

STK6713AMK3

Stepping Motor Fixed-current Driver

Overview

The STK6713AMK3 is a unipolar fixed-current choppertype 4-phase stepping motor driver hybrid IC (HIC) which uses a MOSFET power device. The excitation sequence signal is active High.

Applications

• Serial printer, line printer, PPC, laser beam printer (LBP) paper feed and carriage motor drivers

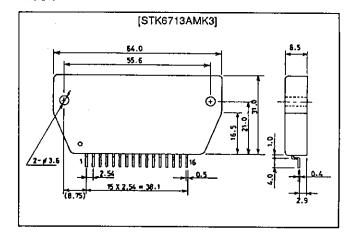
Features

- Fixed-current driver device which uses MOSFET
- Input signal supporting TTL level (Active High drive type)
- On-chip current detection resistor

Package Dimensions

unit: mm

4131

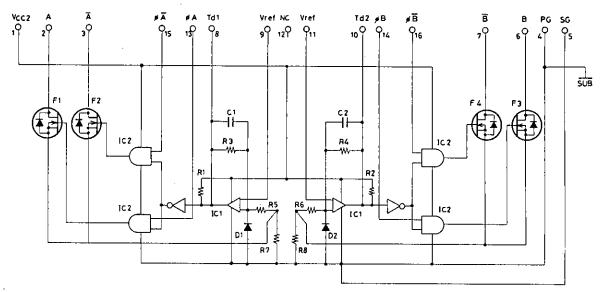


Specifications

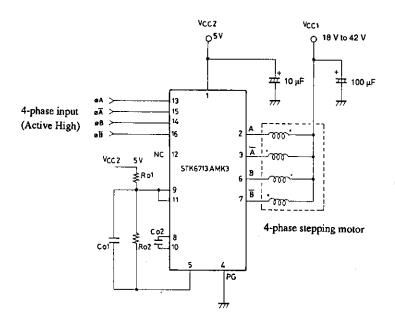
Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions		Ratings		Unit
Maximum supply voltage 1	V _{CC} 1max	No input signal		52		V
Maximum supply voltage 2	V _{CC} 2max	No input signal		7		v
Maximum phase current	I _{OH} max	per phase, $R/L = 5\Omega/10mH$,		3.9		Α
		0.5 s 1 pulse, Vcc input				
Repeated avalanche handling capability	Ear max			42		mJ
Storage temperature	Tstg	r .	-40 to +125			°C
Junction temperature	Tj max			150		°C
Operating substrate temperature	Tc max			105	٠	°C
Allowable Operating Conditions at Ta = 25°C				typ	max	Unit
Supply voltage 1	V _{CC} 1	With input signal	18	_	42	v
Supply voltage 2	V_{CC}^2	With input signal	4.75	5.0	5.25	V
Phase driver withstand voltage	V_{DSS}		100			V
Phase current	I _{OH} max	Duty 50%			3.0	A
Electrical Characteristics at Ta = 25°C, Vcc1 = 36V, Vcc2 = 5V				typ	max	Unit
Output saturation voltage	V_{ST}	$R_{L}=14\Omega, V_{IN}=2.4V$		1.5	2.1	v
Output current (average)	Io ave	Load; R/L=3.5Ω/3.8mH, V _{IN} =2.4V per phase	0.414	0.46	0.506	A
Pin 1 current consumption (average)	I_{CC}^2	Load; R/L = $3.5\Omega/3.8$ mH, V _{IN} = 2.4 V per phase		10	20	mA
FET diode forward voltage	Vdf	$I_f = 1.0A$		1.2	1.8	v
TTL input ON voltage	V _{IH}	Input voltage when F1, 2, 3, 4 ON	2.0			v
TTL input OFF voltage	V _{IL}	Input voltage when F1, 2, 3, 4 OFF			0.8	V
Switching time	t _{ON}	$R_{L}=24\Omega, V_{IN}=2.4V$		80		ns
	t _{OFF}	$R_{L}=24\Omega, V_{IN}=2.4V$		0.2		μs
Note: With regulated voltage power	supply.					

Equivalent Circuit

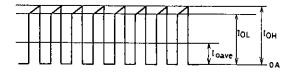


Application Circuit



Note: For reference, when $I_{OH}\approx 1.0 A,\,R_{O1}$ = $6.8 k\Omega$ and R_{O2} = $390\Omega.$

Output current waveform when phases held (locked)



Measure output current values in this state.

$$\begin{split} I_{OH} &= K \ X \ \frac{R_{O2}}{R_{O1} + R_{O2}} \ X \ V_{CC} 2 / R_7 \\ K &\approx 1.2 \\ R_7 &= R_8 = 0.33 \Omega \pm 3\% \end{split}$$

To reduce noise during motor hold, it is possible to mount $C_{O1} \approx 0.01~\mu F$ and $C_{O2} \approx 100\text{-}200~pF$. Normally these are not required.

Note: Both input signals cannot be H at the same time.

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