12-2582.c (F)

Figure 5. Metallic PSRR



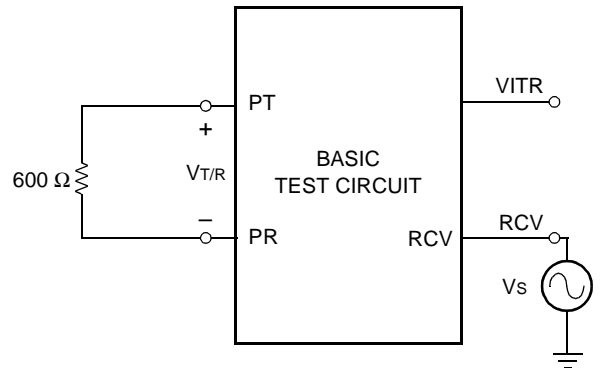
12-2583.b (F)

Figure 6. Longitudinal PSRR



12-2584.c (F)

Figure 7. Longitudinal Balance



12-2587.G (F)

Figure 8. ac Gains

Applications

Power Control

Under normal device operating conditions, power dissipation on the device must be controlled to prevent the device temperature from rising above the thermal shutdown and causing the device to shut down. Power dissipation is highest with higher battery voltages, higher current limit, and under shorter dc loop conditions. Additionally, higher ambient temperature will also reduce thermal margin.

To support required power ringing voltages, this device is meant to operate with a high-voltage primary battery (–65 V to –75 V typically). Thus, power control is normally achieved by use of the battery switch and an auxiliary lower absolute voltage battery. Operating temperature range, maximum current limit, maximum battery voltage, minimum dc loop length and protection resistor values, airflow, and number of PC board layers will influence the overall thermal performance. The following example illustrates typical thermal design considerations.

The thermal resistance of the 28-pin PLCC package is typically 35.5 °C/W, which is representative of the natural airflow as seen in a typical switch cabinet with a multilayer board.

The L9216 will enter thermal shutdown at a temperature of 150 °C. The thermal design should ensure that the SLIC does not reach this temperature under normal operating conditions.

For this example, assume a maximum ambient operating temperature of 85 °C, a maximum current limit of 30 mA, a maximum battery of –75 V, and an auxiliary battery of –21 V. Assume a (worst-case) minimum dc loop of 20 Ω of wire resistance, 30 Ω protection resistors, and 200 Ω for the handset. Additionally, include the effects of parameter tolerance.

1. $T_{TSD} - T_{AMBIENT(max)} =$ allowed thermal rise.
 $150\text{ °C} - 85\text{ °C} = 65\text{ °C}.$
2. Allowed thermal rise = package thermal impedance • SLIC power dissipation.
 $65\text{ °C} = 35.5\text{ °C/W} \bullet \text{SLIC power dissipation}$
SLIC power dissipation (P_D) = 1.83 W.

Thus, if the total power dissipated in the SLIC is less than 1.83 W, it will not enter the thermal shutdown state. Total SLIC power is calculated as:

$$\text{Total } P_D = \text{maximum battery} \bullet \text{maximum current limit} + \text{SLIC quiescent power.}$$

For the L9216, the worst-case SLIC on-hook active power is 75 mW. Thus,

$$\begin{aligned} \text{Total off-hook power} &= (I_{LOOP})(\text{current-limit tolerance}) \bullet (V_{BATAPPLIED}) + \text{SLIC on-hook power} \\ \text{Total off-hook power} &= (0.030\text{ A})(1.08) \bullet (21) + 75\text{ mW} \\ \text{Total off-hook power} &= 755.4\text{ mW} \end{aligned}$$

The power dissipated in the SLIC is the total power dissipation less the power that is dissipated in the loop.

$$\begin{aligned} \text{SLIC } P_D &= \text{total power} - \text{loop power} \\ \text{Loop off-hook power} &= (I_{LOOP} \bullet 1.08)^2 \bullet (R_{LOOP(dc)} \text{ min} + 2R_{HANDSET}) \\ \text{Loop off-hook power} &= (0.030\text{ A})(1.08)^2 \bullet (20\ \Omega + 60\ \Omega + 200\ \Omega) \\ \text{Loop off-hook power} &= 293.9\text{ mW} \\ \text{SLIC off-hook power} &= \text{Total off-hook power} - \text{loop off-hook power} \\ \text{SLIC off-hook power} &= 755.4\text{ mW} - 293.9\text{ mW} \\ \text{SLIC off-hook power} &= 461.5\text{ mW} < 1.83\text{ W} \end{aligned}$$

Thus, under the operating conditions of this example, the thermal design, using the auxiliary, is adequate to ensure the device is not driven into thermal shutdown under worst-case operating conditions.

Applications (continued)

dc Loop Current Limit

Current limit may be chosen from two discrete values, 25 mA or 40 mA, depending on if V_{PROG} is grounded (25 mA) or left floating (40 mA). Note that there is a 12.5 kΩ slope to the I/V characteristic in the current-limit region; thus, once in current limit, the actual loop current will increase slightly, as loop length decreases.

The above describes the active mode steady-state current-limit response. There will be a transient response of the current-limit circuit upon an on- to off-hook transition. Typical active mode transient current-limit response is given in Table 19.

Table 19. Typical Active Mode On- to Off-Hook Tip/Ring Current-Limit Transient Response

Parameter	Value	Unit
dc Loop Current: Active Mode R _{LOOP} = 100 Ω On- to Off-hook Transition t < 5 ms	I _{LIM} + 60	mA
dc Loop Current: Active Mode R _{LOOP} = 100 Ω On- to Off-hook Transition t < 50 ms	I _{LIM} + 20	mA
dc Loop Current: Active Mode R _{LOOP} = 100 Ω On- to Off-hook Transition t < 300 ms	I _{LIM}	mA

Overhead Voltage

Active Mode

Overhead is fixed to a nominal 6.0 V, which is adequate for on-hook transmission of 3.14 dBm into 900 Ω.

Scan Mode

If the magnitude of the primary battery is greater than 51 V, the magnitude of the open loop tip-to-ring open loop voltage is clamped typically between 44 V and 51 V. If the magnitude of the primary battery is less than a nominal 51 V, the overhead voltage will track the magnitude of the battery voltage, i.e., the magnitude of the open circuit tip-to-ring voltage will be 4 V to 6 V less than battery. In the scan mode, overhead is unaffected by V_{OVH}.

On Hook Transmission Mode

If the magnitude of the primary battery is greater than 51 V, the magnitude of the open loop tip-to-ring open loop voltage is clamped typically between 41 V and 49 V. If the magnitude of the primary battery is less than a nominal 51 V, the overhead voltage will track the magnitude of the battery voltage, i.e., the magnitude of the open circuit tip-to-ring voltage will be 6 V to 8 V less than battery. In the scan mode, overhead is unaffected by V_{OVH}.

Applications (continued)

Overhead Voltage (continued)

Ring Mode

In the ring mode, to maximize ringing loop length, the overhead is decreased to the saturation of the tip ring drive amplifiers, a nominal 4 V. The tip to ground voltage is 1 V, and the ring to V_{BAT1} voltage is 3 V.

During the ring mode, to conserve power, the receive input at RCVN/RCVP is deactivated. During the ring mode, to conserve power, the AAC amplifier in the transmit direction at VTR is deactivated. However, if the AX amplifier at VTX is active during the ring mode, differential ring current may be sensed at VTX during the ring mode.

Loop Range

The dc loop range is calculated using:

$$R_L = \frac{|V_{BAT2}| - V_{OH}}{I_{LIMIT}} - 2R_P - R_{DC}$$

V_{BAT2} is typically applied under off-hook conditions for power conservation and SLIC thermal considerations. The L9216 is intended for short-loop applications and, therefore, will always be in current limit during off-hook conditions. However, note that the ringing loop length rather than the dc loop length, will be the factor to determine operating loop length.

Battery Reversal Rate

The rate of battery reverse is controlled or ramped by capacitors FB1 and FB2. Table 20 below shows FB1 and FB2 values vs. typical ramp time. Leave FB1 and FB2 open if it is not desired to ramp the rate of battery reversal.

Table 20. FB1 and FB2 Values vs. Typical Ramp Time

C _{FB1} and C _{FB2}	Transition Time
0.01 μF	20 ms
0.1 μF	220 ms
0.22 μF	440 ms
0.47 μF	900 ms
1.0 μF	1.8 s
1.22 μF	2.25 s
1.3 μF	2.5 s
1.4 μF	2.7 s
1.6 μF	3.2 s

Supervision

The L9216 offers the loop closure and ring trip supervision functions. Internal to the device, the outputs of these detectors are multiplexed into a single package output, NSTAT. Additionally, a common-mode current detector for tip or ring ground detection is included for ground key applications.

Loop Closure

The loop closure has a fixed typical 10.5 mA on- to off-hook threshold in the active mode and a fixed 11.5 mA on- to off-hook threshold from the scan mode. In either case, there is a 2 mA hysteresis with V_{CC} = 5 V and a 1 mA hysteresis with V_{CC} = 3.3 V.

Ring Trip

The ring trip detector requires only a single-pole filter at the input, minimizing external components. An R/C combination of 383 kΩ and 0.1 μF, for a filter pole at 5.15 Hz, is recommended.

The ring trip threshold is internally fixed as a function of battery voltage and is given by:

$$RT \text{ (mA)} = 67 * \{(0.0045 * V_{BAT1}) + 0.317\}$$

where:

RT is ring trip current in mA.

V_{BAT1} is the magnitude of the ring battery in V.

There is a 6 mA to 8 mA hysteresis.

Tip or Ring Ground Detector

In the ground key or ground start applications, a common-mode current detector is used to indicate either a tip- or ring-ground has occurred (ground key) or an off-hook has occurred (ground start).

For ground start applications detection may be seen at the output of the common mode current detector (RGDET) or the loop closure detector (NSTAT).

If ICM is used, the detection threshold is set by connecting a resistor from ICM to V_{CC}.

$$205 \times V_{CC}/R_{ICM} \text{ (k}\Omega\text{)} = I_{TH} \text{ (mA)}$$

Additionally, a filter capacitor across R_{ICM} will set the time constant of the detector. No hysteresis is associated with this detector. The RC filter at ICM gives immunity to longitudinal currents.

Supervision (continued)

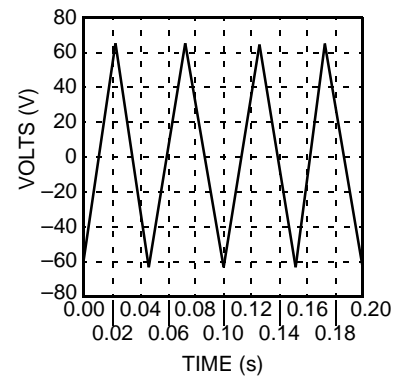
Tip or Ring Ground Detector (continued)

Also in the ground start mode, the fixed loop current threshold associated with the NSTAT detector output is internally adjusted to account for common-mode current detection in ground start mode (as opposed to differential current in loop start mode) maintain the detector at 10 mA. Thus, NSTAT may also be used for loop closure detection in ground start. However, the detector at NSTAT is not filtered against longitudinal currents, which may or may not be an issue in short loop applications. Using NSTAT will also save components at ICM.

Power Ring

The device offers a ring mode, in which a balanced power ring signal is provided to the tip/ring pair. During the ring mode, a user-supplied low-voltage ring signal is input to the device's RING_{IN} input. This signal is amplified to produce the balanced power ring signal. The user may supply a sine wave input, PWM input, or a square wave to produce sinusoidal or trapezoidal ringing at tip and ring.

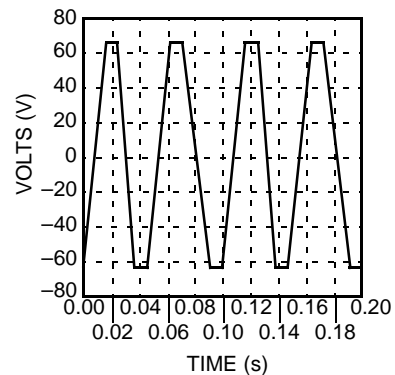
Various crest factors are shown for illustrative purposes.



12-3346a (F)

Note: Slew rate = 5.65 V/ms; trise = tfall = 23 ms; pwidth = 2 ms; period = 50 ms.

Figure 9. Ringing Waveform Crest Factor = 1.6



12-3347a (F)

Note: Slew rate = 10.83 V/ms; trise = tfall = 12 ms; pwidth = 13 ms; period = 50 ms.

Figure 10. Ringing Waveform Crest Factor = 1.2

Voltage applied to the load may be increased by using a filtered square wave input to produce a lower crest factor trapezoidal power ring signal at tip and ring.

Supervision (continued)

Power Ring (continued)

Sine Wave Input Signal and Sine Wave Power Ring Signal Output

The low-voltage sine wave input is applied to the L9216 at pin RING_{IN}. This signal should be ac-coupled through 0.47 μF. During the ring mode, the signal at RING_{IN} is amplified and presented to the subscriber loop. The differential gain from RING_{IN} to tip and ring is a nominal 55.

When the device enters the ring mode, the tip/ring overhead set at OVH and the scan clamp circuit is disabled, allowing the voltage magnitude of the power ring signal to be maximized. Additionally, in the ring mode, the loop current limit is increased 2.5X the value set by the V_{PROG} voltage.

The magnitude of the power ring voltage will be a function of the gain of the ring amplifier, the high voltage battery, and the input signal at RING_{IN}. The input range of the signal at RING_{IN} is 0 V to V_{CC}. As the input voltage at RING_{IN} is increased, the magnitude of the power ring voltage at tip and ring will increase linearly, per the differential gain of 55, until the tip and ring drive amplifiers begin to saturate. Once the tip and ring amplifiers reach saturation, further increases of the input signal will cause clipping distortion of the power ring signal at tip and ring. The ring signal will appear balanced on tip and ring. That is, the power ring signal is applied to both tip and ring, with the signal on tip 180° (180 degrees) out of phase from the signal on ring.

Figure 11 shows typical operation of the ring mode, prior to saturation of the tip and ring drive amplifiers. A -70 V battery is used with a 100 Ω loop and a 1 REN load. The input signal is 1 V through a 0.47 μF capacitor at RING_{IN}, (the input circuit is shown in Figure 12). This produces a voltage swing from -34 V to -60 V

on ring and from -8 V to -34 V on tip, as shown in Figure 11. Thus, the total voltage swing is 52 V (60 V to 8 V) for a 1 V input, which is approximately the differential gain of the device. Note that the tip and ring power ring signals will swing around V_{BATTERY} divided by two. In this case, there is a -70 V battery so tip and ring swing around -34 V.

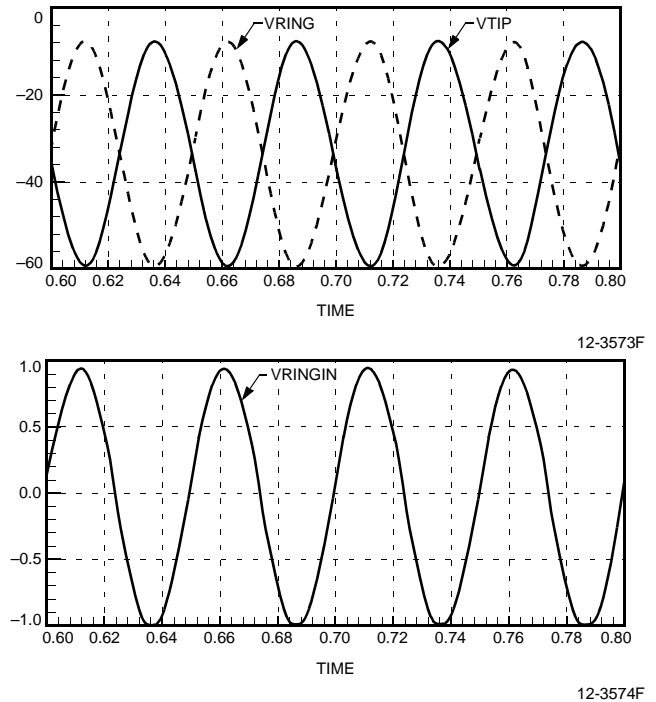


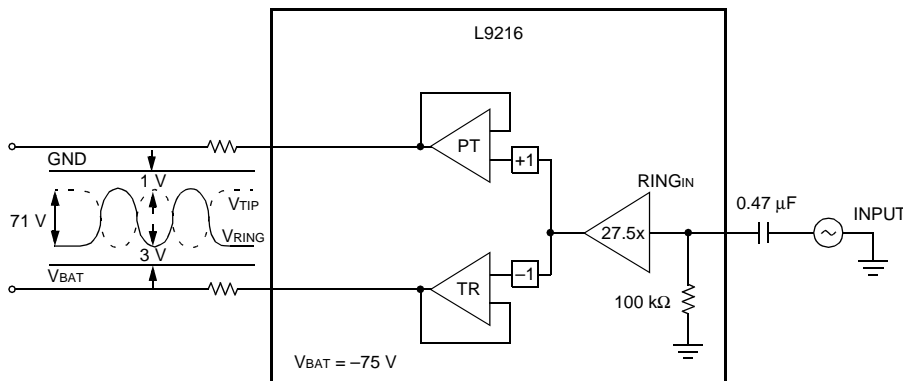
Figure 11. Ring Mode Typical Operation

Supervision (continued)

Power Ring (continued)

Sine Wave Input Signal and Sine Wave Power Ring Signal Output (continued)

It is recommended that the input level at RING_{IN} be adjusted so that the power ring signal at tip and ring is just at the edge or slightly clipping. This gives maximum power transfer with minimal distortion of the sine wave. The tip side will saturate at a nominal 1 V above ground. The ring side will saturate at a nominal 3 V above battery. The input circuit for a sine wave along with waveforms to illustrate the tip and ring saturation is shown in Figure 12.



12-3532J

Figure 12. RING_{IN} Operation

The point at which clipping of the power ring signal begins at tip and ring is a function of the battery voltage, the input capacitor at RING_{IN}, and the input signal at RING_{IN} and V_{cc}. Typical characteristic conditions showing the onset of clipping are given below.

Table 21. Onset of Power Ringing Clipping V_{cc} = 5 V, C_{input} = 0.47 μF

Input		T/R	
V _{BAT1} (V)	V _{rms} (mV)	V _{rms} (V)	Gain
-70.15	891	46.88	52.62
-68.06	858	45.11	52.58
-66.00	833	43.69	52.45
-64.08	814	42.57	52.30
-62.04	789	41.21	52.23
-60.05	747	39.11	52.36

Table 22. Onset of Power Ringing Clipping V_{cc} = 3.1 V, C_{input} = 0.47 μF

Input		T/R	
V _{BAT1} (V)	V _{rms} (mV)	V _{rms} (V)	Gain
-70.12	894	47.15	52.74
-68.07	855	45.11	52.76
-66.06	824	43.38	52.65
-64.01	799	41.95	52.5
-62.00	780	40.79	52.29
-60.00	749	39.09	52.19

Supervision (continued)

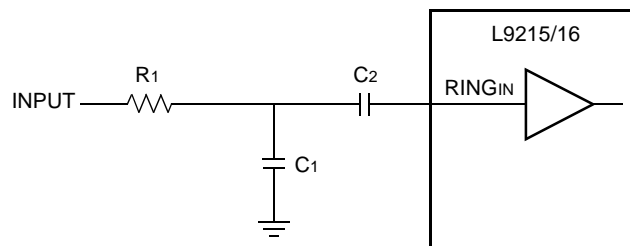
Power Ring (continued)

Sine Wave Input Signal and Sine Wave Power Ring Signal Output (continued)

During nonringing modes, the sinusoidal ringing waveform may be left on at RING_{IN}. Via the state table, the ring signal will be removed from tip and ring even if the low-voltage input is still present at RING_{IN}. There are certain timing considerations that should be made with respect to state changes which are detailed in the *Switching Behavior of L9215/6 Ringing SLIC* Application Note.

PWM Input Signal and Sine Wave Power Ring Signal Output

A pulse-width modulated (PWM) signal may be used to provide the ringing input to RING_{IN}. The signal is applied through a low-pass filter and ac-coupled into RING_{IN} as shown in Figure 13 below. This approach gives a sine wave output at tip and ring.



12-3578bF

Figure 13. L9215/16 Ringing Input Circuit Selection Table for Square Wave and PWM Inputs

Table 23. Signal and Component Selection Chart

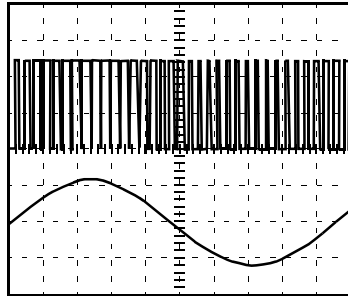
V _{BAT}	V _{CC}	Input	R1	C1	C2	CF	Typical 5 REN Ringing Voltage RMS
70 V	5 V	5 V Square	12 kΩ	1 μF	0.47 μF	1.3	48 V
70 V	3 V	3 V Square	7 kΩ	1 μF	0.47 μF	1.3	49 V
70 V	5 V	10 kHz PWM 5 V	10 kΩ	0.22 μF	0.47 μF	sine	42 V
70 V	3 V	10 kHz PWM 3 V	10 kΩ	0.22 μF	0.47 μF	sine	42 V
70 V	5 V	90 kHz PWM 5 V	7 kΩ	0.1 μF	0.47 μF	sine	42 V
70 V	3 V	90 kHz PWM 3 V	7 kΩ	0.1 μF	0.47 μF	sine	42 V
85 V	5 V	5 V Square	10 kΩ	1 μF	0.47 μF	1.3	59 V
85 V	3 V	3 V Square	7 kΩ	1 μF	0.47 μF	1.3	51 V
85 V	5 V	10 kHz PWM 5 V	10 kΩ	0.22 μF	0.47 μF	sine	51 V
85 V	3 V	10 kHz PWM 3 V	4 kΩ	0.22 μF	0.47 μF	sine	47 V
85 V	5 V	90 kHz PWM 5 V	4 kΩ	0.1 μF	0.47 μF	sine	51 V
85 V	3 V	90 kHz PWM 3 V	4 kΩ	0.1 μF	0.47 μF	sine	49 V

Supervision (continued)

Power Ring (continued)

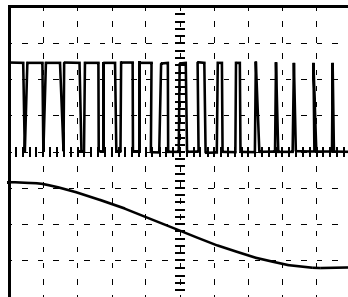
PWM Input Signal and Sine Wave Power Ring Signal Output (continued)

Modulation waveforms showing PWM are in Figure 14 below.



12-3381(F)

**A. Upper = Pwm Signal Centered at 10 kHz
Lower = Modulation Signal**



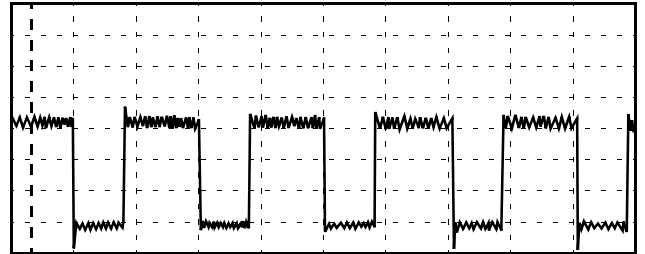
12-3380(F)

B. Same as A but Expanded

Figure 14. Modulation Waveforms

5 V V_{CC} Operation

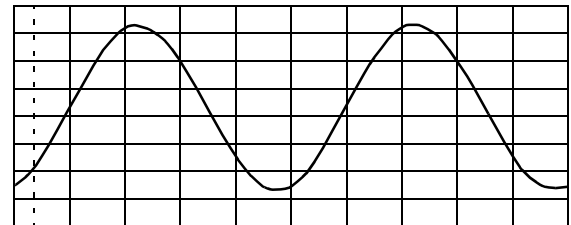
A PWM signal was generated with an *HP*TM 8116 Function Generator modulated with a 20 Hz signal. The optimal frequency used was 10 kHz. The PWM signal amplitude was 5.0 V (0 V to 5 V). This signal is shown in Figure 15.



12-3575F

Figure 15. 5 V PWM Signal Amplitude

This input produced 44.96 V_{rms} ringing signal on tip/ring under open-loop conditions and 42.0 V_{rms} was delivered to 5 REN load. The ringing output on ring, with V_{CC} = 5 V, is shown in Figure 16.



1660

Notes:

The modulating 20 Hz signal THD was measured at 1.3%.

The tip/ring 20 Hz signal THD was measured at 1%.

V_{BAT1} = -70.6 V, V_{BAT2} = -26.5 V, V_{CC} = 5.019 V.

PWM input 10 kHz, 5.0 V_{p-p}.

R₁ = 10 kΩ, C₁ = 0.22 μF, C₂ = 0.47 μF.

Figure 16. Ringing Output on RING, with V_{CC} = 5 V

Supervision (continued)

Power Ring (continued)

3.3 V Vcc Operation

A PWM signal was generated with an HP 8116 Function Generator modulated with a 20 Hz signal. The optimal frequency used was 10 kHz. The PWM signal amplitude was 3.10 V (0 V to 3.10 V). This input signal is shown in Figure 17.

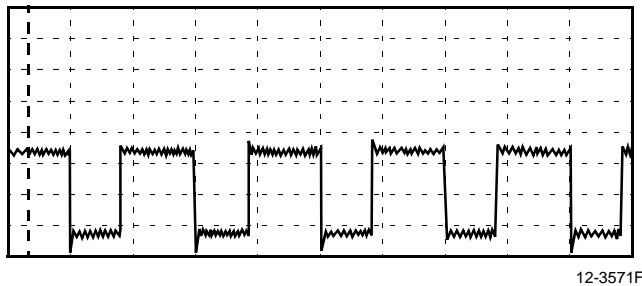
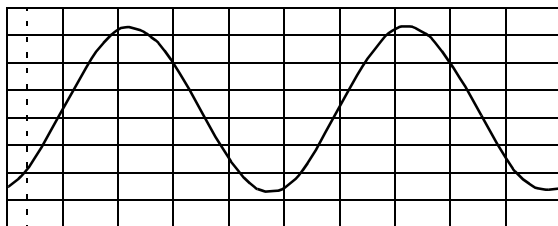


Figure 17. 3.3 V PWM Signal Amplitude

This produced 44.96 Vrms ringing signal on tip/ring under open-loop conditions and 42.0 Vrms was delivered to 5 REN load. The ringing output on ring with Vcc = 3.1 V is shown in Figure 18.



Notes:
The modulating 20 Hz signal THD was measured at 1.3%.
The tip/ring 20 Hz signal THD was measured at 1%.
VBAT1 = -70.6 V, VBAT2 = -26.5 V, VCC = 3.10 V.
PWM input 10 kHz, 3.1 Vp-p.
R1 = 10 kΩ, C1 = 0.22 μF, C2 = 0.47 μF.

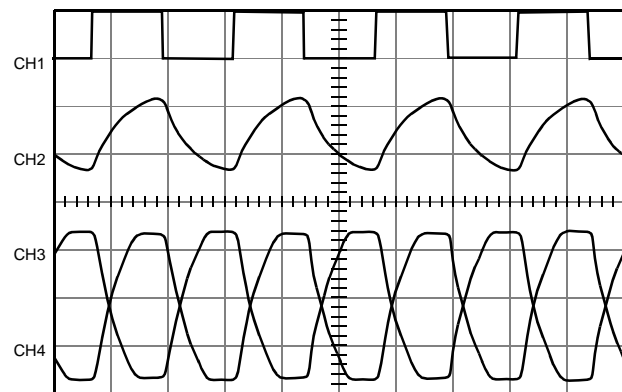
Figure 18. Ringing Output on RING, with Vcc = 3.1 V

During nonring modes, the PWM waveform may be left on at RINGIN. Via the state table, the ring signal will be removed from tip and ring even if the low-voltage input is still present at RINGIN. There are certain timing considerations that should be made with respect to state changes which are detailed in the *Switching Behavior of L9215/6 Ringing SLIC* Application Note.

Square Wave Input Signal and Trapezoidal Power Ring Signal Output

A low-voltage square wave signal may be used to provide the ringing input to RINGIN. The signal is applied through a low-pass filter and ac-coupled into RINGIN as shown in Figure 13 and Table 23. This approach gives a trapezoidal wave output at tip and ring.

Using this approach, a trapezoidal waveform can be achieved at tip and ring. This has the advantage of increasing the power transfer to the load for a given battery voltage, thus increasing the effective ringing loop length as compared to a sine wave. The actual crest factor achieved is a function of the magnitude of the battery, the magnitude of the input voltage, frequency, and R1.



Notes:
CH1—CMOS Input (5 V) at RINGIN.
CH2—Filtered input at RINGIN.
CH3—Tip.
CH4—Ring.
R1 = 14 kΩ, C1 = 1.0 μF, C2 = 0.47 μF.
VBAT1 = -70 V, Vrms = 51 V, Vp-p = 67 V, frequency = 20 Hz, Crest Factor = 1.3.

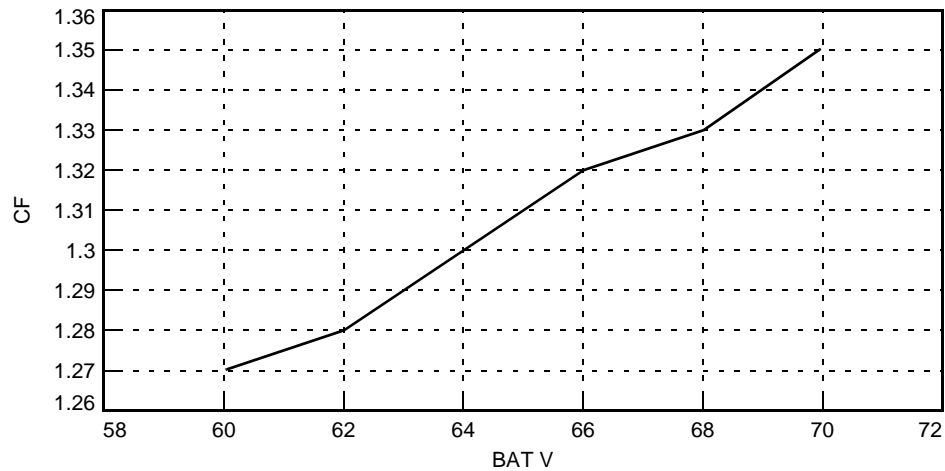
Figure 19. Square Wave Input Signal and Trapezoidal Power Ring Signal Output

Supervision (continued)

Power Ring (continued)

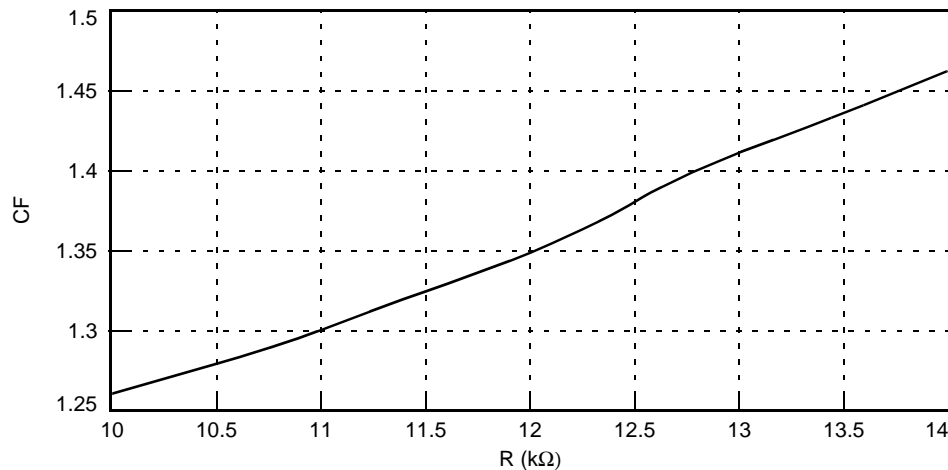
Square Wave Input Signal and Trapezoidal Power Ring Signal Output (continued)

Figure 20 and Figure 21 provide some guidance to the relationship between crest factor, battery voltage, and R₁ value.



12-3576F

Figure 20. Crest Factor vs. Battery Voltage



12-3577F

Figure 21. Crest Factor vs. R (kΩ)

During nonring modes, the square wave input may be left on or removed from RING_{IN}. Via the state table, the ring signal will be removed from tip and ring even if the low-voltage input is still present at RING_{IN}. However, removing the waveform has certain advantages in terms of the timing of state. These advantages are detailed in the *Switching Behavior of L9215/16 Ringing SLIC Application Note*.

ac Applications

ac Parameters

There are four key ac design parameters. **Termination impedance** is the impedance looking into the 2-wire port of the line card. It is set to match the impedance of the telephone loop in order to minimize echo return to the telephone set. **Transmit gain** is measured from the 2-wire port to the PCM highway, while **receive gain** is done from the PCM highway to the transmit port.

Transmit and receive gains may be specified in terms of an actual gain, or in terms of a transmission level point (TLP), that is the actual ac transmission level in dBm. Finally, the **hybrid balance** network cancels the unwanted amount of the receive signal that appears at the transmit port.

Codec Types

At this point in the design, the codec needs to be selected. The interface network between the SLIC and codec can then be designed. Below is a brief codec feature summary.

First-Generation Codecs

These perform the basic filtering, A/D (transmit), D/A (receive), and μ -law/A-law companding. They all have an op amp in front of the A/D converter for transmit gain setting and hybrid balance (cancellation at the summing node). Depending on the type, some have differential analog input stages, differential analog output stages, 5 V only or ± 5 V operation, and μ -law/A-law selectability. These are available in single and quad designs. This type of codec requires continuous time analog filtering via external resistor/capacitor networks to set the ac design parameters. An example of this type of codec is the Agere T7504 quad 5 V only codec.

This type of codec tends to be the most economical in terms of piece part price, but tends to require more external components than a third-generation codec. Further ac parameters are fixed by the external R/C network so software control of ac parameters is difficult.

Third-Generation Codecs

This class of devices includes all ac parameters set digitally under microprocessor control. Depending on the device, it may or may not have data control latches. Additional functionality sometimes offered includes tone plant generation and reception, PPM generation, test algorithms, and echo cancellation. Again, this type of codec may be 3.3 V, 5 V only, or ± 5 V operation, single quad or multichannel, and μ -law/A-law or 16-bit linear coding selectable. Examples of this type of codec are the Agere T8535/6 (5 V only, quad, standard features), T8537/8 (3.3 V only, quad, standard features), T8533/4 (5 V only, quad with echo cancellation), and the T8531/32 (5 V only multichannel).

ac Interface Network

The ac interface network between the L9216 and the codec will vary depending on the codec selected. With a first-generation codec, the interface between the L9216 and codec actually sets the ac parameters. With a third-generation codec, all ac parameters are set digitally, internal to the codec; thus, the interface between the L9216 and this type of codec is designed to avoid overload at the codec input in the transmit direction and to optimize signal to noise ratio (S/N) in the receive direction.

Because the design requirements are very different with a first- or third-generation codec, the L9216 is offered with two different receive gains. Each receive gain was chosen to optimize, in terms of external components required, the ac interface between the L9216 and codec.

ac Applications (continued)

ac Interface Network (continued)

With a first-generation codec, the termination impedance is set by providing gain shaping through a feedback network from the SLIC VITR output to the SLIC RCVN/RCVP inputs. The L9216 provides a transconductance from T/R to VITR in the transmit direction and a single-ended to differential gain from either RCVN or RCVP to T/R in the receive direction. Assuming a short from VITR to RCVN or RCVP, the maximum impedance that is seen looking into the SLIC is the product of the SLIC transconductance multiplied by the SLIC receive gain, plus the protection resistors. The various specified termination impedances can range over the voiceband as low as 300 Ω up to over 1000 Ω . Thus, if the SLIC gains are too low, it will be impossible to synthesize the higher termination impedances. Further, the termination that is achieved will be far less than what is calculated by assuming a short for SLIC output to SLIC input. In the receive direction, in order to control echo, the gain is typically a loss, which requires a loss network at the SLIC RCVN/RCVP inputs, which will reduce the amount of gain that is available for termination impedance. For this reason, a high-gain SLIC is required with a first-generation codec.

With a third-generation codec, the line card designer has different concerns. To design the ac interface, the designer must first decide upon all termination impedance, hybrid balances, and transmission level point (TLP) requirements that the line card must meet. In the transmit direction, the only concern is that the SLIC does not provide a signal that is too hot and overloads the codec input. Thus, for the highest TLP that is being designed to, given the SLIC gain, the designer, as a function of voiceband frequency, must ensure the codec is not overloaded. With a given TLP and a given SLIC gain, if the signal will cause a codec overload, the designer must insert some sort of loss, typically a resistor divider, between the SLIC output and codec input.

Note also that some third-generation codecs require the designer to provide an inherent resistive termination via external networks. The codec will then provide gain shaping, as a function of frequency, to meet the return loss requirements. This feedback will increase the signal at the codec input and increase the likelihood that a resistor divider is needed in the transmit direction. Further stability issues may add external components or excessive ground plane requirements to the design.

In the receive direction, the issue is to optimize the S/N. Again, the designer must consider all the considered TLPs. The idea, for all desired TLPs, is to run the codec at or as close as possible to its maximum output signal, to optimize the S/N. Remember, noise floor is constant, so the hotter the signal from the codec, the better the S/N. The problem is if the codec is feeding a high gain SLIC, either an external resistor divider is needed to knock the gain down to meet the TLP requirements, or the codec is not operated near maximum signal levels, thus compromising the S/N.

Thus, it appears that the solution is to have a SLIC with a low gain, especially in the receive direction. This will allow the codec to operate near its maximum output signal (to optimize S/N), without an external resistor divider (to minimize cost).

To meet the unique requirements of both types of codecs, the L9216 offers two receive gain choices. These receive gains are mask-programmable at the factory and are offered as two different code variations. For interface with a first-generation codec, the L9216 is offered with a receive gain of 8. For interface with a third-generation codec, the L9216 is offered with a receive gain of 2. In either case, the transconductance in the transmit direction or the transmit gain is 300 Ω .

These receive gain options afford the designer the flexibility to maximize performance and minimize external components, regardless of the type of codec chosen.

ac Applications (continued)

Design Examples

First-Generation Codec ac Interface Network— Resistive Termination

The reference circuit in Figure 23 shows the complete SLIC schematic for interface to the Agere T7504 first-generation codec for a resistive termination impedance. For this example, the ac interface was designed for a 600 Ω resistive termination and hybrid balance with transmit gain and receive gain set to 0 dBm.

This is a lower feature application example and uses single battery operation, fixed overhead, current limit, and loop closure threshold.

Resistor RGN is optional. It compensates for any mismatch of input bias voltage at the RCVN/RCVP inputs. If it is not used, there may be a slight offset at tip and ring due to mismatch of input bias voltage at the RCVN/RCVP inputs. It is very common to simply tie RCVN directly to ground in this particular mode of operation. If used, to calculate RGN, the impedance from RCVN to ac ground should equal the impedance from RCVP to ac ground.

Example 1, Real Termination

The following design equations refer to the circuit in Figure 22. Use these to synthesize real termination impedance.

Termination Impedance:

$$z_T = \frac{V_{T/R}}{-I_{T/R}}$$

$$z_T = 50 \Omega + 2R_P + \frac{2400}{1 + \frac{R_{T1}}{R_{GP}} + \frac{R_{T1}}{R_{RCV}}}$$

Receive Gain:

$$g_{rcv} = \frac{V_{T/R}}{V_{FR}}$$

$$g_{rcv} = \frac{8}{\left(1 + \frac{R_{RCV}}{R_{T1}} + \frac{R_{RCV}}{R_{GP}}\right) \left(1 + \frac{Z_T}{Z_{T/R}}\right)}$$

Transmit Gain:

$$g_{tx} = \frac{V_{GSX}}{V_{T/R}}$$

$$g_{tx} = \frac{-R_X}{R_{T2}} \times \frac{300}{Z_{T/R}}$$

Hybrid Balance:

$$h_{bal} = 20 \log \left(\frac{R_X}{R_{HB}} - g_{tx} \times g_{rcv} \right)$$

$$h_{bal} = 20 \log \left(\frac{V_{GSX}}{V_{FR}} \right)$$

To optimize the hybrid balance, the sum of the currents at the VFX input of the codec op amp should be set to 0. The expression for ZHB becomes the following:

$$R_{HB}(k\Omega) = \frac{R_X}{g_{tx} \times g_{rcv}}$$

ac Applications (continued)

Design Examples (continued)

Example 1, Real Termination (continued)

Table 24. Parts List L9216; Agere T7504 First-Generation Codec Resistive Termination; Nonmeter Pulse Application

Name	Value	Tolerance	Rating	Function
Fault Protection				
RPT	30 Ω	1%	Fusible or PTC	Protection resistor.
RPR	30 Ω	1%	Fusible or PTC	Protection resistor.
Protector	Agere L7591	—	—	Secondary protection.
Power Supply				
CBAT1	0.1 μ F	20%	100 V	V _{BAT} filter capacitor.
CBAT2	0.1 μ F	20%	50 V	V _{BAT} filter capacitor. $ V_{BAT2} < V_{BAT1} $.
DBAT1	1N4004	—	—	Reverse current.
CCC	0.1 μ F	20%	10 V	V _{CC} filter capacitor.
CF1	0.22 μ F	20%	100 V	Filter capacitor.
CF2	0.1 μ F	20%	100 V	Filter capacitor.
Ring/Ring Trip				
C ₁	1.0 μ F	20%	10 V	Ring filter for square wave.
C ₂	0.47 μ F	20%	10 V	ac-couple input ring signal.
R ₁	12 k Ω	1%	1/16 W	Ring filter for square wave.
CRT	0.1 μ F	20%	10 V	Ring trip filter capacitor.
RRT	383 k Ω	1%	1/16 W	Ring trip filter resistor.
ac Interface				
R _{GX}	4750 Ω	1%	1/16 W	Sets T/R to V _{ITR} transconductance.
C _{TX}	0.1 μ F	20%	10 V	ac/dc separation.
C _{C1}	0.1 μ F	20%	10 V	dc blocking capacitor.
C _{C2}	0.1 μ F	20%	10 V	dc blocking capacitor.
R _{T3}	69.8 k Ω	1%	1/16 W	With R _{GP} and R _{Rcv} , sets termination impedance and receive gain.
R _{T6}	49.9 k Ω	1%	1/16 W	With R _X , sets transmit gain.
R _X	100 k Ω	1%	1/16 W	With R _{T6} , sets transmit gain.
R _{HB1}	100 k Ω	1%	1/16 W	With R _X , sets hybrid balance.
R _{Rcv}	60.4 k Ω	1%	1/16 W	With R _{GP} and R _{T3} , sets termination impedance and receive gain.
R _{GP}	26.7 k Ω	1%	1/16 W	With R _{Rcv} and R _{T3} , sets termination impedance and receive gain.
R _{GN} Optional	17.6 k Ω	1%	1/16 W	Optional. Compensates for input offset at R _{CVN} /R _{CVp} .

Notes:
Termination Impedance = 600 Ω .
Hybrid Balance = 600 Ω .
Tx = 0 dBm.
Rx = 0 dBm.

ac Applications (continued)

Design Examples (continued)

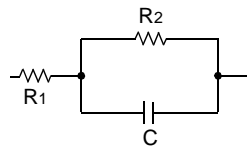
**First-Generation Codec ac Interface Network—
Complex Termination**

The reference circuit in Figure 26 shows the complete SLIC schematic for interface to the Agere T7504 first-generation codec for the German complex termination impedance. For this example, the ac interface was designed for a $220 \Omega + (820 \Omega \parallel 115 \text{ nF})$ complex termination and hybrid balance with transmit gain and receive gain set to 0 dBm. For illustration purposes, 1 Vrms PPM injection was assumed in this example. This implies the overhead voltage is increased to 7.24 V and no meter pulse rejection is required. Also, this example illustrates the device using fixed overhead and current limit.

Complex Termination Impedance Design Example

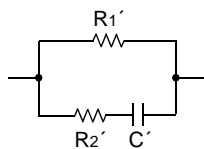
The gain shaping necessary for a complex termination impedance may be done by shaping across the AX amplifier at nodes ITR and VTX.

Complex termination is specified in the form:



5-6396(F)

To work with this application, convert termination to the form:



5-6398(F)

where:

$$R1' = R1 + R2$$

$$R2' = \frac{R1}{R2} (R1 + R2)$$

$$C' = \left(\frac{R2}{R1 + R2} \right)^2 C$$

ac Interface Using First-Generation Codec

$R_{GX}/R_{TGS}/C_{GS}$ (Z_{TG}): these components give gain shaping to get good gain flatness. These components are a scaled version of the specified complex termination impedance.

Note for pure (600 Ω) resistive terminations, components R_{TGS} and C_{GS} are not used. Resistor R_{GX} is used and is still 4750 Ω .

R_X/R_{T6} : with other components set, the transmit gain (for complex and resistive terminations) R_X and R_{T6} are varied to give specified transmit gain.

$R_{T3}/R_{RCV}/R_{GP}$: for both complex and resistive terminations, the ratio of these resistors sets the receive gain. For resistive terminations, the ratio of these resistors sets the return loss characteristic. For complex terminations, the ratio of these resistors sets the low-frequency return loss characteristic.

$C_N/R_{N1}/R_{N2}$: for complex terminations, these components provide high-frequency compensation to the return loss characteristic.

For resistive terminations, these components are not used and R_{CVN} is connected to ground via a resistor.

R_{HB} : sets hybrid balance for all terminations.

Set Z_{TG} —Gain Shaping:

$Z_{TG} = R_{GX} \parallel R_{TGS} + C_{GS}$ which is a scaled version of $Z_{T/R}$ (the specified termination resistance) in the $R1' \parallel R2' + C'$ form.

R_{GX} must be 4750 Ω to set SLIC transconductance to 300 V/A.

$$R_{GX} = 4750 \Omega$$

At dc, C_{GS} and C' are open.

$$R_{GX} = M \times R1'$$

where M is the scale factor.

$$M = \frac{4750}{R1'}$$

It can be shown:

$$R_{TGS} = M \times R2'$$

and

$$C_{TGS} = \frac{C'}{M}$$

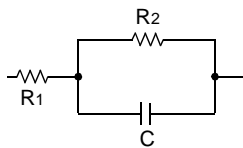
ac Applications (continued)

Design Examples (continued)

Transmit Gain

Transmit gain will be specified as a gain from T/R to PCM, T_X (dB). Since PCM is referenced to 600 Ω and assumed to be 0 dB, and in the case of T/R being referenced to some complex impedance other than 600 Ω resistive, the effects of the impedance transformation must be taken into account.

Again, specified complex termination impedance at T/R is of the form:



5-6396(F)

First, calculate the equivalent resistance of this network at the midband frequency of 1000 Hz.

$$R_{EQ} = \sqrt{\left(\frac{(2 \pi f)^2 C_1^2 R_1 R_2^2 + R_1 + R_2}{1 + (2 \pi f)^2 R_2^2 C_1^2}\right)^2 + \left(\frac{2 \pi f R_2^2 C_1}{1 + (2 \pi f)^2 R_2^2 C_1^2}\right)^2}$$

Using R_{EQ} , calculate the desired transmit gain, taking into account the impedance transformation:

$$T_X \text{ (dB)} = T_X \text{ (specified[dB])} + 20 \log \sqrt{\frac{600}{R_{EQ}}}$$

$T_X \text{ (specified[dB])}$ is the specified transmit gain. 600 Ω is the impedance at the PCM, and R_{EQ} is the impedance at

tip and ring. $20 \log \sqrt{\frac{600}{R_{EQ}}}$ represents the power

loss/gain due to the impedance transformation.

Note that in the case of a 600 Ω pure resistive termination

$$\text{at T/R } 20 \log \sqrt{\frac{600}{R_{EQ}}} = 20 \log \sqrt{\frac{600}{600}} = 0.$$

Thus, there is no power loss/gain due to impedance transformation and $T_X \text{ (dB)} = T_X \text{ (specified[dB])}$.

Finally, convert $T_X \text{ (dB)}$ to a ratio, g_{TX} :

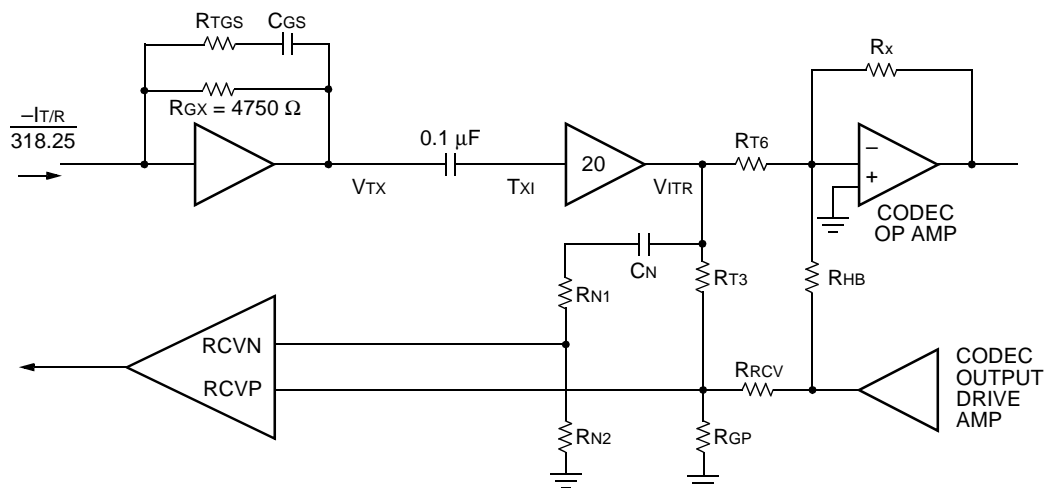
$$T_X \text{ (dB)} = 20 \log g_{TX}$$

The ratio of R_X/R_{T6} is used to set the transmit gain:

$$\frac{R_X}{R_{T6}} = g_{TX} \cdot \frac{318.25}{20} \cdot \frac{1}{M} \text{ with a quad Agere codec}$$

such as T7504:

$$R_X < 200 \text{ k}\Omega$$



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Figure 24. Interface Circuit Using First-Generation Codec (Blocking Capacitors Not Shown)

ac Applications (continued)

Design Examples (continued)

Receive Gain

Ratios of R_{RCV} , R_{T3} , R_{GP} will set both the low-frequency termination and receive gain for the complex case. In the complex case, additional high-frequency compensation, via C_N , R_{N1} , and R_{N2} , is needed for the return loss characteristic. For resistive termination, C_N , R_{N1} , and R_{N2} are not used and R_{CVN} is tied to ground via a resistor.

Determine the receive gain, g_{RCV} , taking into account the impedance transformation in a manner similar to transmit gain.

$$R_X \text{ (dB)} = R_{X \text{ (specified[dB])}} + 20 \log \sqrt{\frac{R_{EQ}}{600}}$$

$$R_X \text{ (dB)} = 20 \log g_{RCV}$$

Then:

$$g_{RCV} = \frac{4}{1 + \frac{R_{RCV}}{R_{T3}} + \frac{R_{RCV}}{R_{GP}}}$$

and low-frequency termination

$$Z_{TER(low)} = \frac{2400}{1 + \frac{R_{T3}}{R_{GP}} + \frac{R_{T3}}{R_{RCV}}} + 2R_P + 50 \Omega$$

$Z_{TER(low)}$ is the specified termination impedance assuming low frequency (C or C' is open).

R_P is the series protection resistor.

50Ω is the typical internal feed resistance.

These two equations are best solved using a computer spreadsheet.

Next, solve for the high-frequency return loss compensation circuit, C_N , R_{N1} , and R_{N2} :

$$C_N R_{N2} = \frac{2R_P}{2400} C_G R_{TGP}$$

$$R_{N1} = R_{N2} \left[\frac{2400}{2R_P} \left(\frac{R_{TGS}}{R_{TGP}} \right) - 1 \right]$$

There is an input offset voltage associated with nodes R_{CVN} and R_{CVP} . To minimize the effect of mismatch of this voltage at T/R, the equivalent resistance to ac ground at R_{CVN} should be approximately equal to that at R_{CVP} . Refer to Figure 25 (with dc blocking capacitors). To meet this requirement, $R_{N2} = R_{GP} \parallel R_{T3}$.

Hybrid Balance

Set the hybrid cancellation via R_{HB} .

$$R_{HB} = \frac{R_X}{g_{RCV} \times g_{TX}}$$

If a 5 V only codec such as the Agere T7504 is used, dc blocking capacitors must be added as shown in Figure 25. This is because the codec is referenced to 2.5 V and the SLIC to ground—with the ac coupling, a dc bias at T/R is eliminated and power associated with this bias is not consumed.

Typically, values of 0.1 μ F to 0.47 μ F capacitors are used for dc blocking. The addition of blocking capacitors will cause a shift in the return loss and hybrid balance frequency response toward higher frequencies, degrading the lower-frequency response. The lower the value of the blocking capacitor, the more pronounced the effect is, but the cost of the capacitor is lower. It may be necessary to scale resistor values higher to compensate for the low-frequency response. This effect is best evaluated via simulation. A *PSPICE*[®] model for the L9216 is available.

Design equation calculations seldom yield standard component values. Conversion from the calculated value to standard value may have an effect on the ac parameters. This effect should be evaluated and optimized via simulation.

ac Applications (continued)

Design Examples (continued)

Blocking Capacitors (continued)

Table 25. Parts List L9216; Agere T7504 First-Generation Codec Complex Termination; Meter Pulse Application

Termination impedance = $220\ \Omega + (820\ \Omega \parallel 115\ \text{nF})$, hybrid balance = $220\ \Omega + (820\ \Omega \parallel 115\ \text{nF})$ Tx = 0 dBm, Rx = 0 dBm.

Name	Value	Tolerance	Rating	Function
Fault Protection				
RPT	30 Ω	1%	Fusible or PTC	Protection resistor.
RPR	30 Ω	1%	Fusible or PTC	Protection resistor.
Protector	Agere L7591	—	—	Secondary protection.
Power Supply				
CBAT1	0.1 μF	20%	100 V	VBAT filter capacitor.
CBAT2	0.1 μF	20%	50 V	VBAT filter capacitor. $ V_{\text{BAT}2} < V_{\text{BAT}1} $.
DBAT1	1N4004	—	—	Reverse current.
CCC	0.1 μF	20%	10 V	VCC filter capacitor.
CF1	0.22 μF	20%	100 V	Filter capacitor.
CF2	0.1 μF	20%	100 V	Filter capacitor.
Ring/Ring Trip				
CRING	0.47 μF	20%	10 V	ac-couple input ring signal.
CRT	0.1 μF	20%	10 V	Ring trip filter capacitor.
RRT	383 k Ω	1%	1/16 W	Ring trip filter resistor.
ac Interface				
RGX	4750 Ω	1%	1/16 W	Sets T/R to VITR transconductance.
RTGS	1.74 k Ω	1%	1/16 W	Gain shaping for complex termination.
CGS	12 nF	5%	10 V	Gain shaping for complex termination.
CTX	0.1 μF	20%	10 V	ac/dc separation.
CC1	0.1 μF	20%	10 V	dc blocking capacitor.
CC2	0.1 μF	20%	10 V	dc blocking capacitor.
RT3	49.9 k Ω	1%	1/16 W	With RGP and RRCV, sets termination impedance and receive gain.
RT6	40.2 k Ω	1%	1/16 W	With Rx, sets transmit gain.
RX	115 k Ω	1%	1/16 W	With RT6, sets transmit gain.
RHB1	113 k Ω	1%	1/16 W	With Rx, sets hybrid balance.
RRCV	59.0 k Ω	1%	1/16 W	With RGP and RT3, sets termination impedance and receive gain.
RGP	54.9 k Ω	1%	1/16 W	With RRCV and RT3, sets termination impedance and receive gain.
CN	120 pF	20%	10 V	High frequency compensation.
RN1	127 k Ω	1%	1/16 W	High frequency compensation.
RN2	47.5 k Ω	1%	1/16 W	High frequency compensation, compensate for dc offset at RCVP/RCVN.

ac Applications (continued)

Design Examples (continued)

Third-Generation Codec ac Interface Network—Complex Termination

The following reference circuit, Figure 27, shows the complete SLIC schematic for interface to the Agere T8536 third-generation codec. All ac parameters are programmed by the T8536. Note this codec differentiates itself in that no external components are required in the ac interface to provide a dc termination impedance or for stability. For illustration purposes, 0.5 Vrms PPM injection was assumed in this example and no meter pulse rejection is used. Also, this example illustrates the device using programmable overhead and current limit. Please see the T8535/6 data sheet for information on coefficient programming.

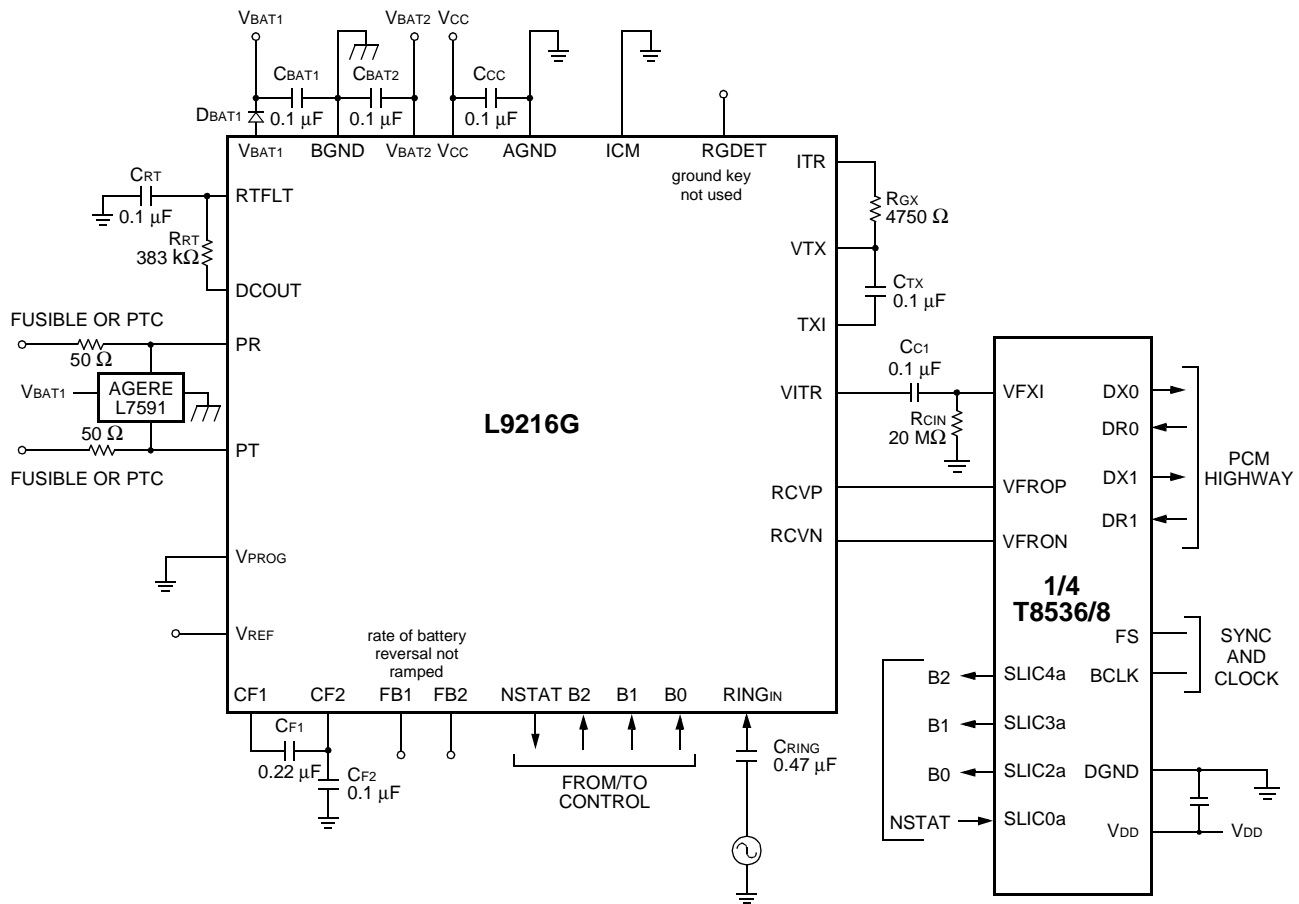


Figure 27. Third-Generation Codec ac Interface Network; Complex Termination

ac Applications (continued)

Design Examples (continued)

Third-Generation Codec ac Interface Network—Complex Termination (continued)

Table 26. Parts List L9216; Agere T8536 Third-Generation Codec ac and dc Parameters; Fully Programmable

Name	Value	Tolerance	Rating	Function
Fault Protection				
RPT	50 Ω	1%	Fusible or PTC	Protection resistor*.
RPR	50 Ω	1%	Fusible or PTC	Protection resistor*.
Protector	Agere L7591	—	—	Secondary protection.
Power Supply				
CBAT1	0.1 μ F	20%	100 V	V _{BAT} filter capacitor.
CBAT2	0.1 μ F	20%	50 V	V _{BAT} filter capacitor. $ V_{BAT2} < V_{BAT1} $.
DBAT1	1N4004	—	—	Reverse current.
CCC	0.1 μ F	20%	10 V	V _{CC} filter capacitor.
CF1	0.22 μ F	20%	100 V	Filter capacitor.
CF2	0.1 μ F	20%	100 V	Filter capacitor.
Ring/Ring Trip				
CRING	0.47 μ F	20%	10 V	ac-couple input ring signal.
CRT	0.1 μ F	20%	10 V	Ring trip filter capacitor.
RRT	383 k Ω	1%	1/16 W	Ring trip filter resistor.
ac Interface				
RGX	4750 Ω	1%	1/16 W	Sets T/R to V _{ITR} transconductance.
RCIN	20 M Ω	5%	1/16 W	dc bias.
CTX	0.1 μ F	20%	10 V	ac/dc separation.
CC1	0.1 μ F	20%	10 V	dc blocking capacitor.

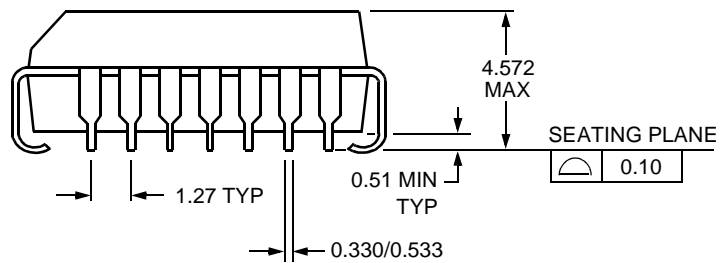
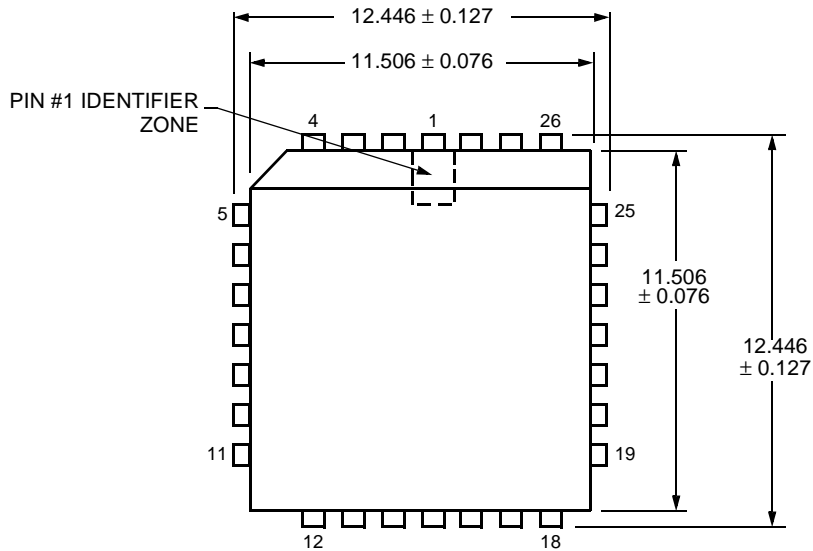
* For loop stability, increase to 50 Ω minimum if synthesizing 900 Ω or 900 Ω + 2.16 μ F termination impedance.

Outline Diagrams

28-Pin PLCC

Dimensions are in millimeters.

Note: The dimensions in this outline diagram are intended for informational purposes only. For detailed schematics to assist your design efforts, please contact your Agere Sales Representative.



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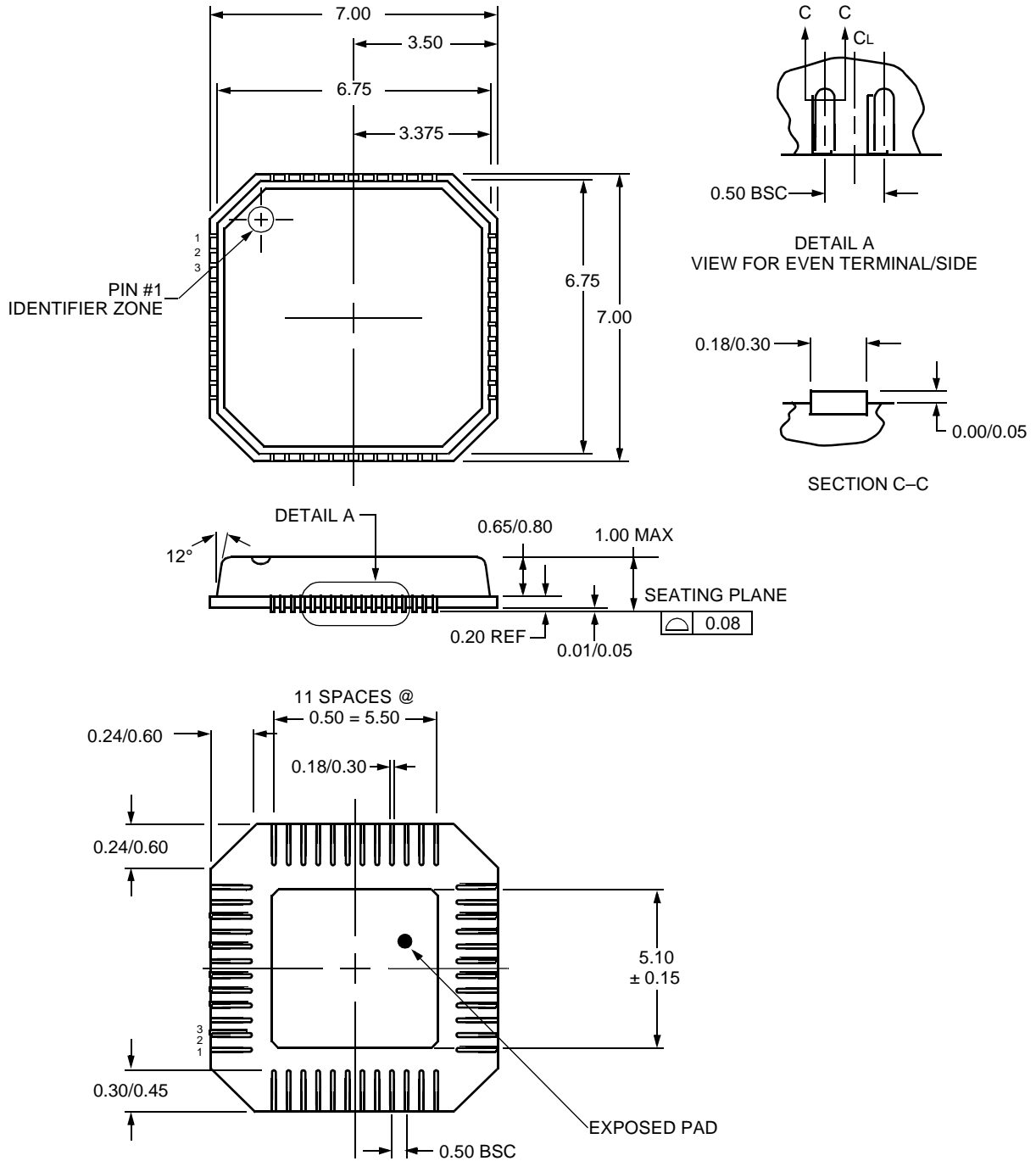
Outline Diagrams (continued)

48-Pin MLCC

Dimensions are in millimeters.

Notes: The dimensions in this outline diagram are intended for informational purposes only. For detailed schematics to assist your design efforts, please contact your Agere Sales Representative.

The exposed pad on the bottom of the package will be at V_{BAT1} potential.



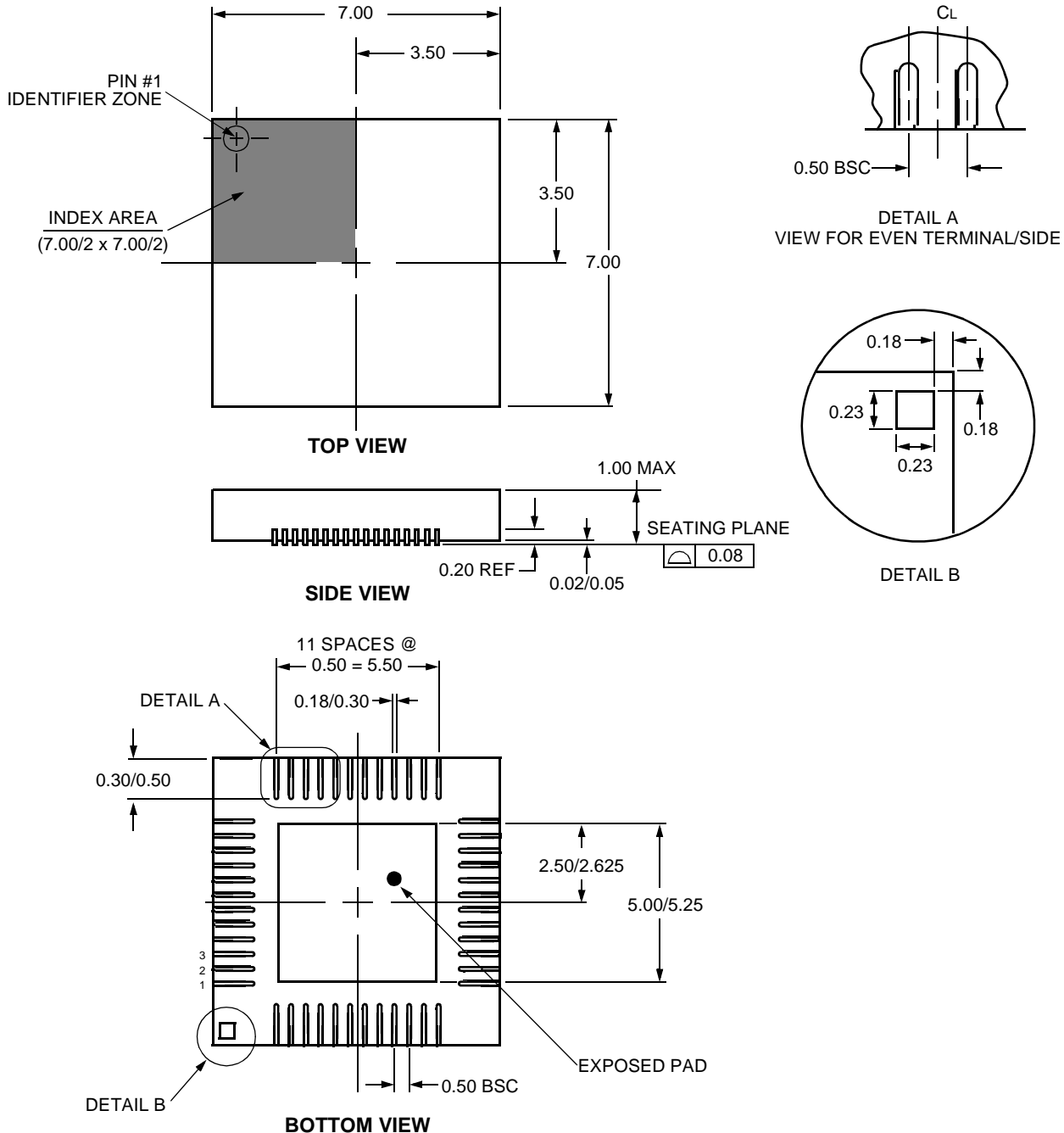
Outline Diagrams (continued)

48-Pin MLCC, JEDEC MO-220 VKKD-2

Dimensions are in millimeters.

Notes: The dimensions in this outline diagram are intended for informational purposes only. For detailed schematics to assist your design efforts, please contact your Agere Sales Representative.

The exposed pad on the bottom of the package will be at V_{BAT1} potential.



0195a

Ordering Information

Device Part No.	Description	Package	Comcode
LUCL9216AGF-D	SLIC Gain = 8	28-Pin PLCC Dry-bagged	108876723
LUCL9216AGF-DT	SLIC Gain = 8	28-Pin PLCC Tape & Reel, Dry-bagged	108876731
LUCL9216GGF-D	SLIC Gain = 2	28-Pin PLCC Tape & Reel	108876780
LUCL9216GGF-DT	SLIC Gain = 2	28-Pin PLCC Tape & Reel, Dry-bagged	108876798
LUCL9216ARG-D	SLIC Gain = 8	48-Pin MLCC Dry-bagged	108955477
LUCL9216GRG-D	SLIC Gain = 2	48-Pin MLCC Dry-bagged	108955469

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